

# 15-213

*“The course that gives CMU its Zip!”*

## Concurrent Servers

### May 3, 2001

#### Topics

- Baseline iterative server
- Process-based concurrent server
- Threads-based concurrent server
- select-based concurrent server

# Error-handling sockets wrappers

To simplify our code, we will use error handling wrappers of the form:

```
int Accept(int s, struct sockaddr *addr, int *addrlen) {
    int rc = accept(s, addr, addrlen);
    if (rc < 0)
        unix_error("Accept");
    return rc;
}
```

```
void unix_error(char *msg) {
    printf("%s: %s\n", msg, strerror(errno));
    exit(0);
};
```

# Echo client revisited

```
/*
 * echoclient.c - A simple connection-based echo client
 * usage: echoclient <host> <port>
 */
#include <ics.h>
#define BUFSIZE 1024

int main(int argc, char **argv) {
    int sockfd; /* client socket */
    struct sockaddr_in serveraddr; /* server socket addr struct */
    struct hostent *server; /* server's DNS entry */
    char *hostname; /* server's domain name */
    int portno; /* server's port number */
    char buf[BUFSIZE];

    /* check command line arguments */
    if (argc != 3) {
        fprintf(stderr, "usage: %s <hostname> <port>\n", argv[0]);
        exit(0);
    }
    hostname = argv[1];
    portno = atoi(argv[2]);
}
```

# Echo client (cont)

```
/* create the socket */
sockfd = Socket(AF_INET, SOCK_STREAM, 0);

/* initialize the server's socket address struct */
server = Gethostbyname(hostname);
bzero((char *) &serveraddr, sizeof(serveraddr));
serveraddr.sin_family = AF_INET;
bcopy((char *)server->h_addr,
      (char *)&serveraddr.sin_addr.s_addr, server->h_length);
serveraddr.sin_port = htons(portno);

/* request a connection to the server */
Connect(sockfd, (struct sockaddr *)&serveraddr,
        sizeof(serveraddr));
```

# Echo client (cont)

```
/* get a message line from the user */
printf("Please enter msg: ");
bzero(buf, BUFSIZE);
fgets(buf, BUFSIZE, stdin);

/* send message line to server and read its echo */
Write(sockfd, buf, strlen(buf));
bzero(buf, BUFSIZE);
Read(sockfd, buf, BUFSIZE);
printf("Echo from server: %s", buf);
Close(sockfd);
exit(0);
}
```

# open\_streamsock helper function

```
int open_streamsock(int portno) {
    int listenfd, optval = 1;
    struct sockaddr_in serveraddr;

    /* create a socket descriptor */
    listenfd = Socket(AF_INET, SOCK_STREAM, 0);
    setsockopt(listenfd, SOL_SOCKET, SO_REUSEADDR,
               (const void *)&optval , sizeof(int));

    /* accept requests to (any IP addr, portno) */
    bzero((char *) &serveraddr, sizeof(serveraddr));
    serveraddr.sin_family = AF_INET;
    serveraddr.sin_addr.s_addr = htonl(INADDR_ANY);
    serveraddr.sin_port = htons((unsigned short)portno);
    Bind(listenfd, (struct sockaddr *) &serveraddr sizeof(serveraddr));

    /* Make it a listening socket ready to accept conn requests */
    Listen(listenfd, 5);
    return listenfd;
}
```



# Iterative echo server

```
/*
 * echoserveri.c - iterative echo server
 * Usage: echoserveri <port>
 */
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);

int main(int argc, char **argv) {
    int listenfd, connfd;
    int portno;
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(struct sockaddr_in);

    /* check command line args */
    if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n",
                argv[0]);
        exit(0);
    }
    portno = atoi(argv[1]);
```



