15-213 "The course that gives CMU its Zip!"

Code Optimization Sept. 25, 2003

Topics

- Machine-Independent Optimizations
- Machine Dependent Optimizations
- Code Profiling

Harsh Reality

There's more to performance than asymptotic complexity

Constant factors matter too!

- Easily see 10:1 performance range depending on how code is written
- Must optimize at multiple levels:
 - algorithm, data representations, procedures, and loops

Must understand system to optimize performance

- How programs are compiled and executed
- How to measure program performance and identify bottlenecks
- How to improve performance without destroying code modularity and generality

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Limitations of Optimizing Compilers

Operate under fundamental constraint

- Must not cause any change in program behavior under any possible condition
- Often prevents it from making optimizations when would only affect behavior under pathological conditions.

Behavior that may be obvious to the programmer can be obfuscated by languages and coding styles

■ e.g., Data ranges may be more limited than variable types suggest

Most analysis is performed only within procedures

■ Whole-program analysis is too expensive in most cases

Most analysis is based only on static information

Compiler has difficulty anticipating run-time inputs

When in doubt, the compiler must be conservative

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Machine-Independent Optimizations

Optimizations that you or compiler should do regardless of processor / compiler

Code Motion

- Reduce frequency with which computation performed
 - If it will always produce same result
 - Especially moving code out of loop

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
  a[n*i + j] = b[j];

for (i = 0; i < n; i++) {
    int ni = n*i;
    for (j = 0; j < n; j++)
        a[ni + j] = b[j];
}</pre>
```

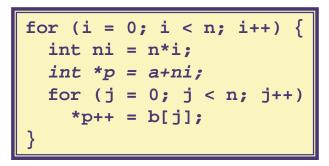
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Compiler-Generated Code Motion

 Most compilers do a good job with array code + simple loop structures

Code Generated by GCC

```
for (i = 0; i < n; i++)
for (j = 0; j < n; j++)
a[n*i + j] = b[j];
```



```
imull %ebx,%eax
                         # i*n
 movl 8(%ebp),%edi
                         # a
  leal (%edi, %eax, 4), %edx # p = a+i*n (scaled by 4)
# Inner Loop
.L40:
 movl 12(%ebp),%edi # b
 movl (%edi,%ecx,4),%eax # b+j (scaled by 4)
 movl %eax,(%edx) # *p = b[j]
 addl $4,%edx
                      # p++ (scaled by 4)
  incl %ecx
                       # 1++
  jl .L40
                         # loop if j<n
```

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Reduction in Strength

- Replace costly operation with simpler one
- Shift, add instead of multiply or divide

```
16*x --> x << 4
```

- Utility machine dependent
- Depends on cost of multiply or divide instruction
- On Pentium II or III, integer multiply only requires 4 CPU cycles
- Recognize sequence of products

```
for (i = 0; i < n; i++)
  for (j = 0; j < n; j++)
   a[n*i + j] = b[j];

int ni = 0;
for (i = 0; i < n; i++) {
  for (j = 0; j < n; j++)
   a[ni + j] = b[j];
  ni += n;
}</pre>
```

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Share Common Subexpressions

- Reuse portions of expressions
- Compilers often not very sophisticated in exploiting arithmetic properties

```
/* Sum neighbors of i,j */
up = val[(i-1)*n + j];
down = val[(i+1)*n + j];
left = val[i*n + j-1];
right = val[i*n + j+1];
sum = up + down + left + right;
```

int inj = i*n + j;
up = val[inj - n];
down = val[inj + n];
left = val[inj - 1];
right = val[inj + 1];
sum = up + down + left + right;

3 multiplications: i*n, (i-1)*n, (i+1)*n

1 multiplication: i*n

```
leal -1(%edx),%ecx # i-1
imull %ebx,%ecx # (i-1)*n
leal 1(%edx),%eax # i+1
imull %ebx,%eax # (i+1)*n
imull %ebx,%edx # i*n
```

Time Scales

Absolute Time

- Typically use nanoseconds
 - 10⁻⁹ seconds
- **Time scale of computer instructions**

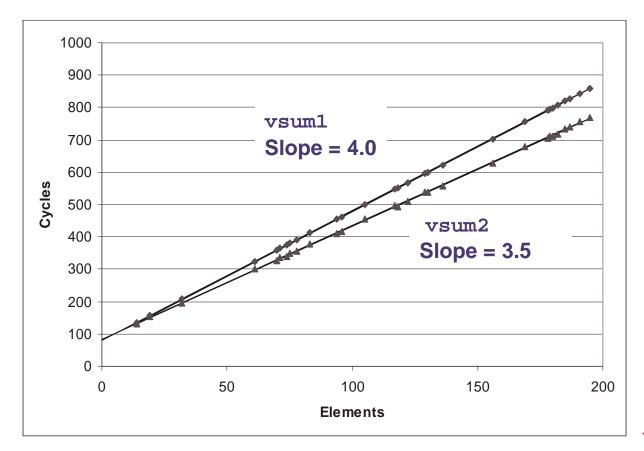
Clock Cycles

- Most computers controlled by high frequency clock signal
- Typical Range
 - 100 MHz
 - » 10⁸ cycles per second
 - » Clock period = 10ns
 - 2 GHz
 - » 2 X 10⁹ cycles per second
 - » Clock period = 0.5ns
- Fish machines: 550 MHz (1.8 ns clock period)

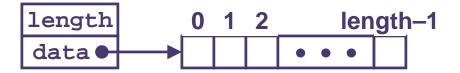
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Cycles Per Element

- Convenient way to express performance of program that operators on vectors or lists
- Length = n
- T = CPE*n + Overhead



Vector Abstract Data Type (ADT)



Procedures

vec_ptr new_vec(int len)

Create vector of specified length

int get_vec_element(vec_ptr v, int index, int *dest)

- Retrieve vector element, store at *dest
- Return 0 if out of bounds, 1 if successful

int *get_vec_start(vec_ptr v)

- Return pointer to start of vector data
- Similar to array implementations in Pascal, ML, Java
 - E.g., always do bounds checking

Optimization Example

