

Lecture 8: Sparsest Cut and the Cheeger bound

①

Recall: sparsity of SSV $\phi(S) = \frac{\text{cap}(S, \bar{S})}{|S||\bar{S}|} = \frac{|E(S, \bar{S})|}{|S||\bar{S}|}$ if capacities = 1 for simplicity. (today).

want sparsest cut S^* st minimizes $\phi(S)$.

Imp. For today: focus on capacities = 1 and regular graphs (all vertices have degree = d)

one way to write sparsity is (very similar to max-cut lecture)

$$\min_{x \in \{-1, 1\}^n} \frac{\sum_{(i,j) \in E} (x_i - x_j)^2}{\sum_{i,j \in V} (x_i - x_j)^2} = 2 \frac{\sum_{i,j \in E} (x_i - x_j)^2}{\sum_{i,j \in V} (x_i - x_j)^2}$$

$i, j \in V \leftarrow$ ordered pair $i, j \in V \leftarrow$ unordered pair

suppose we relax this to be all $x \in \mathbb{R}^n$, then value can only fall. Now,

if $x \in \mathbb{R}^n$ then ① shift so that $x \perp \mathbb{1}$ (ie. $\sum x_i = 0$). Since both num. & den. are differences, does not change. then

② Observe that $\sum_{i,j \in V} (x_i - x_j)^2 = \sum_{i \in V} x_i^2 (2n) - \underbrace{\left(\sum_{i \in V} x_i \right) \left(\sum_{j \in V} x_j \right)}_{= 0}$

$$= \left(\sum_{i \in V} x_i^2 \right) (2n)$$

\Rightarrow relaxation = $\min_{x \perp \mathbb{1}} \left(\frac{2 \sum_{(i,j) \in E} (x_i - x_j)^2}{\sum_{i \in V} x_i^2} \right)^{\frac{1}{2}} \leq \phi(G)$.

$= \min_{x \perp \mathbb{1}} \frac{x^T L_G x}{x^T x} \cdot \frac{1}{(2n)}$ where $L_G = \text{Laplacian matrix of a graph} = dI - \text{Adjacency}$ for d-regular graphs.

Interestingly, $\mathbb{1}$ is the top eigenvector of L_G , so this is the second eigenvalue

this means we get that $\phi(S) \geq \lambda_2(L_G) \cdot \frac{1}{2n}$.

The Cheeger inequality bounds $\phi(S)$ above by a function of λ_2 as well, giving a good characterization of $\phi(S)$ for some families of graphs (esp. expanders).
(But it can be poor for other families as we will soon see).



N.b.: there are many variants of sparsity.

- sparsity,
- edge expansion \cong $\frac{1}{n}(\text{sparsity}) \times n$.
- conductance = $\frac{|E(S, \bar{S})|}{\min(\sum_{v \in S} \text{degree}(v), \sum_{v \in \bar{S}} \text{degree}(v))}$ etc.

And for irregular graphs we may need to look at the normalized Laplacian which is $I - D^{-1/2} A D^{-1/2}$.

There are connections, ~~and~~ but when you look up "Cheeger" you should make sure the version you have is relating the quantities you have in hand. Else you may need to do translations.



Today: Cheeger bounds, for d-regular graphs

$$\frac{\lambda_2(L_G)}{2n} \leq \phi(S) \leq \frac{\sqrt{\lambda_2(L_G)} \cdot d}{\theta(n)}$$

Already saw the lower bound, see the upper bound soon!

(Also \exists graphs where ~~the~~ bounds are tight.)

Upper bound (Algorithmic)

Find an eigenvector corresponding to λ_2 . Call it $x \in \mathbb{R}^n$

Sort ~~vectors~~ vectors so that $x_1 \leq x_2 \leq x_3 \dots \leq x_n$.

Let $S_i = \{1, 2, \dots, i\}$ in this order.

Output the set S_i with smallest sparsity $\phi(S_i)$.

Notation: $R(x) = \frac{\sum_{i \in E} (x_i - x_j)^2}{\sum_i x_i^2} = \frac{x^T L_G x}{x^T x}$ (Rayleigh quotient)

Proof in 2 lemmas.

First take $x \rightarrow$ break into its positive and negative parts (almost).

get vectors y and z .

Lemma 1: Given x , get y, z st both non-negative and $R(y), R(z) \leq \frac{1}{2} R(x)$.
and have disjoint supports.

Say y has $\leq n/2$ sized support (disjointness \Rightarrow at least one of y, z does.)

