COZMO

Big brain. Bigger personality.

Maze Navigator

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Objectives

- Detecting the Walls
- Detecting distances and rotations to walls
- Deciding the moves to make
- Mapping the walls



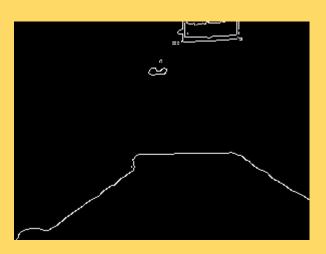
Detecting the Walls

Thresholded Image for detecting edges of the wall

Process the image to generate a series of lines

Process the lines to generate the specific walls





Navigating the Maze

Build dictionary to hold a points -> walls

Detect the walls and add walls to dictionary

Keeps track of block coordinates to make decision on next move

Moves are deciding based on Depth-First-Search



Things to Finish

Fixing errors for cozmo to move at the center of each block

Fixing the DFS to take into account visited blocks