```
void combine1(vec_ptr v, int *dest)
{
  int i;
  *dest = 0;
  for (i = 0; i < vec_length(v); i++) {
    int val;
    get_vec_element(v, i, &val);
    *dest += val;
  }
}</pre>
```

Procedure

- Compute sum of all elements of integer vector
- Store result at destination location
- Vector data structure and operations defined via abstract data type

Pentium II/III Performance: Clock Cycles / Element

- 11 - ■ 42.06 (Compiled -g) 31.25 (Compiled -O2)

Understanding Loop

```
void combine1-goto(vec_ptr v, int *dest)
    int i = 0;
    int val;
    *dest = 0;
    if (i >= vec_length(v))
      goto done;
                                 1 iteration
  loop:
    get_vec_element(v, i, &val);
    *dest += val;
    i++;
    if (i < vec_length(v))</pre>
      goto loop
  done:
```

Inefficiency

- Procedure vec_length called every iteration
- **■** Even though result always the same

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Move vec_length Call Out of Loop

```
void combine2(vec_ptr v, int *dest)
{
  int i;
  int length = vec_length(v);
  *dest = 0;
  for (i = 0; i < length; i++) {
    int val;
    get_vec_element(v, i, &val);
    *dest += val;
  }
}</pre>
```

Optimization

- Move call to vec_length out of inner loop
 - Value does not change from one iteration to next
 - Code motion
- **CPE: 20.66 (Compiled -O2)**
 - vec_length requires only constant time, but significant overhead

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Optimization Blocker: Procedure Calls

Why couldn't compiler move vec_len out of inner loop?

- Procedure may have side effects
 - Alters global state each time called
- Function may not return same value for given arguments
 - Depends on other parts of global state
 - Procedure lower could interact with strlen

Why doesn't compiler look at code for vec_len?

Interprocedural optimization is not used extensively due to cost

Warning:

- Compiler treats procedure call as a black box
- Weak optimizations in and around them

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Reduction in Strength

```
void combine3(vec_ptr v, int *dest)
{
  int i;
  int length = vec_length(v);
  int *data = get_vec_start(v);
  *dest = 0;
  for (i = 0; i < length; i++) {
    *dest += data[i];
}</pre>
```

Optimization

- Avoid procedure call to retrieve each vector element
 - Get pointer to start of array before loop
 - Within loop just do pointer reference
 - Not as clean in terms of data abstraction
- **■** CPE: 6.00 (Compiled -O2)
 - Procedure calls are expensive!
 - Bounds checking is expensive

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Eliminate Unneeded Memory Refs

```
void combine4(vec_ptr v, int *dest)
{
  int i;
  int length = vec_length(v);
  int *data = get_vec_start(v);
  int sum = 0;
  for (i = 0; i < length; i++)
    sum += data[i];
  *dest = sum;
}</pre>
```

Optimization

- Don't need to store in destination until end
- Local variable sum held in register
- Avoids 1 memory read, 1 memory write per cycle
- **■** CPE: 2.00 (Compiled -O2)
 - Memory references are expensive!

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Detecting Unneeded Memory Refs.

Combine3

```
.L18:

movl (%ecx,%edx,4),%eax
addl %eax,(%edi)
incl %edx
cmpl %esi,%edx
jl .L18
```

Combine4

```
.L24:

addl (%eax,%edx,4),%ecx

incl %edx
cmpl %esi,%edx
jl .L24
```

Performance

- **Combine3**
 - •5 instructions in 6 clock cycles
 - add1 must read and write memory
- Combine4
 - 4 instructions in 2 clock cycles

Optimization Blocker: Memory Aliasing

Aliasing

■ Two different memory references specify single location

Example

```
■ v: [3, 2, 17]
```

- combine3(v, get_vec_start(v)+2) --> ?
- combine4(v, get_vec_start(v)+2) --> ?

Observations

- Easy to have happen in C
 - Since allowed to do address arithmetic
 - Direct access to storage structures
- Get in habit of introducing local variables
 - Accumulating within loops
 - Your way of telling compiler not to check for aliasing

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General Forms of Combining

