

Lecture #3: Hardness for Max-Coverage

①

We prove that $1-\text{vs-}(\frac{3}{4}+\epsilon)$ decision problem for Max Coverage is NP-hard.

i.e. An algo for \uparrow that runs in polytime $\Rightarrow P=NP$.

Build on a theory of hardness of approximations

Cook-Levin ~~theorem~~ theorem says $1-\text{vs-}(1-\frac{1}{m})$ decision problem for ^{Max-}3SAT is NP-hard

PCP theorem says $1-\text{vs-}(1-\epsilon)$ " " for Max3SAT for some $\epsilon > 0$

Raz's Parallel Repetition Thm says $1-\text{vs-}\eta$ " " for Max-Label-Cover for every constant $\eta > 0$.

This is where we catch the story.

Max-Label-Cover: Bipartite graph $G=(U, V, E)$

~~Labels~~ Keys K for vertices in U , Labels L for vertices in V .

Each edge has a "projection" function $\pi_{uv}: L \rightarrow K$. (π_{uv})

Objective: assign keys to U , labels to V . i.e. $f: U \rightarrow K$
 $V \rightarrow L$

s.t. $\#\{(u, v) \mid f(u) = \pi_{uv}(f(v))\}$ is maximized.

Thm: $\forall \eta > 0, \exists q = \text{poly}(1/\eta)$ s.t. the $1-\text{vs-}\eta$ decision problem for Max Label Cover ~~is~~ is NP-hard with $|K|, |L| \leq q$.

Moreover: $|U|=|V|$ for these instances, and bipartite graph is regular.

Reduction:

(2)

Take instances of MaxLC $G \longrightarrow$ instances H of MaxCoverage sat.

Completeness

$$\text{val}(G) = 1 \implies \text{val}(H) = 1$$

Soundness

$$\text{val}(G) < \gamma \implies \text{val}(H) < \frac{\gamma}{4} + \epsilon \quad \epsilon = \epsilon(\gamma).$$

How?

① Elements: Q_{uv} cube for each edge.

$$Q_{uv} = \{0, 1\}^k.$$

$$\implies |E| \cdot 2^k \text{ nodes.}$$

$$k = |K| = \# \text{ keys.}$$

$$< |L|.$$

② Sets: for each $u \in U, \forall a \in K,$

$$S_{u,a} = \bigcup_{v \sim u} \{x \in Q_{uv} \mid x_a = 0\}.$$

"left half of cubes along the a^{th} dimension".

$$S_{v,a} = \bigcup_{u \sim v} \{x \in Q_{uv} \mid x_{\pi(u)} = 1\}$$

$$\implies k \cdot |U| + \ell \cdot |V| = d(\gamma) (|U| + |V|) \text{ sets.}$$

③ Target $T = |U| + |V| = 2|U|$

(\implies is exact cover)

Note: Completeness! If G satisfiable $\implies H$ has coverage solⁿ of value 1.

Pf: sps. f is labeling that sat's all edges.

then choose $S_{u,f(u)}$ and $S_{v,f(v)}$ sets, one per vertex.

Note: $\forall u,v$ edge $f(u) = \pi_{uv}(f(v))$ so $S_{u,f(u)}$ covers all $x \in Q_{uv}$ with 0 along that dimension

and $S_{v,f(v)}$ covers the other Q_{uv} points.

Q: What about soundness?

Theorem: if $\text{val}(H) \geq \frac{3}{4} + \epsilon$ then $\text{val}(G) > \epsilon^3/2000 := \eta(\epsilon)$

(3)

[Contrapositive of Claimed Soundness]

Main Idea: suppose \mathcal{S}^* is a solution of value $\geq \frac{3}{4} + \epsilon$.

• And assume: \mathcal{S}^* chooses exactly one set per vertex. i.e. both $S_{u,a}$ & $S_{u,b}$ not in \mathcal{S}^* .

then consider the map f s.t. $S_{u,f(u)} \in \mathcal{S}^*$, $S_{v,f(v)} \in \mathcal{S}^*$ for each u, v .

