



# Machine-Level Programming IV: Data

15-213/18-213/14-513/15-513/18-613: Introduction to Computer Systems  
8<sup>th</sup> Lecture, September 19, 2019

# Today

## ■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

## ■ Structures

- Allocation
- Access
- Alignment

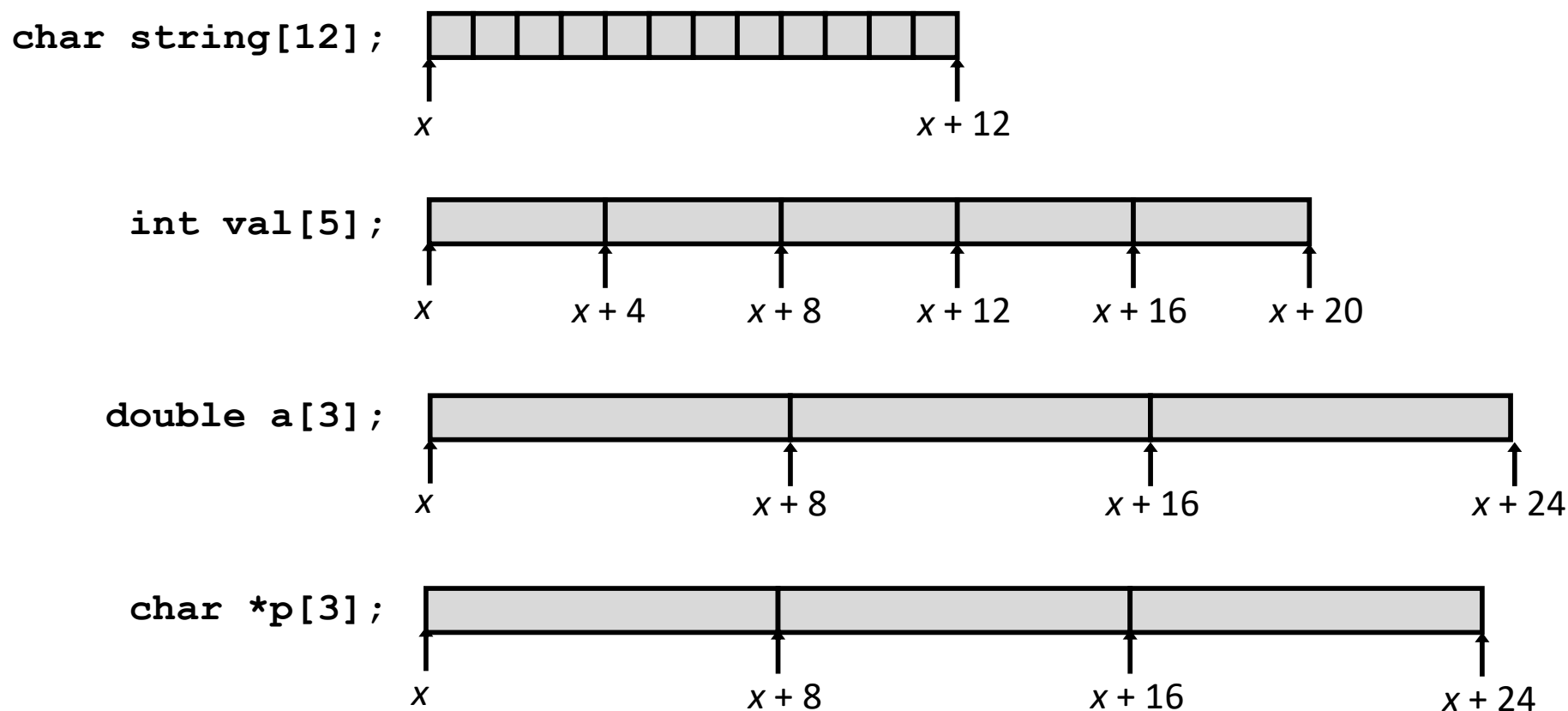
## ■ Floating Point

# Array Allocation

## ■ Basic Principle

$T \ A[L];$

- Array of data type  $T$  and length  $L$
- Contiguously allocated region of  $L * \text{sizeof}(T)$  bytes in memory

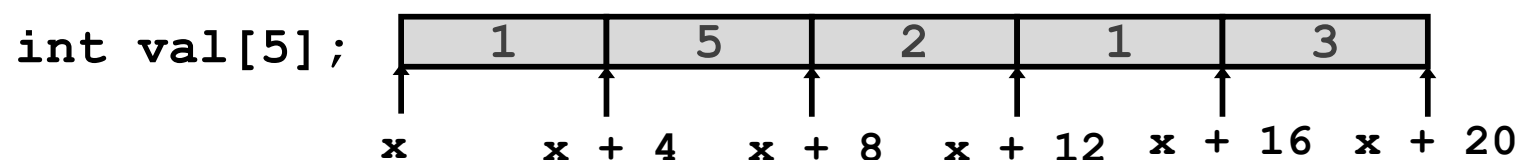


# Array Access

## ■ Basic Principle

$T$  **A**[ $L$ ] ;

- Array of data type  $T$  and length  $L$
- Identifier **A** can be used as a pointer to array element 0: Type  $T^*$



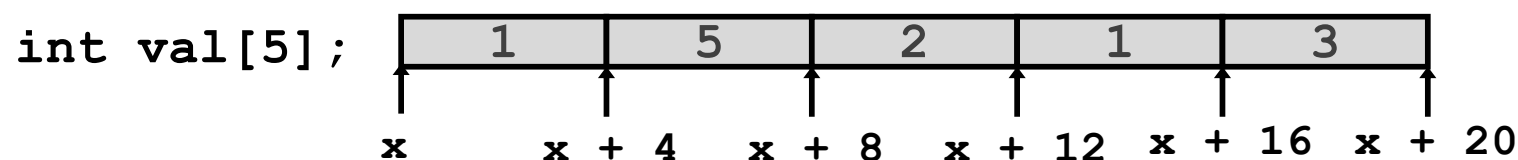
■ Reference	Type	Value
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	
<code>val+1</code>	<code>int *</code>	
<code>&amp;val[2]</code>	<code>int *</code>	
<code>val[5]</code>	<code>int</code>	
<code>*(val+1)</code>	<code>int</code>	
<code>val + i</code>	<code>int *</code>	

# Array Access

## ■ Basic Principle

$T$  **A**[ $L$ ] ;

- Array of data type  $T$  and length  $L$
- Identifier **A** can be used as a pointer to array element 0: Type  $T^*$

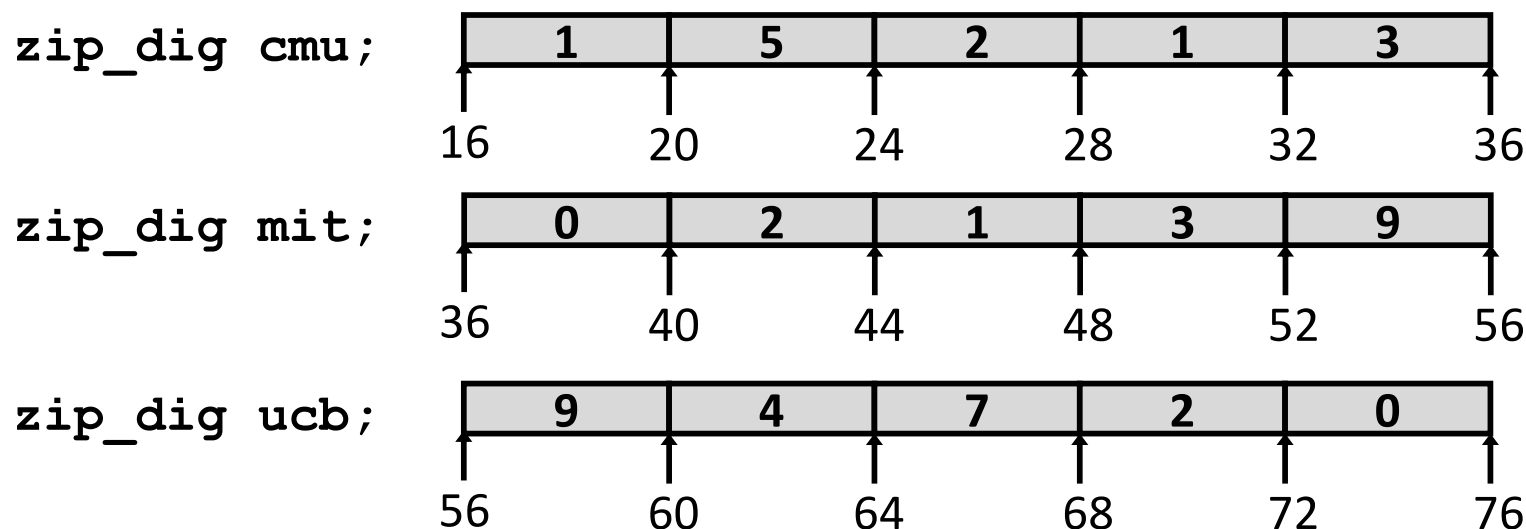


■ Reference	Type	Value
<code>val[4]</code>	<code>int</code>	3
<code>val</code>	<code>int *</code>	$x$
<code>val+1</code>	<code>int *</code>	$x + 4$
<code>&amp;val[2]</code>	<code>int *</code>	$x + 8$
<code>val[5]</code>	<code>int</code>	??
<code>*(val+1)</code>	<code>int</code>	5 <code>//val[1]</code>
<code>val + i</code>	<code>int *</code>	$x + 4 * i$ <code>//&amp;val[i]</code>

# Array Example

```
#define ZLEN 5
typedef int zip_dig[ZLEN];

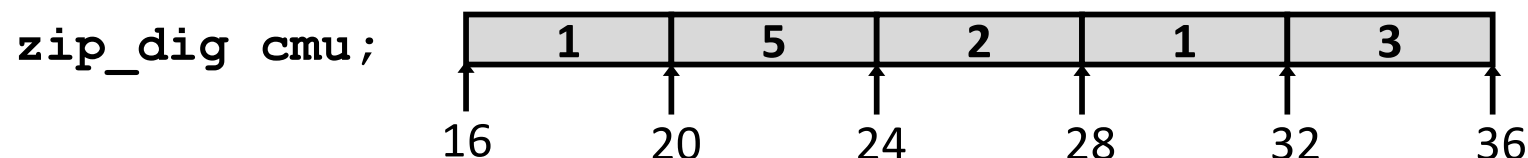
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```



- Declaration “`zip_dig cmu`” equivalent to “`int cmu[5]`”
- Example arrays were allocated in successive 20 byte blocks
  - Not guaranteed to happen in general



# Array Accessing Example