# Iterative echo server (cont)

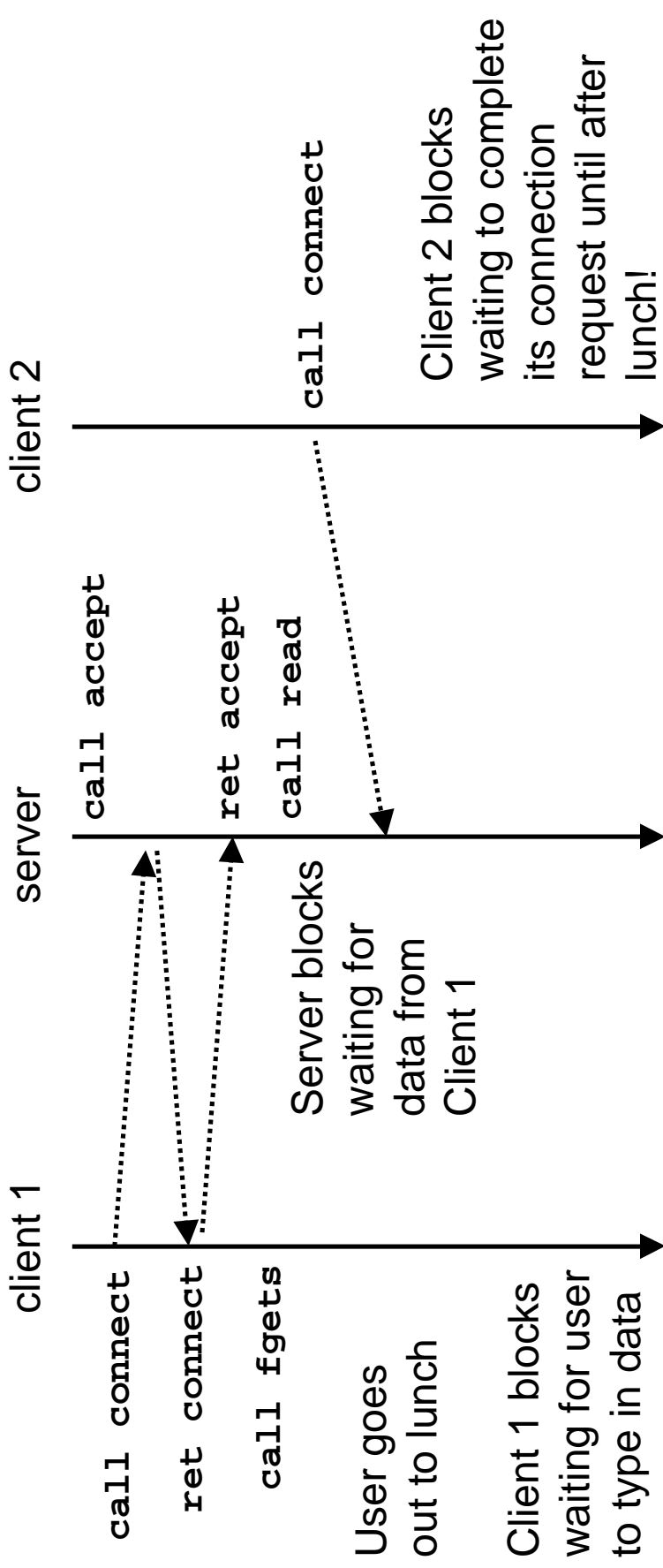
```
/* open the listening socket */
listenfd = open_streamsock(portno);

/* main server loop */
while (1) {
    connfd = Accept(listenfd,
                    (struct sockaddr *) &clientaddr, &clientlen);
    echo(connfd);
    Close(connfd);
}

/* echo - read and echo a line from a client connection */
void echo(int connfd) {
    int n;
    char buf[BUFSIZE];
    bzero(buf, BUFSIZE);
    n = Read(connfd, buf, BUFSIZE);
    printf("server received %d bytes: %s", n, buf);
    Write(connfd, buf, strlen(buf));
}
```

# Pros and cons of iterative servers

- + simple
- can process only one request at a time
  - one slow client can hold up thousands of others
  - Example: echo clients and server



