

CONCURRENT SEPARATION LOGIC...

semantics and soundness

Stephen Brookes
Carnegie Mellon University

Tutorial
MFPS 2006

Outline

- Denotational semantics
 - parallel programs with shared mutable state
- Logic
 - resource-sensitive partial correctness
- Soundness
 - ownership transfer
 - every provable formula is race-free



Semantics

- A *process* denotes a set of *traces*
- A trace is a sequence of *actions*
- Actions have *effect* on *state*
- State = store + heap + resources

*A trace represents a
fair interactive computation*

Actions

- Idle δ
- Store $i=v$ $i:=v$
- Heap $[l]=v$ $[l]:=v$ $alloc(l, L)$ $disp(l)$
- Resource $try(r)$ $acq(r)$ $rel(r)$
- Error $abort$

i ranges over program variables, r over resource names,
 v over integers, l over heap cells, L over lists of integers

Traces

A trace is a finite or infinite sequence of actions

- Let Λ be the set of actions
- The set of traces is $\text{Tr} = \Lambda^* \cup \Lambda^\omega$

λ will range over Λ

$\alpha, \beta, \gamma, \rho$ will range over Tr

Semantic functions

$$\llbracket e \rrbracket \subseteq \mathbf{Tr} \times V_{\text{int}}$$

$$\llbracket E \rrbracket \subseteq \mathbf{Tr} \times V_{\text{int}}^*$$

$$\llbracket b \rrbracket \subseteq \mathbf{Tr} \times V_{\text{bool}}$$

$$\llbracket c \rrbracket \subseteq \mathbf{Tr}$$

defined denotationally...

Semantics of expressions

$$\llbracket e \rrbracket \subseteq \mathbf{Tr} \times V_{\text{int}}$$

$$\llbracket i \rrbracket = \{(i=v, v) \mid v \in V_{\text{int}}\}$$

$$\begin{aligned} \llbracket e_1 + e_2 \rrbracket = \\ \{(\rho_1 \rho_2, v_1 + v_2) \mid \\ (\rho_1, v_1) \in \llbracket e_1 \rrbracket \ \& \ (\rho_2, v_2) \in \llbracket e_2 \rrbracket\} \end{aligned}$$

Semantics of expressions

$$\llbracket b \rrbracket \subseteq \mathbf{Tr} \times V_{\text{bool}}$$

$$\llbracket \text{true} \rrbracket = \{(\delta, \text{true})\}$$

$$\llbracket \text{not } b \rrbracket = \{(\rho, \neg t) \mid (\rho, t) \in \llbracket b \rrbracket\}$$

Semantics of commands

$$\llbracket c \rrbracket \subseteq \text{Tr}$$

$$\llbracket \text{skip} \rrbracket = \{\delta\}$$

$$\llbracket i := e \rrbracket = \{\rho \ i := v \mid (\rho, v) \in \llbracket e \rrbracket\}$$

$$\llbracket c_1; c_2 \rrbracket = \{\alpha_1 \alpha_2 \mid \alpha_1 \in \llbracket c_1 \rrbracket, \alpha_2 \in \llbracket c_2 \rrbracket\}$$

concatenation

Semantics of commands

$$\llbracket \text{if } b \text{ then } c_1 \text{ else } c_2 \rrbracket = \\ \llbracket b \rrbracket_{\text{true}} \llbracket c_1 \rrbracket \cup \llbracket b \rrbracket_{\text{false}} \llbracket c_2 \rrbracket$$

$$\llbracket \text{while } b \text{ do } c \rrbracket = \text{iteration} \\ (\llbracket b \rrbracket_{\text{true}} \llbracket c \rrbracket)^* \llbracket b \rrbracket_{\text{false}} \cup (\llbracket b \rrbracket_{\text{true}} \llbracket c \rrbracket)^\omega$$

where

$$\begin{aligned} \llbracket b \rrbracket_{\text{true}} &=_{\text{def}} \{ \rho \mid (\rho, \text{true}) \in \llbracket b \rrbracket \} \\ \llbracket b \rrbracket_{\text{false}} &=_{\text{def}} \{ \rho \mid (\rho, \text{false}) \in \llbracket b \rrbracket \} \end{aligned}$$

Semantics of commands

HEAP COMMANDS

$$\llbracket i := [e] \rrbracket = \{ \rho \ [l] = v \ i := v \mid (\rho, l) \in \llbracket e \rrbracket \}$$

$$\begin{aligned} \llbracket [e_1] := e_2 \rrbracket = & \{ \rho_1 \rho_2 \ [v_1] := v_2 \mid \\ & (\rho_1, v_1) \in \llbracket e_1 \rrbracket, (\rho_2, v_2) \in \llbracket e_2 \rrbracket \} \end{aligned}$$

$$\llbracket i := \mathbf{cons}(E) \rrbracket = \{ \rho \ \mathit{alloc}(l, L) \ i := l \mid (\rho, L) \in \llbracket E \rrbracket \}$$

$$\llbracket \mathbf{dispose}(e) \rrbracket = \{ \rho \ \mathit{disp}(l) \mid (\rho, l) \in \llbracket e \rrbracket \}$$

