Synchronization: Basics

15-213: Introduction to Computer Systems 24th Lecture, April, 12, 2016

Instructors:

Seth Copen Goldstein, Franz Franchetti, Ralf Brown, and Brian Railing

Today

- **■** Threads review
- Sharing
- Mutual exclusion
- Semaphores

Process: Traditional View

Process = process context + code, data, and stack

Process context

Program context:

Data registers
Condition codes

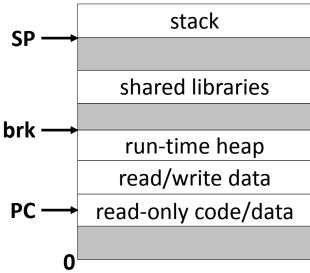
Stack pointer (SP)

Program counter (PC)

Kernel context:

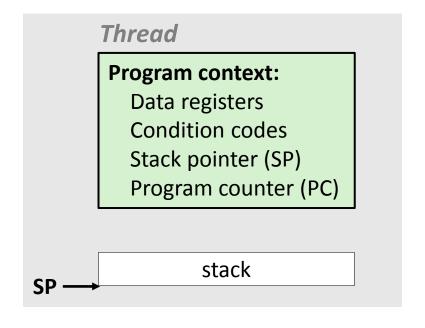
VM structures
Descriptor table
brk pointer

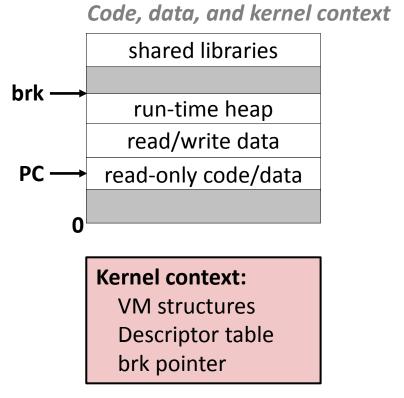
Code, data, and stack



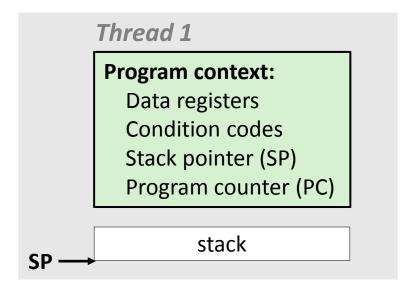
Process: Alternative View

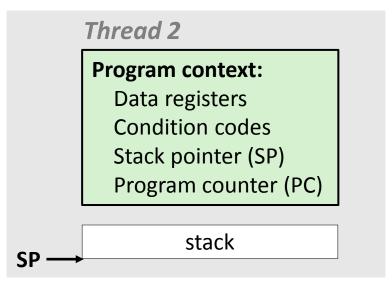
Process = thread + code, data, and kernel context





Process with Two Threads





shared libraries brk run-time heap read/write data PC read-only code/data Kernel context:

Shared Variables in Threaded C Programs

- Question: Which variables in a threaded C program are shared?
 - The answer is not as simple as "global variables are shared" and "stack variables are private"
- Def: A variable x is shared if and only if multiple threads reference some instance of x.
- Requires answers to the following questions:
 - What is the memory model for threads?
 - How are instances of variables mapped to memory?
 - How many threads might reference each of these instances?

Threads Memory Model

Conceptual model:

- Multiple threads run within the context of a single process
- Each thread has its own separate thread context
 - Thread ID, stack, stack pointer, PC, condition codes, and GP registers
- All threads share the remaining process context
 - Code, data, heap, and shared library segments of the process virtual address space
 - Open files and installed handlers

Operationally, this model is not strictly enforced:

- Register values are truly separate and protected, but...
- Any thread can read and write the stack of any other thread

The mismatch between the conceptual and operation model is a source of confusion and errors

