15-213

"The course that gives CMU its Zip!"

Dynamic Memory Allocation I October 28, 2003

Topics

- Simple explicit allocators
 - Data structures
 - Mechanisms
 - Policies

class19.ppt

Harsh Reality

Memory Matters

Memory is not unbounded

- It must be allocated and managed
- Many applications are memory dominated
 - Especially those based on complex, graph algorithms

Memory referencing bugs especially pernicious

Effects are distant in both time and space

Memory performance is not uniform

- Cache and virtual memory effects can greatly affect program performance
- Adapting program to characteristics of memory system can lead to major speed improvements

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Dynamic Memory Allocation

Application

Dynamic Memory Allocator

Heap Memory

Explicit vs. Implicit Memory Allocator

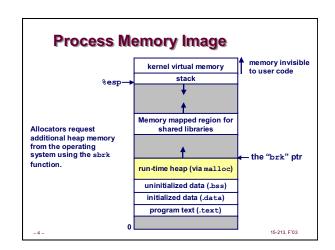
- Explicit: application allocates and frees space
- E.g., malloc and free in C
- Implicit: application allocates, but does not free space
 E.g. garbage collection in Java, ML or Lisp

Allocation

- In both cases the memory allocator provides an abstraction of memory as a set of blocks
- Doles out free memory blocks to application
- Will discuss simple explicit memory allocation today

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```
#include <stdlib.h>

void *malloc (size_t size)

If successful:

Returns a pointer to a memory block of at least size bytes, (typically) aligned to 8-byte boundary.

If size == 0, returns NULL

If unsuccessful: returns NULL (0) and sets errno.

void free (void *p)

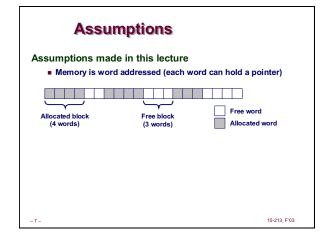
Returns the block pointed at by p to pool of available memory

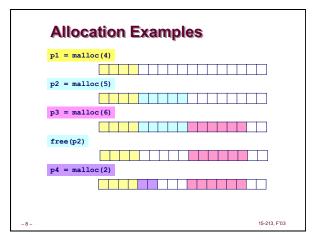
p must come from a previous call to malloc or realloc.

void *realloc (void *p, size_t size)

Changes size of block p and returns pointer to new block.