Semantics of commands

CONDITIONAL CRITICAL REGIONS

$$\llbracket \text{with } r \text{ when } b \text{ do } c \rrbracket = \text{wait}^* \text{ enter} \cup \text{wait}^\omega$$

where

$$\text{wait} = \text{acq}(r) \llbracket b \rrbracket_{\text{false}} \text{rel}(r) \cup \{\text{try}(r)\}$$

$$\text{enter} = \text{acq}(r) \llbracket b \rrbracket_{\text{true}} \llbracket c \rrbracket \text{rel}(r)$$

Semantics of commands

LOCAL RESOURCE BLOCKS

$$\llbracket \text{resource } r \text{ in } c \rrbracket = \{ \alpha \setminus r \mid \alpha \in \llbracket c \rrbracket_r \}$$

*obtained by
erasing actions on r*

*from traces in which
 r is interference-free*

A local channel cannot be
accessed outside the scope

Semantics of commands

PARALLEL COMPOSITION

$$\llbracket c_1 \parallel c_2 \rrbracket = \llbracket c_1 \rrbracket \parallel_{\emptyset \emptyset} \llbracket c_2 \rrbracket$$

*resource-sensitive,
race-detecting,
fair interleaving*

$$\alpha_1 \parallel \alpha_2$$

$A_1 \quad A_2$

parallel composition of traces,
with disjoint sets of resources

Parallel composition

$$\lambda_1 \beta_1 \parallel \lambda_2 \beta_2$$

$A_1 \quad A_2$

*mutual exclusion
for resources*

$$\begin{aligned}
 =_{\text{def}} & \{ \lambda_1 \beta \mid \beta \in \beta_1 \parallel \lambda_2 \beta_2 \text{ \& } (A_1, A_2) \xrightarrow{\lambda_1} (A'_1, A_2) \} \\
 & \cup \{ \lambda_2 \beta \mid \beta \in \lambda_1 \beta_1 \parallel \beta_2 \text{ \& } (A_2, A_1) \xrightarrow{\lambda_2} (A'_2, A_1) \} \\
 & \cup \{ \text{abort} \mid \lambda_1 \bowtie \lambda_2 \}
 \end{aligned}$$

race causes error

Interference

concurrent write to
same variable or heap cell

$$\lambda_1 \bowtie \lambda_2 \text{ iff } \begin{array}{l} \text{free}(\lambda_1) \cap \text{writes}(\lambda_2) \neq \emptyset \\ \text{or} \\ \text{writes}(\lambda_1) \cap \text{free}(\lambda_2) \neq \emptyset \end{array}$$

Mutual exclusion

process with A_1 can do λ
in environment with A_2

$$\begin{array}{ll} (A_1, A_2) \xrightarrow{\text{acq}(r)} (A_1 \cup \{r\}, A_2) & \text{iff } r \notin A_1 \cup A_2 \\ (A_1, A_2) \xrightarrow{\text{rel}(r)} (A_1 \setminus r, A_2) & \text{iff } r \in A_1 \\ (A_1, A_2) \xrightarrow{\lambda} (A_1, A_2) & \text{otherwise} \end{array}$$

Examples

$$\llbracket x := 1 \parallel x := 2 \rrbracket = \{x:=1 \ x:=2, x:=2 \ x:=1\} \\ \cup \{abort \mid v \in V_{\text{int}}\}$$

$$\llbracket \text{with } r \text{ do } x := 1 \rrbracket = \text{try}(r)^\infty \text{acq}(r) \{x:=1\} \text{rel}(r)$$

$$\llbracket \text{with } r \text{ do } x := 2 \rrbracket = \text{try}(r)^\infty \text{acq}(r) \{x:=2\} \text{rel}(r)$$

$$\llbracket \text{resource } r \text{ in} \\ \text{with } r \text{ do } x := 1 \parallel \text{with } r \text{ do } x := 2 \rrbracket \\ = \{x:=1 \ x:=2, x:=2 \ x:=1\}$$

Actions and state

- So far we have kept state *implicit*
 - state = store + heap + resources
 - $\sigma = (s, h, A)$
- But actions have *effect*
 - when *enabled*
 - cause state change
 - may produce runtime error

Effects

$$(s, h, A) \xRightarrow{\lambda} (s', h', A')$$

$$(s, h, A) \xRightarrow{\lambda} \text{abort}$$

a *transition relation*

specifying

when the action λ is *enabled*
and its *effect* when executed

Effects

READ

$$(s, h, A) \xRightarrow{i=v} (s, h, A) \quad \text{if } (i, v) \in s$$

$$(s, h, A) \xRightarrow{i=v} \mathbf{abort} \quad \text{if } i \notin \text{dom}(s)$$

WRITE

$$(s, h, A) \xRightarrow{i:=v} ([s|i:v], h, A) \quad \text{if } i \in \text{dom}(s)$$

$$(s, h, A) \xRightarrow{i:=v} \mathbf{abort} \quad \text{if } i \notin \text{dom}(s)$$

