

## What about continuous hypothesis spaces?

$\operatorname{error}_{t r u e}(h) \leq \operatorname{error}_{t r a i n}(h)+\sqrt{\frac{\ln |H|+\ln \frac{1}{\delta}}{2 m}}$

- Continuous hypothesis space:
$\square|\mathrm{H}|=\infty$
$\square$ Infinite variance???
- As with decision trees, only care about the maximum number of points that can be classified exactly!




## Shattering a set of points

Definition: a dichotomy of a set $S$ is a partition of $S$ into two disjoint subsets.

Definition: a set of instances $S$ is shattered by hypothesis space $H$ if and only if for every dichotomy of $S$ there exists some hypothesis in $H$ consistent with this dichotomy.

## VC dimension

Definition: The Vapnik-Chervonenkis
dimension, $V C(H)$, of hypothesis space $H$
defined over instance space $X$ is the size of
the largest finite subset of $X$ shattered by $H$.
If arbitrarily large finite sets of $X$ can be shattered by $H$, then $V C(H) \equiv \infty$.

## PAC bound using VC dimension

- Number of training points that can be classified exactly is VC dimension!!!

Measures relevant size of hypothesis space, as with decision trees with $k$ leaves
Bound for infinite dimension hypothesis spaces:
$\operatorname{error}_{t r u e}(h) \leq \operatorname{error}_{\text {train }}(h)+\sqrt{\frac{V C(H)\left(\ln \frac{2 m}{V C(H)}+1\right)+\ln \frac{4}{\delta}}{m}}$

## Examples of VC dimension

Linear classifiers:
$\mathrm{VC}(\mathrm{H})=\mathrm{d}+1$, for $d$ features plus constant term $b$

- Neural networks
$\square \mathrm{VC}(\mathrm{H})=$ \#parameters
$\square$ Local minima means NNs will probably not find best parameters

1-Nearest neighbor?

## Another VC dim. example --What can we shatter?

- What's the VC dim. of decision stumps in 2d?

Another VC dim. example -- What can't we shatter?

What's the VC dim. of decision stumps in 2d?

## What you need to know

- Finite hypothesis space
$\square$ Derive results
$\square$ Counting number of hypothesis
$\square$ Mistakes on Training data
- Complexity of the classifier depends on number of points that can be classified exactly
$\square$ Finite case - decision trees
$\square$ Infinite case - VC dimension
- Bias-Variance tradeoff in learning theory
- Remember: will your algorithm find best classifier?



## Webpage classification



Personal home page vs

University home page vs


## Webpage classification 2



## Today - Bayesian networks

- One of the most exciting advancements in statistical AI in the last 10-15 years
- Generalizes naïve Bayes and logistic regression classifiers
- Compact representation for exponentially-large probability distributions
- Exploit conditional independencies


## Causal structure

- Suppose we know the following:
$\square$ The flu causes sinus inflammation
$\square$ Allergies cause sinus inflammation
$\square$ Sinus inflammation causes a runny nose
$\square$ Sinus inflammation causes headaches
- How are these connected?





## (Marginal) Independence

Flu and Allergy are (marginally) independent

| Flu $=\mathrm{t}$ |  |
| :--- | :--- |
| Flu $=\mathrm{f}$ |  |

- More Generally:

| Allergy $=\mathrm{t}$ |  |
| :--- | :--- |
| Allergy $=\mathrm{f}$ |  |


|  | Flu $=\mathrm{t}$ | Flu $=\mathrm{f}$ |
| :--- | :--- | :--- |
| Allergy $=\mathrm{t}$ |  |  |
| Allergy $=\mathrm{f}$ |  |  |

## Marginally independent random variables

- Sets of variables $\mathbf{X}, \mathbf{Y}$
- $X$ is independent of $Y$ if
$\square P \vDash(\mathbf{X}=\mathbf{x} \perp \mathbf{Y}=\mathbf{y}), \forall \mathbf{x} \in \operatorname{Val}(\mathbf{X}), \mathbf{y} \in \operatorname{Val}(\mathbf{Y})$
- Shorthand:

Marginal independence: $P \vDash(\mathbf{X} \perp \mathbf{Y})$

■ Proposition: $P$ statisfies $(\mathbf{X} \perp \mathbf{Y})$ if and only if $P(\mathbf{X}, \mathbf{Y})=P(\mathbf{X}) P(\mathbf{Y})$