Lemma 2: For non-negative vector x , $\exists S \subseteq \text{support}(x)$ st. $\phi(S) \leq \sqrt{\dots}$ (obtained from Lemma 1)

$$\phi(S) \leq \sqrt{\dots}$$

(Moreover this set will be one of the sets considered in our algo above)

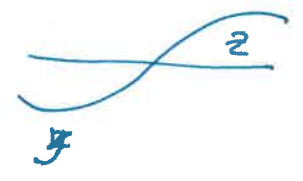
Lemma 1:

Try #1: $y = \max(x, 0)$ component wise max
 $z = -\min(x, 0)$ — " — min

$x = (-0.7, -0.3, 0, 0.5, 1.2)$
 $y = (0, 0, 0, 0.5, 1.2)$
 $z = (0.7, 0.3, 0, 0, 0)$

then ~~then~~

(*) $\sum (y_i - y_j)^2, \sum (z_i - z_j)^2 \leq \sum (x_i - x_j)^2$



if only $\sum z_i^2, \sum y_i^2 \geq \Omega(1)$, but maybe not?

eg. $x = (1, \frac{1}{n-1}, \frac{1}{n-1}, \dots, \frac{1}{n-1})$ so $x \perp 1$
 but $\|z\| = \frac{1}{\sqrt{n}}$ ☹️

~~So shift~~ So shift x . Sps $\|z\|^2 < \frac{1}{4}$ (and $\|y\|^2 \geq \frac{3}{4}$)

Try #2: $x' = x - \frac{1}{2\sqrt{n}}$ $y' = \max(x', 0)$
 $z' = -\min(x', 0)$

"moves mass to help z"

(*) still holds for y', z'

but now. $\|x'\|^2 = \|x\|^2 + \|\frac{1}{2\sqrt{n}}1\|^2 = \|x\|^2 + \frac{1}{4} = \frac{5}{4}$
 \uparrow
 $x \perp 1$ (Pythagoras)

$\cdot \|y'\|^2 \leq \|x\|^2 \leq 1 \Rightarrow \|z'\|^2 = \frac{5}{4} - \|y'\|^2 \geq \frac{1}{4}$
 \uparrow because negative shift $\uparrow y' \perp z'$

$\cdot \frac{3}{4} \leq \|y\|^2 = \sum_i y_i^2 \leq \sum_i (y'_i + \frac{1}{2\sqrt{n}})^2 \leq 2(\sum_i (y_i'^2 + \frac{1}{4n})) = 2\|y'\|^2 + \frac{1}{2}$
 $\Rightarrow \|y'\|^2 \geq \frac{1}{8}$



So $x \rightarrow y', z'$ disjoint supports
 and $R(y'), R(z') \geq BR(x)$.

Also, note that all we've done is shifted and truncated x , so level sets in y, z are both level sets in x .

Now focus on y say. (where $\text{supp}(y) \leq n/2$).

Lemma 2: \exists level set in support of y st.

Remember: $y \geq 0$
 $\text{supp}(y) \leq n/2$

$$\phi(S) \leq \sqrt{\frac{2d R(y)}{n}}$$

Pf: Suppose $y_i \in [0, 1]$ for all i (scaling does not change $R(y)$).

Choose α uniformly in $[0, 1]$.

$$S_\alpha := \{i \mid y_i^2 \geq \alpha\} \quad \text{random set.}$$

$$\mathbb{E}[|E(S_\alpha, \bar{S}_\alpha)|] = \sum_{(i,j) \in E} \mathbb{P}_\alpha[\text{one of } y_i^2, y_j^2 < \alpha, \text{ other } \geq \alpha]$$

$$= \sum_{i,j \in E} |y_i^2 - y_j^2| = \sum_{i,j \in E} |(y_i - y_j)(y_i + y_j)|$$

$$\text{(Cauchy Schwarz)} \leq \sqrt{\sum_{i,j \in E} (y_i - y_j)^2} \cdot \sqrt{\sum_{i,j \in E} (y_i + y_j)^2} \leq 2(y_i^2 + y_j^2)$$

$$\leq \sqrt{\sum_{i,j \in E} (y_i - y_j)^2} \cdot \sqrt{2d \sum_i y_i^2}$$

because graph is d-regular

$$= \sqrt{2d \cdot R(y)} \cdot \left(\sum_i y_i^2\right)^{1/2}$$

$$\text{because } R(y) = \frac{\sum_{i,j \in E} (y_i - y_j)^2}{\sum_i y_i^2}$$

$$\mathbb{E}[|S_\alpha|] = \sum_i \mathbb{P}_\alpha[y_i^2 > \alpha] = \sum_i y_i^2 \quad \text{equal}$$

$$\Rightarrow \mathbb{E}[|E(S_\alpha, \bar{S}_\alpha)| - \sqrt{2d R(y)} \cdot |S_\alpha|] \leq 0$$

⇒ by the probabilistic method, ∃α ∈ [0, 1] st.

$$\frac{|E(S_\alpha, \bar{S}_\alpha)|}{|S_\alpha|} \leq \sqrt{2dR(y)}$$

and so

$$\frac{|E(S_\alpha, \bar{S}_\alpha)|}{|S_\alpha||\bar{S}_\alpha|} \leq \frac{|E(S_\alpha, \bar{S}_\alpha)|}{|S_\alpha| \cdot \eta/2} \leq \frac{2}{\eta} \cdot \sqrt{2dR(y)}$$

since $|S_\alpha| \leq \eta/2$
⇒ $|\bar{S}_\alpha| \geq \eta/2$
from above.