Effects

LOOKUP

$$(s, h, A) \xRightarrow{[l]=v} (s, h, A) \quad \text{if } (l, v) \in h$$

$$(s, h, A) \xRightarrow{[l]=v} \mathbf{abort} \quad \text{if } l \notin \text{dom}(h)$$

UPDATE

$$(s, h, A) \xRightarrow{[l]:=v} (s, [h|l:v], A) \quad \text{if } l \in \text{dom}(h)$$

$$(s, h, A) \xRightarrow{[l]:=v} \mathbf{abort} \quad \text{if } l \notin \text{dom}(h)$$

Effects

ALLOCATE

$$\begin{array}{c} \text{alloc}(l, [v_0, \dots, v_n]) \\ (s, h, A) \Rightarrow (s, h', A) \\ \text{if } \{l, l+1, \dots, l+n\} \cap \text{dom}(h) = \emptyset \\ \text{and } h' = [h \mid l:v_0, \dots, l+n:v_n] \end{array}$$

DISPOSE

$$(s, h, A) \xRightarrow{\text{disp}(l)} (s, h \setminus l, A) \quad \text{if } l \in \text{dom}(h)$$

$$(s, h, A) \xRightarrow{\text{disp}(l)} \text{abort} \quad \text{if } l \notin \text{dom}(h)$$

Effects

RESOURCE ACTIONS

$$(s, h, A) \xRightarrow{acq(r)} (s, h, A \cup \{r\}) \quad \text{if } r \notin A$$

$$(s, h, A) \xRightarrow{rel(r)} (s, h, A \setminus r) \quad \text{if } r \in A$$

$$(s, h, A) \xRightarrow{try(r)} (s, h, A) \quad \text{always}$$

Effects

IDLE

$$(s, h, A) \xRightarrow{\delta} (s, h, A)$$

ERROR

$$(s, h, A) \xRightarrow{abort} \mathbf{abort}$$

$$\mathbf{abort} \xRightarrow{\lambda} \mathbf{abort}$$

Respect for resources

THEOREM

If $\alpha \in \llbracket c \rrbracket$

and

$$(s, h, \emptyset) \xRightarrow{\alpha} (s', h', A')$$

then $\text{dom}(s) = \text{dom}(s')$

and $A' = \emptyset$

We usually omit $\emptyset$

and write $(s, h) \xRightarrow{\alpha} (s', h')$

Race-free programs

DEFINITION

c is *race-free* from (s, h)

iff

$$\neg \exists \alpha \in \llbracket c \rrbracket. (s, h) \xRightarrow{\alpha} \mathbf{abort}$$

every execution of *c*
from (s, h)
is error-free

Examples

PUT :: with r when full=0 do (z:=x; full:=1)

GET :: with r when full=1 do (y:=z; full:=0)

(PUT; **dispose** x) || GET

PUT || (GET; **dispose** y)

PUT^M || GET^N (M, N > 0)

are race-free from (s, h) if

$\{x, y, z\} \subseteq \text{dom}(s) \ \& \ s(x) \in \text{dom}(h) \ \& \ s(\text{full})=0$

$(s, h) \models \text{full}=0 \wedge x \mapsto _$

Summary

- Trace semantics, defined denotationally, supports compositional reasoning
- Treats a potential race as catastrophe
- Suitable for race-free partial correctness, total correctness, safety and liveness

*Will provide foundation for
concurrent separation logic...*

Concurrent separation logic

- A more formal treatment of the logic underlying Peter O'Hearn's work
- Syntax and semantics
- Proof of soundness

Key notions:
rely/guarantee
ownership transfer

Syntax

Resource-sensitive partial correctness formulas

$$\Gamma \vdash \{p\}c\{q\}$$

where

Γ is a *resource context*

$$r_1(X):R_1, \dots, r_n(X):R_n$$

protection list

resource
invariant

subject to well-formedness constraints...

Notation

For $\Gamma = r_1(X):R_1, \dots, r_k(X):R_k$

- $\text{dom}(\Gamma) = \{r_1, \dots, r_k\}$ *resource names*
- $\text{owned}(\Gamma) = X_1 \cup \dots \cup X_k$ *protected variables*
- $\text{free}(\Gamma) = \text{free}(R_1) \cup \dots \cup \text{free}(R_k)$ *variables mentioned in resource invariants*
- $\text{inv}(\Gamma) = R_1 \star \dots \star R_k$ *separate conjunction of resource invariants*

Well-formed formulas

$$r_1(X_1):R_1, \dots, r_n(X_n):R_n \vdash \{p\}c\{q\}$$

is *well-formed* iff

pre- and post-conditions
don't mention protected variables

- R_i is *precise* & $\text{free}(p,q) \cap X_i = \emptyset$ for all i
- $r_i \neq r_j$, $X_i \cap X_j = \emptyset$, $\text{free}(R_i) \cap X_j = \emptyset$ for $i \neq j$

protected variables are partitioned
among the resources

Precision

DEFINITION

*R is precise iff for all s, h
there is at most one $h' \subseteq h$
such that $(s, h') \models R$*