```
void abstract_combine4(vec_ptr v, data_t *dest)
{
  int i;
  int length = vec_length(v);
  data_t *data = get_vec_start(v);
  data_t t = IDENT;
  for (i = 0; i < length; i++)
    t = t OP data[i];
  *dest = t;
}</pre>
```

Data Types

- Use different declarations for data_t
- int
- float
- double

Operations

- Use different definitions of OP and IDENT
- **+** / 0
- ***** / 1

Machine Independent Opt. Results

Optimizations

■ Reduce function calls and memory references within loop

Integer		Floating Point	
+	*	+	*
42.06	41.86	41.44	~ 160.00
31.25	33.25	31.25	143.00
20.66	21.25	21.15	↑ 135.00
6.00	9.00	8.00	117.00
2.00	4.00	3.00	5.00
	+ 42.06 31.25 20.66 6.00	+ * 42.06 41.86 31.25 33.25 20.66 21.25 6.00 9.00	+ * + 42.06 41.86 41.44 31.25 33.25 31.25 20.66 21.25 21.15 6.00 9.00 8.00

Performance Anomaly

- Computing FP product of all elements exceptionally slow.
- Very large speedup when accumulate in temporary
- Caused by quirk of IA32 floating point
 - Memory uses 64-bit format, register use 80
 - Benchmark data caused overflow of 64 bits, but not 80

Machine-Independent Opt. Summary

Code Motion

- Compilers are good at this for simple loop/array structures
- Don't do well in presence of procedure calls and memory aliasing

Reduction in Strength

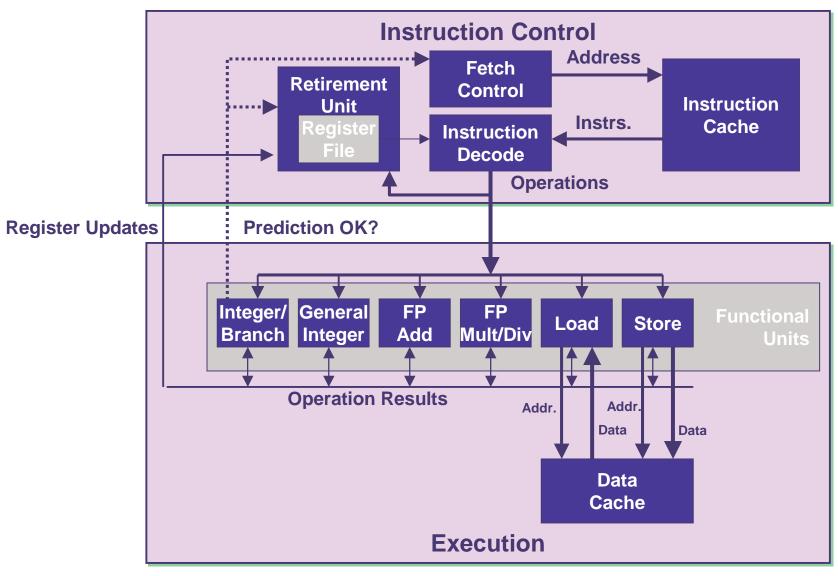
- Shift, add instead of multiply or divide
 - compilers are (generally) good at this
 - Exact trade-offs machine-dependent
- Keep data in registers rather than memory
 - compilers are not good at this, since concerned with aliasing

Share Common Subexpressions

compilers have limited algebraic reasoning capabilities

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Modern CPU Design



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CPU Capabilities of Pentium III

Multiple Instructions Can Execute in Parallel

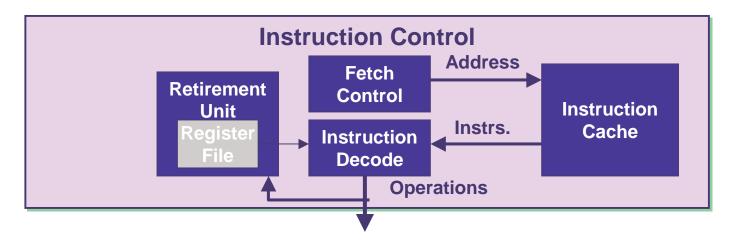
- 1 load
- 1 store
- 2 integer (one may be branch)
- 1 FP Addition
- 1 FP Multiplication or Division

Some Instructions Take > 1 Cycle, but Can be Pipelined

Instruction	Latency	Cycles/Issue
Load / Store	3	1
Integer Multiply	4	1
Integer Divide	36	36
■ Double/Single FP Mul	tiply 5	2
■ Double/Single FP Add	3	1
■ Double/Single FP Divi	ide 38	38

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Instruction Control



Grabs Instruction Bytes From Memory

- Based on current PC + predicted targets for predicted branches
- Hardware dynamically guesses whether branches taken/not taken and (possibly) branch target

Translates Instructions Into Operations

- Primitive steps required to perform instruction
- Typical instruction requires 1–3 operations

Converts Register References Into *Tags*

 Abstract identifier linking destination of one operation with sources of later operations

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Version of Combine4

Integer data, multiply operation

Translation of First Iteration

