

## 15-745: Optimizing Compilers for Modern Architectures

### Lecture 1: Introduction

What would you get out of this course?

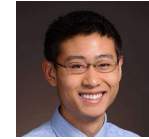
Structure of a Compiler

Optimization Example

## Course Logistics

- Want to get off the waitlist?
  - See me in my office (GHC 7221) after class to discuss
  - This course is not intended to be your first compiler course

- Let Dominic know if can't get on Piazza or Blackboard for this course



- Need to get the book



- Let's run through the course webpage at <http://www.cs.cmu.edu/~15745/>

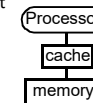
## What Do Compilers Do?

1. Translate one language into another
  - e.g., convert C++ into x86 object code
  - difficult for "natural" languages, but feasible for computer languages
2. Improve (i.e. "optimize") the code
  - e.g., make the code run 3 times faster
    - or more energy efficient, more robust, etc.
  - driving force behind modern processor design

## How Can the Compiler Improve Performance?

**Execution time = Operation count \* Machine cycles per operation**

- **Minimize the number of operations**
  - arithmetic operations, memory accesses
- **Replace expensive operations with simpler ones**
  - e.g., replace 4-cycle multiplication with 1-cycle shift
- **Minimize cache misses**
  - both data and instruction accesses
- **Perform work in parallel**
  - instruction scheduling within a thread
  - parallel execution across multiple threads

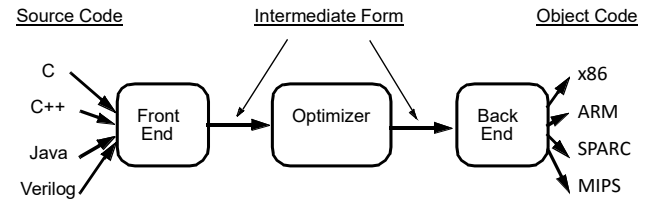


More accurately, machine cycles per operation must account for instruction overlap

## What Would You Get Out of This Course?

- Basic knowledge of existing compiler optimizations
- Hands-on experience in constructing optimizations within a fully functional research compiler
- Basic principles and theory for the development of new optimizations

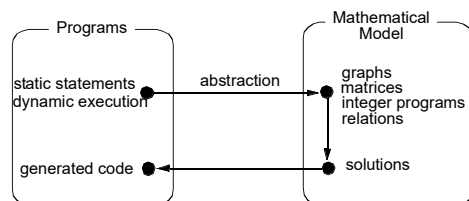
## II. Structure of a Compiler



- Optimizations are performed on an “**intermediate form**”
  - similar to a generic RISC instruction set
- Allows easy **portability** to multiple source languages, target machines

## Ingredients in a Compiler Optimization

- **Formulate optimization problem**
  - Identify opportunities of optimization
    - applicable across many programs
    - affect key parts of the program (loops/recursions)
    - amenable to “efficient enough” algorithm
- **Representation**
  - Must **abstract essential details** relevant to optimization



## Ingredients in a Compiler Optimization

- **Formulate optimization problem**
  - Identify opportunities of optimization
    - applicable across many programs
    - affect key parts of the program (loops/recursions)
    - amenable to “efficient enough” algorithm
- **Representation**
  - Must abstract essential details relevant to optimization
- **Analysis**
  - Detect when it is desirable and safe to apply transformation
- **Code Transformation**
- **Experimental Evaluation (and repeat process)**

## Representation: Instructions

- **Three-address code**  
`A := B op C`
  - LHS: name of variable e.g. `x`, `A[t]` (address of `A` + contents of `t`)
  - RHS: value
- **Typical instructions**  
`A := B op C`  
`A := unaryop B`  
`A := B`  
`GOTO s`  
`IF A relop B GOTO s`  
`CALL f`  
`RETURN`

## III. Optimization Example

- **Bubblesort** program that sorts an array `A` that is allocated in static storage:
  - an element of `A` requires **four bytes** of a byte-addressed machine
  - elements of `A` are numbered **1 through `n`** (`n` is a variable)
  - `A[j]` is in location `&A+4*(j-1)`

```
FOR i := n-1 DOWNTO 1 DO
  FOR j := 1 TO i DO
    IF A[j] > A[j+1] THEN BEGIN
      temp := A[j];
      A[j] := A[j+1];
      A[j+1] := temp
    END
```