```
int get_digit
    (zip_dig z, int digit)
{
    return z[digit];
}
```

## x86-64

```
# %rdi = z
# %rsi = digit
movl (%rdi,%rsi,4), %eax # z[digit]
```

- Register `%rdi` contains starting address of array
- Register `%rsi` contains array index
- Desired digit at  $\text{\%rdi} + 4 * \text{\%rsi}$
- Use memory reference  $(\text{\%rdi}, \text{\%rsi}, 4)$



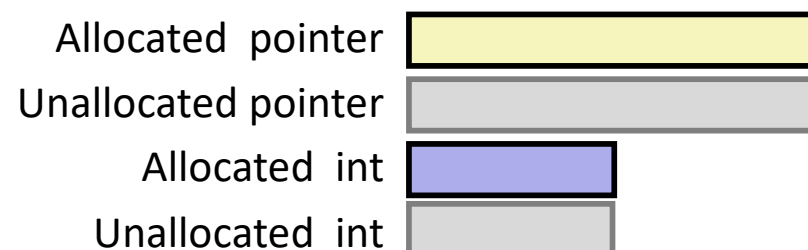
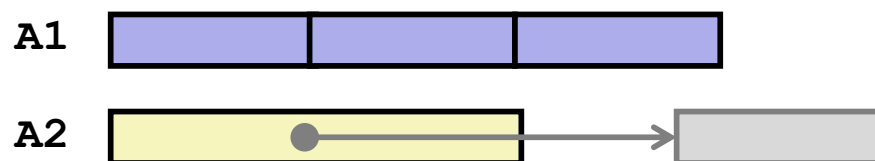
# Array Loop Example

```
void zincr(zip_dig z) {  
    size_t i;  
    for (i = 0; i < ZLEN; i++)  
        z[i]++;  
}
```

```
# %rdi = z  
movl    $0, %eax  
jmp     .L3  
.L4:  
addl    $1, (%rdi,%rax,4)  
addq    $1, %rax  
.L3:  
cmpq    $4, %rax  
jbe     .L4  
rep; ret
```

# Understanding Pointers & Arrays #1

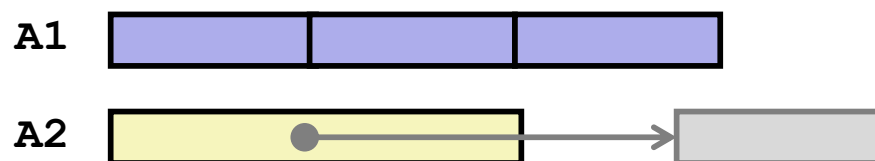
Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
<code>int A1[3]</code>						
<code>int *A2</code>						



- **Comp:** Compiles (Y/N)
- **Bad:** Possible bad pointer reference (Y/N)
- **Size:** Value returned by `sizeof`

# Understanding Pointers & Arrays #1

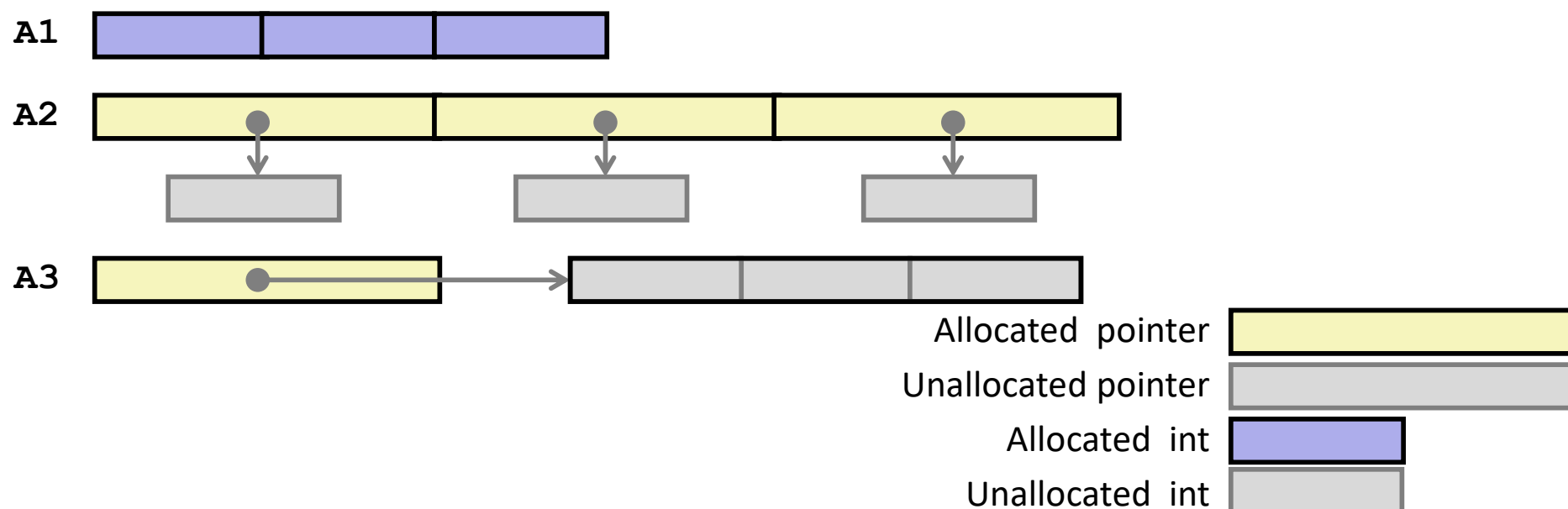
Decl	A1 , A2			*A1 , *A2		
	Comp	Bad	Size	Comp	Bad	Size
<code>int A1[3]</code>	Y	N	12	Y	N	4
<code>int *A2</code>	Y	N	8	Y	Y	4



- **Comp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by `sizeof`**

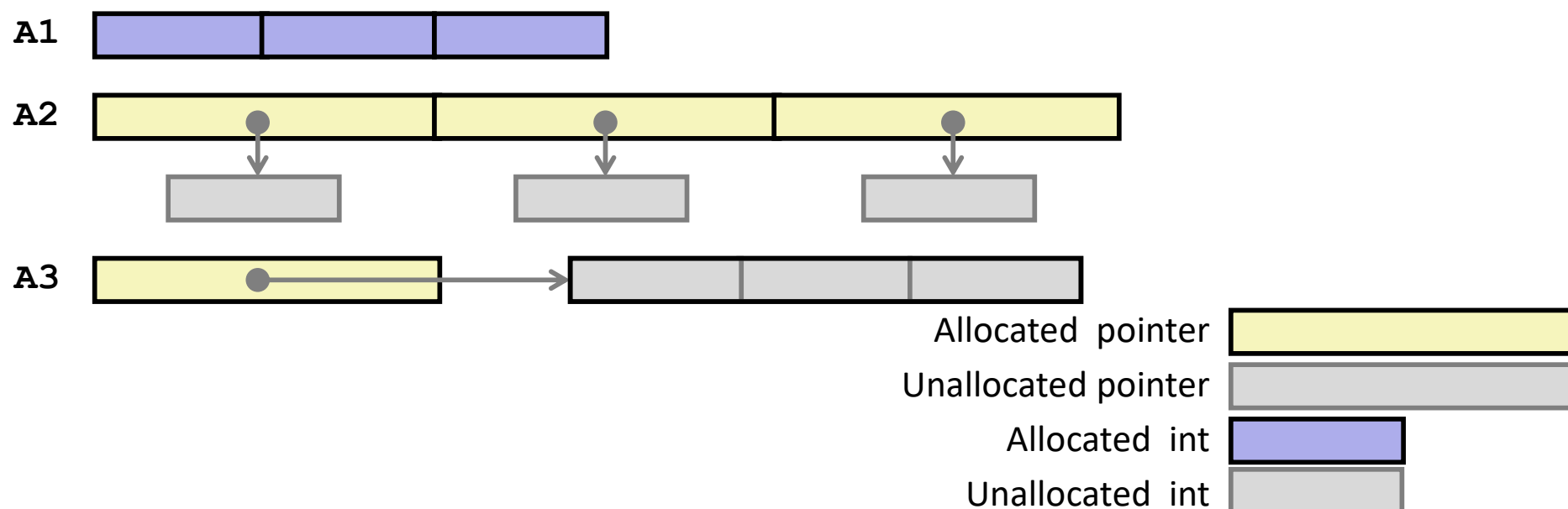
# Understanding Pointers & Arrays #2

Decl	<i>An</i>			<i>*An</i>			<i>**An</i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>									
<code>int *A2[3]</code>									
<code>int (*A3)[3]</code>									



# Understanding Pointers & Arrays #2

Decl	<i>A<sub>n</sub></i>			<i>*A<sub>n</sub></i>			<i>**A<sub>n</sub></i>		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3]</code>	<b>Y</b>	<b>N</b>	<b>12</b>	<b>Y</b>	<b>N</b>	<b>4</b>	<b>N</b>	<b>-</b>	<b>-</b>
<code>int *A2[3]</code>	<b>Y</b>	<b>N</b>	<b>24</b>	<b>Y</b>	<b>N</b>	<b>8</b>	<b>Y</b>	<b>Y</b>	<b>4</b>
<code>int (*A3)[3]</code>	<b>Y</b>	<b>N</b>	<b>8</b>	<b>Y</b>	<b>Y</b>	<b>12</b>	<b>Y</b>	<b>Y</b>	<b>4</b>



# Multidimensional (Nested) Arrays

## ■ Declaration

`T A[R][C];`

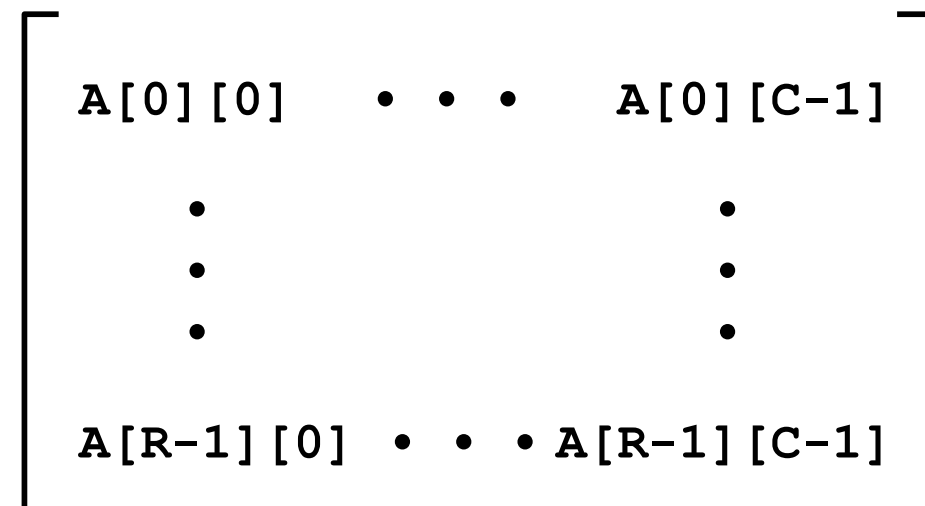
- 2D array of data type  $T$
- $R$  rows,  $C$  columns

## ■ Array Size

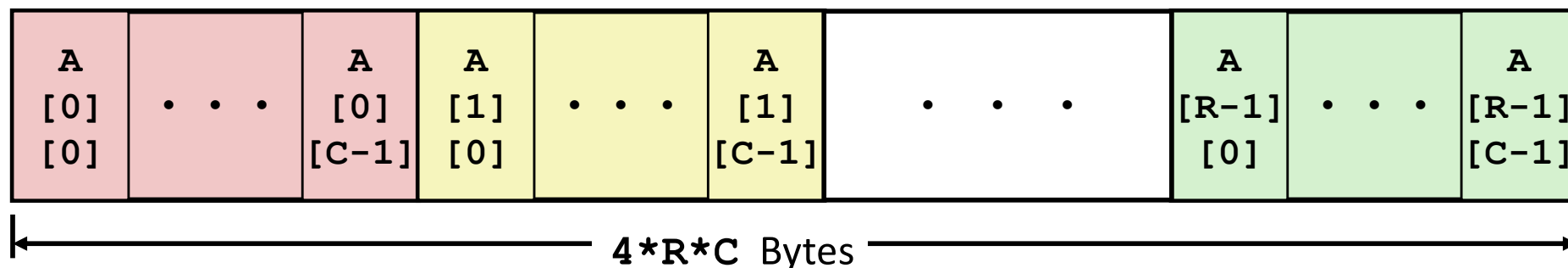
- $R * C * \text{sizeof}(T)$  bytes

## ■ Arrangement

- Row-Major Ordering



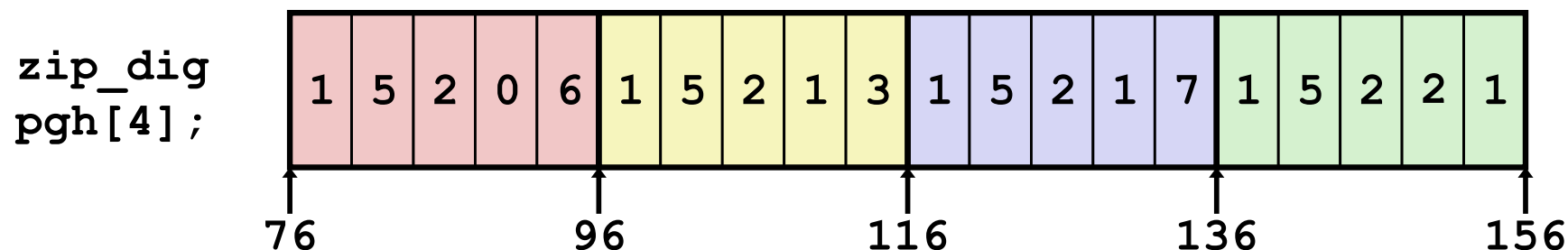
`int A[R][C];`



# Nested Array Example