```
.L24:
imull (%eax,%edx,4),%ecx
incl %edx
cmpl %esi,%edx
jl .L24
```

```
load (%eax,%edx.0,4) → t.1
imull t.1, %ecx.0 → %ecx.1
incl %edx.0 → %edx.1
cmpl %esi, %edx.1 → cc.1
jl-taken cc.1
```

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imull (%eax,%edx,4),%ecx

```
load (%eax,%edx.0,4) → t.1
imull t.1, %ecx.0 → %ecx.1
```

- Split into two operations
 - load reads from memory to generate temporary result t.1
 - Multiply operation just operates on registers
- Operands
 - Register %eax does not change in loop. Values will be retrieved from register file during decoding
 - Register %ecx changes on every iteration. Uniquely identify different versions as %ecx.0, %ecx.1, %ecx.2, ...
 - » Register renaming
 - » Values passed directly from producer to consumers

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incl %edx

incl %edx.0 → %edx.1

■ Register %edx changes on each iteration. Rename as %edx.0, %edx.1, %edx.2, ...

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cmpl %esi,%edx

cmpl %esi, %edx.1 → cc.1

- Condition codes are treated similar to registers
- Assign tag to define connection between producer and consumer

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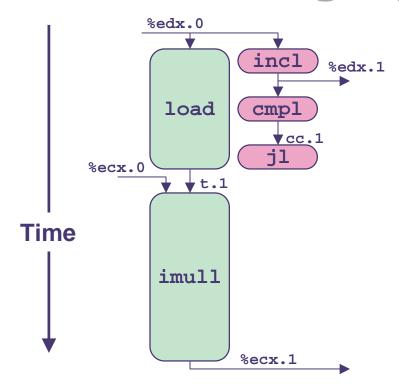
jl .L24

jl-taken cc.1

- Instruction control unit determines destination of jump
- Predicts whether will be taken and target
- Starts fetching instruction at predicted destination
- Execution unit simply checks whether or not prediction was OK
- If not, it signals instruction control
 - Instruction control then "invalidates" any operations generated from misfetched instructions
 - Begins fetching and decoding instructions at correct target

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Visualizing Operations



```
load (%eax,%edx,4) → t.1
imull t.1, %ecx.0 → %ecx.1
incl %edx.0 → %edx.1
cmpl %esi, %edx.1 → cc.1
jl-taken cc.1
```

Operations

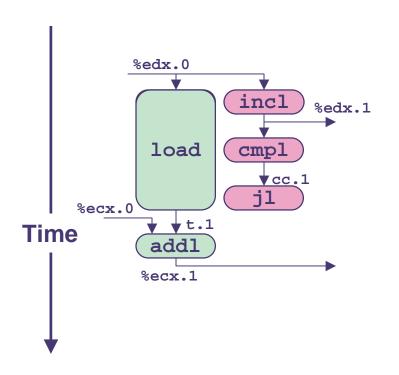
- Vertical position denotes time at which executed
 - Cannot begin operation until operands available
- Height denotes latency

Operands

Arcs shown only for operands that are passed within execution unit

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Visualizing Operations (cont.)



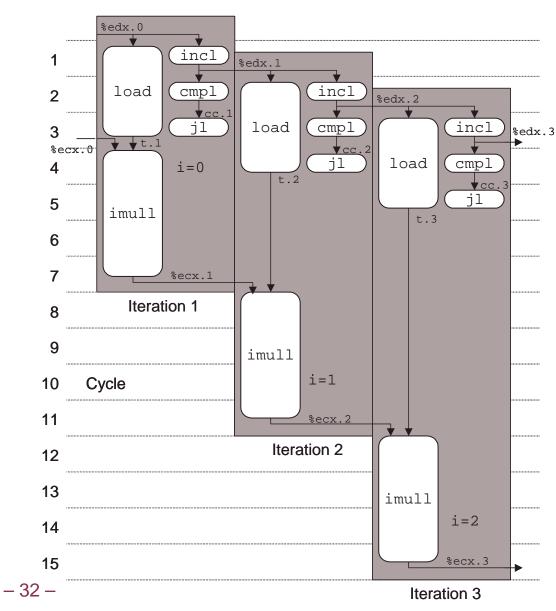
```
load (%eax,%edx,4) → t.1
iaddl t.1, %ecx.0 → %ecx.1
incl %edx.0 → %edx.1
cmpl %esi, %edx.1 → cc.1
jl-taken cc.1
```

Operations

Same as before, except that add has latency of 1

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3 Iterations of Combining Product



Unlimited Resource Analysis

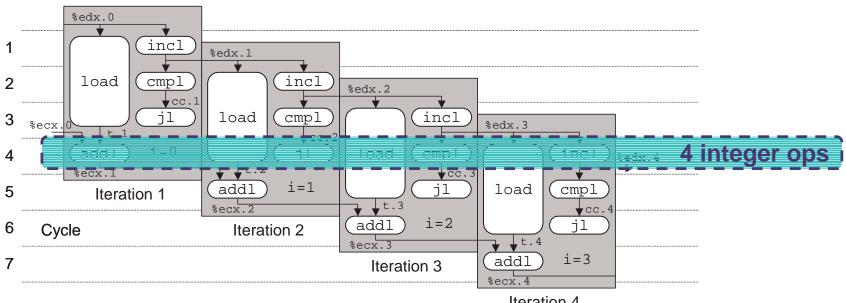
- Assume operation can start as soon as operands available
- Operations for multiple iterations overlap in time

Performance

- Limiting factor becomes latency of integer multiplier
- Gives CPE of 4.0

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4 Iterations of Combining Sum



Iteration 4

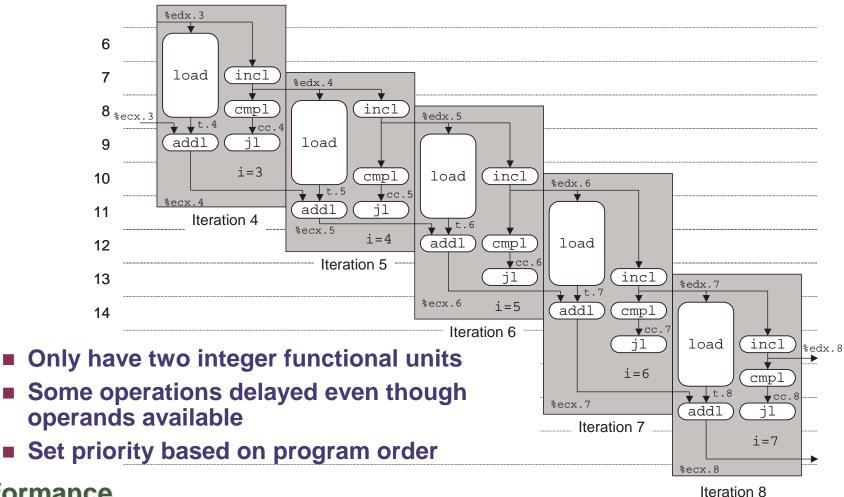
Unlimited Resource Analysis

Performance

- Can begin a new iteration on each clock cycle
- Should give CPE of 1.0
- Would require executing 4 integer operations in parallel

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Combining Sum: Resource Constraints



Performance

Sustain CPE of 2.0

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Loop Unrolling