Example Program to Illustrate Sharing

```
char **ptr; /* global var */
int main()
  long i;
  pthread_t tid;
  char *msgs[2] = {
     "Hello from foo",
     "Hello from bar"
  };
  ptr = msgs;
  for (i = 0; i < 2; i++)
     Pthread_create(&tid,
       NULL.
       thread,
       (void *)i);
  Pthread_exit(NULL);
                                    sharing.c
```

```
void *thread(void *vargp)
{
  long myid = (long)vargp;
  static int cnt = 0;

  printf("[%ld]: %s (cnt=%d)\n",
      myid, ptr[myid], ++cnt);
  return NULL;
}
```

Peer threads reference main thread's stack indirectly through global ptr variable

Mapping Variable Instances to Memory

Global variables

- Def: Variable declared outside of a function
- Virtual memory contains exactly one instance of any global variable

Local variables

- Def: Variable declared inside function without static attribute
- Each thread stack contains one instance of each local variable

Local static variables

- Def: Variable declared inside function with the static attribute
- Virtual memory contains exactly one instance of any local static variable.

Mapping Variable Instances to Memory

```
Global var: 1 instance (ptr [data])
                                        Local vars: 1 instance (i.m, msgs.m)
char **ptr; /* global var */
                                               Local var: 2 instances (
                                                  myid.p0 [peer thread 0's stack],
int main()
                                                  myid.p1 [peer thread 1's stack]
  long i;
  pthread_t tid;
  char *msgs[2] = {
                                               void *thread(vojd *vargp)
     "Hello from foo",
     "Hello from bar"
  };
                                                  long myid = (long)vargp;
                                                  static int cnt = 0;
  ptr = msgs;
  for (i = 0; i < 2; i++)
                                                  printf("[%|d]: %s (cnt=%d)\n",
     Pthread_create(&tid,
                                                     myid, ptr[myid], ++cnt);
       NULL.
                                                  return NULL;
       thread,
       (void *)i);
                                                     Local static var: 1 instance (cnt [data])
  Pthread_exit(NULL);
                                  sharing.c
```

Shared Variable Analysis

Which variables are shared?

```
Variable Referenced by Referenced by
                                       Referenced by
instance main thread? peer thread 0? peer thread 1?
              yes
                             yes
                                             yes
ptr
cnt
              no
                             yes
                                             yes
                             no
                                             no
i.m
              yes
msgs.m
              yes
                             yes
                                             yes
myid.p0
             no
                                             no
                             yes
myid.p1
              no
                             no
                                             yes
```

```
/* thread routine */
void *thread(void *vargp)
{
   int myid = (int)vargp;
   static int cnt = 0;

   printf("[%d]: %s (svar=%d)\n",
        myid, ptr[myid], ++cnt);
}
```

Shared Variable Analysis

Which variables are shared?

Variable instance	Referenced by main thread?	Referenced by peer thread 0?	Referenced by peer thread 1?
ptr	yes no	yes yes	yes yes
cnt i.m	yes	no	no
msgs.m	yes	yes	yes
myid.p0 myid.p1		yes no	no yes

- Answer: A variable x is shared iff multiple threads reference at least one instance of x. Thus:
 - ptr, cnt, and msgs are shared
 - i and myid are *not* shared

Synchronizing Threads

- Shared variables are handy...
- ...but introduce the possibility of nasty synchronization errors.

badcnt.c: Improper Synchronization

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */
int main(int argc, char **argv)
  long niters;
  pthread t tid1, tid2;
  niters = atoi(argv[1]);
  Pthread_create(&tid1, NULL,
     thread, &niters);
  Pthread_create(&tid2, NULL,
     thread, &niters);
  Pthread_join(tid1, NULL);
  Pthread_join(tid2, NULL);
  /* Check result */
  if (cnt != (2 * niters))
     printf("BOOM! cnt=%ld\n", cnt);
  else
     printf("OK cnt=%ld\n", cnt);
  exit(0);
                                           badcnt.c
```

```
linux> ./badcnt 10000
OK cnt=20000
linux> ./badcnt 10000
BOOM! cnt=13051
linux>
```

cnt should equal 20,000.

What went wrong?

Assembly Code for Counter Loop

C code for counter loop in thread i