So the best level set has at most this sparsity
———— x ————

Finishes proof of Lem 2
⇒ of Cheeger!

To recap: Cheeger says

$$\Omega\left(\frac{\lambda_2}{n}\right) \leq \phi(S) \leq O\left(\frac{\sqrt{\lambda_2 d}}{n}\right)$$

~~the fact~~ So when $d = \text{constant}$, $\lambda_2 = O(1)$ then correct up to constants.

we have a way to certify a constant degree expander.

In general $\lambda_2 \in [0, d]$ so when $\lambda_2 = \Omega(d)$ we're pretty tight!

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spectral definition of expander.

Tightness of bounds:

Hypercube $\{0, 1\}^d$: $n = 2^d$

• $\phi(G) = \text{sparsity of cut } (\{x_i = 0\}, \{x_i = 1\}) = \frac{2^{d-1}}{2^d \cdot 2^{d-1}} = \frac{2}{n}$

• $\lambda_2(G) = 2$

so the lower bound of Cheeger is tight here.

Path or Cycle:

• $\phi(G) = \phi(\text{any balanced cut}) = \frac{\Theta(1)}{n^2}$

• $\lambda_2(G) = \Theta(n^2)$ so $\sqrt{\frac{\lambda_2 \cdot d}{n}} = \Theta\left(\frac{1}{n^2}\right)$

_____ x _____

- Can generalize to non-regular graphs, but there ~~is~~ it is convenient to use "conductance".

$$\text{vol}(S) = \sum_{i \in S} \text{degree}(i) / 2m = \text{"fraction of edges hitting } S \text{"}$$

$$\text{conductance}(G) = \min_{S: \text{vol}(S) \leq 1/2} \frac{|E(S, \bar{S})|}{\text{vol}(S)}$$

And then $\mathcal{L}(G) = I - D^{-1/2} A D^{-1/2}$ is normalized Laplacian

and Cheeger says

(*)

$$\Theta(\lambda_2) \leq \text{conductance} \leq \Theta(\sqrt{\lambda_2})$$

λ₂ of Normalized Laplacian

Sanity Check:

for d-regular graphs, $\text{conductance}(S) = \frac{|E(S, \bar{S})|}{\text{vol}(S)} = \frac{|E(S, \bar{S})|}{d \cdot |S|} \cong \frac{n}{d} \cdot \phi(S)$

so and $\mathcal{L}(G) = \frac{1}{d} \cdot L_G$ so $\lambda_2(\mathcal{L}) = \frac{1}{d} \lambda_2(L_G)$

→ (*) says $\Theta\left(\frac{\lambda_2(L_G)}{d}\right) \leq \frac{n}{d} \phi(S) \leq \Theta\left(\sqrt{\frac{\lambda_2(L_G)}{d}}\right)$ which is what we proved!

$\lambda_2(L_G)$ as a notion of connectivity

Recall: if Graph has k connected components, then

$$\lambda_1(L_G) = \lambda_2 = \dots = \lambda_k = 0.$$

So $\lambda_2 = 0$ means graph is disconnected.

- λ_2 "close to 0" means graph has a sparse cut (by Cheeger).
- λ_2 "far from 0" means ~~no~~ sparse cuts (by other side of Cheeger).

• A graph is a "spectral expander" if

$$\lambda_2(L_G) \geq \Omega(d).$$

So there's a huge 'spectral gap'

$$\lambda = 0 \quad \longleftrightarrow \quad \lambda_2 = \Omega(d).$$

$$\dots \lambda_n \leq \Theta(d)$$

————— x —————

Algorithmic Aspects of Cheeger

Upper bound proof Algorithmic.

In fact shows that best level cut has sparsity $\leq \sqrt{\frac{\Theta(d)}{n} R(x)}$

- So we don't really need to find the exact 2nd eigenvalue, as long as we find x with small Rayleigh coefficient, we're good.

• Commonly used in vision applications (this 2nd ev called Fiedler vector)

• Results of Kwok et al: spectral partitioning good even when k large for some later λ_k . $\phi(S) \leq O(k \cdot \lambda_2 / \sqrt{\lambda_k}) \cdot 1/n$. See Lap Chi's notes.

Takeaways:

- Cheeger shows that $\lambda_2(L_G)$ is a good approx to $\phi(G)$ when the expansion of G is large.
- Leighton Rao shows that the LP integrality gaps arise in exactly these expander-like examples.

(Q1) Can we combine the two techniques?

Using SDPs (which capture spectral ideas + ~~LPs~~ LPs)?
(Yes)

(Q2) This idea of using the λ_2 to get an algorithm for sparsest cut is cool.

Can we use eigenvector based methods for Max-Cut too?
(Yes)

~~Fig~~

More on these in the next Lectures.

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