# Concurrent servers

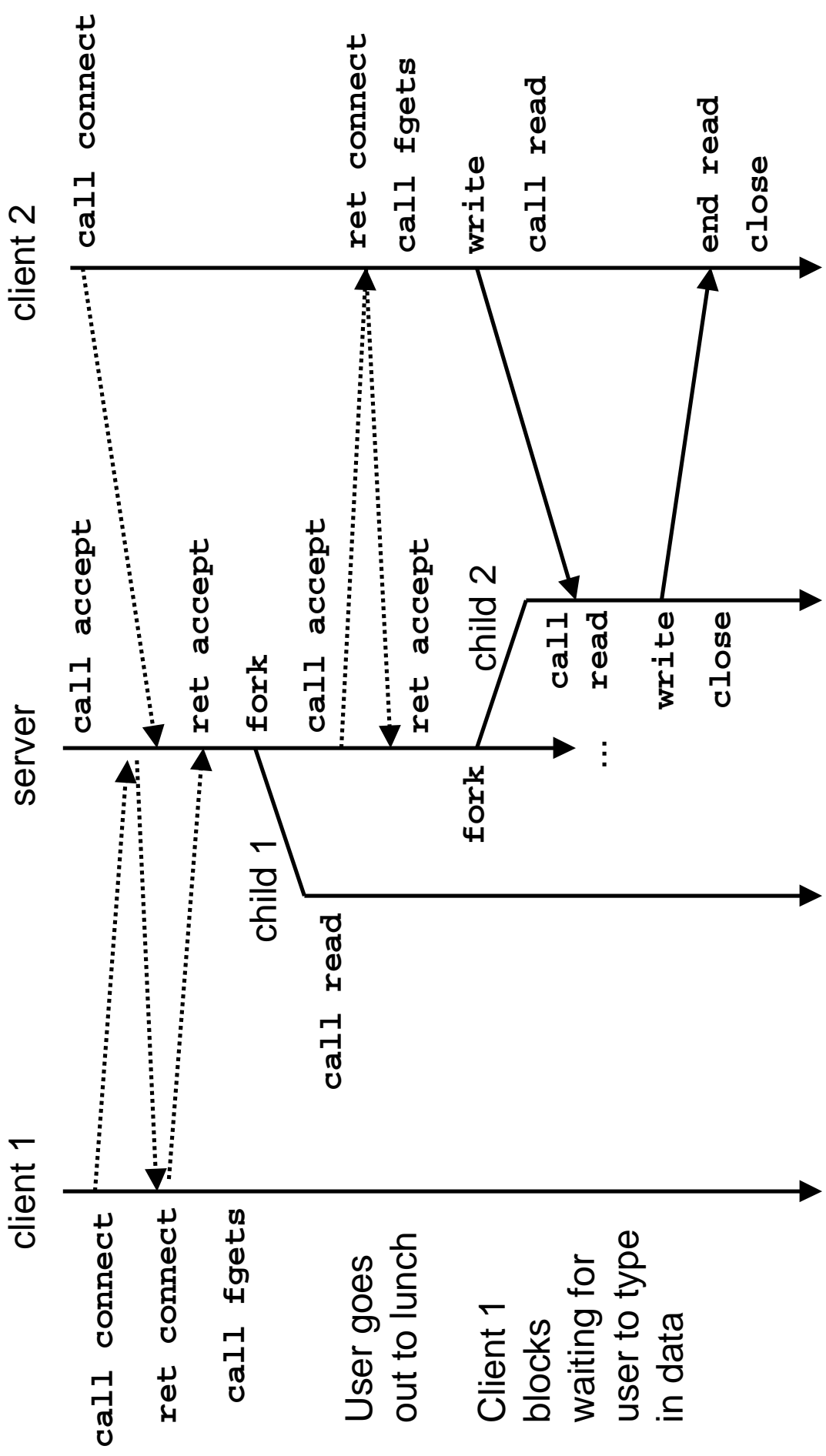
## Concurrent servers process multiple requests concurrently.

- The basic idea is to use multiple control flows to handle multiple requests.

## Example concurrent server designs:

- Fork a new child process for each request.
- Create a new thread for each request.
- Pre-fork a pool of child processes to handle requests. (*not discussed*)
- Pre-create a pool of threads to handle requests. (*not discussed*)
- Manually interleave the processing for multiple open connections.
  - Uses Linux `select()` function to notice pending socket activity
  - Form of application-level concurrency

# Example: Concurrent echo server



client 1

server

client 2

child 1

child 2

call connect

ret connect

call fgets

User goes out to lunch

Client 1 blocks waiting for user to type in data

call accept

ret accept

fork

call accept

ret accept

fork

call read

write

close

call connect

ret connect

call fgets

write

call read

end read

close

# Process-based concurrent server

```
/*
 * echoserverp.c - A concurrent echo server based on processes
 * Usage: echoserverp <port>
 */
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);
void handler(int sig);

int main(int argc, char **argv) {
    int listenfd, connfd;
    int portno;
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(struct sockaddr_in);

    if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n", argv[0]);
        exit(0);
    }
    portno = atoi(argv[1]);
    listenfd = open_streamsock(portno);
```

# Process-based server (cont)

```
signal(SIGCHLD, handler); /* parent must reap children! */

/* main server loop */
while (1) {
    /* for complete portability, must restart if interrupted by */
    /* call to SIGCHLD handler */
    if ((connfd = accept(listenfd, (struct sockaddr *) &clientaddr,
                        &clientlen)) < 0) {
        if (errno == EINTR)
            continue; /* go back */
        else
            unix_error("accept");
    }

    if (Fork() == 0) {
        Close(listenfd); /* child closes its listening socket */
        echo(connfd); /* child reads and echos input line */
        Close(connfd); /* child is done with this client */
        exit(0); /* child exits */
    }
    Close(connfd); /* parent must close connected socket! */
}
}
```

# Reaping zombie children

```
/* handler - reaps children as they terminate */  
void handler(int sig) {  
    pid_t pid;  
    int stat;  
  
    while ((pid = waitpid(-1, &stat, WNOHANG)) > 0)  
        ;  
    return;  
}
```

**Question: Why is the call to `waitpid` in a loop?**

# Issues with process-based design

**Server should restart `accept` call if it is interrupted by a transfer of control to the `SIGCHLD` handler**

- not necessary for systems such as Linux that support Posix signal handling.
- required for portability on some older Unix systems.