```
for (i = 0; i < niters; i++)
    cnt++;</pre>
```

Asm code for thread i

```
movq (%rdi), %rcx
    testq %rcx, %rcx
                              H_i: Head
    jle .L2
    movl $0, %eax
.L3:
                              L_i: Load cnt
    movq cnt(%rip),%rdx
                              U_i: Update cnt
    addq $1, %rdx
                              S_i: Store cnt
    movq %rdx, cnt(%rip)
    addq $1, %rax
    cmpq %rcx, %rax
                              T_i: Tail
    ine
           .L3
.L2:
```

Concurrent Execution

- Key idea: In general, any sequentially consistent interleaving is possible, but some give an unexpected result!
 - I_i denotes that thread i executes instruction I
 - %rdx_i is the content of %rdx in thread i's context

i (thread)	instr _i	$ m \%rdx_1$	%rdx ₂	cnt		
1	H ₁	-	-	0		Thread 1
1	L ₁	0	-	0		critical section
1	U_1	1	-	0		
1	S_1	1	-	1		Thread 2
2	H_2	-	-	1		critical section
2	L_2	-	1	1		
2	U_2	-	2	1		
2	S ₂	-	2	2		
2	T ₂	-	2	2		
1	T_1	1	_	2	OK	

Concurrent Execution (cont)

Incorrect ordering: two threads increment the counter, but the result is 1 instead of 2

i (thread)	instr _i	$%$ rd x_1	$%$ rd x_2	cnt
1	H ₁	-	-	0
1	L ₁	0	-	0
1	U ₁	1	-	0
2	H ₂	-	-	0
2	L ₂	-	0	0
1	S ₁	1	-	1
1	T ₁	1	-	1
2	U ₂	-	1	1
2	S ₂	-	1	1
2	T ₂	-	1	1

Oops:

Concurrent Execution (cont)

How about this ordering?

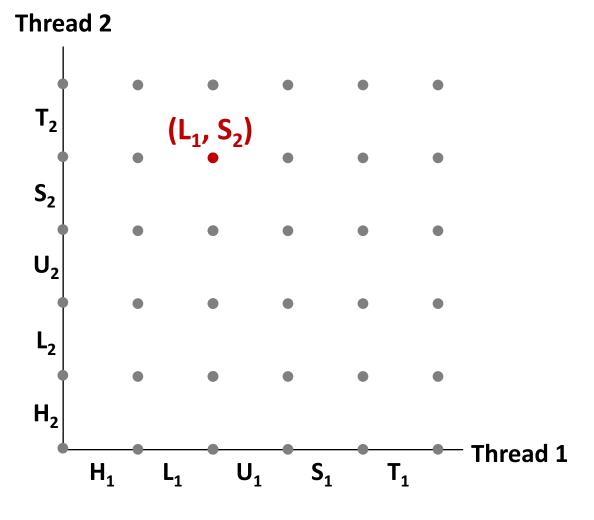
i (thread)	instr _i	$%$ rd x_1	$%$ rd x_2	cnt
1	H ₁			0
1	L ₁	0		
2	H_2			
2	L ₂		0	
2	U ₂		1	
2	S ₂		1	1
1	U ₁	1		
1	S ₁	1		1
