Concurrent Programming

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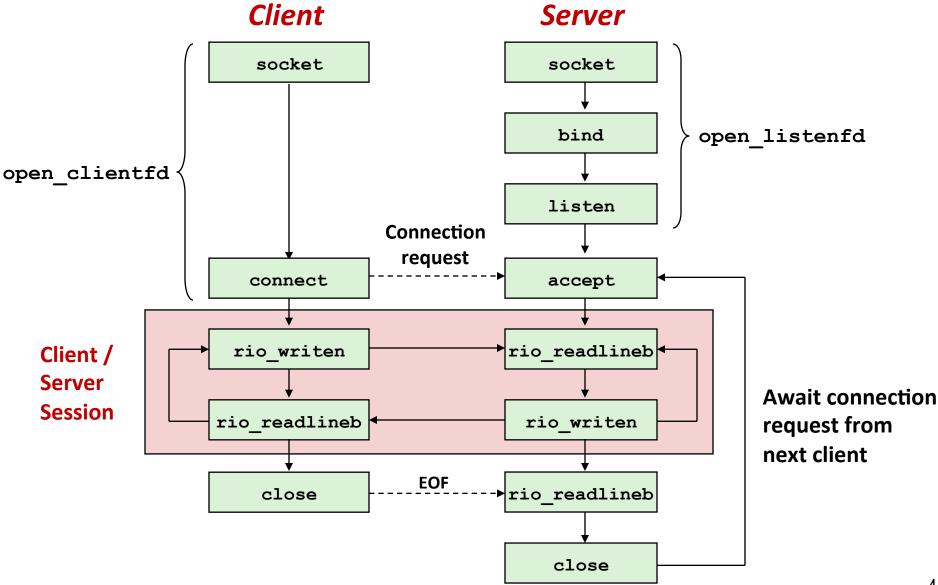
Concurrent Programming is Hard!

- The human mind tends to be sequential
- The notion of time is often misleading
- Thinking about all possible sequences of events in a computer system is at least error prone and frequently impossible

Concurrent Programming is Hard!

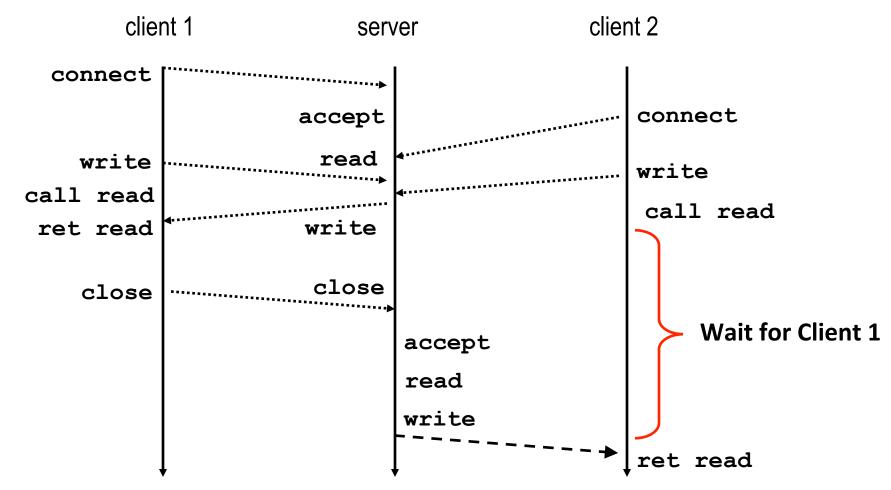
- Classical problem classes of concurrent programs:
 - Races: outcome depends on arbitrary scheduling decisions elsewhere in the system
 - Example: who gets the last seat on the airplane?
 - Deadlock: improper resource allocation prevents forward progress
 - Example: traffic gridlock
 - Livelock / Starvation / Fairness: external events and/or system scheduling decisions can prevent sub-task progress
 - Example: people always jump in front of you in line
- Many aspects of concurrent programming are beyond the scope of 15-213
 - but, not all [©]

Reminder: Iterative Echo Server



Iterative Servers

Iterative servers process one request at a time



Where Does Second Client Block?