## Translated Code

```

i := n-1
S5: if i<1 goto s1
j := 1
s4: if j>i goto s2
t1 := j-1
t2 := 4*t1
t3 := A[t2] ;A[j]
t4 := j+1
t5 := t4-1
t6 := 4*t5
t7 := A[t6] ;A[j+1]
if t3<=t7 goto s3

t8 := j-1
t9 := 4*t8
temp := A[t9] ;A[j]
t10 := j+1
t11 := t10-1
t12 := 4*t11
t13 := A[t12] ;A[j+1]
t14 := j-1
t15 := 4*t14
A[t15] := t13 ;A[j]:=A[j+1]
t16 := j+1
t17 := t16-1
t18 := 4*t17
A[t18]:=temp ;A[j+1]:=temp
s3: j := j+1
goto S4
S2: i := i-1
goto S5
s1:
```

```
FOR i := n-1 DOWNTO 1 DO
  FOR j := 1 TO i DO
    IF A[j] > A[j+1] THEN BEGIN
      temp := A[j];
      A[j] := A[j+1];
      A[j+1] := temp
    END
```

## Representation: a Basic Block

- **Basic block** = a sequence of 3-address statements
  - only the first statement can be reached from outside the block (no branches into middle of block)
  - all the statements are executed consecutively if the first one is (no branches out or halts except perhaps at end of block)
- We require basic blocks to be *maximal*
  - they cannot be made larger without violating the conditions
- Optimizations within a basic block are *local* optimizations

## Flow Graphs

- **Nodes:** basic blocks
- **Edges:**  $B_i \rightarrow B_j$ , iff  $B_j$  can follow  $B_i$  immediately in *some* execution
  - Either first instruction of  $B_j$  is target of a goto at end of  $B_i$
  - Or,  $B_j$  physically follows  $B_i$ , which does not end in an unconditional goto.
- The block led by first statement of the program is the *start*, or *entry* node.

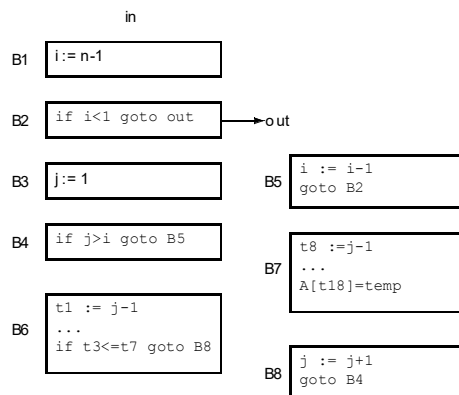
## Find the Basic Blocks

```

i := n-1
S5: if i<1 goto s1
j := 1
s4: if j>i goto s2
t1 := j-1
t2 := 4*t1
t3 := A[t2] ;A[j]
t4 := j+1
t5 := t4-1
t6 := 4*t5
t7 := A[t6] ;A[j+1]
if t3<=t7 goto s3

t8 :=j-1
t9 := 4*t8
temp := A[t9] ;A[j]
t10 := j+1
t11:= t10-1
t12 := 4*t11
t13 := A[t12] ;A[j+1]
t14 := j-1
t15 := 4*t14
A[t15] := t13 ;A[j]:=A[j+1]
t16 := j+1
t17 := t16-1
t18 := 4*t17
A[t18]:=temp ;A[j+1]:=temp
s3: j := j+1
goto s4
S2: i := i-1
goto s5
s1:
    
```

## Basic Blocks from Example



## Sources of Optimizations

- **Algorithm optimization**
- **Algebraic optimization**

$$A := B+0 \quad \Rightarrow \quad A := B$$
- **Local optimizations**
  - within a basic block -- across instructions
- **Global optimizations**
  - within a flow graph -- across basic blocks
- **Interprocedural analysis**
  - within a program -- across procedures (flow graphs)

## Local Optimizations

- Analysis & transformation performed **within a basic block**
- **No control flow information is considered**
- **Examples of local optimizations:**
  - local **common subexpression elimination**  
analysis: same expression evaluated more than once in b.  
transformation: replace with single calculation
  - local **constant folding or elimination**  
analysis: expression can be evaluated at compile time  
transformation: replace by constant, compile-time value
  - **dead code elimination**

## Example

```

i := n-1
S5: if i<1 goto s1
j := 1
S4: if j>i goto s2
t1 := j-1
t2 := 4*t1
t3 := A[t2] ;A[j]
t4 := j+1
t5 := t4-1
t6 := 4*t5
t7 := A[t6] ;A[j+1]
if t3<=t7 goto s3

t8 :=j-1
t9 := 4*t8
temp := A[t9] ;A[j]
t10 := j+1
t11:= t10-1
t12 := 4*t11
t13 := A[t12] ;A[j+1]
t14 := j-1
t15 := 4*t14
A[t15] := t13 ;A[j]:=A[j+1]
t16 := j+1
t17 := t16-1
t18 := 4*t17
A[t18]:=temp ;A[j+1]:=temp
S3: j := j+1
goto S4
S2: i := i-1
goto S5
S1:
  