1				1
2	T ₂			1

Oops!

■ We can analyze the behavior using a *progress graph*

Progress Graphs





A progress graph depicts the discrete execution state space of concurrent threads.

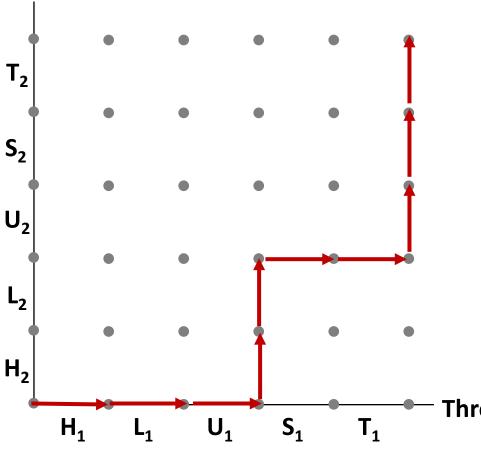
Each axis corresponds to the sequential order of instructions in a thread.

Each point corresponds to a possible *execution state* (Inst₁, Inst₂).

E.g., (L₁, S₂) denotes state where thread 1 has completed L₁ and thread 2 has completed S₂.

Trajectories in Progress Graphs

Thread 2



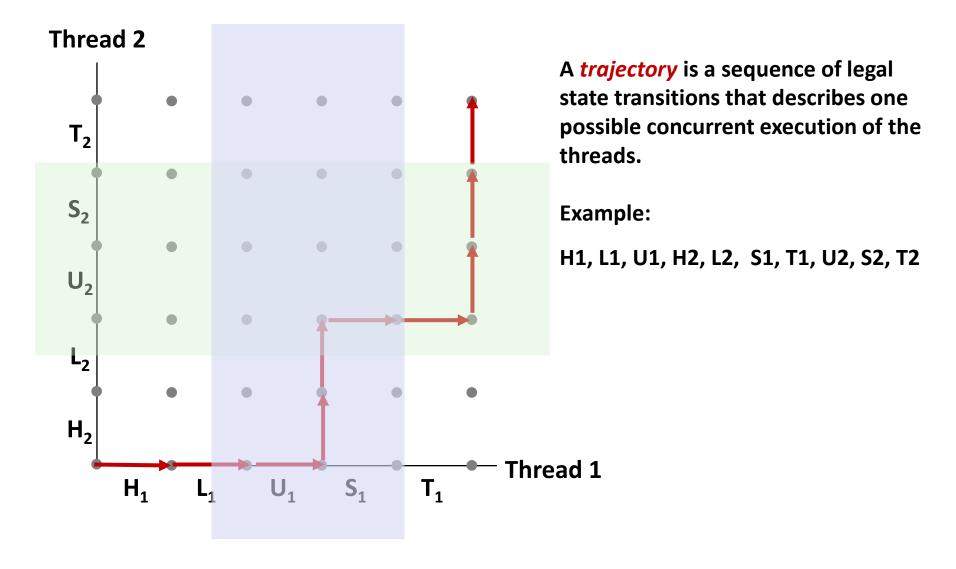
A *trajectory* is a sequence of legal state transitions that describes one possible concurrent execution of the threads.

Example:

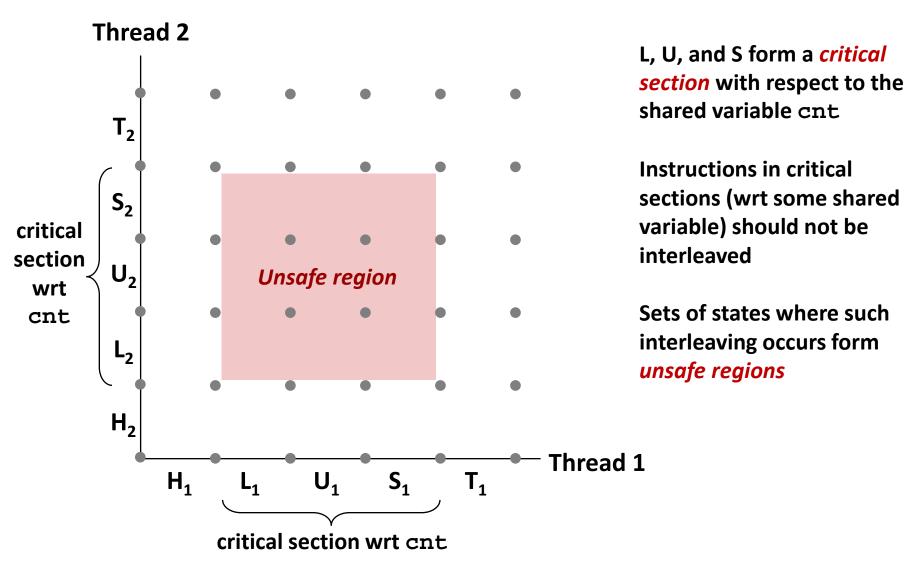
H1, L1, U1, H2, L2, S1, T1, U2, S2, T2

Thread 1

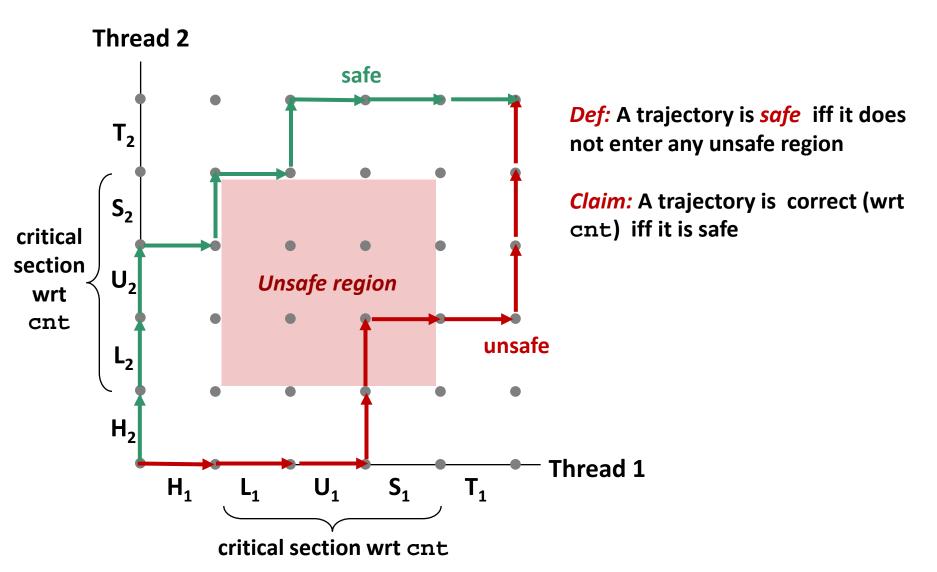
Trajectories in Progress Graphs



Critical Sections and Unsafe Regions



Critical Sections and Unsafe Regions



badcnt.c: Improper Synchronization

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volatile long cnt = 0; /* Counter */
int main(int argc, char **argv)
  long niters;
  pthread t tid1, tid2;
  niters = atoi(argv[1]);
  Pthread_create(&tid1, NULL,
     thread, &niters);
  Pthread_create(&tid2, NULL,
     thread, &niters);
  Pthread_join(tid1, NULL);
  Pthread_join(tid2, NULL);
  /* Check result */
  if (cnt != (2 * niters))
     printf("BOOM! cnt=%ld\n", cnt);
  else
     printf("OK cnt=%ld\n", cnt);
  exit(0);
                                           badcnt.c
```