**Server must reap zombie children**

- to avoid fatal memory leak.

**Server must `close` its copy of `connfd`.**

- kernel keeps reference count of descriptors that point to each socket.
- after `fork`, `refcnt(connfd)=2`.
- Connection will not be closed until `refcnt(connfd)=0`.



# Pros and cons of process-based design

- + handles multiple connections concurrently
- + clean sharing model
  - descriptors (yes)
  - global variables (no)
- + simple and straightforward
- nontrivial to share data between processes
  - requires IPC (interprocess communication mechanisms)
    - FIFO's
    - System V shared memory
    - System V semaphores
- additional overhead for process control

# Threads-based server

```
/*
 * echoserver2.c - A concurrent echo server using threads
 * Usage: echoserver2 <port>
 */
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);
void *thread(void *vargp);

int main(int argc, char **argv) {
    int listenfd, *connfdp;
    int portno;
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(struct sockaddr_in);
    pthread_t tid;

    /* check command line args */
    if (argc != 2) {
        fprintf(stderr, "usage: %s <port>\n", argv[0]);
        exit(0);
    }
    portno = atoi(argv[1]);
```

# Threads-based server (cont)

```
/* open the listening socket */
listenfd = open_streamsock(portno);

/* main server loop */
while (1) {
    connfdp = Malloc(sizeof(int));
    *connfdp = Accept(listenfd,
                     (struct sockaddr *) &clientaddr, &clientlen);

    Pthread_create(&tid, NULL, thread, (void *)connfdp);
}
}
```

# Threads-based server (cont)

```
/* thread - thread routine */
void *thread(void *vargp) {
    int connfd;

    /* run detached to avoid a memory leak */
    Pthread_detach(pthread_self());

    connfd = *((int *)vargp);
    Free(vargp);

    echo(connfd);
    Close(connfd);
    return NULL;
}
```

# Issues with threads-based servers

## Must run “detached” to avoid memory leak.

- At any point in time, a thread is either *joinable* or *detached*.
- joinable thread:
  - can be reaped and killed by other threads.
  - must be reaped (with `pthread_join`) to free memory resources.
- detached thread:
  - cannot be reaped or killed by other threads.
  - resources are automatically reaped on termination.
- default state is joinable.
  - use `pthread_detach(pthread_self())` to make detached.

## Must be careful to avoid unintended sharing.

- For example, what happens if we pass the address of `connfd` to the thread routine?
- `pthread_create(&tid, NULL, thread, (void *) &connfd);`

# Pros and cons of thread-based design

- + Arguably the simplest option
  - No reaping zombies
  - No signal handling
- + Easy to share data structures between threads
  - e.g., logging information, file cache.
- + Threads are more efficient than processes.
- Unintentional sharing can introduce subtle and hard to reproduce race conditions between threads.
  - malloc an argument struct for each thread and pass ptr to struct to thread routine.
  - Keep globals to a minimum.
  - If a thread references a global variable:
    - protect it with a semaphore or a mutex or
    - think carefully about whether unprotected is safe:
      - » e.g., one writer thread, multiple readers is OK.

# select function

`select` sleeps until one or more file descriptors in the set `readset` are ready for reading.

```
#include <sys/select.h>

int select(int maxfdp1, fd_set *readset, NULL, NULL, NULL);
```

`readset`

- opaque bit vector (max `FD_SETSIZE` bits) that indicates membership in a *descriptor set*.
- if bit `k` is 1, then descriptor `k` is a member of the descriptor set.

`maxfdp1`

- maximum descriptor in descriptor set plus 1.
- tests descriptors 0, 1, 2, ..., `maxfdp1 - 1` for set membership.

`select` returns the number of ready descriptors and sets each bit of `readset` to indicate the ready status of its corresponding descriptor.

# Macros for manipulating set descriptors

```
void FD_ZERO(fd_set *fdset);
```

- turn off all bits in `fdset`.

```
void FD_SET(int fd, fd_set *fdset);
```

- turn on bit `fd` in `fdset`.

```
void FD_CLR(int fd, fd_set *fdset);
```

- turn off bit `fd` in `fdset`.

```
int FD_ISSET(int fd, *fdset);
```

- is bit `fd` in `fdset` turned on?