FACTS

$\text{emp}, e \mapsto e'$ are precise

*if p_1 and p_2 are precise,
so are*

$$p_1 \star p_2$$
$$(b \wedge p_1) \vee (\neg b \wedge p_2)$$

Inference rules

- Syntax-directed rules
 - for each program construct
- Structural rules
 - rule of consequence, auxiliary variables
- Static side conditions
 - impose well-formedness constraints

Parallel

$$\frac{\Gamma \vdash \{p_1\}c_1\{q_1\} \quad \Gamma \vdash \{p_2\}c_2\{q_2\}}{\Gamma \vdash \{p_1 \star p_2\}c_1 \parallel c_2\{q_1 \star q_2\}}$$

provided

$$\begin{aligned} & \text{free}(p_1, q_1) \cap \text{writes}(c_2) = \emptyset \\ & \text{free}(p_2, q_2) \cap \text{writes}(c_1) = \emptyset \\ & \text{free}(c_1) \cap \text{writes}(c_2) \subseteq \text{owned}(\Gamma) \\ & \text{free}(c_2) \cap \text{writes}(c_1) \subseteq \text{owned}(\Gamma) \end{aligned}$$

Region

$$\Gamma \vdash \{(p \star R) \wedge b\} c \{q \star R\}$$

$$\Gamma, r(X):R \vdash \{p\} \text{ with } r \text{ do } c \{q\}$$

provided

$$\text{free}(p,q) \cap X = \emptyset$$

R precise

Resource

$$\Gamma, r(X):R \vdash \{p\}c\{q\}$$

$$\Gamma \vdash \{p \star R\} \text{ resource } r \text{ in } c\{q \star R\}$$

Frame

$$\frac{\Gamma \vdash \{p\}c\{q\}}{\Gamma \vdash \{p \star I\} c \{q \star I\}}$$

provided

$$\begin{aligned} \text{free}(I) \cap \text{writes}(c) &= \emptyset \\ \text{free}(I) \cap \text{owned}(\Gamma) &= \emptyset \end{aligned}$$

Validity

$\Gamma \vdash \{p\}c\{q\}$ is valid

iff

Every *finite interactive computation* of c ,
in an environment that respects Γ ,
from a state satisfying $p \star \text{inv}(\Gamma)$
is error-free, respects Γ , and
ends in a state satisfying $q \star \text{inv}(\Gamma)$

... needs to be formalized!

Separation Principle

At all stages of execution:

- For each available resource, the invariant holds, separately
- The heap is partitioned among processes and available resources
- ownership transfers when resource is acquired or released

Formalized using
local states, local transitions...

Local states

A state is *local* for Γ if it provides sufficient resources for its protected variables...

(s, h, A)

is local for Γ

iff

$$\text{dom}(s) \cap \text{owned}(\Gamma) = \text{owned}(\Gamma \upharpoonright A)$$

*the piece of global state visible to a
process with resources A
that respects Γ*

Local transitions

- Interactive computation
in an environment that respects Γ
 - ownership transfer
 - protection rules
 - preservation of invariants

*the local view
of a global computation
as seen by a process*

global and local views

A global state (s, h, A)
in which processes own
 $(h_1, A_1), \dots, (h_n, A_n)$
and resource invariants
hold separately, in h'

$$\begin{aligned} A &= A_1 \cup \dots \cup A_n \\ h &= h_1 \cup \dots \cup h_n \cup h' \\ (s, h') &\models \text{inv}(\Gamma \setminus A) \end{aligned}$$



local states
 $(s \setminus \text{owned}(\Gamma \setminus A_1), h_1, A_1),$
 $\dots$
 $(s \setminus \text{owned}(\Gamma \setminus A_n), h_n, A_n)$

Local transitions

READ

$$(s, h, A) \xrightarrow[\Gamma]{i=v} (s, h, A) \quad \text{if } (i, v) \in s$$

$$(s, h, A) \xrightarrow[\Gamma]{i=v} \mathbf{abort} \quad \text{if } i \notin \text{dom}(s)$$

WRITE

$$(s, h, A) \xrightarrow[\Gamma]{i:=v} ([s|i:v], h, A) \\ \text{if } i \in \text{dom}(s) - \text{free}(\Gamma \setminus A)$$

$$(s, h, A) \xrightarrow[\Gamma]{i:=v} \mathbf{abort} \\ \text{if } i \notin \text{dom}(s) \text{ or } i \in \text{free}(\Gamma \setminus A)$$

Local transitions

LOOKUP

$$(s, h, A) \xrightarrow[\Gamma]{[l]=v} (s, h, A) \quad \text{if } (l, v) \in h$$

$$(s, h, A) \xrightarrow[\Gamma]{[l]=v} \mathbf{abort} \quad \text{if } l \notin \text{dom}(h)$$

UPDATE

$$(s, h, A) \xrightarrow{[l]:=v} (s, [h|l:v], A) \quad \text{if } l \in \text{dom}(h)$$

$$(s, h, A) \xrightarrow[\Gamma]{[l]:=v} \mathbf{abort} \quad \text{if } l \notin \text{dom}(h)$$