Variable	main	thread1	thread2
cnt	no	yes	yes
niters.m	yes	no	no
tid1.m	yes	no	no
i.1	no	yes	no
i.2	No	No	Yes
niters.1	No	Yes	No

No

ves

No

niters.2

Enforcing Mutual Exclusion

- Question: How can we guarantee a safe trajectory?
- Answer: We must synchronize the execution of the threads so that they can never have an unsafe trajectory.
 - i.e., need to guarantee mutually exclusive access for each critical section.
- Classic solution:
 - Semaphores (Edsger Dijkstra)
- Other approaches (out of our scope)
 - Mutex and condition variables (Pthreads)
 - Monitors (Java)

Semaphores

- Semaphore: non-negative global integer synchronization variable. Manipulated by P and V operations.
- P(s)
 - If s is nonzero, then decrement s by 1 and return immediately.
 - Test and decrement operations occur atomically (indivisibly)
 - If s is zero, then suspend thread until s becomes nonzero and the thread is restarted by a V operation.
 - After restarting, the P operation decrements s and returns control to the caller.
- V(s):
 - Increment s by 1.
 - Increment operation occurs atomically
 - If there are any threads blocked in a P operation waiting for s to become non-zero, then restart exactly one of those threads, which then completes its P operation by decrementing s.
- Semaphore invariant: (s >= 0)