```
void combine5(vec ptr v, int *dest)
  int length = vec_length(v);
  int limit = length-2;
  int *data = get vec start(v);
  int sum = 0;
  int i;
  /* Combine 3 elements at a time */
  for (i = 0; i < limit; i+=3) {
    sum += data[i] + data[i+2]
           + data[i+1];
  /* Finish any remaining elements */
  for (; i < length; i++) {
    sum += data[i];
  *dest = sum;
```

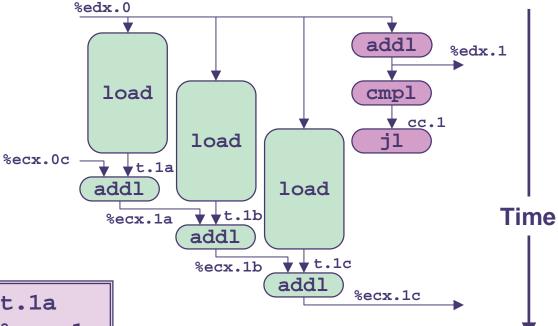
Optimization

- Combine multiple iterations into single loop body
- Amortizes loop overhead across multiple iterations
- Finish extras at end
- Measured CPE = 1.33

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Visualizing Unrolled Loop

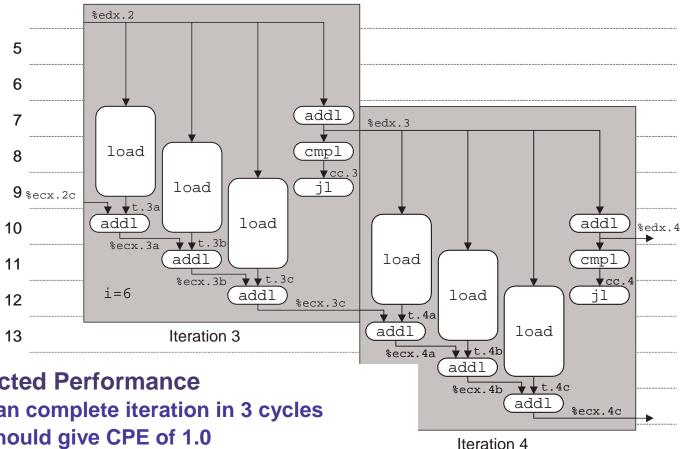
- Loads can pipeline, since don't have dependencies
- Only one set of loop control operations