Second client attempts to connect to iterative server

Client socket open clientfd Connection request connect rio writen rio readlineb

Call to connect returns

- Even though connection not yet accepted
- Server side TCP manager queues request
- Feature known as "TCP listen backlog"

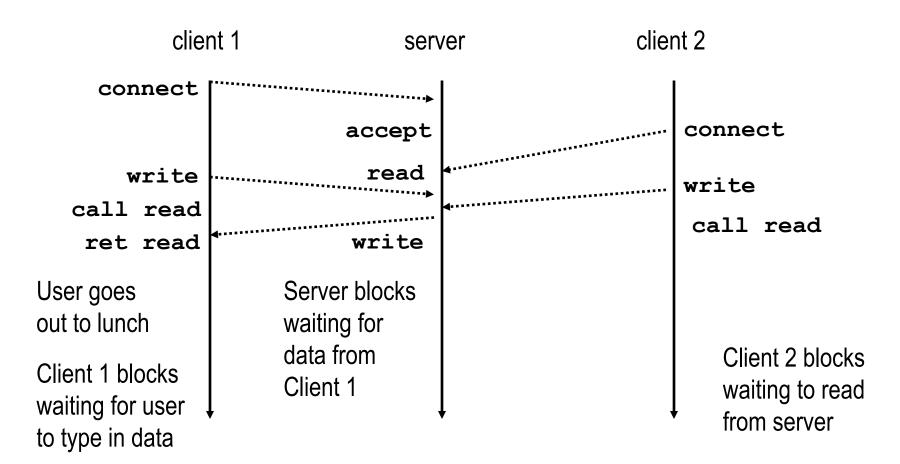
Call to rio_writen returns

Server side TCP manager buffers input data

Call to rio_readlineb blocks

Server hasn't written anything for it to read yet.

Fundamental Flaw of Iterative Servers



Solution: use concurrent servers instead

 Concurrent servers use multiple concurrent flows to serve multiple clients at the same time

Server concurrency (3 approaches)

Allow server to handle multiple clients simultaneously

■ 1. Processes

- Kernel automatically interleaves multiple logical flows
- Each flow has its own private address space

2. Threads

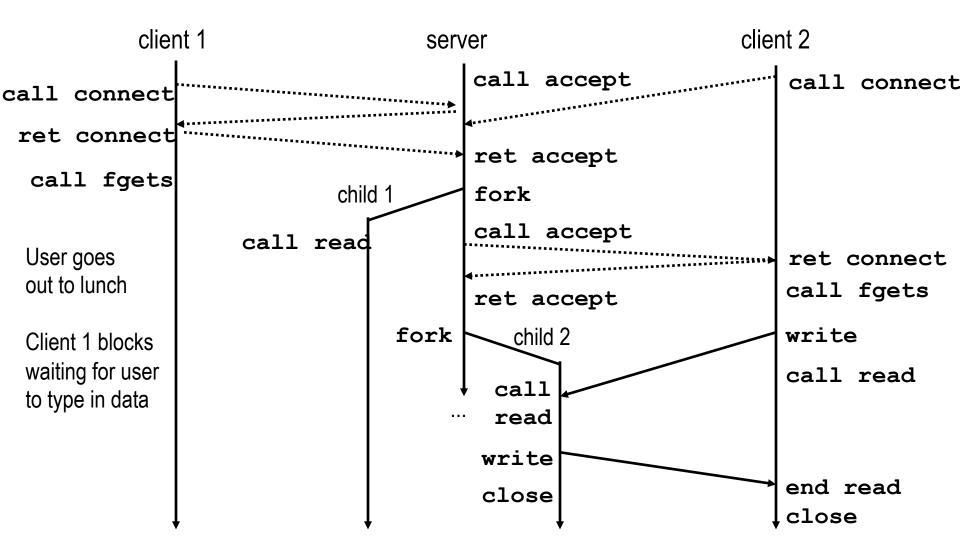
- Kernel automatically interleaves multiple logical flows
- Each flow shares the same address space

