## Supplementary Notes on Aggregate Data Structures

15-312: Foundations of Programming Languages Frank Pfenning

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Before we go into aggregate data structures (pairs, sums, and some recursive types), we discuss how run-time errors can be handled in a type-safe language [Ch. 9.3]. Consider extending our MinML language by a partial division operator,  $\operatorname{div}(e_1,e_2)$ . Besides the usual typing rules and search rules for the operational semantics, we would also have the following reduction rule:

$$\frac{(n_2 \neq 0)}{\operatorname{div}(\operatorname{num}(n_1), \operatorname{num}(n_2)) \mapsto \operatorname{num}(\lfloor n_1/n_2 \rfloor)}$$

The condition  $n_2 \neq 0$  means that there is no rule for div(num(n), num(0)) and evaluation gets stuck. Progress would be violated.

We can restore an amended progress theorem if we introduce a new judgment e aborts to explicitly require that run-time errors will abort the program rather than continuing in some random state. We add the rule

$$\overline{\text{div}(\text{num}(n_1),\text{num}(0))}$$
 aborts

However, we are not finished, because an expression such as

must also abort, but we have no rule that allows us to conclude this. So in addition to the search rules we have "abort propagation" rules that propagate run-time errors up to the overall program we are trying to evaluate.

We show the two rules for application as an example; similar rules are necessary for all search rules to account for a possible abort.

$$rac{e_1 ext{ aborts}}{ ext{apply}(e_1,e_2) ext{ aborts}} \ rac{v_1 ext{ value} \quad e_2 ext{ aborts}}{ ext{apply}(v_1,e_2) ext{ aborts}}$$

Now we can refine the statements progress and determinism to account for the new judgment. Note that preservation does not change, because it only has to account for a successful computation step.

- 1. (Preservation) If  $\cdot \vdash e : \tau$  and  $e \mapsto e'$  then  $\cdot \vdash e' : \tau$ .
- 2. (Progress) If  $\cdot \vdash e : \tau$  then either
  - (i)  $e \mapsto e'$  for some e', or
  - (ii) e value, or
  - (iii) e aborts.
- 3. (Determinism) If  $\cdot \vdash e : \tau$  then exactly one of
  - (i)  $e \mapsto e'$  for some unique e', or
  - (ii) e value, or
  - (iii) e aborts.

We do not give her a proof of these properties, nor do we discuss how the language might be extended with a try...handle...end construct in order to catch error conditions.

Now we come to various language extensions which make MinML a more realistic language without changing its basic character.

**Products.** Introducing products just means adding pairs and a unit element to the language [Ch. 19.1]. We could also directly add *n*-ary products, but we will instead discuss records later when we talk about object-oriented programming. MinML is a call-by-value language. For consistency with the basic choice, the pair constructor also evaluates its arguments—otherwise we would be dealing with *lazy pairs*. In addition to the pair

<sup>&</sup>lt;sup>1</sup>See Assignment 3

constructor, we can extract the first and second component of a pair.<sup>2</sup>

$$\frac{\Gamma \vdash e_1 : \tau_1 \quad \Gamma \vdash e_2 : \tau_2}{\Gamma \vdash \mathtt{pair}(e_1, e_2) : \mathtt{cross}(\tau_1, \tau_2)}$$

$$\frac{\Gamma \vdash e : \mathtt{cross}(\tau_1, \tau_2)}{\Gamma \vdash \mathtt{fst}(e) : \tau_1} \qquad \frac{\Gamma \vdash e : \mathtt{cross}(\tau_1, \tau_2)}{\Gamma \vdash \mathtt{snd}(e) : \tau_2}$$

For the unit type we only have a constructor but no destructor, since there are no components to extract.

$$\overline{\Gamma \vdash \text{unitel} : \text{unit}}$$

We often adopt a more mathematical notation according to the table at the end of these notes. However, it is important to remember that the mathematical shorthand is just that: it is just a different way to shorten higher-order abstract syntax or make it easier to read.

A pair is a value if both components are values. If not, we can use the search rules to reduce, using a left-to-right order. Finally, the reduction rules extract the corresponding component of a pair.

$$\frac{e_1 \; \mathsf{value} \quad e_2 \; \mathsf{value}}{\mathsf{pair}(e_1, e_2) \; \mathsf{value}}$$

$$\frac{e_1 \mapsto e_1'}{\texttt{pair}(e_1, e_2) \mapsto \texttt{pair}(e_1', e_2)} \quad \frac{v_1 \, \texttt{value} \quad e_2 \mapsto e_2'}{\texttt{pair}(v_1, e_2) \mapsto \texttt{pair}(v_1, e_2')}$$

$$\frac{e \mapsto e'}{\texttt{fst}(e) \mapsto \texttt{fst}(e')} \quad \frac{e \mapsto e'}{\texttt{snd}(e) \mapsto \texttt{snd}(e')}$$

$$\frac{v_1 \text{ value } v_2 \text{ value}}{\text{fst}(\text{pair}(v_1, v_2)) \mapsto v_1} \quad \frac{v_1 \text{ value } v_2 \text{ value}}{\text{snd}(\text{pair}(v_1, v_2)) \mapsto v_2}$$

Since it is at the core of the progress property, we make the value inversion property explicit.

If 
$$\cdot \vdash v : \mathtt{cross}(\tau_1, \tau_2)$$
 and  $v$  value then  $v = \mathtt{pair}(v_1, v_2)$  for some  $v_1$  value and  $v_2$  value.

<sup>&</sup>lt;sup>2</sup>An alternative treatment is given in [Ch. 19.1], where the destructor provides access to both components of a pair simultaneously. Also, the unit type comes with a corresponding check construct.