```
#define PCOUNT 4
typedef int zip_dig[5];

zip_dig pgh[PCOUNT] =
    {{1, 5, 2, 0, 6},
     {1, 5, 2, 1, 3 },
     {1, 5, 2, 1, 7 },
     {1, 5, 2, 2, 1 }};
```



- “zip\_dig pgh[4]” equivalent to “int pgh[4][5]”
  - Variable **pgh**: array of 4 elements, allocated contiguously
  - Each element is an array of 5 **int**’s, allocated contiguously
- “Row-Major” ordering of all elements in memory

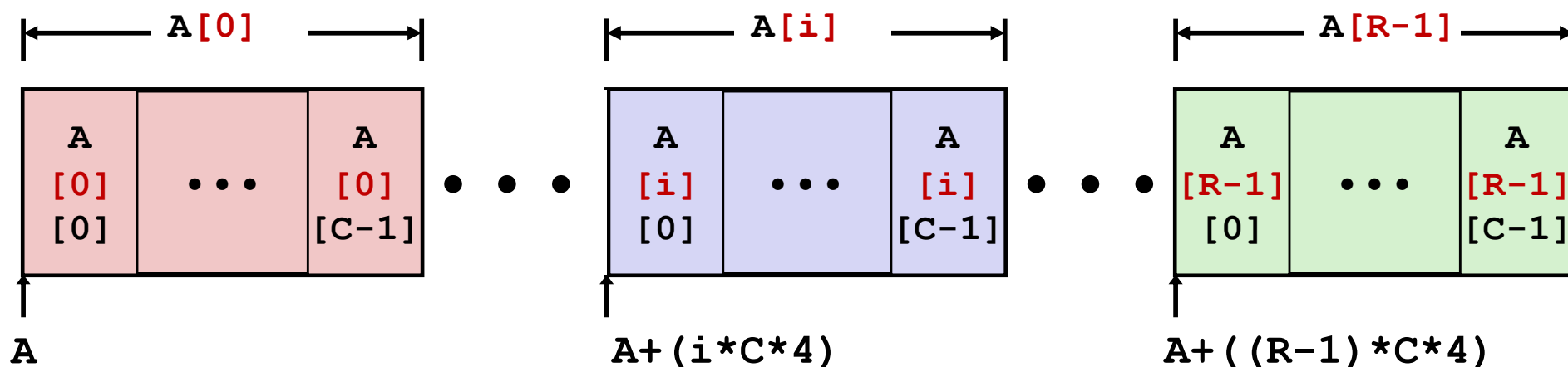


# Nested Array Row Access

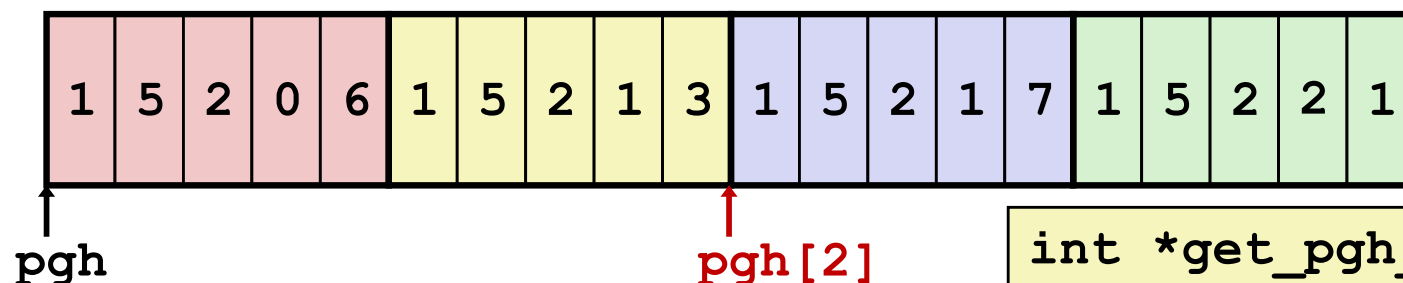
## ■ Row Vectors

- $A[i]$  is array of  $C$  elements of type  $T$
- Starting address  $A + i * (C * \text{sizeof}(T))$

```
int A[R][C];
```



# Nested Array Row Access Code



```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

```
# %rdi = index
leaq (%rdi,%rdi,4),%rax # 5 * index
leaq pgh(,%rax,4),%rax  # pgh + (20 * index)
```

## ■ Row Vector

- `pgh[index]` is array of 5 `int`'s
- Starting address `pgh+20*index`

## ■ Machine Code

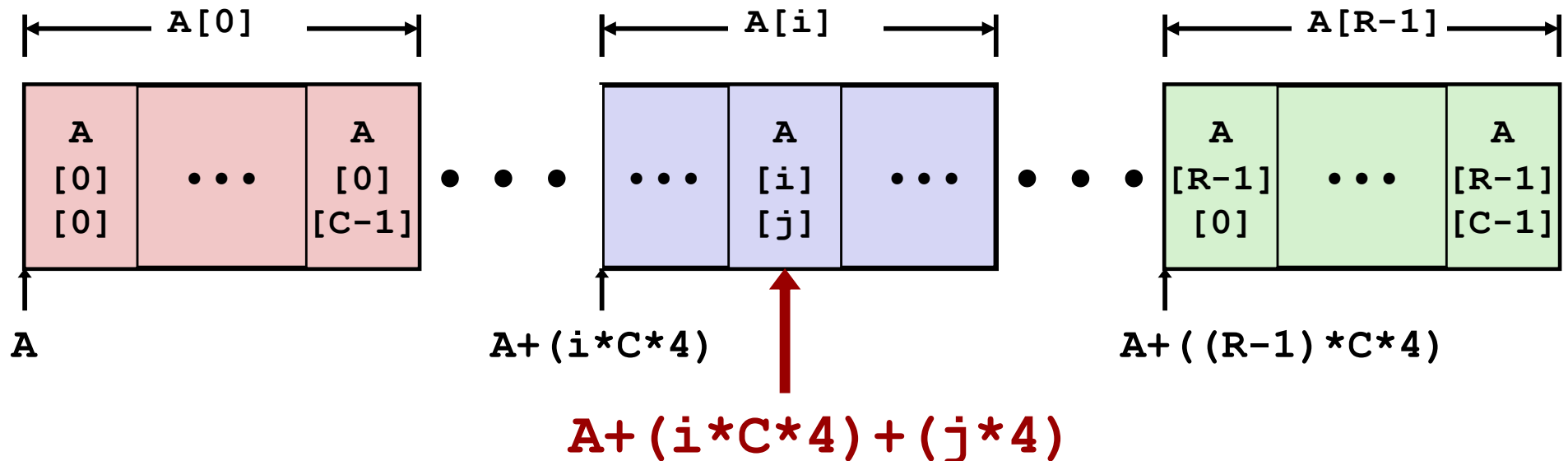
- Computes and returns address
- Compute as `pgh + 4*(index+4*index)`