■ 3. I/O multiplexing with select()

- Programmer manually interleaves multiple logical flows
- All flows share the same address space
- Relies on lower-level system abstractions

Concurrent Servers: Multiple Processes

Spawn separate process for each client



Review: Iterative Echo Server

```
int main(int argc, char **argv)
    int listenfd, connfd;
    int port = atoi(argv[1]);
    struct sockaddr in clientaddr;
    int clientlen = sizeof(clientaddr);
    listenfd = Open listenfd(port);
    while (1) {
      connfd = Accept(listenfd, (SA *)&clientaddr, &clientlen);
      echo(connfd);
      Close (connfd);
    exit(0);
```

- Accept a connection request
- Handle echo requests until client terminates

Process-Based Concurrent Echo Server

```
int main(int argc, char **argv)
                                         Fork separate process for
{
                                           each client
    int listenfd, connfd;
    int port = atoi(argv[1]);
                                         Does not allow any
    struct sockaddr in clientaddr;
                                           communication between
    int clientlen=sizeof(clientaddr);
                                           different client handlers
    Signal(SIGCHLD, sigchld handler);
    listenfd = Open listenfd(port);
   while (1) {
       connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
       if (Fork() == 0) {
           Close(listenfd); /* Child closes its listening socket */
           echo(connfd); /* Child services client */
           Close (connfd); /* Child closes connection with client */
                           /* Child exits */
           exit(0);
       Close(connfd); /* Parent closes connected socket (important!) */
```

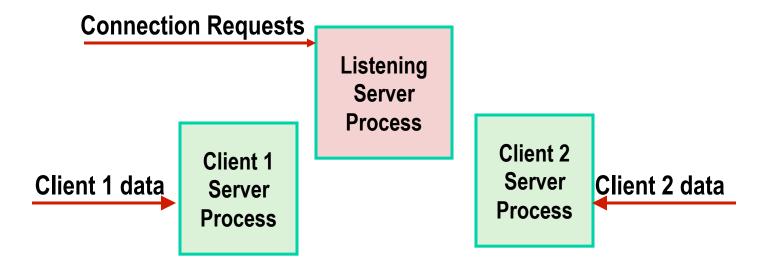
Process-Based Concurrent Echo Server (cont)

```
void sigchld_handler(int sig)
{
    while (waitpid(-1, 0, WNOHANG) > 0)
    ;
    return;
}
```

Reap all zombie children



Process Execution Model

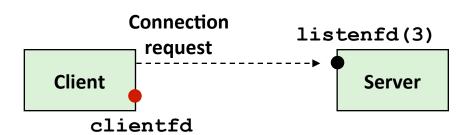


- Each client handled by independent process
- No shared state between them
- Both parent & child have copies of listenfd and connfd
 - Parent must close connfd
 - Child must close listenfd

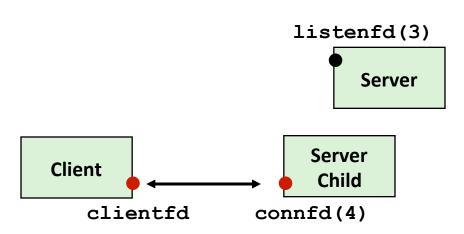
Concurrent Server: accept Illustrated



1. Server blocks in accept, waiting for connection request on listening descriptor listenfd



2. Client makes connection request by calling connect



3. Server returns connfd from accept. Forks child to handle client. Connection is now established between clientfd and connfd

Implementation Must-dos With Process-Based Designs

- Listening server process must reap zombie children
 - to avoid fatal memory leak
- Listening server process must close its copy of connfd
 - Kernel keeps reference for each socket/open file
 - After fork, refcnt (connfd) = 2
 - Connection will not be closed until refent (connfd) == 0