Contents of new block unchanged up to min of old and new size.
```





Constraints

- Can issue arbitrary sequence of allocation and free requests
- Free requests must correspond to an allocated block

- Can't control number or size of allocated blocks
- Must respond immediately to all allocation requests
 - •i.e., can't reorder or buffer requests
- Must allocate blocks from free memory
- ●i.e., can only place allocated blocks in free memory
- Must align blocks so they satisfy all alignment requirements •8 byte alignment for GNU malloc (libc malloc) on Linux boxes
- Can only manipulate and modify free memory
- Can't move the allocated blocks once they are allocated
- ●i.e., compaction is not allowed

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Goals of Good malloc/free

Primary goals

- Good time performance for malloc and free
 - Ideally should take constant time (not always possible)
 - Should certainly not take linear time in the number of blocks
- Good space utilization
 - User allocated structures should be large fraction of the heap.
- Want to minimize "fragmentation".

Some other goals

- Good locality properties
 - Structures allocated close in time should be close in space
 - "Similar" objects should be allocated close in space
- Robust
 - Can check that free (p1) is on a valid allocated object p1
 - Can check that memory references are to allocated space

Performance Goals: Throughput

Given some sequence of malloc and free requests:

R₀, R₁, ..., R_k, ..., R_{n-1}

Want to maximize throughput and peak memory utilization.

■ These goals are often conflicting

Throughput:

- Number of completed requests per unit time
- Example:
 - 5,000 malloc calls and 5,000 free calls in 10 seconds
 - Throughput is 1,000 operations/second.

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Performance Goals: Peak Memory Utilization

Given some sequence of malloc and free requests:

 \blacksquare $R_0, R_1, ..., R_k, ..., R_{n-1}$

Def: Aggregate payload P_k:

- malloc(p) results in a block with a payload of p bytes..
- After request R_k has completed, the aggregate payload P_k is the sum of currently allocated payloads.

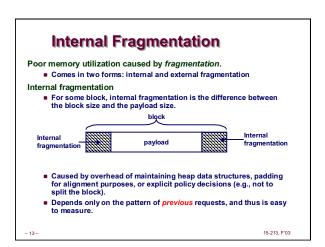
Def: Current heap size is denoted by H_k

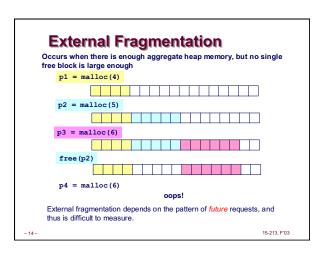
■ Assume that H_k is monotonically nondecreasing

Def: Peak memory utilization:

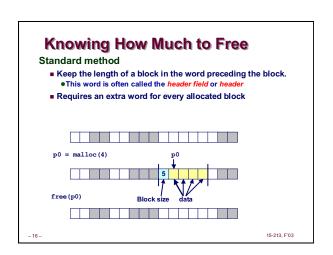
- After k requests, peak memory utilization is:
 - $U_k = (\max_{i < k} P_i) / H_k$

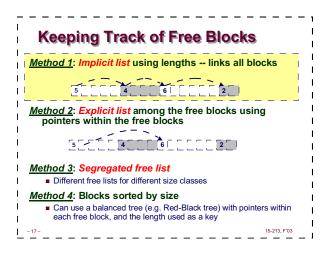
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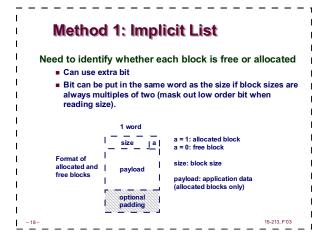




Implementation Issues How do we know how much memory to free just given a pointer? How do we keep track of the free blocks? What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in? How do we pick a block to use for allocation -- many might fit? How do we reinsert freed block?







Implicit List: Finding a Free Block ■ Search list from beginning, choose first free block that fits p = start; while ((p < end) && ((*p & 1) || \\ not passed end \\ already allocated (*p <= len))) p = p + (*p & -2); \\ too small \\ goto next block ■ Can take linear time in total number of blocks (allocated and free) ■ In practice it can cause "splinters" at beginning of list ■ Like first-fit, but search list from location of end of previous search Research suggests that fragmentation is worse ■ Search the list, choose the free block with the closest size that fits ■ Keeps fragments small --- usually helps fragmentation ■ Will typically run slower than first-fit 15-213, F'03

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Bitfields

How to represent the Header:

• Masks and bitwise operators

#define PACK(size, alloc) ((size) | (alloc))

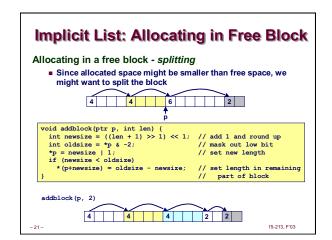
#define getSize(x) ((x)->size & SIZEMASK)

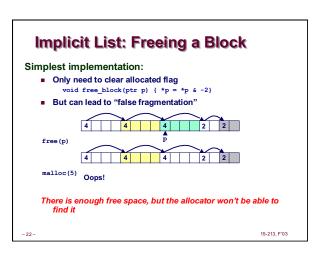
• bitfields

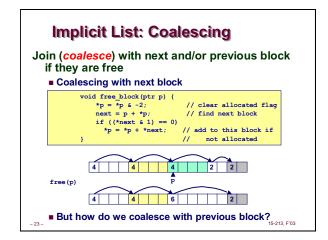
struct

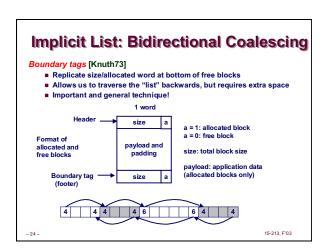
{

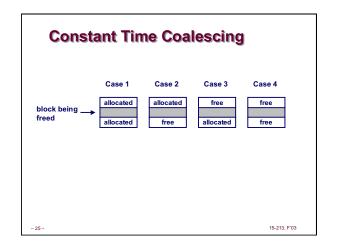
unsigned allocated:1;
unsigned size:31;
} Header;
```

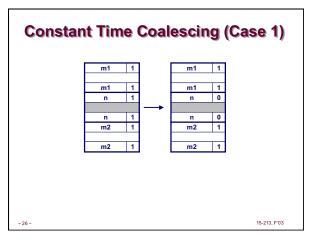


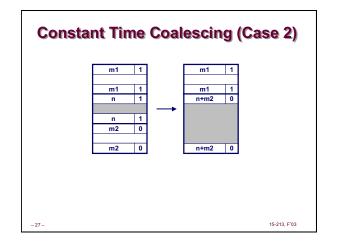


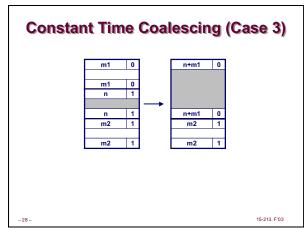


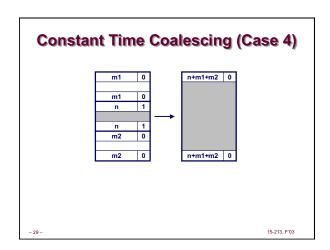












Summary of Key Allocator Policies

Placement policy:

- First fit, next fit, best fit, etc.
- Trades off lower throughput for less fragmentation
 - Interesting observation: segregated free lists (next lecture) approximate a best fit placement policy without having the search entire free list.

Splitting policy:

- When do we go ahead and split free blocks?
- How much internal fragmentation are we willing to tolerate?

Coalescing policy:

- Immediate coalescing: coalesce adjacent blocks each time free is
- Deferred coalescing: try to improve performance of free by deferring coalescing until needed. e.g.,

 • Coalesce as you scan the free list for malloc

 - Coalesce when the amount of external fragmentation reaches some

Implicit Lists: Summary

- Implementation: very simple
- Allocate: linear time worst case
- Free: constant time worst case -- even with coalescing
- Memory usage: will depend on placement policy
 - First fit, next fit or best fit

Not used in practice for malloc/free because of linear time allocate. Used in many special purpose applications.

However, the concepts of splitting and boundary tag coalescing are general to all allocators.