## Conditional independence

- Flu and Headache are not (marginally) independent

■ Flu and Headache are independent given Sinus infection

- More Generally:


## Conditionally independent random variables

■ Sets of variables $\mathbf{X}, \mathbf{Y}, \mathbf{Z}$

- $X$ is independent of $Y$ given $Z$ if

$$
\square P \vDash(\mathbf{X}=\mathbf{x} \perp \mathbf{Y}=\mathbf{y} \mid \mathbf{Z}=\mathbf{z}), \forall \mathbf{x} \in \operatorname{Val}(\mathbf{X}), \mathbf{y} \in \operatorname{Val}(\mathbf{Y}), \mathbf{z} \in \operatorname{Val}(\mathbf{Z})
$$

- Shorthand:

Conditional independence: $P \vDash(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z})$
$\square$ For $P \vDash(\mathbf{X} \perp \mathbf{Y} \mid \emptyset)$, write $\mathrm{P} \vDash(\mathbf{X} \perp \mathbf{Y})$

- Proposition: $P$ statisfies $(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z})$ if and only if
$\square P(\mathbf{X}, \mathbf{Y} \mid \mathbf{Z})=P(\mathbf{X} \mid \mathbf{Z}) P(\mathbf{Y} \mid \mathbf{Z})$


## Properties of independence

- Symmetry:
$\square(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z}) \Rightarrow(\mathbf{Y} \perp \mathbf{X} \mid \mathbf{Z})$
- Decomposition:
$\square(\mathbf{X} \perp \mathbf{Y}, \mathbf{W} \mid \mathbf{Z}) \Rightarrow(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z})$
■ Weak union:
$\square(\mathbf{X} \perp \mathbf{Y}, \mathbf{W} \mid \mathbf{Z}) \Rightarrow(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z}, \mathbf{W})$
■ Contraction:
$\square \mathbf{X} \perp \mathbf{W} \mid \mathbf{Y}, \mathbf{Z}) \&(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{Z}) \Rightarrow(\mathbf{X} \perp \mathbf{Y}, \mathbf{W} \mid \mathbf{Z})$
- Intersection:
$\square(\mathbf{X} \perp \mathbf{Y} \mid \mathbf{W}, \mathbf{Z}) \&(\mathbf{X} \perp \mathbf{W} \mid \mathbf{Y}, \mathbf{Z}) \Rightarrow(\mathbf{X} \perp \mathbf{Y}, \mathbf{W} \mid \mathbf{Z})$
$\square$ Only for positive distributions!
$\square \mathrm{P}(\alpha)>0, \forall \alpha, \alpha \neq \emptyset$





## The chain rule of probabilities

- $P(A, B)=P(A) P(B \mid A)$


■ More generally:

$$
\square P\left(X_{1}, \ldots, X_{n}\right)=P\left(X_{1}\right) \cdot P\left(X_{2} \mid X_{1}\right) \cdot \ldots \cdot P\left(X_{n} \mid X_{1}, \ldots, X_{n-1}\right)
$$

## Chain rule \& Joint distribution



## Two (trivial) special cases

Edgeless graph
Fully-connected graph

## The Representation Theorem Joint Distribution to BN

BN:


## Encodes independence assumptions

If conditional independencies in BN are subset of conditional independencies in $P$

## Obtain distribution:

$$
P\left(X_{1}, \ldots, X_{n}\right)=\prod_{i=1}^{n} P\left(X_{i} \mid \mathbf{P a}_{X_{i}}\right)
$$

Joint probability

## Real Bayesian networks applications

- Diagnosis of lymph node disease
- Speech recognition
- Microsoft office and Windows
$\square$ http://www.research.microsoft.com/research/dtg/
- Study Human genome
- Robot mapping
- Robots to identify meteorites to study
- Modeling fMRI data
- Anomaly detection
- Fault dianosis
- Modeling sensor network data


## A general Bayes net

Set of random variables

- Directed acyclic graph
$\square$ Encodes independence assumptions
- CPTs
- Joint distribution:

$$
P\left(X_{1}, \ldots, X_{n}\right)=\prod_{i=1}^{n} P\left(X_{i} \mid \mathbf{P} \mathbf{a}_{X_{i}}\right)
$$

How many parameters in a BN ?