# Nested Array Element Access

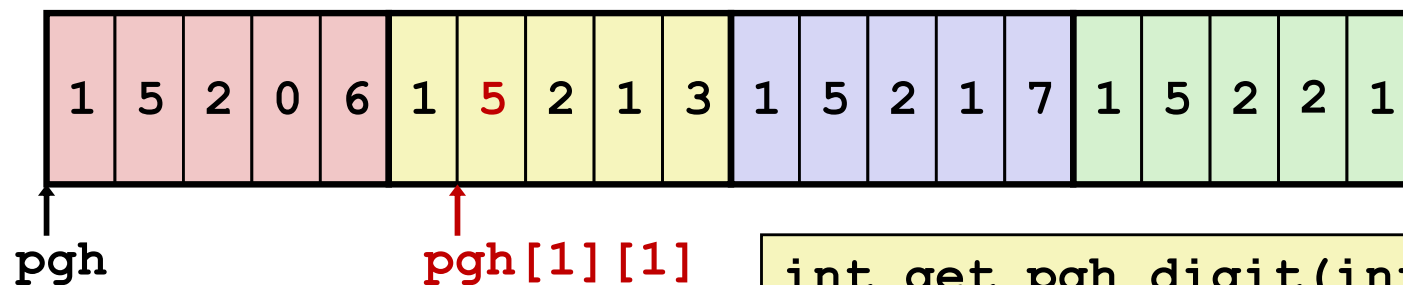
## ■ Array Elements

- $A[i][j]$  is element of type  $T$ , which requires  $K$  bytes
- Address  $A + i * (C * K) + j * K$   
 $= A + (i * C + j) * K$

```
int A[R][C];
```



# Nested Array Element Access Code



```
int get_pgh_digit(int index, int dig)
{
    return pgh[index][dig];
}
```

```
leaq    (%rdi,%rdi,4), %rax    # 5*index
addl    %rax, %rsi             # 5*index+dig
movl    pgh(,%rsi,4), %eax     # M[pgh + 4*(5*index+dig)]
```

## ■ Array Elements

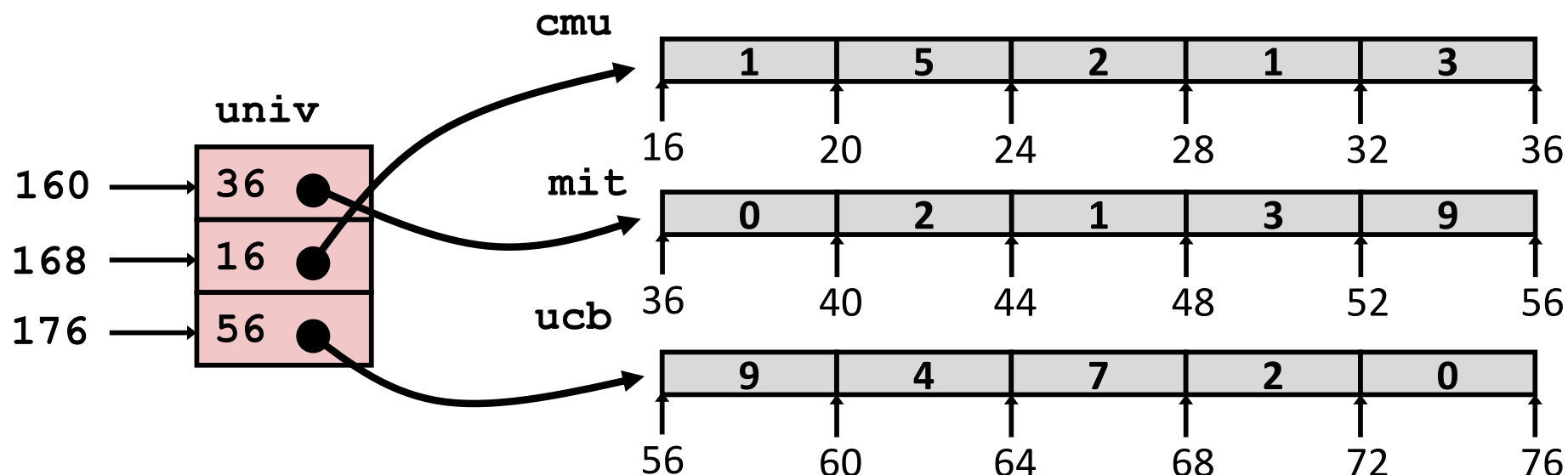
- `pgh[index][dig]` is `int`
- Address:  $\text{pgh} + 20 \cdot \text{index} + 4 \cdot \text{dig}$   
 $= \text{pgh} + 4 \cdot (5 \cdot \text{index} + \text{dig})$

# Multi-Level Array Example

```
zip_dig cmu = { 1, 5, 2, 1, 3 };
zip_dig mit = { 0, 2, 1, 3, 9 };
zip_dig ucb = { 9, 4, 7, 2, 0 };
```

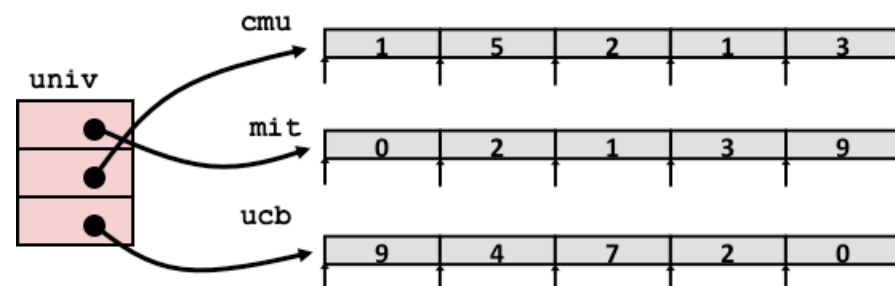
```
#define UCOUNT 3
int *univ[UCOUNT] = {mit, cmu, ucb};
```

- Variable `univ` denotes array of 3 elements
- Each element is a pointer
  - 8 bytes
- Each pointer points to array of `int`'s



# Element Access in Multi-Level Array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



```
salq    $2, %rsi          # 4*digit
addq    univ(,%rdi,8), %rsi # p = univ[index] + 4*digit
movl    (%rsi), %eax       # return *p
ret
```

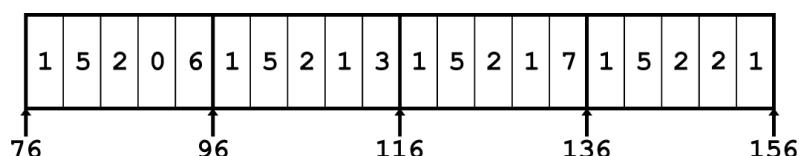
## ■ Computation

- Element access `Mem[Mem[univ+8*index]+4*digit]`
- Must do two memory reads
  - First get pointer to row array
  - Then access element within array

# Array Element Accesses

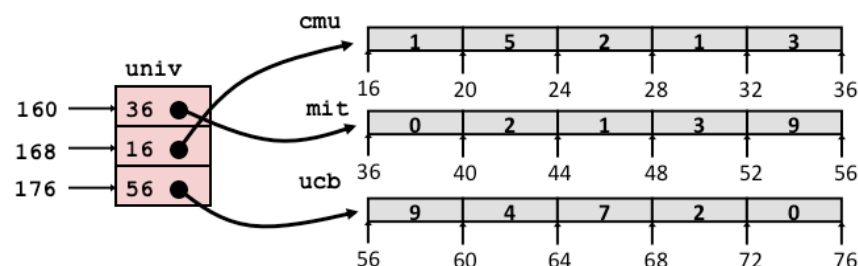
## Nested array

```
int get_pgh_digit
(size_t index, size_t digit)
{
    return pgh[index][digit];
}
```



## Multi-level array

```
int get_univ_digit
(size_t index, size_t digit)
{
    return univ[index][digit];
}
```



Accesses looks similar in C, but address computations very different:

$\text{Mem}[\text{pgh} + 20 * \text{index} + 4 * \text{digit}]$        $\text{Mem}[\text{Mem}[\text{univ} + 8 * \text{index}] + 4 * \text{digit}]$



# $N \times N$ Matrix Code

## ■ Fixed dimensions

- Know value of  $N$  at compile time

```
#define N 16
typedef int fix_matrix[N][N];
/* Get element A[i][j] */
int fix_ele(fix_matrix A,
            size_t i, size_t j)
{
    return A[i][j];
}
```

## ■ Variable dimensions, explicit indexing

- Traditional way to implement dynamic arrays

```
#define IDX(n, i, j) ((i)*(n)+(j))
/* Get element A[i][j] */
int vec_ele(size_t n, int *A,
            size_t i, size_t j)
{
    return A[IDX(n,i,j)];
}
```

## ■ Variable dimensions, implicit indexing

- Now supported by gcc

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n],
            size_t i, size_t j) {
    return A[i][j];
}
```

# 16 X 16 Matrix Access

## ■ Array Elements

- `int A[16][16];`
- Address  $A + i * (C * K) + j * K$
- $C = 16, K = 4$

```
/* Get element A[i][j] */
int fix_ele(fix_matrix A, size_t i, size_t j) {
    return A[i][j];
}
```

```
# A in %rdi, i in %rsi, j in %rdx
salq    $6, %rsi           # 64*i
addq    %rsi, %rdi          # A + 64*i
movl    (%rdi,%rdx,4), %eax # Mem[A + 64*i + 4*j]
ret
```

# $n \times n$ Matrix Access

## ■ Array Elements

- `size_t n;`
- `int A[n][n];`
- Address  $A + i * (C * K) + j * K$
- $C = n, K = 4$
- Must perform integer multiplication