Semaphores

- Semaphore: non-negative global integer synchronization variable
- Manipulated by P and V operations:
 - P(s): [while (s == 0) wait(); s--;]
 - Dutch for "Proberen" (test)
 - V(s): [s++;]
 - Dutch for "Verhogen" (increment)
- OS kernel guarantees that operations between brackets [] are executed indivisibly
 - Only one P or V operation at a time can modify s.
 - When while loop in P terminates, only that P can decrement s
- Semaphore invariant: (s >= 0)

C Semaphore Operations

Pthreads functions:

```
#include <semaphore.h>
int sem_init(sem_t *s, 0, unsigned int val);} /* s = val */
int sem_wait(sem_t *s); /* P(s) */
int sem_post(sem_t *s); /* V(s) */
```

CS:APP wrapper functions:

```
#include "csapp.h"

void P(sem_t *s); /* Wrapper function for sem_wait */
void V(sem_t *s); /* Wrapper function for sem_post */
```

badcnt.c: Improper Synchronization

```
/* Global shared variable */
volatile long cnt = 0; /* Counter */
int main(int argc, char **argv)
  long niters:
  pthread t tid1, tid2;
  niters = atoi(argv[1]);
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     thread, &niters);
  Pthread_create(&tid2, NULL,
     thread, &niters);
  Pthread_join(tid1, NULL);
  Pthread_join(tid2, NULL);
  /* Check result */
  if (cnt != (2 * niters))
     printf("BOOM! cnt=%ld\n", cnt);
  else
     printf("OK cnt=%ld\n", cnt);
  exit(0);
                                            badcnt.c
```

How can we fix this using semaphores?

Using Semaphores for Mutual Exclusion

Basic idea:

- Associate a unique semaphore mutex, initially 1, with each shared variable (or related set of shared variables).
- Surround corresponding critical sections with P(mutex) and V(mutex) operations.

Terminology:

- Binary semaphore: semaphore whose value is always 0 or 1
- Mutex: binary semaphore used for mutual exclusion
 - P operation: "locking" the mutex
 - V operation: "unlocking" or "releasing" the mutex
 - "Holding" a mutex: locked and not yet unlocked.
- Counting semaphore: used as a counter for set of available resources.

goodcnt.c: Proper Synchronization

Define and initialize a mutex for the shared variable cnt:

```
volatile long cnt = 0; /* Counter */
sem_t mutex; /* Semaphore that protects cnt */
Sem_init(&mutex, 0, 1); /* mutex = 1 */
```

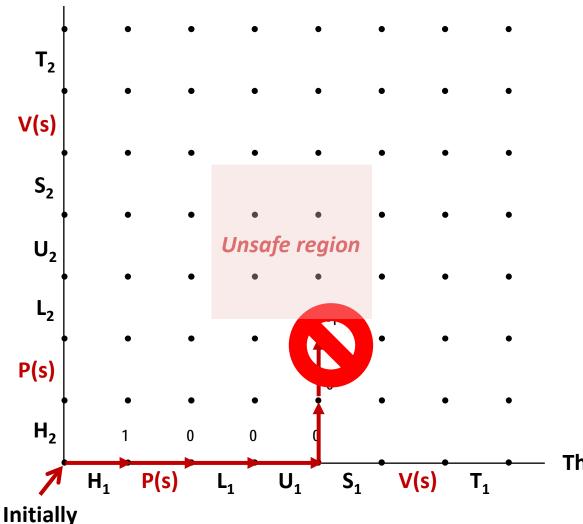
Surround critical caction with D and W.

owdown
)X
ΣX
aN
)

And slower means much slower!

