

# 15-213

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## Concurrency I: Threads

### Nov 9, 2000

#### Topics

- Thread concept
- Posix threads (Pthreads) interface
- Linux Pthreads implementation
- Concurrent execution
- Sharing data

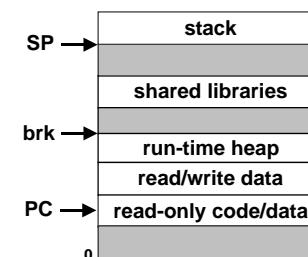
## Traditional view of a process

Process = process context + code, data, and stack

#### Process context

**Program context:**  
Data registers  
Condition codes  
Stack pointer (SP)  
Program counter (PC)  
**Kernel context:**  
VM structures  
Open files  
Signal handlers  
brk pointer

#### Code, data, and stack



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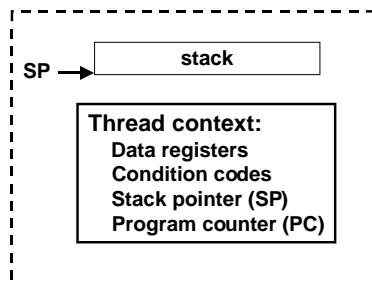
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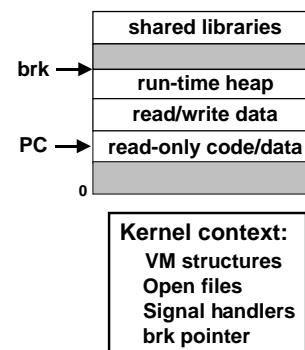
## Modern view of a process

Process = thread + code, data, and kernel context

#### Thread (main thread)



#### Code and Data

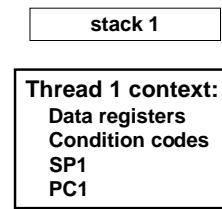


## A process with multiple threads

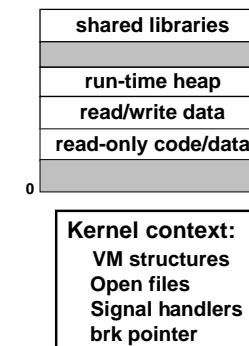
Multiple threads can be associated with a process

- Each thread has its own logical control flow (sequence of PC values)
- Each thread shares the same code, data, and kernel context
- Each thread has its own thread id (tid)

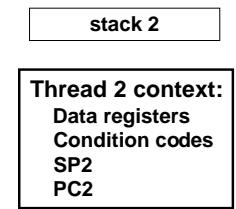
#### Thread 1 (main thread)



#### Shared code and data



#### Thread 2 (peer thread)



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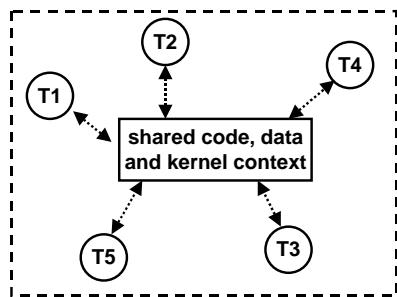
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## Logical view of threads

Threads associated with a process form a pool of peers.

- unlike processes which form a tree hierarchy

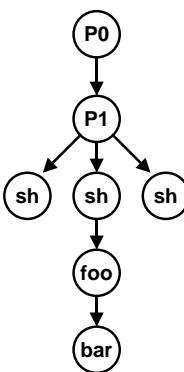
Threads associated with process foo



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Process hierarchy



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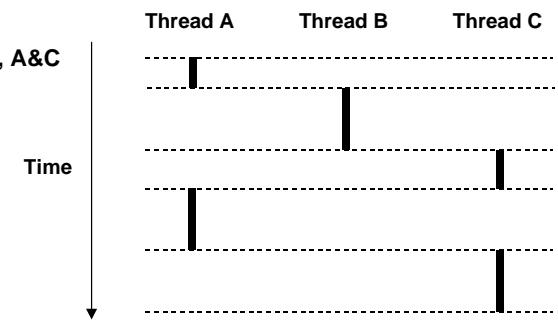
## Concurrent thread execution

Two threads *run concurrently* (are concurrent) if their logical flows overlap in time.

Otherwise, they are *sequential*.

Examples:

- Concurrent: A & B, A&C
- Sequential: B & C



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## Threads vs processes

How threads and processes are similar

- Each has its own logical control flow.
- Each can run concurrently.
- Each is context switched.

How threads and processes are different

- Threads share code and data, processes (typically) do not.
- Threads are somewhat less expensive than processes.
  - process control (creating and reaping) is twice as expensive as thread control.
  - Linux/Pentium III numbers:
    - » 20K cycles to create and reap a process.
    - » 10K cycles to create and reap a thread.

## Threads are a unifying abstraction for exceptional control flow

Exception handler

- A handler can be viewed as a thread
- Waits for a "signal" from CPU
- Upon receipt, executes some code, then waits for next "signal"

Process

- A process is a thread + shared code, data, and kernel context.