```
→ t.1a
load (%eax,%edx.0,4)
                     → %ecx.1a
iaddl t.1a, %ecx.0c
load 4(%eax,%edx.0,4)
                     → t.1b
iaddl t.1b, %ecx.1a
                     → %ecx.1b
load 8(\%eax,\%edx.0,4) \rightarrow t.1c
                     → %ecx.1c
iaddl t.1c, %ecx.1b
iaddl $3,%edx.0
                     → %edx.1
                     → cc.1
cmpl %esi, %edx.1
il-taken cc.1
```

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Executing with Loop Unrolling



- **Predicted Performance**
 - Can complete iteration in 3 cycles
 - Should give CPE of 1.0
- Measured Performance
 - CPE of 1.33
 - One iteration every 4 cycles

Effect of Unrolling

Unrolling Degree		1	2 3		4	8	16	
Integer	Sum	2.00 1.50 1.33 1.50 1.25 1.0						
Integer	Product	4.00						
FP	Sum	3.00						
FP	Product	5.00						

- Only helps integer sum for our examples
 - Other cases constrained by functional unit latencies
- Effect is nonlinear with degree of unrolling
 - Many subtle effects determine exact scheduling of operations

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Parallel Loop Unrolling

```
void combine6(vec ptr v, int *dest)
  int length = vec length(v);
  int limit = length-1;
  int *data = get_vec_start(v);
  int x0 = 1;
  int x1 = 1;
  int i;
  /* Combine 2 elements at a time */
  for (i = 0; i < limit; i+=2) {
    x0 *= data[i];
   x1 *= data[i+1];
  /* Finish any remaining elements */
  for (; i < length; i++) {
    x0 *= data[i];
  *dest = x0 * x1;
```

Code Version

Integer product

Optimization

- Accumulate in two different products
 - Can be performed simultaneously
- **■** Combine at end
- 2-way parallism

Performance

- CPE = 2.0
- 2X performance

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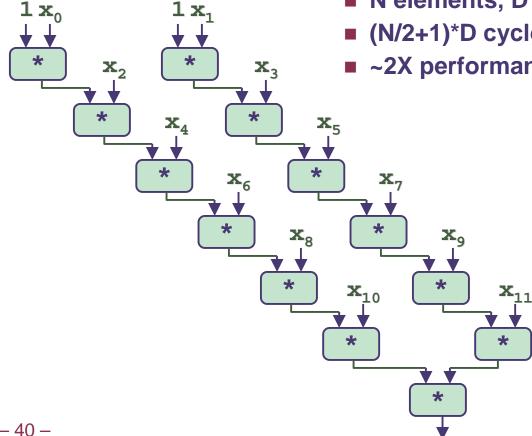
Dual Product Computation

Computation

$$((((((((1 * x_0) * x_2) * x_4) * x_6) * x_8) * x_{10}) * (((((((1 * x_1) * x_3) * x_5) * x_7) * x_9) * x_{11})$$

Performance

- N elements, D cycles/operation
- (N/2+1)*D cycles
- ~2X performance improvement



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Requirements for Parallel Computation

Mathematical

- Combining operation must be associative & commutative
 - OK for integer multiplication
 - Not strictly true for floating point
 - » OK for most applications

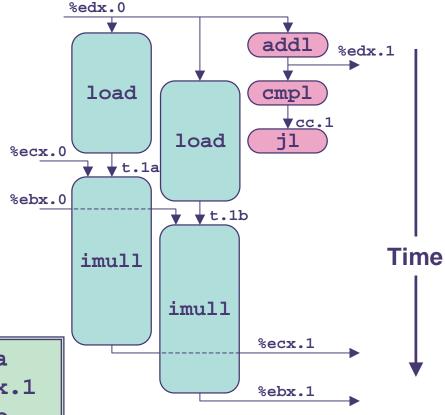
Hardware

- Pipelined functional units
- Ability to dynamically extract parallelism from code

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Visualizing Parallel Loop

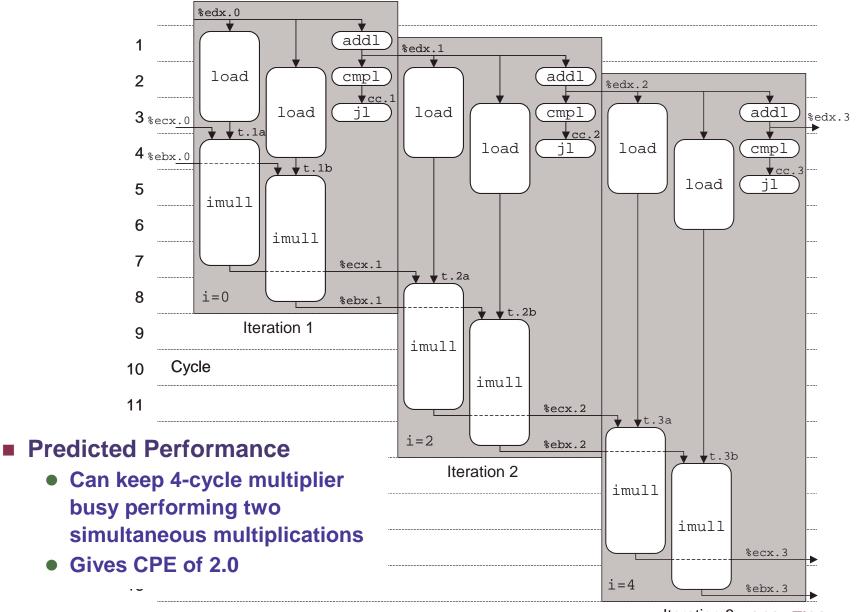
- Two multiplies within loop no longer have data depency
- Allows them to pipeline