Pros and Cons of Process-Based Designs

- + Handle multiple connections concurrently
- + Clean sharing model
 - descriptors (no)
 - file tables (yes)
 - global variables (no)
- + Simple and straightforward
- Additional overhead for process control
- Nontrivial to share data between processes
 - Requires IPC (interprocess communication) mechanisms
 - FIFO's (named pipes), System V shared memory and semaphores

Approach #2: Multiple Threads

- Very similar to approach #1 (multiple processes)
 - but, with threads instead of processes

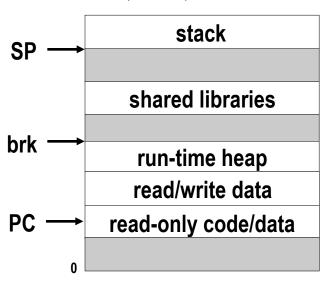
Traditional View of a Process

Process = process context + code, data, and stack

Process context

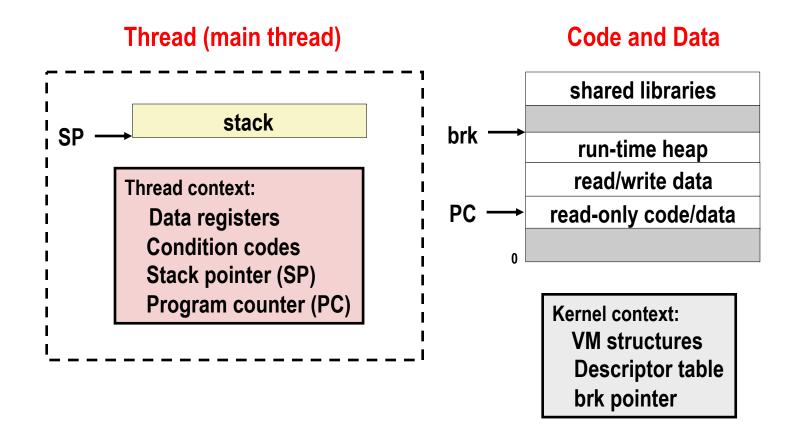
Program context:
Data registers
Condition codes
Stack pointer (SP)
Program counter (PC)
Kernel context:
VM structures
Descriptor table
brk pointer

Code, data, and stack



Alternate View of a Process

Process = thread + code, data, and kernel context



A Process With Multiple Threads

- Multiple threads can be associated with a process
 - Each thread has its own logical control flow
 - Each thread shares the same code, data, and kernel context
 - Share common virtual address space (inc. stacks)
 - Each thread has its own thread id (TID)

Thread 1 (main thread)

stack 1

Thread 1 context:

Data registers

Condition codes

SP1

PC1

Shared code and data

shared libraries

run-time heap

read/write data

read-only code/data

Kernel context:

VM structures
Descriptor table
brk pointer

Thread 2 (peer thread)

stack 2

Thread 2 context:

Data registers

Condition codes

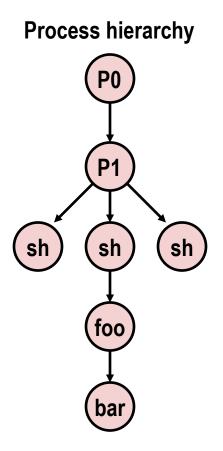
SP2

PC2

Logical View of Threads

- Threads associated with process form a pool of peers
 - Unlike processes which form a tree hierarchy