Local transitions

ALLOCATE

$$\begin{array}{c} \text{alloc}(l, [v_0, \dots, v_n]) \\ (s, h, A) \xrightarrow{\Gamma} (s, h', A) \\ \text{if } \{l, l+1, \dots, l+n\} \cap \text{dom}(h) = \emptyset \\ \text{and } h' = [h \mid l:v_0, \dots, l+n:v_n] \end{array}$$

DISPOSE

$$(s, h, A) \xrightarrow{\text{disp}(l)} (s, h \setminus l, A) \quad \text{if } l \in \text{dom}(h)$$

$$(s, h, A) \xrightarrow{\text{disp}(l)} \mathbf{abort} \quad \text{if } l \notin \text{dom}(h)$$

Local transitions

non-deterministic!

ACQUIRE

$$\begin{array}{l} \text{acq}(r) \\ (s, h, A) \xrightarrow{\Gamma, r(X):R} (s \cup s', h \cup h', A \cup \{r\}) \\ \text{if } r \notin A, \text{ dom}(s')=X, h \perp h', (s \cup s', h') \models R \end{array}$$

*process assumes that
environment preserves invariants*

*and claims ownership of
variables protected by r
+ heap satisfying the invariant*

Local transitions

RELEASE

R precise... so at most one h'

$$(s, h, A) \xrightarrow[\Gamma, r(X):R]{rel(r)} (s \setminus X, h - h', A - \{r\})$$

if $r \in A, h' \subseteq h, (s, h') \models R$

$$(s, h, A) \xrightarrow[\Gamma, r(X):R]{rel(r)} \text{abort}$$

if $r \in A, \forall h' \subseteq h. (s, h') \models \neg R$

*process guarantees to preserve invariants
and cedes ownership of
variables protected by r
+ heap satisfying invariant*

Local transitions

IDLE

$$(s, h, A) \xrightarrow[\Gamma]{\delta} (s, h, A)$$

ERROR

$$(s, h, A) \xrightarrow[\Gamma]{abort} \mathbf{abort}$$

$$\mathbf{abort} \xrightarrow[\Gamma]{\lambda} \mathbf{abort}$$

Local computation

$$\sigma \xrightarrow[\Gamma]{\lambda_1 \dots \lambda_n} \sigma'$$

means

$$\sigma \xrightarrow[\Gamma]{\lambda_1} \dots \xrightarrow[\Gamma]{\lambda_n} \sigma'$$

$$\sigma \xrightarrow[\Gamma]{\lambda_1 \dots \lambda_n} \text{abort}$$

means

$$\sigma \xrightarrow[\Gamma]{\lambda_1} \dots \xrightarrow[\Gamma]{\lambda_n} \text{abort}$$

Example

A local computation of PUT using Γ

$\Gamma :: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge z \mapsto -)$

$$\begin{aligned} ([x:v_0], [v_0:v], \emptyset) &\xrightarrow[\Gamma]{\text{acq}(\text{buf})} ([x:v_0, \text{full}:0, z:v_1], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\beta} ([x:v_0, \text{full}:1, z:v_0], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\text{rel}(\text{buf})} ([x:v_0], [], \emptyset) \end{aligned}$$

where

$\beta : \text{full}=0 \ x=v_0 \ z:=v_0 \ \text{full}:=1$

Example

A local computation of GET using Γ

$\Gamma:: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge z \mapsto -)$

$$\begin{aligned} ([y:v_2], [], \emptyset) &\xrightarrow[\Gamma]{\text{acq}(\text{buf})} ([y:v_2, \text{full}:1, z:v_0], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\gamma} ([y:v_0, \text{full}:0, z:v_0], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\text{rel}(\text{buf})} ([y:v_0], [v_0:v], \emptyset) \end{aligned}$$

where

$\gamma : \text{full}=1 \ z=v_0 \ y:=v_0 \ \text{full}:=0$

Example

A local computation of PUT using Γ'

$\Gamma':: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge \text{emp})$

$$\begin{aligned} ([x:v_0], [v_0:v], \emptyset) &\xrightarrow[\Gamma']{\text{acq}(\text{buf})} ([x:v_0, \text{full}:0, z:v_1], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma']{\beta} ([x:v_0, \text{full}:1, z:v_0], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma']{\text{rel}(\text{buf})} ([x:v_0], [v_0:v], \emptyset) \end{aligned}$$

where

$\beta : \text{full}=0 \ x=v_0 \ z:=v_0 \ \text{full}:=1$

GET

A local computation of GET using Γ'