```
load (%eax,%edx.0,4)  → t.1a
imull t.1a, %ecx.0  → %ecx.1
load 4(%eax,%edx.0,4)  → t.1b
imull t.1b, %ebx.0  → %ebx.1
iaddl $2,%edx.0  → %edx.1
cmpl %esi, %edx.1  → cc.1
jl-taken cc.1
```

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Executing with Parallel Loop



Summary: Results for Pentium III

Method	Integer		Floating Point		
	+	*	+	*	
Abstract -g	42.06	41.86	41.44	160.00	
Abstract -O2	31.25	33.25	31.25	143.00	
Move vec_length	20.66	21.25	21.15	135.00	
data access	6.00	9.00	8.00	117.00	
Accum. in temp	2.00	4.00	3.00	5.00	
Pointer	3.00	4.00	3.00	5.00	
Unroll 4	1.50	4.00	3.00	5.00	
Unroll 16	1.06	4.00	3.00	5.00	
2 X 2	1.50	2.00	2.00	2.50	
4 X 4	1.50	2.00	1.50	2.50	
8 X 4	1.25	1.25	1.50	2.00	
Theoretical Opt.	1.00	1.00	1.00	2.00	
Worst : Best	39.7	33.5	27.6	80.0	

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Limitations of Parallel Execution

Need Lots of Registers

- To hold sums/products
- Only 6 usable integer registers
 - Also needed for pointers, loop conditions
- 8 FP registers
- When not enough registers, must spill temporaries onto stack
 - Wipes out any performance gains
- Not helped by renaming
 - Cannot reference more operands than instruction set allows
 - Major drawback of IA32 instruction set

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Register Spilling Example

Example

- 8 X 8 integer product
- 7 local variables share 1 register
- See that are storing locals on stack
- E.g., at -8(%ebp)

```
.L165:
     imull (%eax),%ecx
    movl -4(%ebp),%edi
     imull 4(%eax),%edi
    mov1 %edi,-4(%ebp)
    mov1 -8(%ebp),%edi
     imull 8(%eax),%edi
    mov1 %edi,-8(%ebp)
    movl -12(%ebp),%edi
     imull 12(%eax),%edi
    mov1 %edi,-12(%ebp)
    movl -16(%ebp),%edi
     imull 16(%eax),%edi
    mov1 %edi,-16(%ebp)
    addl $32,%eax
    addl $8,%edx
    cmpl -32(%ebp),%edx
     jl .L165
```

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Results for Alpha Processor

Method	Intege	jer Floating Poil		
	+	*	+	*
Abstract -g	40.14	47.14	52.07	53.71
Abstract -O2	25.08	36.05	37.37	32.02
Move vec_length	19.19	32.18	28.73	32.73
data access	6.26	12.52	13.26	13.01
Accum. in temp	1.76	9.01	8.08	8.01
Unroll 4	1.51	9.01	6.32	6.32
Unroll 16	1.25	9.01	6.33	6.22
4 X 2	1.19	4.69	4.44	4.45
8 X 4	1.15	4.12	2.34	2.01
8 X 8	1.11	4.24	2.36	2.08
Worst : Best	36.2	11.4	22.3	26.7

- Overall trends very similar to those for Pentium III.
- Even though very different architecture and compiler

Results for Pentium 4 Processor

Method	Intege	er	Floating Point		
	+	*	+	*	
Abstract -g	35.25	35.34	35.85	38.00	
Abstract -O2	26.52	30.26	31.55	32.00	
Move vec_length	18.00	25.71	23.36	24.25	
data access	3.39	31.56	27.50	28.35	
Accum. in temp	2.00	14.00	5.00	7.00	
Unroll 4	1.01	14.00	5.00	7.00	
Unroll 16	1.00	14.00	5.00	7.00	
4 X 2	1.02	7.00	2.63	3.50	
8 X 4	1.01	3.98	1.82	2.00	
8 X 8	1.63	4.50	2.42	2.31	
Worst : Best	35.2	8.9	19.7	19.0	

- Higher latencies (int * = 14, fp + = 5.0, fp * = 7.0)
 - Clock runs at 2.0 GHz
 - Not an improvement over 1.0 GHz P3 for integer *
- Avoids FP multiplication anomaly

Machine-Dependent Opt. Summary

Loop Unrolling

- Some compilers do this automatically
- Generally not as clever as what can achieve by hand

Exposing Instruction-Level Parallelism

Generally helps, but extent of improvement is machine dependent

Warning:

- Benefits depend heavily on particular machine
- Best if performed by compiler
 - But GCC on IA32/Linux is not very good
- Do only for performance-critical parts of code

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Important Tools

Observation

- Generating assembly code
 - Lets you see what optimizations compiler can make
 - Understand capabilities/limitations of particular compiler

Measurement

- Accurately compute time taken by code
 - Most modern machines have built in cycle counters
 - Using them to get reliable measurements is tricky
 - » Chapter 9 of the CS:APP textbook
- Profile procedure calling frequencies
 - Unix tool gprof

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Code Profiling Example

Task

- Count word frequencies in text document
- Produce sorted list of words from most frequent to least

Steps

- Convert strings to lowercase
- Apply hash function
- Read words and insert into hash table
 - Mostly list operations
 - Maintain counter for each unique word
- Sort results

Data Set

- Collected works of Shakespeare
- 946,596 total words, 26,596 unique
- Initial implementation: 9.2 seconds

Shakespeare's most frequent words

29,801	the
27,529	and
21,029	I
20,957	to
18,514	of
15,370	а
14010	you
12,936	my
11,722	in
11,519	that

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Code Profiling

Augment Executable Program with Timing Functions

- Computes (approximate) amount of time spent in each function
- Time computation method
 - Periodically (~ every 10ms) interrupt program
 - Determine what function is currently executing
 - Increment its timer by interval (e.g., 10ms)
- Also maintains counter for each function indicating number of times called

Using