Threads associated with process foo T2 shared code, data and kernel context T3



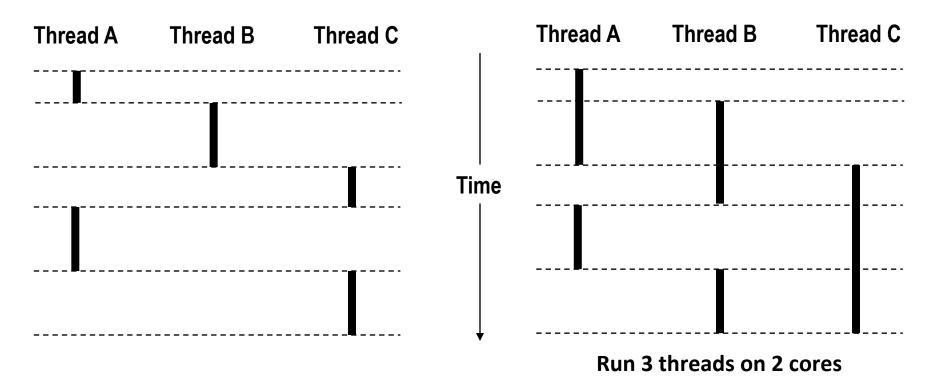
Thread Execution

Single Core Processor

Simulate concurrency by time slicing

Multi-Core Processor

Can have true concurrency



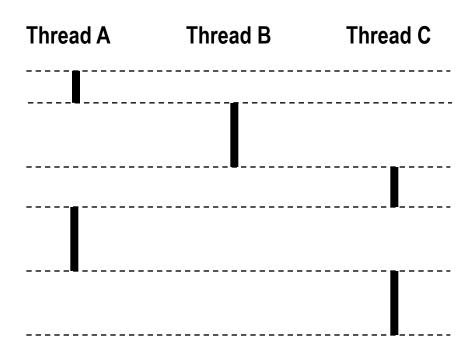
Logical Concurrency

- Two threads are (logically) concurrent if their flows overlap in time
- Otherwise, they are sequential

Examples:

- Concurrent: A & B, A&C
- Sequential: B & C

Time



Threads vs. Processes

How threads and processes are similar

- Each has its own logical control flow
- Each can run concurrently with others (possibly on different cores)
- Each is context switched

How threads and processes are different

- Threads share code and some data
 - Processes (typically) do not
- Threads are somewhat less expensive than processes
 - Process control (creating and reaping) twice as expensive as thread control
 - Linux numbers:
 - ~20K cycles to create and reap a process
 - ~10K cycles (or less) to create and reap a thread

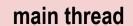
Posix Threads (Pthreads) Interface

- Pthreads: Standard interface for ~60 functions that manipulate threads from C programs
 - Creating and reaping threads
 - pthread create()
 - pthread join()
 - Determining your thread ID
 - pthread_self()
 - Terminating threads
 - pthread cancel()
 - pthread_exit()
 - exit() [terminates all threads], RET [terminates current thread]
 - Synchronizing access to shared variables
 - pthread_mutex_init
 - pthread mutex [un]lock
 - pthread cond init
 - pthread cond [timed]wait

The Pthreads "hello, world" Program

```
* hello.c - Pthreads "hello, world" program
 */
#include "csapp.h"
                                                 Thread attributes
                                                  (usually NULL)
void *thread(void *varqp);
int main() {
                                                 Thread arguments
  pthread t tid;
                                                     (void *p)
  Pthread create(&tid, NULL, thread, NULL);
  Pthread join(tid, NULL);
  exit(0);
                                                 return value
                                                  (void **p)
/* thread routine */
void *thread(void *vargp) {
  printf("Hello, world!\n");
  return NULL;
```

Execution of Threaded"hello, world"



any peer threads

call Pthread_create() Pthread_create() returns peer thread call Pthread_join() printf() main thread waits for return NULL; peer thread to terminate (peer thread terminates) Pthread_join() returns exit() terminates main thread and

Thread-Based Concurrent Echo Server

```
int main(int argc, char **argv) {
    int port = atoi(argv[1]);
    struct sockaddr in clientaddr;
    int clientlen=sizeof(clientaddr);
    pthread t tid;
    int listenfd = Open listenfd(port);
    while (1) {
      int *connfdp = Malloc(sizeof(int));
      *connfdp = Accept(listenfd,
                         (SA *) &clientaddr, &clientlen);
      Pthread create(&tid, NULL, echo thread, connfdp);
```