$\Gamma':: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge \text{emp})$

$$\begin{aligned} ([y:v_2], [], \emptyset) &\xrightarrow[\Gamma']{\text{acq}(\text{buf})} ([y:v_2, \text{full}:1, z:v_0], [], \{\text{buf}\}) \\ &\xrightarrow[\Gamma']{\gamma} ([y:v_0, \text{full}:0, z:v_0], [], \{\text{buf}\}) \\ &\xrightarrow[\Gamma']{\text{rel}(\text{buf})} ([y:v_0], [], \emptyset) \end{aligned}$$

where

$\gamma : \text{full}=1 \ z=v_0 \ y:=v_0 \ \text{full}:=0$

Local computations

- Execution in an environment that respects protection rules and maintains invariants
- Abort if process breaks protection rules or fails to guarantee invariant

*A formalization of
dynamic ownership transfer*

Validity

DEFINITION

$\Gamma \vdash \{p\}c\{q\}$ is *valid*
iff

$\forall \alpha \in \llbracket c \rrbracket. \forall \sigma: \text{dom}(\sigma) \supseteq \text{free}(c, \Gamma) \text{-owned}(\Gamma).$

$\sigma \models p \ \& \ \sigma \xrightarrow[\Gamma]{\alpha} \sigma' \text{ implies } \sigma' \models q$

$\sigma' \neq \text{abort}$

*A formal definition
matching the intuition given earlier*

Examples

$\Gamma :: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge z \mapsto -)$

$\Gamma \vdash \{x \mapsto -\} \text{PUT}\{\text{emp}\}$

$\Gamma \vdash \{\text{emp}\} \text{GET}\{y \mapsto -\}$

valid

$\Gamma' :: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge \text{emp})$

$\Gamma' \vdash \{x \mapsto -\} \text{PUT}\{x \mapsto -\}$

$\Gamma' \vdash \{\text{emp}\} \text{GET}\{\text{emp}\}$

valid

$$\Gamma \vdash \{x \mapsto -\} \text{PUT}\{\text{emp}\}$$

$$\Gamma :: \text{buf}(z, \text{full}): (\text{full}=0 \wedge \text{emp}) \vee (\text{full}=1 \wedge z \mapsto -)$$

$x \mapsto -$

$$\begin{aligned} ([x:v_0], [v_0:v], \emptyset) &\xrightarrow[\Gamma]{\text{acq}(\text{buf})} ([x:v_0, \text{full}:0, z:v_1], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\beta} ([x:v_0, \text{full}:1, z:v_0], [v_0:v], \{\text{buf}\}) \\ &\xrightarrow[\Gamma]{\text{rel}(\text{buf})} ([x:v_0], [], \emptyset) \end{aligned}$$

emp

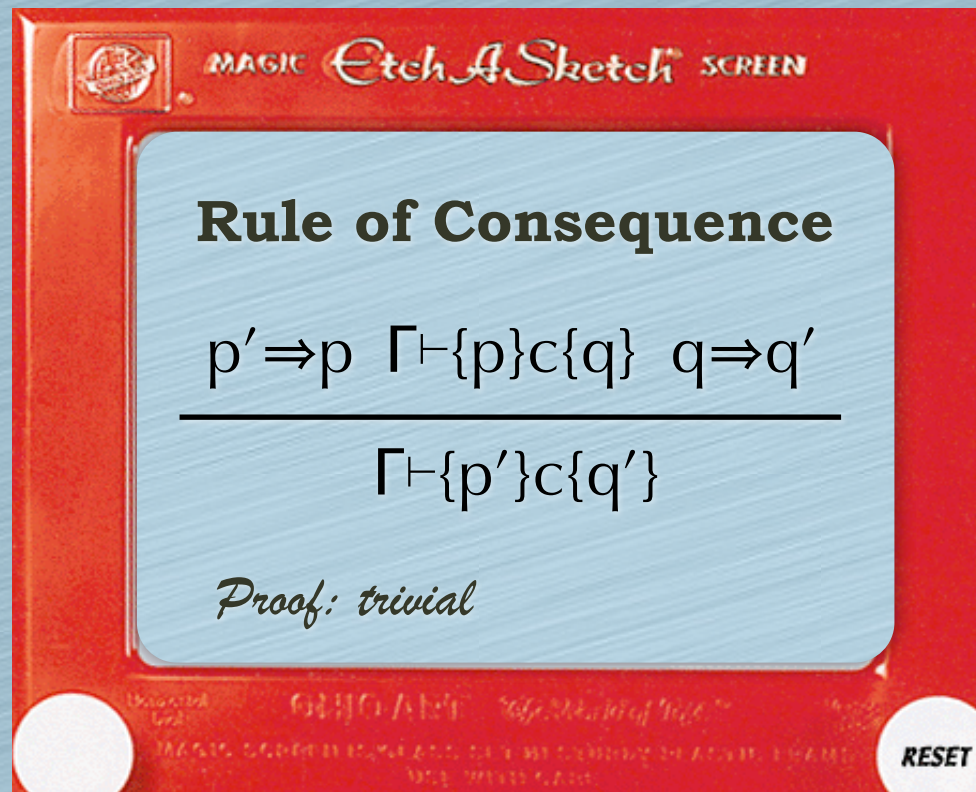
Soundness Theorem

- Concurrent separation logic is sound
 - every provable formula is valid

Proof:
Each inference rule
preserves validity
when its side conditions hold

Proof sketch

- We consider the rules for Parallel, Region, Local Resource, Frame
- Other rules are similar