- Discrete variables $X_{1}, \ldots, X_{n}$
- Graph
$\square$ Defines parents of $X_{i}, P a_{x_{i}}$
- CPTs - $\mathrm{P}\left(\mathrm{X}_{\mathrm{i}} \mid \mathrm{Pa}_{\mathrm{x}_{\mathrm{i}}}\right)$


## Another example

- Variables:
$\square$ B - Burglar
$\square \mathrm{E}$ - Earthquake
$\square$ A - Burglar alarm
$\square \mathrm{N}$ - Neighbor calls
$\square \mathrm{R}$ - Radio report
- Both burglars and earthquakes can set off the alarm
- If the alarm sounds, a neighbor may call
- An earthquake may be announced on the radio



## Independencies encoded in BN

- We said: All you need is the local Markov assumption
$\square\left(\mathrm{X}_{\mathrm{i}} \perp\right.$ NonDescendants $\left._{\mathrm{x}_{\mathrm{i}}} \mid \mathrm{Pa}_{\mathrm{x}_{\mathrm{i}}}\right)$
- But then we talked about other (in)dependencies
$\square$ e.g., explaining away
- What are the independencies encoded by a BN?

Only assumption is local Markov
But many others can be derived using the algebra of conditional independencies!!!



An active trail - Example


When are $A$ and $H$ independent?

## Active trails formalized

- A path $X_{1}-X_{2}-\cdots-X_{k}$ is an active trail when variables $\mathbf{O} \subseteq\left\{X_{1}, \ldots, X_{n}\right\}$ are observed if for each consecutive triplet in the trail:
$\square X_{i-1} \rightarrow X_{i} \rightarrow X_{i+1}$, and $X_{i}$ is not observed ( $X_{i} \notin \mathbf{O}$ )
$\square \mathrm{X}_{\mathrm{i}-1} \leftarrow \mathrm{X}_{\mathrm{i}} \leftarrow \mathrm{X}_{\mathrm{i}+1}$, and $\mathrm{X}_{\mathrm{i}}$ is not observed ( $\mathrm{X}_{\mathrm{i}} \notin \mathbf{O}$ )
$\square \mathrm{X}_{\mathrm{i}-1} \leftarrow \mathrm{X}_{\mathrm{i}} \rightarrow \mathrm{X}_{\mathrm{i}+1}$, and $\mathrm{X}_{\mathrm{i}}$ is not observed ( $\mathrm{X}_{\mathrm{i}} \notin \mathbf{O}$ )
$\square X_{i-1} \rightarrow X_{i} \leftarrow X_{i+1}$, and $X_{i}$ is observed ( $X_{i} \in \mathcal{O}$ ), or one of its descendents


## Active trails and independence?

- Theorem: Variables $\mathbf{X}_{\mathbf{i}}$ and $X_{j}$ are independent given $Z \subseteq\left\{X_{1}, \ldots, X_{n}\right\}$ if the is no active trail between $X_{i}$ and $X_{j}$ when variables $Z \subseteq\left\{X_{1}, \ldots, X_{n}\right\}$ are observed



## The BN Representation Theorem

| If conditional <br> independencies <br> in BN are subset of <br> conditional <br> independencies in $\boldsymbol{P}$ | Obtain |
| :---: | :---: |$\quad$| Joint probability |
| :---: |
| distribution: |

Important because:
Every P has at least one BN structure G

| If joint |  |
| :---: | :---: |
| probability | Obtain | | Then conditional |
| :---: |
| independencies |
| in BN are subset of |
| instribution: |$\quad$| conditional |
| :---: |
| independencies in $P$ |

Important because:
Read independenciess of $P$ from BN structure G

## "Simpler" BNs

A distribution can be represented by many BNs:

- Simpler BN, requires fewer parameters



## Queries in Bayes nets

- Given BN, find:
$\square$ Probability of X given some evidence, $\mathrm{P}(\mathrm{X} \mid \mathrm{e})$

Most probable explanation, $\max _{\mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{n}}} \mathrm{P}\left(\mathrm{x}_{1}, \ldots, \mathrm{x}_{\mathrm{n}} \mid \mathrm{e}\right)$
$\square$ Most informative query

Learn more about these next class

## What you need to know

- Bayesian networks
$\square$ A compact representation for large probability distributions
$\square$ Not an algorithm
- Semantics of a BN
$\square$ Conditional independence assumptions
- Representation
$\square$ Variables
$\square$ Graph
$\square$ CPTs
- Why BNs are useful
- Learning CPTs from fully observable data
- Play with applet!!! :)


## Acknowledgements

- JavaBayes applet
$\square$ http://www.pmr.poli.usp.br/Itd/Software/javabayes/Ho me/index.html

