

Recitation 13

Minimum Spanning Trees

13.1 Announcements

- *SegmentLab* has been released, and is due **Friday, November 17**. It's worth 135 points.

13.2 Prim's Algorithm

Minimum spanning trees are useful for a variety of applications in computer science, such as resource allocation, clustering, and image processing. They exhibit certain “greedy” properties that allow fast computation.

In particular, the *light-edge property*, or *cut property*, states that when a graph $G = (V, E)$ has its vertices cut into two partitions $(U, V \setminus U)$, then the edge with minimum weight that crosses from U into $V \setminus U$ is in the MST of G .

Prim's algorithm allows us to exploit this property to greedily insert edges into the partial MST until the full tree is built. The algorithm performs a priority-first search in a fashion similar to Dijkstra's algorithm. A partial implementation for connected, weighted, undirected graphs is given below.

Algorithm 13.1. Prim's Algorithm (Partial)

```

1 fun Prim G =
2   let
3     fun prim (X, T, Q) =
4       case PQ.deleteMin Q of
5         (NONE, _) => _____
6       | (SOME (d, (u, v)), Q') =>
7         if v ∈ X then _____ else
8         let
9           val X' = _____
10          val T' = case u of
11            NONE => _____
12          | SOME u' => _____
13          fun relax (Q, (v', w)) = _____
14          val Q'' = iterate relax Q' (NG+(v))
15        in
16          prim (X', T', Q'')
17        end
18   in
19     prim ({}, [], PQ.singleton (0, (NONE, 0)))
20   end

```

Task 13.2. Complete the implementation above by filling in the blanks. The similarity of Prim's and Dijkstra's algorithms should yield a $O(m \log n)$ work and span bound as for Dijkstra's algorithm.

Task 13.3. *In Dijkstra's algorithm, it was possible to terminate the algorithm early when we first reached some vertex t to obtain the shortest path from s to t . Can we make a similar optimization in Prim's algorithm? If so, what is it?*

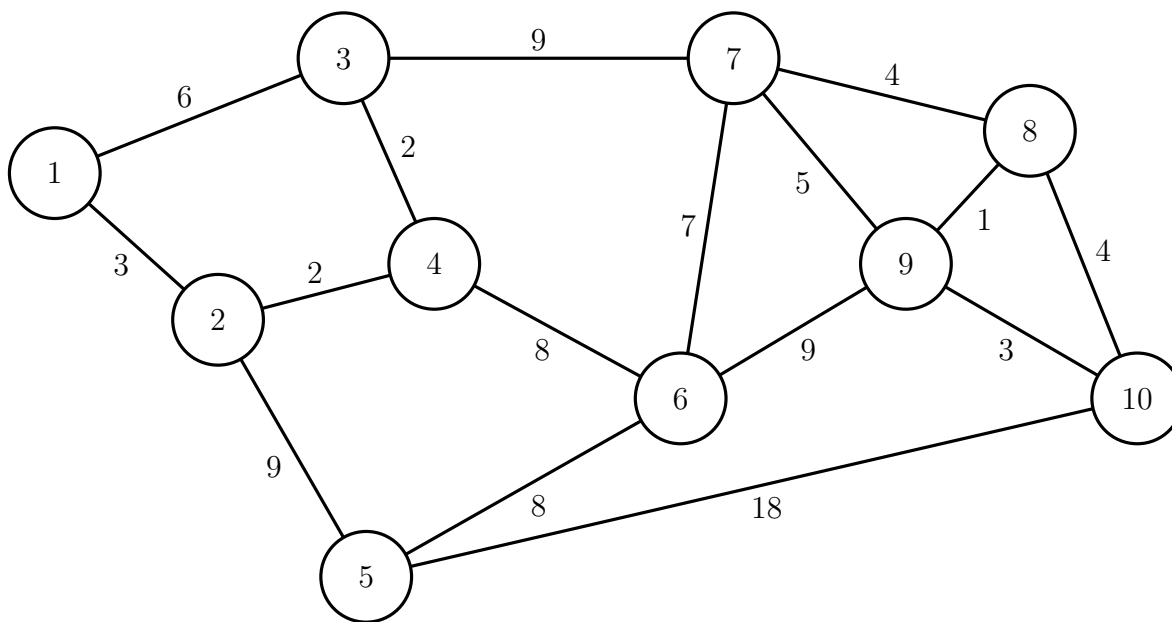
Remark 13.4. *Just as we generalized DFS to solve problems ranging from connectivity to bridge edges, we see it is possible to generalize Dijkstra's algorithm to obtain BFS, A* search, or Prim's algorithm. How versatile!*

Since the algorithm is so similar to Dijkstra's algorithm, we would expect the same work and span bounds, or possibly faster using a more advanced heap structure. However, Prim's algorithm has no parallelism, while Borůvka's algorithm does.

13.3 Borůvka's Algorithm

The textbook describes two versions of Borůvka's algorithm: one which performs tree contraction at each round, and another which performs a single round of star contraction at each round. We will be using the latter, since it has better overall span, $O(\log^2 n)$ rather than $O(\log^3 n)$.

Task 13.5. Run Borůvka's algorithm on the following graph. Draw the graph at each round, and identify which edges are MST edges. Use the coin flips specified.



Round	Vertices									
	1	2	3	4	5	6	7	8	9	10
0	H	T	H	T	T	H	T	H	T	T
1	T	H	T			T		T		H
2		T				H				T

13.4 Additional Exercises

Exercise 13.6. *The vertex-joiners selected in any round of Borůvka’s algorithm form a forest when no two edge weights are equal. Prove this fact.*

Hint: a forest, by definition, has no cycles.

Exercise 13.7. *In graph theory, an **independent set** is a set of vertices for which no two vertices are neighbors of one another. The **maximal independent set (MIS)** problem is defined as follows:*

For a graph (V, E) , find an independent set $I \subseteq V$ such that for all $v \in (V \setminus I)$, $I \cup \{v\}$ is not an independent set.^a

Design an efficient parallel algorithm based on graph contraction which solves the MIS problem.

^aThe condition that we cannot extend such an independent set I with another vertex is what makes it “maximal.” There is a closely related problem called **maximum independent set** where you find the largest possible I . However, this problem turns out to be NP-hard!