Parallel rule

$\Gamma \vdash \{p_1\}c_1\{q_1\}$ valid

$\Gamma \vdash \{p_2\}c_2\{q_2\}$ valid

$\text{free}(p_1, q_1) \cap \text{writes}(c_2) = \emptyset$

$\text{free}(p_2, q_2) \cap \text{writes}(c_1) = \emptyset$

$\text{free}(c_1) \cap \text{writes}(c_2) \subseteq \text{owned}(\Gamma)$

$\text{free}(c_2) \cap \text{writes}(c_1) \subseteq \text{owned}(\Gamma)$

1

2

3



PARALLEL DECOMPOSITION Lemma

$\Gamma \vdash \{p_1 * p_2\}c_1 || c_2\{q_1 * q_2\}$
valid

Parallel Decomposition Lemma

Suppose

$\text{free}(\alpha_1) \cap \text{writes}(\alpha_2) \subseteq \text{owned}(\Gamma)$

$\text{free}(\alpha_2) \cap \text{writes}(\alpha_1) \subseteq \text{owned}(\Gamma)$

$\alpha \in \alpha_1 || \alpha_2, h = h_1 \cup h_2, h_1 \perp h_2$

3

If

$(s, h) \xrightarrow[\Gamma]{\alpha} \text{abort}$

then

$(s \setminus \text{writes}(\alpha_2), h_1) \xrightarrow[\Gamma]{\alpha_1} \text{abort}$

or

$(s \setminus \text{writes}(\alpha_1), h_2) \xrightarrow[\Gamma]{\alpha_2} \text{abort}$

If

$(s, h) \xrightarrow[\Gamma]{\alpha} (s', h')$

$(s \setminus \text{writes}(\alpha_2), h_1) \xrightarrow[\Gamma]{\alpha_1} (s_1', h_1')$

$(s \setminus \text{writes}(\alpha_1), h_2) \xrightarrow[\Gamma]{\alpha_2} (s_2', h_2')$

then

$h' = h_1' \cup h_2', h_1' \perp h_2'$

$s_1' = s' \setminus \text{writes}(\alpha_2)$

$s_2' = s' \setminus \text{writes}(\alpha_1)$

Soundness of Par

- Suppose $(s, h) \models p_1 \star p_2$, $(s, h) \xrightarrow[\Gamma]{\alpha} \sigma'$
- Choose $h_1 \perp h_2$ so that $h = h_1 \cup h_2$, $(s, h_1) \models p_1$, $(s, h_2) \models p_2$
- Then $(s \setminus \text{writes}(\alpha_2), h_1) \models p_1$, $(s \setminus \text{writes}(\alpha_1), h_2) \models p_2$ by ②
- By Decomposition Lemma, ①, ③,
$$\sigma' = (s', h') \quad h' = h_1' \cup h_2' \quad h_1' \perp h_2'$$
$$(s \setminus \text{writes}(\alpha_2), h_1) \xrightarrow[\Gamma]{\alpha_1} (s' \setminus \text{writes}(\alpha_2), h_1') \models q_1$$
$$(s \setminus \text{writes}(\alpha_1), h_2) \xrightarrow[\Gamma]{\alpha_2} (s' \setminus \text{writes}(\alpha_1), h_2') \models q_2$$
- Hence $(s', h_1') \models q_1$ and $(s', h_2') \models q_2$ by ②
- So $\sigma' \models q_1 \star q_2$ as required

Region rule

$\Gamma \vdash \{(p * R) \wedge b\} c \{q * R\}$ valid
 $\text{free}(p, q) \cap X = \emptyset$
 R precise



REGION LEMMA

$\Gamma, r(X):R \vdash \{p\} \text{with } r \text{ when } b \text{ do } c \{q\}$
valid

Soundness of region rule

$\llbracket \text{with } r \text{ when } b \text{ do } c \rrbracket = \text{acq}(r) \llbracket b \rrbracket_{\text{true}} \llbracket c \rrbracket \text{rel}(r) \dots$

• Let $(s, h) \models p$, $\beta \in \llbracket b \rrbracket_{\text{true}}$, $\gamma \in \llbracket c \rrbracket$

• If $(s, h) \xrightarrow[\Gamma, r(X):R]{\text{acq}(r) \ \beta \gamma \ \text{rel}(r)} \sigma'$

there are (s_0, h_0) , (s'_0, h'_0) , $h' \perp h'_0$ such that

$(s, h) \xrightarrow[\Gamma, r(X):R]{\text{acq}(r)} (s \cup s_0, h \cup h_0) \models (p \star R) \wedge b$

$\xrightarrow[\Gamma, r(X):R]{\beta \gamma} (s' \cup s'_0, h' \cup h'_0) \models q \star R$