```
/* Get element A[i][j] */
int var_ele(size_t n, int A[n][n], size_t i, size_t j)
{
    return A[i][j];
}
```

```
# n in %rdi, A in %rsi, i in %rdx, j in %rcx
imulq    %rdx, %rdi          # n*i
leaq     (%rsi,%rdi,4), %rax  # A + 4*n*i
movl     (%rax,%rcx,4), %eax  # A + 4*n*i + 4*j
ret
```

# Example: Array Access

```
#include <stdio.h>
#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgh[PCOUNT] =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3 },
         {1, 5, 2, 1, 7 },
         {1, 5, 2, 2, 1 }};
    int *linear_zip = (int *) pgh;
    int *zip2 = (int *) pgh[2];
    int result =
        pgh[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
result: 9
```

# Example: Array Access

```
#include <stdio.h>
#define ZLEN 5
#define PCOUNT 4
typedef int zip_dig[ZLEN];

int main(int argc, char** argv) {
    zip_dig pgh[PCOUNT] =
        {{1, 5, 2, 0, 6},
         {1, 5, 2, 1, 3 },
         {1, 5, 2, 1, 7 },
         {1, 5, 2, 2, 1 }};
    int *linear_zip = (int *) pgh;
    int *zip2 = (int *) pgh[2];
    int result =
        pgh[0][0] +
        linear_zip[7] +
        *(linear_zip + 8) +
        zip2[1];
    printf("result: %d\n", result);
    return 0;
}
```

```
linux> ./array
result: 9
```

# Quiz Time!

Check out:

<https://canvas.cmu.edu/courses/10968>

# Today

## ■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

## ■ Structures

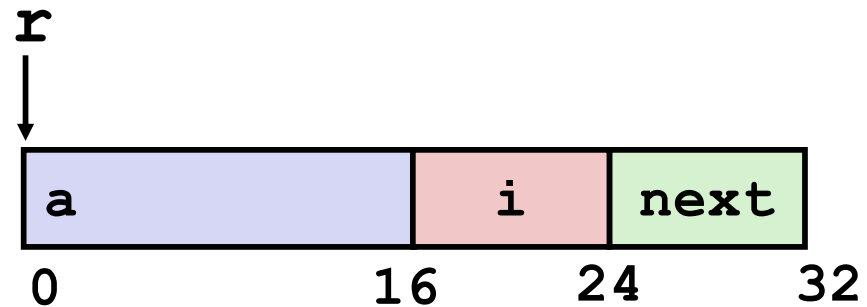
- Allocation
- Access
- Alignment

## ■ Floating Point



# Structure Representation

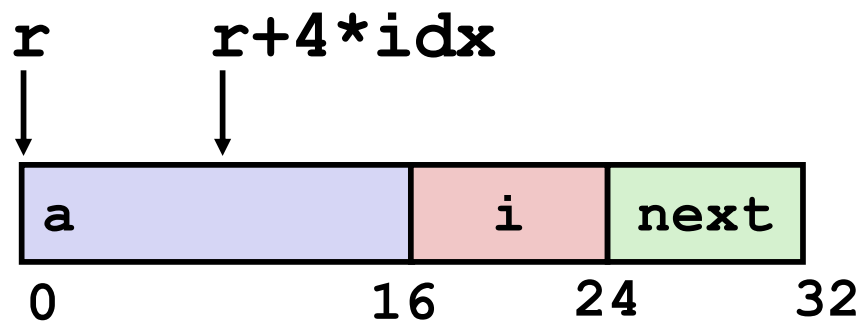
```
struct rec {  
    int a[4];  
    size_t i;  
    struct rec *next;  
};
```



- **Structure represented as block of memory**
  - Big enough to hold all of the fields
- **Fields ordered according to declaration**
  - Even if another ordering could yield a more compact representation
- **Compiler determines overall size + positions of fields**
  - Machine-level program has no understanding of the structures in the source code

# Generating Pointer to Structure Member

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



## ■ Generating Pointer to Array Element

- Offset of each structure member determined at compile time
- Compute as  $r + 4 * idx$

```
int *get_ap
(struct rec *r, size_t idx)
{
    return &r->a[idx];
}
```

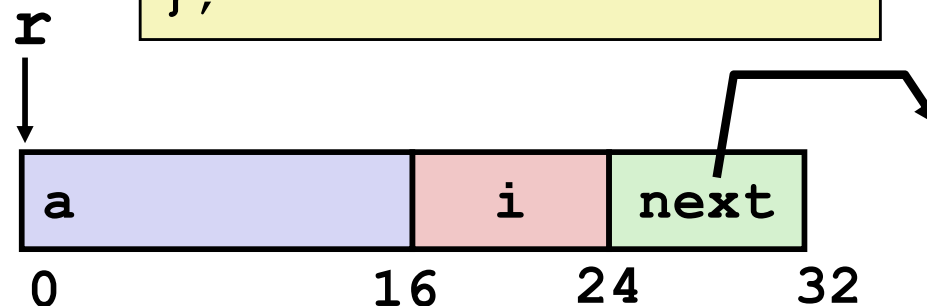
```
# r in %rdi, idx in %rsi
leaq (%rdi,%rsi,4), %rax
ret
```

# Following Linked List #1

## ■ C Code

```
long length(struct rec*r) {
    long len = 0L;
    while (r) {
        len ++;
        r = r->next;
    }
    return len;
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



Register	Value
<code>%rdi</code>	<code>r</code>
<code>%rax</code>	<code>len</code>

## ■ Loop assembly code

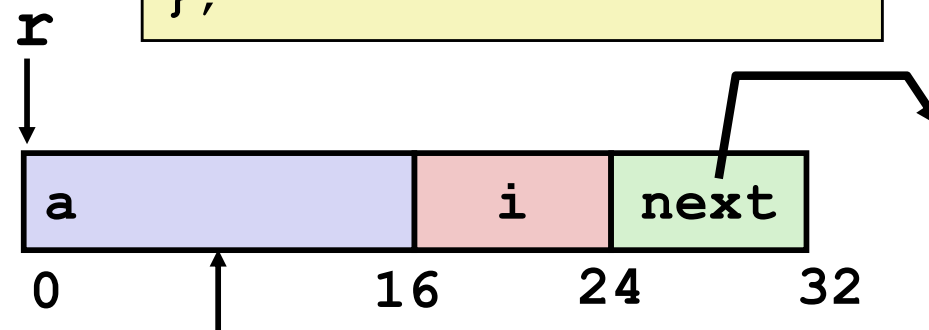
<code>.L11:</code>	<code>addq \$1, %rax</code>	<code># loop:</code>
	<code>movq 24(%rdi), %rdi</code>	<code># len ++</code>
	<code>testq %rdi, %rdi</code>	<code># r = Mem[r+24]</code>
	<code>jne .L11</code>	<code># Test r</code>
		<code># If != 0, goto loop</code>

# Following Linked List #2

## ■ C Code

```
void set_val
(struct rec *r, int val)
{
    while (r) {
        size_t i = r->i;
        // No bounds check
        r->a[i] = val;
        r = r->next;
    }
}
```

```
struct rec {
    int a[4];
    size_t i;
    struct rec *next;
};
```



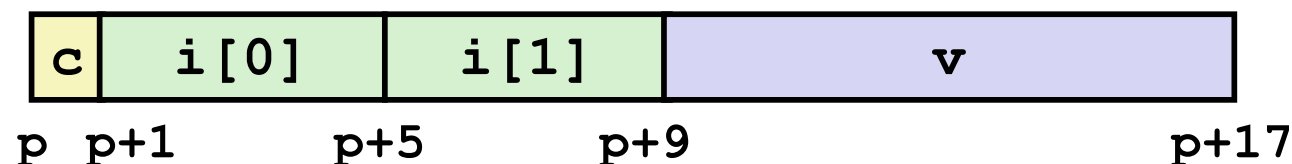
Element i

Register	Value
<code>%rdi</code>	<code>r</code>
<code>%rsi</code>	<code>val</code>

```
.L11:                                # loop:
    movq    16(%rdi), %rax           # i = Mem[r+16]
    movl    %esi, (%rdi,%rax,4)     # Mem[r+4*i] = val
    movq    24(%rdi), %rdi          # r = Mem[r+24]
    testq   %rdi, %rdi              # Test r
    jne     .L11                    # if !=0 goto loop
```

# Structures & Alignment

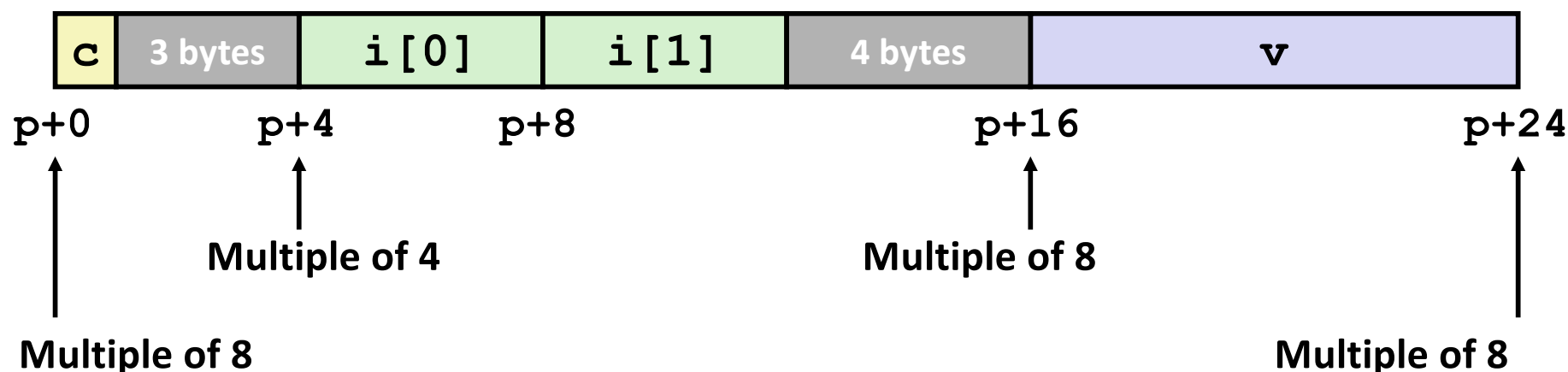
## ■ Unaligned Data



```
struct S1 {
    char c;
    int i[2];
    double v;
} *p;
```

## ■ Aligned Data

- Primitive data type requires `B` bytes implies  
Address must be multiple of `B`



# Alignment Principles

## ■ Aligned Data

- Primitive data type requires B bytes
- Address must be multiple of B
- Required on some machines; advised on x86-64

## ■ Motivation for Aligning Data

- Memory accessed by (aligned) chunks of 4 or 8 bytes (system dependent)
  - Inefficient to load or store datum that spans cache lines (64 bytes).  
Intel states should avoid crossing 16 byte boundaries.