```
gcc -02 -pg prog. -o prog ./prog
```

- Executes in normal fashion, but also generates file gmon.out gprof prog
 - Generates profile information based on gmon.out

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Profiling Results

% cu	mulative	self		self	total	
time	seconds	seconds	calls	ms/call	ms/call	name
86.60	8.21	8.21	1	8210.00	8210.00	sort_words
5.80	8.76	0.55	946596	0.00	0.00	lower1
4.75	9.21	0.45	946596	0.00	0.00	find_ele_rec
1.27	9.33	0.12	946596	0.00	0.00	h_add

Call Statistics

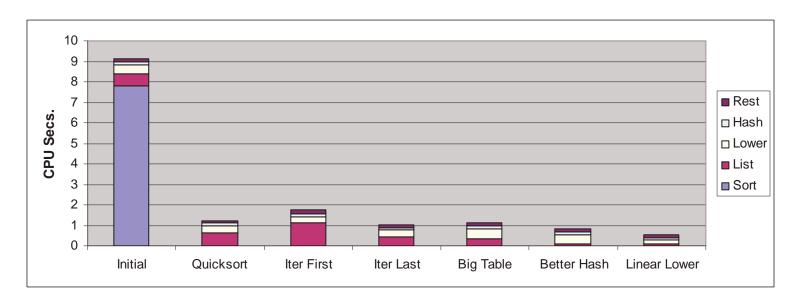
Number of calls and cumulative time for each function

Performance Limiter

- Using inefficient sorting algorithm
- Single call uses 87% of CPU time

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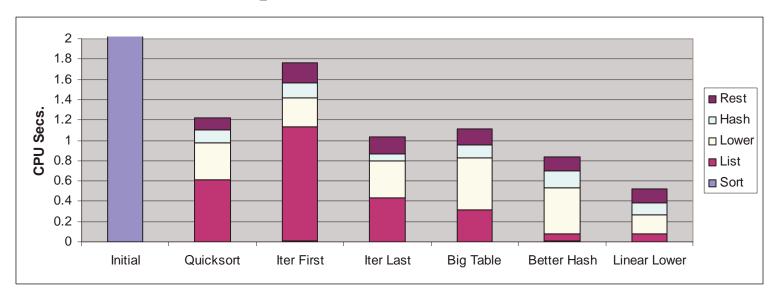
Code Optimizations



- First step: Use more efficient sorting function
- Library function qsort

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Further Optimizations



- Iter first: Use iterative function to insert elements into linked list
 - Causes code to slow down
- Iter last: Iterative function, places new entry at end of list
 - Tend to place most common words at front of list
- Big table: Increase number of hash buckets
- Better hash: Use more sophisticated hash function
- Linear lower: Move strlen out of loop

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Profiling Observations

Benefits

- Helps identify performance bottlenecks
- Especially useful when have complex system with many components

Limitations

- Only shows performance for data tested
- E.g., linear lower did not show big gain, since words are short
 - Quadratic inefficiency could remain lurking in code
- Timing mechanism fairly crude
 - Only works for programs that run for > 3 seconds

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Role of Programmer

How should I write my programs, given that I have a good, optimizing compiler?

Don't: Smash Code into Oblivion

■ Hard to read, maintain, & assure correctness

Do:

- Select best algorithm
- Write code that's readable & maintainable
 - Procedures, recursion, without built-in constant limits
 - Even though these factors can slow down code
- Eliminate optimization blockers
 - Allows compiler to do its job

Focus on Inner Loops

- Do detailed optimizations where code will be executed repeatedly
- Will get most performance gain here

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