# select example

```
/*
 * main loop: wait for connection request or stdin command.
 * If connection request, then echo input line
 * and close connection. If command, then process.
 */
printf("server> ");
fflush(stdout);

while (notdone) {
    /*
     * select: check if the user typed something to stdin or
     * if a connection request arrived.
     */
    FD_ZERO(&readfds);          /* initialize the fd set */
    FD_SET(listenfd, &readfds); /* add socket fd */
    FD_SET(0, &readfds);        /* add stdin fd (0) */
    Select(listenfd+1, &readfds, NULL, NULL, NULL);
}
```

# select example

First we check for a pending event on stdin.

```
/* if the user has typed a command, process it */
if (FD_ISSET(0, &readfds)) {
    fgets(buf, BUFSIZE, stdin);
    switch (buf[0]) {
        case 'c': /* print the connection count */
            printf("Received %d conn. requests so far.\n", connectcnt);
            printf("server> ");
            fflush(stdout);
            break;
        case 'q': /* terminate the server */
            notdone = 0;
            break;
        default: /* bad input */
            printf("ERROR: unknown command\n");
            printf("server> ");
            fflush(stdout);
    }
}
```

# select example

Next we check for a pending connection request.

```
/* if a connection request has arrived, process it */
if (FD_ISSET(listenfd, &readfds)) {
    connfd = Accept(listenfd,
                    (struct sockaddr *) &clientaddr, &clientlen);
    connectcnt++;

    bzero(buf, BUFSIZE);
    Read(connfd, buf, BUFSIZE);
    Write(connfd, buf, strlen(buf));
    Close(connfd);
} /* while */
```

# I/O multiplexing with select

```
/*
 * echoservers.c - A concurrent echo server based on select
 * Usage: echoservers <port>
 */
#include <ics.h>
#define BUFSIZE 1024
void echo(int connfd);

int main(int argc, char **argv) {
    int listenfd, connfd;
    int portno;
    struct sockaddr_in clientaddr;
    int clientlen = sizeof(struct sockaddr_in);

    fd_set allset; /* descriptor set for select */
    fd_set rset;   /* copy of allset for select */
    int maxfd;     /* max descriptor value for select */

    int client[FD_SETSIZE]; /* pool of connected descriptors */
    int maxi;           /* highwater index into client pool */
    int nready;         /* number of ready descriptors from select */
    int i, sockfd;      /* misc */
}
```

# I/O multiplexing with select (cont)

```
/* check command line args */
if (argc != 2) {
    fprintf(stderr, "usage: %s <port>\n", argv[0]);
    exit(0);
}
portno = atoi(argv[1]);

/* open the listening socket */
listenfd = open_streamsock(portno);

/* initialize the pool of active client connections */
maxi = -1;
maxfd = listenfd;
for (i=0; i< FD_SETSIZE; i++)
    client[i] = -1;
FD_ZERO(&allset);
FD_SET(listenfd, &allset);
```

# I/O multiplexing with select (cont)

```
/* main server loop */
while (1) {
    rset = allset;
    nready = Select(maxfd+1, &rset, NULL, NULL, NULL);

    /* PART I: add a new connected descriptor to the pool */
    if (FD_ISSET(listenfd, &rset)) {
        connfd = Accept(listenfd, (struct_sockaddr *)
                        &clientaddr, &clientlen);

        nready--;
    }
}
```

# I/O multiplexing with select (cont)

```
/* update the client pool */
for (i=0; i<FD_SETSIZE; i++)
    if (client[i] < 0) {
        client[i] = connfd;
        break;
    }
    if (i == FD_SETSIZE)
        app_error("Too many clients\n");

/* update the read descriptor set */
FD_SET(connfd, &allset);
if (connfd > maxfd)
    maxfd = connfd;
if (i > maxi)
    maxi = i;
} /* if (FD_ISSET(listenfd, &rset) */
```

# I/O multiplexing with select (cont)

```
/* PART II: check the pool of connected descs for client data */
for (i=0; (i<=maxi) && (nready > 0); i++) {
    sockfd = client[i];
    if ((sockfd > 0) && (FD_ISSET(sockfd, &rset))) {
        echo(sockfd);
        Close(sockfd);
        FD_CLR(sockfd, &allset);
        client[i] = -1;
        nready--;
    }
} /* for */
} /* while(1) */
}
```



# Pro and cons of select-based design

- + one logical control flow.
- + can single step with a debugger.
- + no process or thread control overhead.
- significantly more complex to code initially than process or thread designs.
- vulnerable to denial of service attack
  - How?