*[Cache lines will be discussed in Lecture 11.]*

- Virtual memory trickier when datum spans 2 pages (4 KB pages)

*[Virtual memory pages will be discussed in Lecture 17.]*

## ■ Compiler

- Inserts gaps in structure to ensure correct alignment of fields

# Specific Cases of Alignment (x86-64)

- **1 byte: `char`, ...**
  - no restrictions on address
- **2 bytes: `short`, ...**
  - lowest 1 bit of address must be 0<sub>2</sub>
- **4 bytes: `int`, `float`, ...**
  - lowest 2 bits of address must be 00<sub>2</sub>
- **8 bytes: `double`, `long`, `char *`, ...**
  - lowest 3 bits of address must be 000<sub>2</sub>



# Satisfying Alignment with Structures

## ■ Within structure:

- Must satisfy each element's alignment requirement

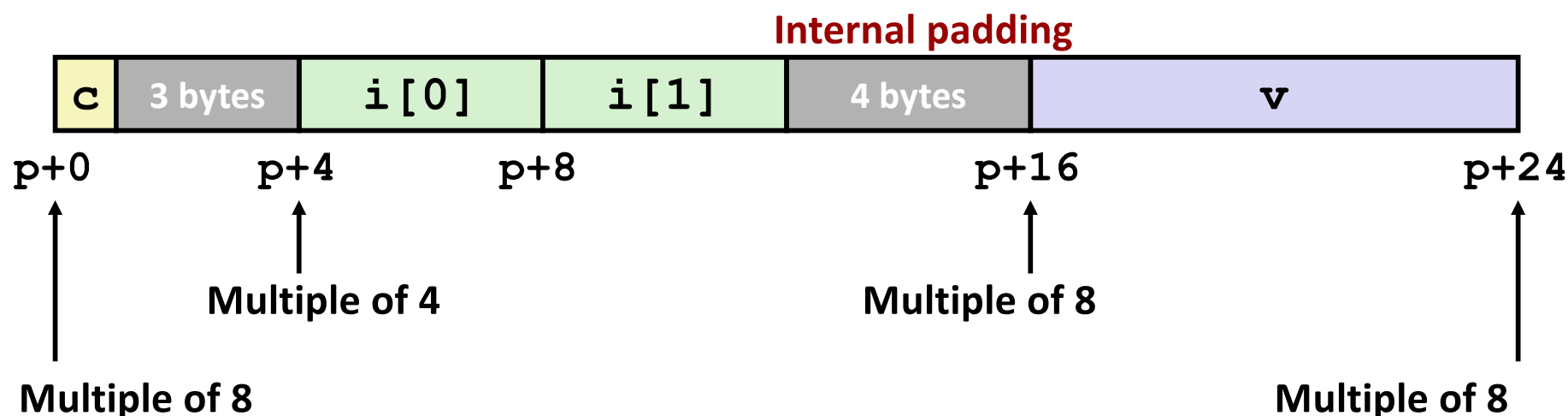
## ■ Overall structure placement

- Each structure has alignment requirement K
  - K = Largest alignment of any element
- Initial address & structure length must be multiples of K

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *p;
```

## ■ Example:

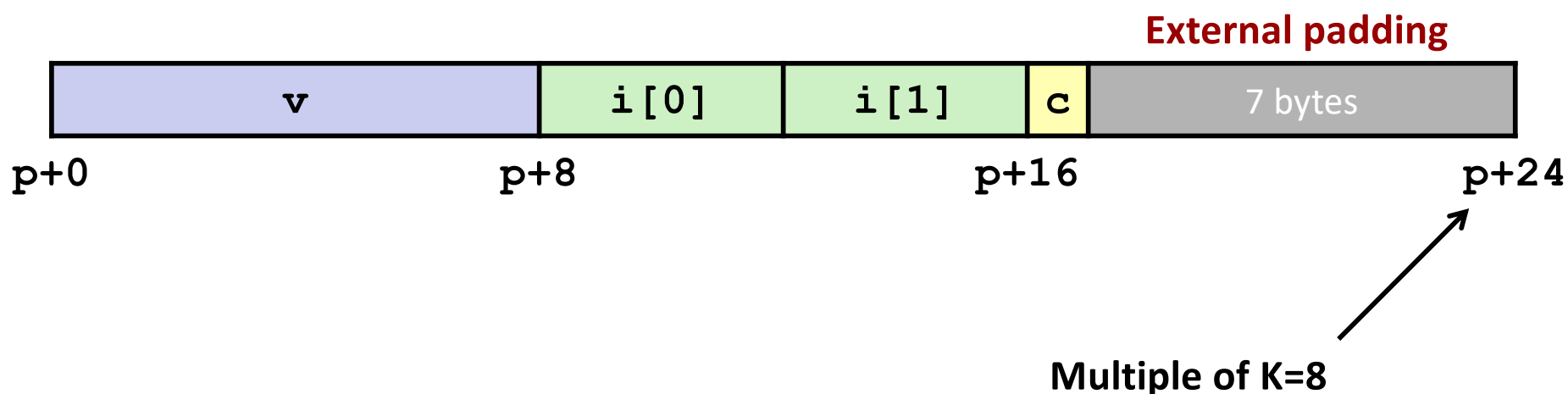
- K = 8, due to **double** element



# Meeting Overall Alignment Requirement

- For largest alignment requirement  $K$
- Overall structure must be multiple of  $K$

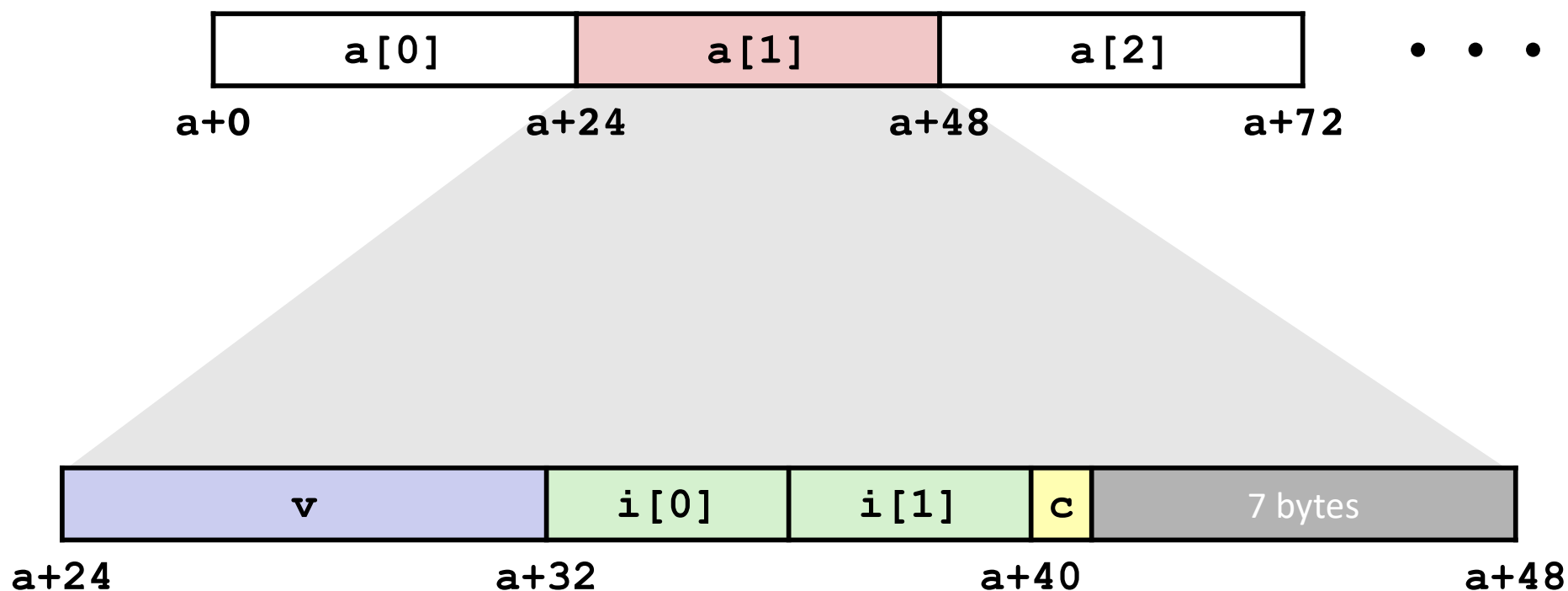
```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} *p;
```



# Arrays of Structures

- Overall structure length multiple of K
- Satisfy alignment requirement for every element

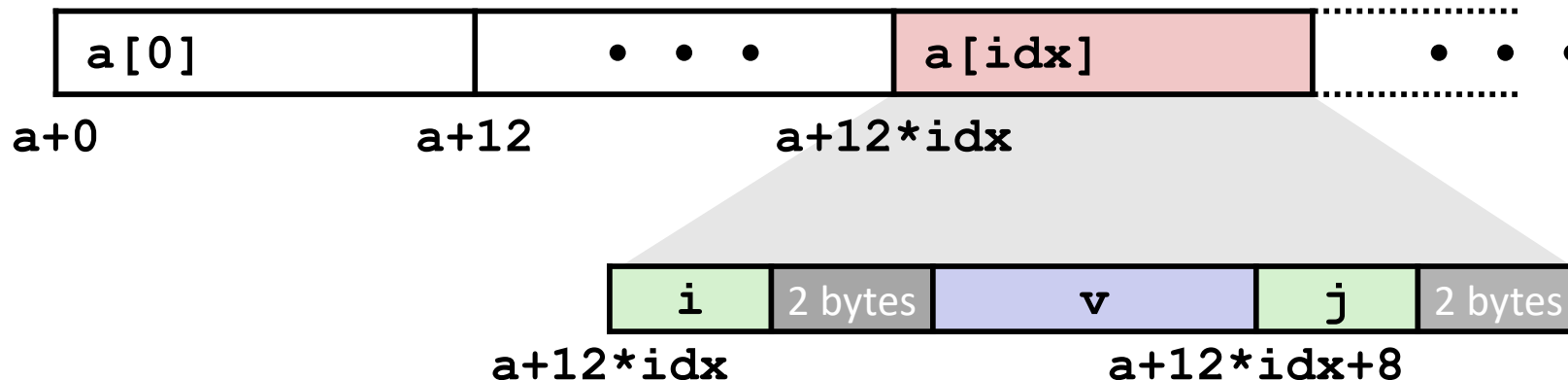
```
struct S2 {  
    double v;  
    int i[2];  
    char c;  
} a[10];
```



# Accessing Array Elements