ver

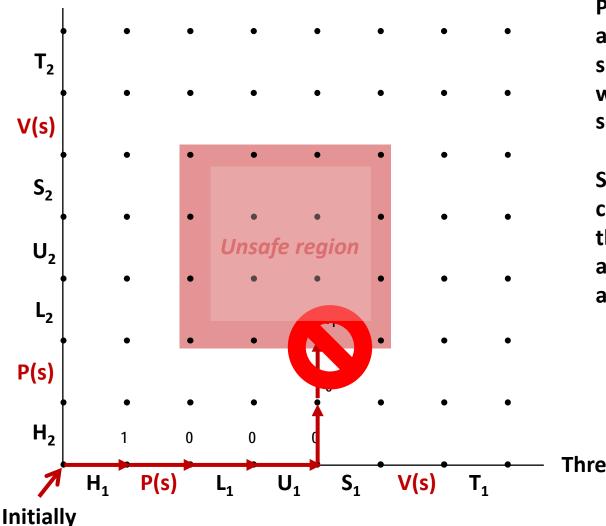
Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with *P* and *V* operations on semaphore s (initially set to 1)

Thread 1

Thread 2



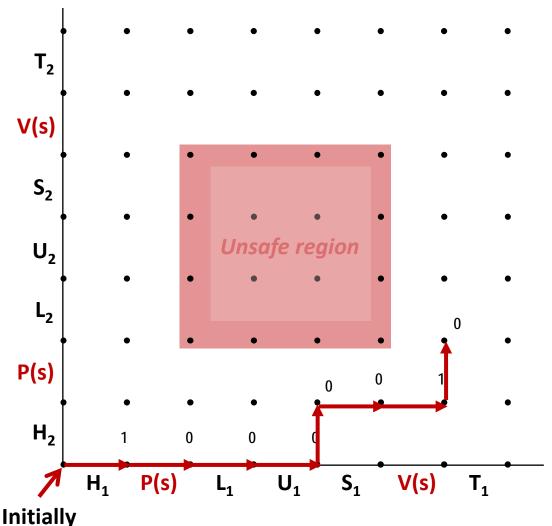
Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant creates a forbidden region that encloses unsafe region and that cannot be entered by any trajectory.

Thread 1

S = 1Bryant and O'Hallaron, Computer Systems: A Programmer's Perspective, Third Edition

Thread 2

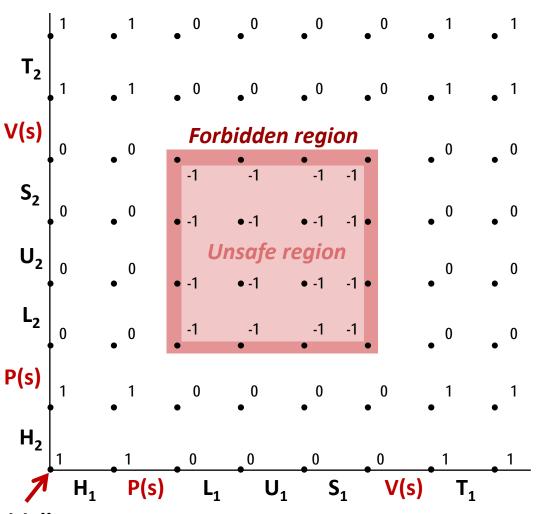


Provide mutually exclusive access to shared variable by surrounding critical section with P and V operations on semaphore s (initially set to 1)

Semaphore invariant creates a forbidden region that encloses unsafe region and that cannot be entered by any trajectory.

Thread 1

Thread 2



Provide mutually exclusive access to shared variable by surrounding critical section with *P* and *V* operations on semaphore s (initially set to 1)

Semaphore invariant creates a *forbidden region* that encloses unsafe region and that cannot be entered by any trajectory.

Thread 1

Initially

Summary

- Programmers need a clear model of how variables are shared by threads.
- Variables shared by multiple threads must be protected to ensure mutually exclusive access.
- Semaphores are a fundamental mechanism for enforcing mutual exclusion.