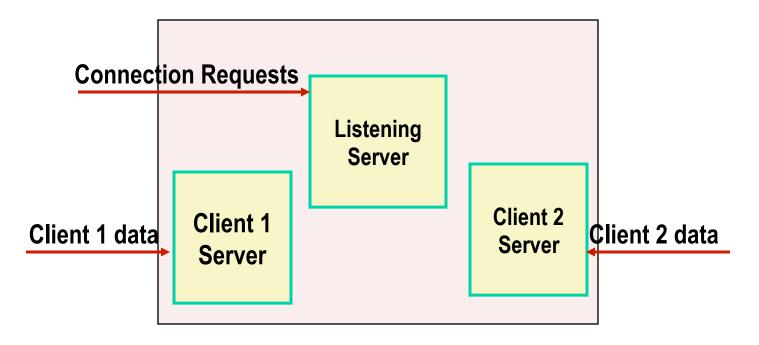
- Spawn new thread for each client
- Pass it copy of connection file descriptor
- Note use of Malloc()!
 - Without corresponding Free()

Thread-Based Concurrent Server (cont)

```
/* thread routine */
void *echo_thread(void *vargp)
{
   int connfd = *((int *)vargp);
   Pthread_detach(pthread_self());
   Free(vargp);
   echo(connfd);
   Close(connfd);
   return NULL;
}
```

- Run thread in "detached" mode
 - Runs independently of other threads
 - Reaped automatically (by kernel) when it terminates
- Free storage allocated to hold clientfd
 - "Producer-Consumer" model

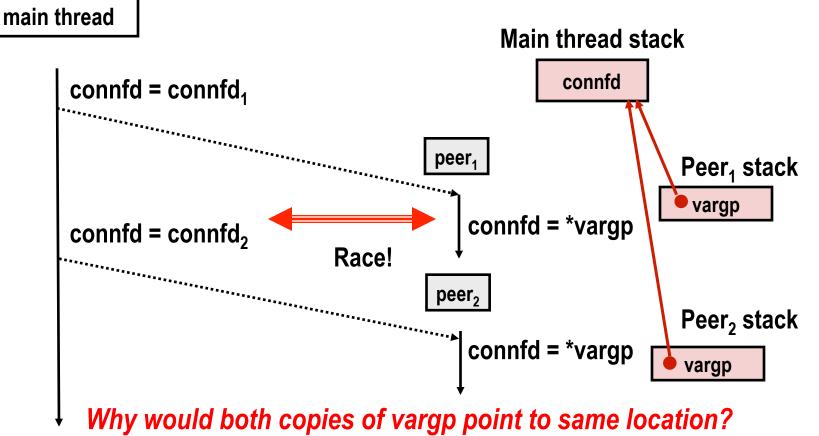
Threaded Execution Model



- Multiple threads within single process
- Some state between them
 - e.g., file descriptors

Potential Form of Unintended Sharing

```
while (1) {
    int connfd = Accept(listenfd, (SA *) &clientaddr, &clientlen);
    Pthread_create(&tid, NULL, echo_thread, (void *) &connfd);
}
```



Could this race occur?

Main

Thread

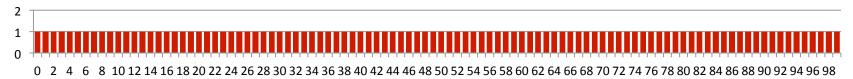
```
void *thread(void *vargp)
{
  int i = *((int *)vargp);
  Pthread_detach(pthread_self());
  save_value(i);
  return NULL;
}
```

Race Test

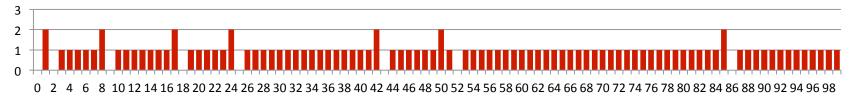
- If no race, then each thread would get different value of i
- Set of saved values would consist of one copy each of 0 through 99