Signal handler

- A signal handler can be viewed as a thread
- Waits for a signal from the kernel or another process
- Upon receipt, executes some code, then waits for next signal.

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## Posix threads (Pthreads) interface

Pthreads: Standard interface for ~60 functions that manipulate threads from C programs.

- Creating and reaping threads.
  - `pthread_create`
  - `pthread_join`
- Determining your thread ID
  - `pthread_self`
- Terminating threads
  - `pthread_cancel`
  - `pthread_exit`
  - `exit()` [terminates all threads], `ret` [terminates current thread]
- Synchronizing access to shared variables
  - `pthread_mutex_init`
  - `pthread_mutex_[un]lock`
  - `pthread_cond_init`
  - `pthread_cond_[timed]wait`

## The Pthreads "hello, world" program

```
/*
 * hello.c - Pthreads "hello, world" program
 */
#include <ics.h>

void *thread(void *vargp);

int main() {
    pthread_t tid;

    Pthread_create(&tid, NULL, thread, NULL);
    Pthread_join(tid, NULL);
    exit(0);
}

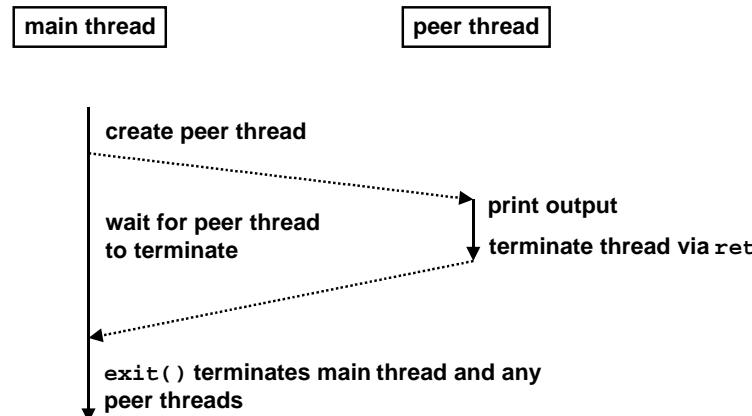
/* thread routine */
void *thread(void *vargp) {
    printf("Hello, world!\n");
    return NULL;
}
```

Thread attributes (usually NULL)

Thread arguments (void \*p)

return value (void \*\*p)

## Execution of "hello, world"



## Unix vs Posix error handling

### Unix-style error handling (Unix syscalls)

- if error: return -1 and set `errno` variable to error code.
- if OK: return useful result as value  $\geq 0$ .

```
if ((pid = wait(NULL)) < 0) {
    perror("wait");
    exit(0);
}
```

### Posix-style error handling (newer Posix functions)

- if error: return nonzero error code, zero if OK
- useful results are passed back in an argument.

```
if ((rc = pthread_join(tid, &retvalp)) != 0) {
    printf("pthread_create: %s\n", strerror(rc));
    exit(0);
}
```

## Suggested error handling macros

Error checking crucial, but cluttered. Use these to simplify your error checking:

```
/*
 * macro for unix-style error handling
 */
#define unix_error(msg) do {\  
    printf("%s: %s\n", msg, strerror(errno));\  
    exit(0);\  
} while (0)
```

```
/*
 * macro for posix-style error handling
 */
#define posix_error(code,msg) do {\  
    printf("%s: %s\n", msg, strerror(code));\  
    exit(0);\  
} while (0)
```

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## Pthreads wrappers

We advocate Steven's convention of providing wrappers for each system-level function call.

- wrapper is denoted by capitalizing first letter of function name.
- wrapper has identical interface as the original function.
- each wrapper does appropriate unix or posix style error checking.
- wrapper typically return nothing.
- declutters code without compromising safety.

```
/*
 * wrapper function for pthread_join
 */
void Pthread_join(pthread_t tid, void **thread_return) {
    int rc = pthread_join(tid, thread_return);
    if (rc != 0)
        posix_error(rc, "Pthread_join");
}
```

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## Basic thread control: create a thread

```
int pthread_create(pthread_t *tidp, pthread_attr_t *attrp,
                   void *(*routine)(void *), void *argp);
```

### Creates a new peer thread

- **tidp**: thread id
- **attrp**: thread attributes (usually NULL)
- **routine**: thread routine
- **argp**: input parameters to routine

### Akin to `fork()`

- but without the confusing "call once return twice" semantics.
- peer thread has local stack variables, but shares all global variables.

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## Basic thread control: join

```
int pthread_join(pthread_t tid, void **thread_return);
```

Waits for a specific peer thread to terminate, and then reaps it.