$\xrightarrow[\Gamma, r(X):R]{\text{rel}(r)} (s', h') = \sigma' \models q$

as required

*precision
is crucial!*

Resource rule

$$\Gamma, r(X):R \vdash \{p\}c\{q\}$$

valid



RESOURCE LEMMA

$$\Gamma \vdash \{p*R\}\mathbf{resource\ } r \text{ in } c\{q*R\}$$

valid

Soundness of resource rule

$$\llbracket \text{resource } r \text{ in } c \rrbracket = \{\beta \setminus r \mid \beta \in \llbracket c \rrbracket_r\}$$

• Let $(s, h) \models p \star R$, $\beta \in \llbracket c \rrbracket_r$, $(s, h) \xrightarrow[\Gamma]{\beta \setminus r} \sigma'$

• Choose $h_1 \perp h_2$ such that

$$(s, h_1) \models p, \quad (s, h_2) \models R, \quad h = h_1 \cup h_2$$

• Then there must be $h_1' \perp h_2'$ such that

$$(s, h_1) \xrightarrow[\Gamma, r(X):R]{\beta} (s', h_1') \quad \sigma' = (s', h_1' \cup h_2')$$

$$(s', h_1') \models q \quad (s', h_2') \models R$$

• Hence $\sigma' \models q \star R$ as required

Frame rule

$\Gamma \vdash \{p\}c\{q\}$ valid

$\text{free}(l) \cap \text{writes}(c) = \emptyset$

$\text{free}(l) \cap \text{owned}(\Gamma) = \emptyset$



FRAME LEMMA

$\Gamma \vdash \{p \star l\}c\{q \star l\}$ valid

Frame Lemma

Suppose
 $h = h_1 \cup h_2, h_1 \perp h_2$

If
 $(s, h) \xrightarrow[\Gamma]{\alpha} \text{abort}$
then
 $(s, h_1) \xrightarrow[\Gamma]{\alpha} \text{abort}$

If
 $(s, h) \xrightarrow[\Gamma]{\alpha} (s', h')$
 $(s, h_1) \xrightarrow[\Gamma]{\alpha} (s_1', h_1')$
then
 $s_1' = s' \quad h_1' \perp h_2$
 $h' = h_1' \cup h_2$

Soundness of Frame rule

- Let $\alpha \in \llbracket c \rrbracket$, $(s, h) \models p \star I$, $(s, h) \xrightarrow[\Gamma]{\alpha} \sigma'$
- Choose $h_1 \perp h_2$ so that $h = h_1 \cup h_2$ and
 $(s, h_1) \models p$, $(s, h_2) \models I$
- Since $\Gamma \vdash \{p\}c\{q\}$ is valid, there are s' , h_1' such that $(s, h_1) \xrightarrow[\Gamma]{\alpha} (s', h_1') \models q$
- By Frame Lemma $h_1' \perp h_2$ $\sigma' = (s', h_1' \cup h_2')$
- Since $\text{free}(p) \cap \text{writes}(\alpha) = \emptyset$, $(s', h_2) \models I$
- Hence $\sigma' \models q \star I$ as required

And so on...

- For each inference rule,
a similar proof case

Summary:
every provable formula is valid

Validity, revisited

- We defined validity in terms of *local* states and *local* computation
- Need to connect with *global* notions
 - independent of the logic
 - related to standard operational semantics
 - show that provable programs are guaranteed to be race-free

Global/local lemma

Suppose $h=h_1 \cup h_2$, $h_1 \perp h_2$, $(s, h_2) \models \text{inv}(\Gamma)$

If $(s, h) \xRightarrow{\alpha} \text{abort}$

then $(s \setminus \text{owned}(\Gamma), h_1) \xrightarrow[\Gamma]{\alpha} \text{abort}$

If $(s, h) \xRightarrow{\alpha} (s', h')$

and $\neg (s \setminus \text{owned}(\Gamma), h_1) \xrightarrow[\Gamma]{\alpha} \text{abort}$

then there are $h_1' \perp h_2'$ such that

$(s \setminus \text{owned}(\Gamma), h_1) \xrightarrow[\Gamma]{\alpha} (s' \setminus \text{owned}(\Gamma), h_1')$

$h' = h_1' \cup h_2'$, $(s', h_2') \models \text{inv}(\Gamma)$

Corollary

If $\Gamma \vdash \{p\}c\{q\}$ is valid,

$\forall \alpha \in \llbracket c \rrbracket.$

$\forall \sigma: \text{dom}(\sigma) \supseteq \text{free}(c). \forall \sigma'.$

$\sigma \models p \star \text{inv}(\Gamma) \ \& \ \sigma \xRightarrow{\alpha} \sigma'$

implies

$\sigma' \models q \star \text{inv}(\Gamma)$

*provable
implies
race-free*



*When you gather all
your resources together,
goals are accomplished*

Precision is crucial

Region rule is unsound
with imprecise invariants

valid

$$\frac{\vdash\{(\text{emp} \vee x \mapsto _) \star \text{true}\} \text{ skip } \{\text{emp} \star \text{true}\}}{r:\text{true} \vdash\{\text{emp} \vee x \mapsto _ \} \text{ with } r \text{ do skip } \{\text{emp}\}}$$

invalid

(Example due to John Reynolds)