**Unit Type.** The unit types does not yield any new search or reduction rules, only a new value. At first it may not seem very useful, but we will see an application in the next section on sums.

```
unitel value
```

The value inversion property is also simple.

```
If \cdot \vdash v: unit then v = \langle \rangle.
```

**Sums.** Unions, as one might now them from the C programming language, are inherently not type safe. They can be abused in order to access the underlying representations of data structures and intentionally violate any kind of abstraction that might be provided by the language. Consider, for example, the following snippet from C.

```
union {
    float f;
    int i;
} unsafe;

unsafe.f = 5.67e-5;
printf("%d", unsafe.i);
```

Here we set the member of the union as a floating point number and then print the underlying bit pattern as if it represented an integer. Of course, much more egregious examples can be imagined here.

In a type-safe language we replace unions by disjoint sums. In the implementation, the members of a disjoint sum type are tagged with their origin so we can safely distinguish the cases. In order for every expression to have a unique type, we also need to index the corresponding injection operator with their target type.<sup>3</sup>

$$\begin{split} \frac{\Gamma \vdash e_1 : \tau_1}{\Gamma \vdash \text{inl}(\tau_1, \tau_2, e_1) : \text{sum}(\tau_1, \tau_2)} & \frac{\Gamma \vdash e_2 : \tau_2}{\Gamma \vdash \text{inr}(\tau_1, \tau_2, e_2) : \text{sum}(\tau_1, \tau_2)} \\ \frac{\Gamma \vdash e : \text{sum}(\tau_1, \tau_2) \quad \Gamma, x_1 : \tau_1 \vdash e_1 : \sigma \quad \Gamma, x_2 : \tau_2 \vdash e_2 : \sigma}{\Gamma \vdash \text{case}(e, x_1.e_1, x_2.e_2) : \sigma} \end{split}$$

<sup>&</sup>lt;sup>3</sup>Strictly speaking, some of this information is redundant, but it is easier read if we are fully explicit here.

Note that we require both branches of a case-expression to have the same type  $\sigma$ , just as for a conditional, because we cannot be sure at type-checking time which branch will be taken.

$$\begin{array}{c} \frac{e_1 \text{ value}}{\text{inl}(\tau_1,\tau_2,e_1) \text{ value}} & \frac{e_2 \text{ value}}{\text{inr}(\tau_1,\tau_2,e_2) \text{ value}} \\ \\ \frac{e \mapsto e'}{\text{case}(e,x_1.e_1,x_2.e_2) \mapsto \text{case}(e',x_1.e_1,x_2.e_2)} \\ \\ \frac{v_1 \text{ value}}{\text{case}(\text{inl}(\tau_1,\tau_2,v_1),x_1.e_1,x_2.e_2) \mapsto \{v_1/x_1\}e_1} \\ \\ \frac{v_2 \text{ value}}{\text{case}(\text{inr}(\tau_1,\tau_2,v_2),x_1.e_1,x_2.e_2) \mapsto \{v_2/x_2\}e_2} \end{array}$$

We also state the value inversion property.

If 
$$\cdot \vdash v : \operatorname{sum}(\tau_1, \tau_2)$$
 then either  $v = \operatorname{inl}(\tau_1, \tau_2, v_1)$  with  $v_1$  value or  $v = \operatorname{inr}(\tau_1, \tau_2, v_2)$  with  $v_2$  value.

**Empty Type.** The empty type can be thought of as a zero-ary sum. It has no values and a corresponding abort construct which should never be executable unless we add an error value to the language.

$$\frac{\Gamma \vdash e : \mathtt{void}}{\Gamma \vdash \mathtt{abort}(\tau, e) : \tau}$$

There is only one search rule of computation, but no actual reduction rule.

$$\frac{e \mapsto e'}{\mathtt{abort}(\tau, e) \mapsto \mathtt{abort}(\tau, e')}$$

The value inversion property here just expresses that there are no values of void type.

If  $\cdot \vdash v$ : void then we have a contradiction.

Higher-Order Abstract Syntax	Concrete Syntax	Mathematical Syntax
$\texttt{arrow}(\tau_1,\tau_2)$	$\tau_1 \rightarrow \tau_2$	$ au_1  ightarrow  au_2$
$\mathtt{cross}( au_1, au_2)$	$\tau_1 * \tau_2$	$ au_1  imes  au_2$
unit	unit	1
$sum( au_1, au_2)$	$ au_1$ + $ au_2$	$ au_1 +  au_2$
void	void	0
$\mathtt{pair}(e_1,e_2)$	$(e_1$ , $e_2$ )	$\langle e_1, e_2 \rangle$
$\mathtt{fst}(e)$	$\sharp 1 e$	$\pi_1e$
$\mathtt{snd}(e)$	#2e	$\pi_2  e$
unitel	( )	⟨⟩
$\mathtt{inl}(\tau_1,\tau_2,e_1)$	$\mathtt{inl}(e_1):\tau_1 {+} \tau_2$	$inl_{ au_1+ au_2}(e_1)$
$\mathtt{inr}( au_1, au_2,e_2)$	$\mathtt{inr}(e_2): au_1$ + $ au_2$	$inr_{ au_1+ au_2}(e_2)$
$\mathtt{case}(e, x_1.e_1, x_2.e_2)$	$\mathtt{case}e$	$case(e, x_1.e_1, x_2.e_2)$
	of $inl(x_1) \Rightarrow e_1$	
	$  \operatorname{inr}(x_2) \Rightarrow e_2$	
	esac	
$\mathtt{abort}(\tau,e)$	$\mathtt{abort}(e):  au$	$abort_{ au}(e)$