- **tid**: thread ID of thread to wait for.
- **thread\_return**: object returned by peer thread via `ret` stmt

### Akin to `wait` and `wait_pid` but unlike `wait ...`

- Any thread can reap any other thread (not just children)
- Must wait for a \*specific\* thread
  - no way to wait for \*any\* thread.
  - perceived by some as a flaw in the Pthreads design

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# Linux implementation of Pthreads

Linux implements threads in an elegant way:

- Threads are just processes that share the same kernel context.
- `fork()`: creates a child process with a new kernel context
- `clone()`: creates a child process that shares some or all of the parent's kernel context.

```
int __clone(int (*fn)(void *arg), void *child_stack,  
           int flags, void *arg);
```

Creates a new process and executes function `fn` with argument `arg` in that process using the stack space pointed to by `child_stack`. Returns `pid` of new process.

`flags` determine the degree of kernel context sharing: e.g.,

- `CLONE_VM`: share virtual address space
- `CLONE_FS`: share file system information
- `CLONE_FILES`: share open file descriptors

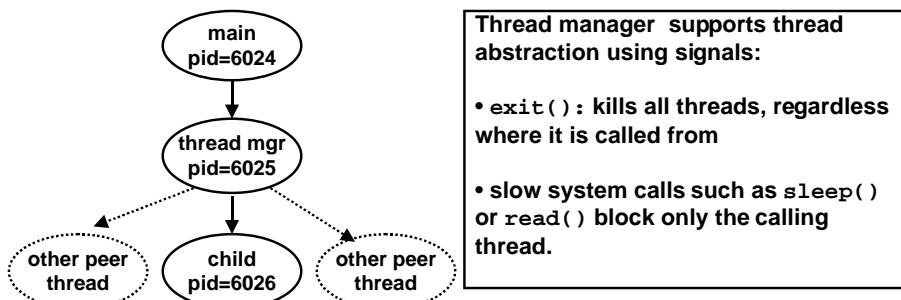
## hellolid.c

The following routine will show us the process hierarchy of a Linux thread pool:

```
#include <ics.h>  
void *thread(void *vargp);  
  
int main() {  
    pthread_t tid;  
    printf("Hello from main thread! tid:%ld pid:%d\n",  
          pthread_self(), getpid());  
    Pthread_create(&tid, NULL, thread, NULL);  
    Pthread_join(tid, NULL);  
    exit(0);  
}  
  
void *thread(void *vargp) {  
    printf("Hello from child thread! tid:%ld pid:%d ppid:%d\n",  
          pthread_self(), getpid(), getppid());  
    return NULL;  
}
```

## Linux process hierarchy for threads

```
bass> hellolid  
Hello from main thread! tid:1024 pid:6024  
Hello from child thread! tid:1025 pid:6026 ppid:6025
```



## beep.c: Performing concurrent tasks

```
/*  
 * beeps until the user hits a key  
 */  
#include <ics.h>  
void *thread(void *vargp);  
  
/* shared by both threads */  
char shared = '\0';  
  
int main() {  
    pthread_t tid;  
    Pthread_create(&tid, NULL,  
                  thread, NULL);  
    while (shared == '\0') {  
        printf("BEEP\n");  
        sleep(1);  
    }  
    Pthread_join(tid, NULL);  
    printf("DONE\n");  
    exit(0);  
}  
  
/* thread routine */  
void *thread(void *vargp) {  
    shared = getchar();  
    return NULL;  
}
```

## badcnt.c: Sharing data between threads

```
/* bad sharing */
#include <ics.h>
#define NITERS 1000
void *count(void *arg);

struct {
    int counter;
} shared;

int main() {
    pthread_t tid1, tid2;
    Pthread_create(&tid1, NULL,
                   count, NULL);
    Pthread_create(&tid2, NULL,
                   count, NULL);
    if (shared.counter != NITERS*2)
        printf("BOOM! counter=%d\n",
               shared.counter);
    else
        printf("OK counter=%d\n",
               shared.counter);
}
```

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```
/* thread routine */
void *count(void *arg) {
    int i, val;

    for (i=0; i<NITERS; i++) {
        val = shared.counter;
        printf("%d: %d\n",
               (int)pthread_self(),
               val);
        shared.counter = val + 1;
    }
    return NULL;
}
```

### Key point:

“struct shared” is visible to all threads.

“i” and “val” are visible only to the count thread.

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## Running badcnt.c

### Output of run 1

```
1025: 0
1025: 1
1025: 2
...
1025: 997
1025: 998
1025: 999
2050: 969
2050: 970
2050: 971
...
2050: 1966
2050: 1967
2050: 1968
BOOM! counter=1969
```

### Output of run 2

```
1025: 0
1025: 1
1025: 2
...
1025: 997
1025: 998
1025: 999
2050: 712
2050: 713
2050: 714
...
2050: 1709
2050: 1710
2050: 1711
BOOM! counter=1712
```

### Output of run 3

```
1025: 0
1025: 1
1025: 2
...
1025: 997
1025: 998
1025: 999
2050: 1000
2050: 1001
2050: 1002
...
2050: 1997
2050: 1998
2050: 1999
OK counter=2000
```

So what's the deal?  
We must synchronize concurrent accesses to shared thread data  
(the topic of our next lecture)

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