```
struct S3 {
    short i;
    float v;
    short j;
} a[10];
```

- Compute array offset  $12 * \text{idx}$ 
  - `sizeof(S3)`, including alignment spacers
- Element `j` is at offset 8 within structure
- Assembler gives offset `a+8`
  - Resolved during linking



```
short get_j(int idx)
{
    return a[idx].j;
}
```

```
# %rdi = idx
leaq (%rdi,%rdi,2),%rax # 3*idx
movzwl a+8(,%rax,4),%eax
```

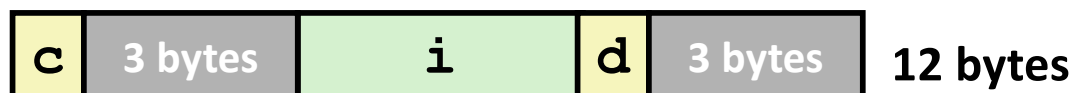
# Saving Space

- Put large data types first

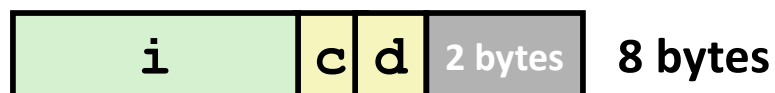
```
struct S4 {  
    char c;  
    int i;  
    char d;  
} *p;
```



```
struct S5 {  
    int i;  
    char c;  
    char d;  
} *p;
```



- Effect (largest alignment requirement K=4)



## Example Struct Exam Question

**Problem 5. (8 points):**

*Struct alignment.* Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

1. Show how `foo` would be allocated in memory on an x86-64 Linux system. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.

A 10x10 grid of dashed lines with vertical bars at the intersections, representing a coordinate system for a 10x10 grid of points.

<http://www.cs.cmu.edu/~213/oldexams/exam1-f12.pdf>

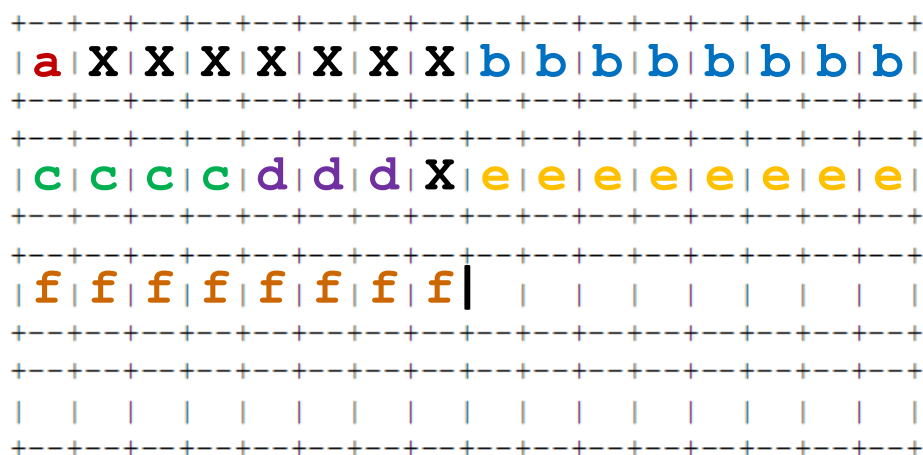
# Example Struct Exam Question

## Problem 5. (8 points):

*Struct alignment.* Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

1. Show how `foo` would be allocated in memory on an x86-64 Linux system. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an `X` to denote space that is allocated in the struct as padding.



<http://www.cs.cmu.edu/~213/oldexams/exam1-f12.pdf>

## Example Struct Exam Question (Cont'd)

**Problem 5. (8 points):**

*Struct alignment.* Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

2. Rearrange the elements of `foo` to conserve the most space in memory. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.

<http://www.cs.cmu.edu/~213/oldexams/exam1-f12.pdf>



## Example Struct Exam Question (Cont'd)

**Problem 5. (8 points):**

*Struct alignment.* Consider the following C struct declaration:

```
typedef struct {
    char a;
    long b;
    float c;
    char d[3];
    int *e;
    short *f;
} foo;
```

2. Rearrange the elements of `f00` to conserve the most space in memory. Label the bytes with the names of the various fields and **clearly mark the end of the struct**. Use an X to denote space that is allocated in the struct as padding.



<http://www.cs.cmu.edu/~213/oldexams/exam1-f12.pdf>

# Today

## ■ Arrays

- One-dimensional
- Multi-dimensional (nested)
- Multi-level

## ■ Structures

- Allocation
- Access
- Alignment

## ■ Floating Point

# Background

## ■ History

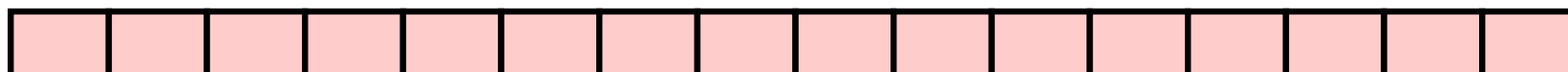
- x87 FP
  - Legacy, very ugly
- SSE FP
  - Supported by Shark machines
  - Special case use of vector instructions
- AVX FP
  - Newest version
  - Similar to SSE (but registers are 32 bytes instead of 16)
  - Documented in book

# Programming with SSE4

## XMM Registers

■ 16 total, each 16 bytes

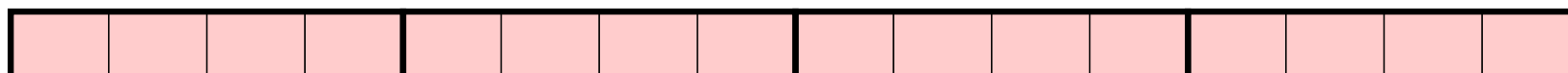
■ 16 single-byte integers



■ 8 16-bit integers



■ 4 32-bit integers



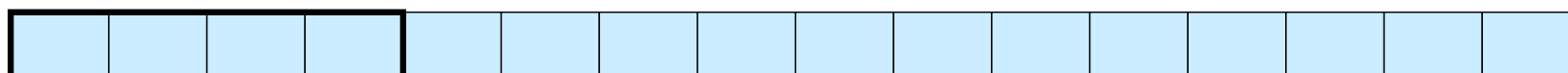
■ 4 single-precision floats



■ 2 double-precision floats



■ 1 single-precision float



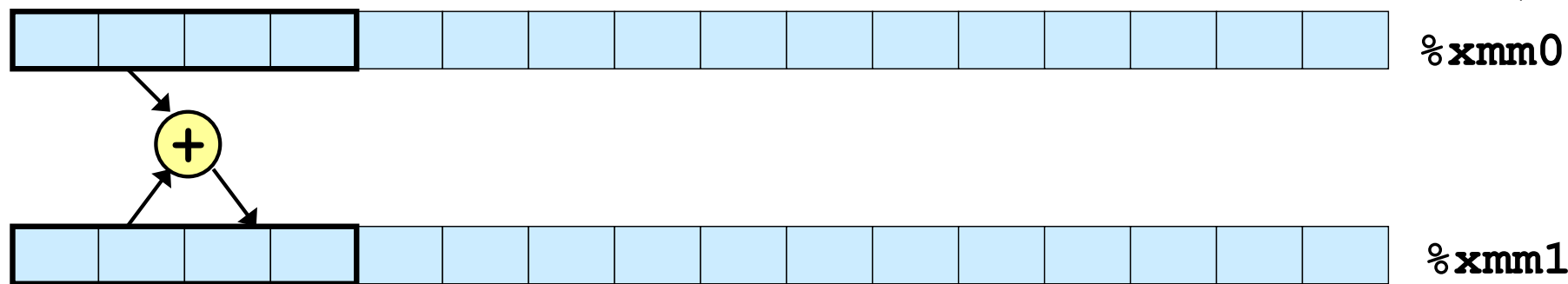
■ 1 double-precision float



# Scalar & SIMD Operations

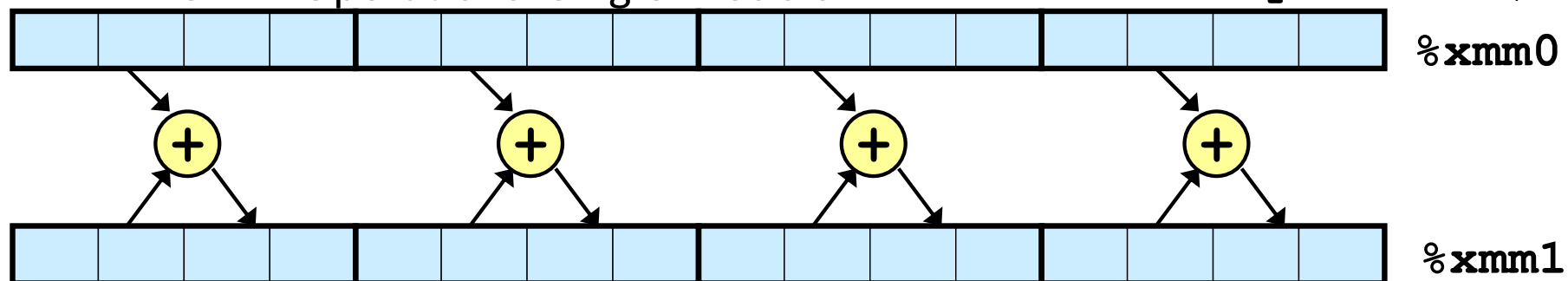
## ■ Scalar Operations: Single Precision

**addss** %xmm0, %xmm1



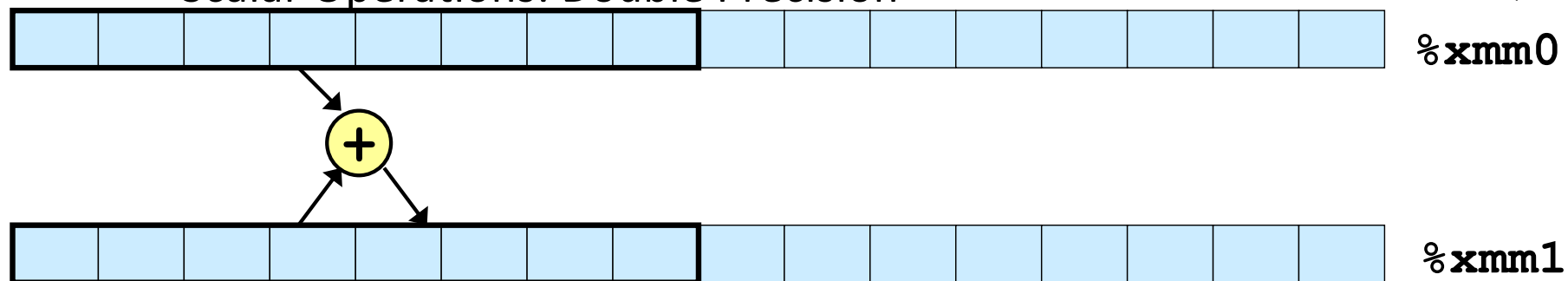
## ■ SIMD Operations: Single Precision

**addps** %xmm0, %xmm1



## ■ Scalar Operations: Double Precision

**addsd** %xmm0, %xmm1



# FP Basics

- Arguments passed in `%xmm0`, `%xmm1`, ...
- Result returned in `%xmm0`
- All XMM registers caller-saved