```

## Example

```

B1: i := n-1
B2: if i<1 goto out
B3: j := 1
B4: if j>i goto B5
B6: t1 := j-1
t2 := 4*t1
t3 := A[t2] ;A[j]
t6 := 4*j
t7 := A[t6] ;A[j+1]
if t3<=t7 goto B8

B7: t8 :=j-1
t9 := 4*t8
temp := A[t9] ;temp:=A[j]
t12 := 4*j
t13 := A[t12] ;A[j+1]
A[t9] := t13 ;A[j]:=A[j+1]
A[t12]:=temp ;A[j+1]:=temp
B8: j := j+1
goto B4
B5: i := i-1
goto B2
out:
  
```

## (Intraprocedural) Global Optimizations

- **Global versions of local optimizations**
  - global common subexpression elimination
  - global constant propagation
  - dead code elimination
- **Loop optimizations**
  - reduce code to be executed in each iteration
  - code motion
  - induction variable elimination
- **Other control structures**
  - Code hoisting: eliminates copies of identical code on parallel paths in a flow graph to reduce code size.

### Example

```
B1: i := n-1
B2: if i<1 goto out
B3: j := 1
B4: if j>i goto B5
B6: t1 := j-1
    t2 := 4*t1
    t3 := A[t2] ;A[j]
    t6 := 4*j
    t7 := A[t6] ;A[j+1]
    if t3<=t7 goto B8
B7: t8 := j-1
    t9 := 4*t8
    temp := A[t9] ;temp:=A[j]
    t12 := 4*j
    t13 := A[t12] ;A[j+1]
    A[t9] := t13 ;A[j]:=A[j+1]
    A[t12] := temp ;A[j+1] := temp
B8: j := j+1
    goto B4
B5: i := i-1
    goto B2
out:
```

### Example (After Global CSE)

```
B1: i := n-1
B2: if i<1 goto out
B3: j := 1
B4: if j>i goto B5
B6: t1 := j-1
    t2 := 4*t1
    t3 := A[t2] ;A[j]
    t6 := 4*j
    t7 := A[t6] ;A[j+1]
    if t3<=t7 goto B8
B7: A[t2] := t7
    A[t6] := t3
B8: j := j+1
    goto B4
B5: i := i-1
    goto B2
out:
```

### Induction Variable Elimination

- **Intuitively**
  - Loop indices are induction variables (counting iterations)
  - Linear functions of the loop indices are also induction variables (for accessing arrays)
- **Analysis: detection of induction variable**
- **Optimizations**
  - strength reduction:
    - replace multiplication by additions
  - elimination of loop index:
    - replace termination by tests on other induction variables

### Example

```
B1: i := n-1
B2: if i<1 goto out
B3: j := 1
B4: if j>i goto B5
B6: t1 := j-1
    t2 := 4*t1
    t3 := A[t2] ;A[j]
    t6 := 4*j
    t7 := A[t6] ;A[j+1]
    if t3<=t7 goto B8
B7: A[t2] := t7
    A[t6] := t3
B8: j := j+1
    goto B4
B5: i := i-1
    goto B2
out:
```

### Example (After Induction Variable Elimination)

```
B1: i := n-1
B2: if i<1 goto out
B3: t2 := 0
    t6 := 4
B4: t19 := 4*i
    if t6>t19 goto B5
B6: t3 := A[t2]
    t7 := A[t6] ;A[j+1]
    if t3<=t7 goto B8
B7: A[t2] := t7
    A[t6] := t3
B8: t2 := t2+4
    t6 := t6+4
    goto B4
B5: i := i-1
    goto B2
out:
```

### Loop Invariant Code Motion

- **Analysis**
  - a computation is done within a loop and
  - result of the computation is the same as long as we keep going around the loop
- **Transformation**
  - move the computation outside the loop

```
B4: t19 := 4*i
    if t6>t19 goto B5
t19 := 4*i
B4: if t6>t19 goto B5
```

### Machine Dependent Optimizations

- Register allocation
- Instruction scheduling
- Memory hierarchy optimizations
- etc.

### Wednesday's Class

- Dominic will present "LLVM Compiler: Getting Started"
  - part 1 of 2 on LLVM
- Assignment 1 will be handed out