Experimental Results

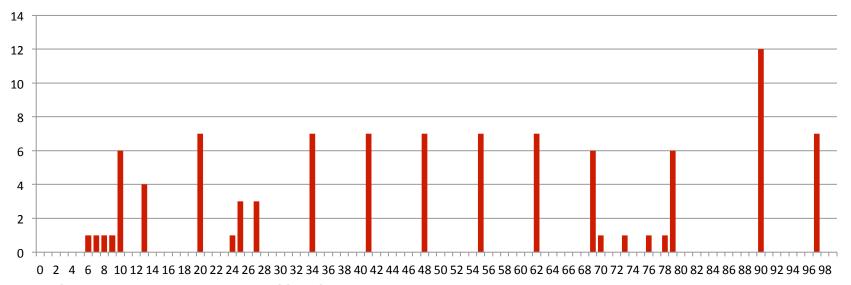
No Race



Single core laptop



Multicore server



The race can really happen!

Issues With Thread-Based Servers

Must run "detached" to avoid memory leak

- At any point in time, a thread is either joinable or detached
- Joinable thread can be reaped and killed by other threads
 - must be reaped (with pthread join) to free memory resources
- Detached thread cannot be reaped or killed by other threads
 - resources are automatically reaped on termination
- Default state is joinable
 - use pthread_detach (pthread_self()) to make detached

Must be careful to avoid unintended sharing

- For example, passing pointer to main thread's stack
 - Pthread create(&tid, NULL, thread, (void *)&connfd);

All functions called by a thread must be thread-safe

(next lecture)

Pros and Cons of Thread-Based Designs

- + Easy to share data structures between threads
 - e.g., logging information, file cache
- + Threads are more efficient than processes
- Unintentional sharing can introduce subtle and hardto-reproduce errors!
 - The ease with which data can be shared is both the greatest strength and the greatest weakness of threads
 - Hard to know which data shared & which private
 - Hard to detect by testing
 - Probability of bad race outcome very low
 - But nonzero!
 - Future lectures

Approaches to Concurrency

Processes

- Hard to share resources: Easy to avoid unintended sharing
- High overhead in adding/removing clients

Threads

- Easy to share resources: Perhaps too easy
- Medium overhead
- Not much control over scheduling policies
- Difficult to debug
 - Event orderings not repeatable

■ I/O Multiplexing

- Tedious and low level
- Total control over scheduling
- Very low overhead
- Cannot create as fine grained a level of concurrency
- Does not make use of multi-core

View from Server's TCP Manager

Client 1 Client 2 Server

srv> ./echoserverp 15213

cl1> ./echoclient greatwhite.ics.cs.cmu.edu 15213

srv> connected to (128.2.192.34), port 50437

cl2> ./echoclient greatwhite.ics.cs.cmu.edu 15213

srv> connected to (128.2.205.225), port 41656

| Connection | Host | Port | Host | Port |
|------------|---------------|-------|--------------|-------|
| Listening | | | 128.2.220.10 | 15213 |
| cl1 | 128.2.192.34 | 50437 | 128.2.220.10 | 15213 |
| c12 | 128.2.205.225 | 41656 | 128.2.220.10 | 15213 |

View from Server's TCP Manager

| Connection | Host | Port | Host | Port |
|------------|---------------|-------|--------------|-------|
| Listening | | | 128.2.220.10 | 15213 |
| cl1 | 128.2.192.34 | 50437 | 128.2.220.10 | 15213 |
| c12 | 128.2.205.225 | 41656 | 128.2.220.10 | 15213 |

Port Demultiplexing

- TCP manager maintains separate stream for each connection
 - Each represented to application program as socket
 - New connections directed to listening socket
 - Data from clients directed to one of the connection sockets