```
float fadd(float x, float y)
{
    return x + y;
}
```

```
double dadd(double x, double y)
{
    return x + y;
}
```

```
# x in %xmm0, y in %xmm1
addss    %xmm1, %xmm0
ret
```

```
# x in %xmm0, y in %xmm1
addsd    %xmm1, %xmm0
ret
```

# FP Memory Referencing

- Integer (and pointer) arguments passed in regular registers
- FP values passed in XMM registers
- Different mov instructions to move between XMM registers, and between memory and XMM registers

```
double dincr(double *p, double v)
{
    double x = *p;
    *p = x + v;
    return x;
}
```

```
# p in %rdi, v in %xmm0
movapd    %xmm0, %xmm1    # Copy v
movsd     (%rdi), %xmm0    # x = *p
addsd     %xmm0, %xmm1    # t = x + v
movsd     %xmm1, (%rdi)    # *p = t
ret
```

# Other Aspects of FP Code

## ■ *Lots of instructions*

- Different operations, different formats, ...

## ■ Floating-point comparisons

- Instructions `ucomiss` and `ucomisd`
- Set condition codes ZF, **PF** and CF
- Zeros OF and SF

Parity Flag

```
UNORDERED: ZF,PF,CF ← 111
GREATER_THAN: ZF,PF,CF ← 000
LESS_THAN: ZF,PF,CF ← 001
EQUAL: ZF,PF,CF ← 100
```

## ■ Using constant values

- Set XMM0 register to 0 with instruction `xorpd %xmm0, %xmm0`
- Others loaded from memory



# Summary

## ■ Arrays

- Elements packed into contiguous region of memory
- Use index arithmetic to locate individual elements

## ■ Structures

- Elements packed into single region of memory
- Access using offsets determined by compiler
- Possible require internal and external padding to ensure alignment

## ■ Combinations

- Can nest structure and array code arbitrarily

## ■ Floating Point

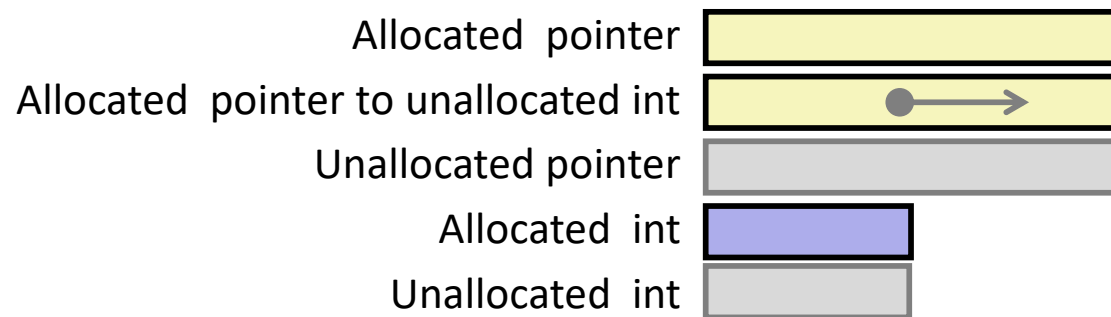
- Data held and operated on in XMM registers

# Understanding Pointers & Arrays #3

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3][5]</code>									
<code>int *A2[3][5]</code>									
<code>int (*A3)[3][5]</code>									
<code>int *(A4[3][5])</code>									
<code>int (*A5[3])[5]</code>									

- **Cmp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by `sizeof`**

Decl	***An		
	Cmp	Bad	Size
<code>int A1[3][5]</code>			
<code>int *A2[3][5]</code>			
<code>int (*A3)[3][5]</code>			
<code>int *(A4[3][5])</code>			
<code>int (*A5[3])[5]</code>			



### Declaration

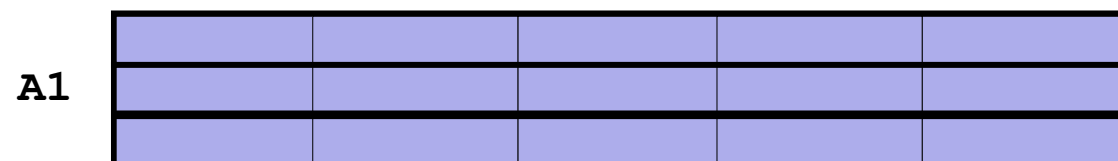
```
int A1[3][5]
```

```
int *A2[3][5]
```

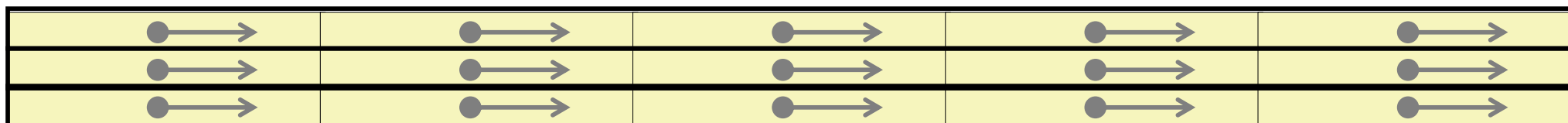
```
int (*A3)[3][5]
```

```
int *(A4[3][5])
```

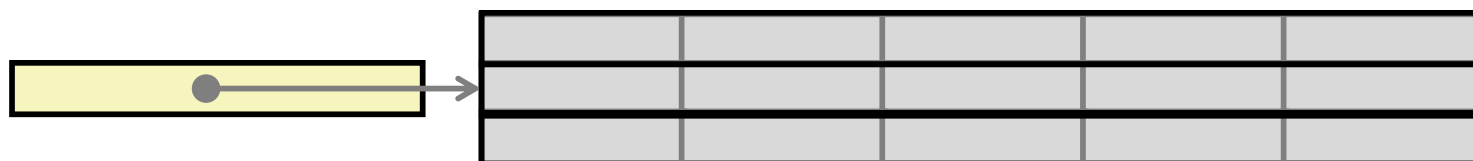
```
int (*A5[3])[5]
```



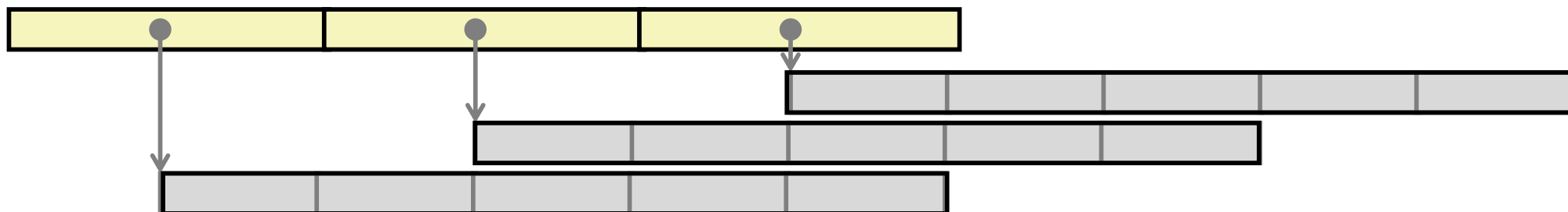
**A2/A4**



**A3**



**A5**



# Understanding Pointers & Arrays #3

Decl	An			*An			**An		
	Cmp	Bad	Size	Cmp	Bad	Size	Cmp	Bad	Size
<code>int A1[3][5]</code>	Y	N	60	Y	N	20	Y	N	4
<code>int *A2[3][5]</code>	Y	N	120	Y	N	40	Y	N	8
<code>int (*A3)[3][5]</code>	Y	N	8	Y	Y	60	Y	Y	20
<code>int *(A4[3][5])</code>	Y	N	120	Y	N	40	Y	N	8
<code>int (*A5[3])[5]</code>	Y	N	24	Y	N	8	Y	Y	20

- **Cmp: Compiles (Y/N)**
- **Bad: Possible bad pointer reference (Y/N)**
- **Size: Value returned by `sizeof`**

Decl	***An		
	Cmp	Bad	Size
<code>int A1[3][5]</code>	N	–	–
<code>int *A2[3][5]</code>	Y	Y	4
<code>int (*A3)[3][5]</code>	Y	Y	4
<code>int *(A4[3][5])</code>	Y	Y	4
<code>int (*A5[3])[5]</code>	Y	Y	4