Claim: value of this map $f \geq \Omega(\epsilon)$.

Why? for each unsatisfied edge u, v ,

$S_{u,f(u)}$ and $S_{v,f(v)}$ cover $\frac{3}{4}$ of cube.

So in order to get $\frac{3}{4} + \epsilon$ coverage,

$\Omega(\epsilon)$ fraction of edges must be ~~satisfied~~ satisfied! 😊

$$(p \cdot 1 + (1-p) \cdot \frac{3}{4}) = \frac{3}{4} + \epsilon \Rightarrow p = 4\epsilon$$

But solution could choose multiple sets per vertex (or none at all)

• How to show that \exists good value labeling?

• Hope 1: on average one set chosen per vertex, so maybe not so bad.

• Hope 2: picking many sets per cube (that are not complementary) gives diminishing returns.

Now we make these ideas precise

Recall $S^* =$ ~~the~~ coverage solution of value $\frac{3}{4} + \epsilon$.

$$\text{Suggest}(u) = \{a \in K \mid S_{u,a} \in S^*\} \quad \text{Suggest}(v) = \{\alpha \in L \mid S_{v,\alpha} \in S^*\}.$$

$$\text{Suggest}(u,v) = \text{Suggest}(u) \cup \text{Suggest}(v).$$

Fact: $E_{(u,v)}[|\text{Suggest}(u,v)|] = 2.$

// use fact that bip graph is regular.

Pf: $E_{u,v}[|\text{Suggest}(u,v)|] = E_u[|\text{Suggest}(u)|] + E_v[|\text{Suggest}(v)|] = \frac{1}{|u|} [\sum |\text{Suggest}(u)| + |\text{Suggest}(v)|]$
↑ regularity ↑ $|u|=|v| = \frac{|u|+|v|}{2} = 2.$

Random decoding: pick random element from $\text{Suggest}(u)$ to be $f(u)$
if $\text{Suggest}(u) = \emptyset$, $f(u) =$ arbitrary.

Claim 1: $E_f[\text{Coverage}] \geq \frac{3}{2000}$. $\Rightarrow \exists$ good labeling for G .

Def: (u,v) consistent if $\exists \alpha \in \text{Suggest}(u)$ s.t. $\pi_{uv}(\alpha) = \alpha$
 $\alpha \in \text{Suggest}(v)$

Def: u sparse if $|\text{Suggest}(u)| \leq 19\epsilon$.
 (u,v) sparse if u sparse and v sparse.

Def: (u,v) good if ~~sparse~~ if sparse and consistent.

Claim 2: $\geq \frac{\epsilon}{20}$ ^{fraction of} edges are good.

Pf of Claim 1 (assuming claim 2).

$\frac{\epsilon}{20}$ fraction are good. for each, $f(u), f(v)$ chosen to be such that $\pi_{uv}(f(v)) = f(u)$

w.p. $(\frac{\epsilon}{10}) \cdot (\frac{\epsilon}{10})$.
 \uparrow by sparsity

\Rightarrow total ~~prob~~ of sat. edges $\geq (\frac{\epsilon^3}{2000})$.

To recap:

Hardness of Label Cover says. NP-hard to distinguish between

$val(G) = 1$ vs. $val(G) = \eta$

This reduction says: if we can distinguish $val(H) = 1$ vs $val(H) \geq \frac{3}{4} + \epsilon$ | in polytime

H = Max Coverage instance

\Rightarrow can ~~not~~ distinguish of $val(G) = 1$ vs. $val(G) = \Omega(\epsilon^3)$

\Rightarrow 1-vs- $(\frac{3}{4} + \epsilon)$ decision problem is NP-hard

\Rightarrow cannot approx Max Coverage to better than $\frac{3}{4} = 0.75$

Fancier Reduction gives:

cannot approx Max Coverage to better than $(1 - \frac{1}{e}) \cong 0.63...$

Uses a k-partite version of Label Cover. [Feje 95]

A different extension: - hardness of $\Omega(\log n)$ for Set Cover.

~~can be for this label cover.~~

[Lund-Yannakakis, Feje, Dinur-Steuver]