

Unbounded, Fully Symbolic Model Checking of Timed Automata using Boolean Methods

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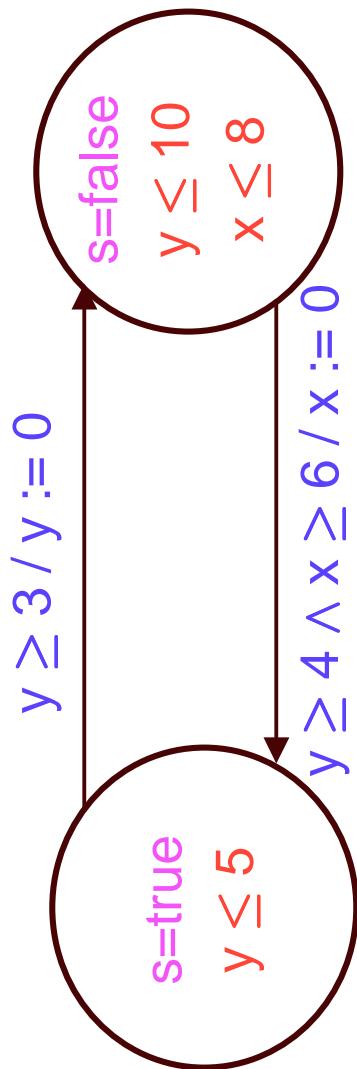
Verifying Timed Embedded Systems

- Many **embedded systems** are **real-time**
 - E.g., drive-by-wire systems in automobiles
 - **Confidence in system reliability is increased by verification of system models**
 - **Model Checking has been successfully used for verifying finite-state models**
- ```
graph LR; Model --> MC[Model Checker]; Property --> MC; MC --> Yes[Yes, model satisfies property]; MC --> No[No, here's a counterexample]
```
- **However, the same level of success has eluded model checking of real-time models**
    - State space contains both continuous and discrete parts
    - Hard to find a compact representation that combines both parts

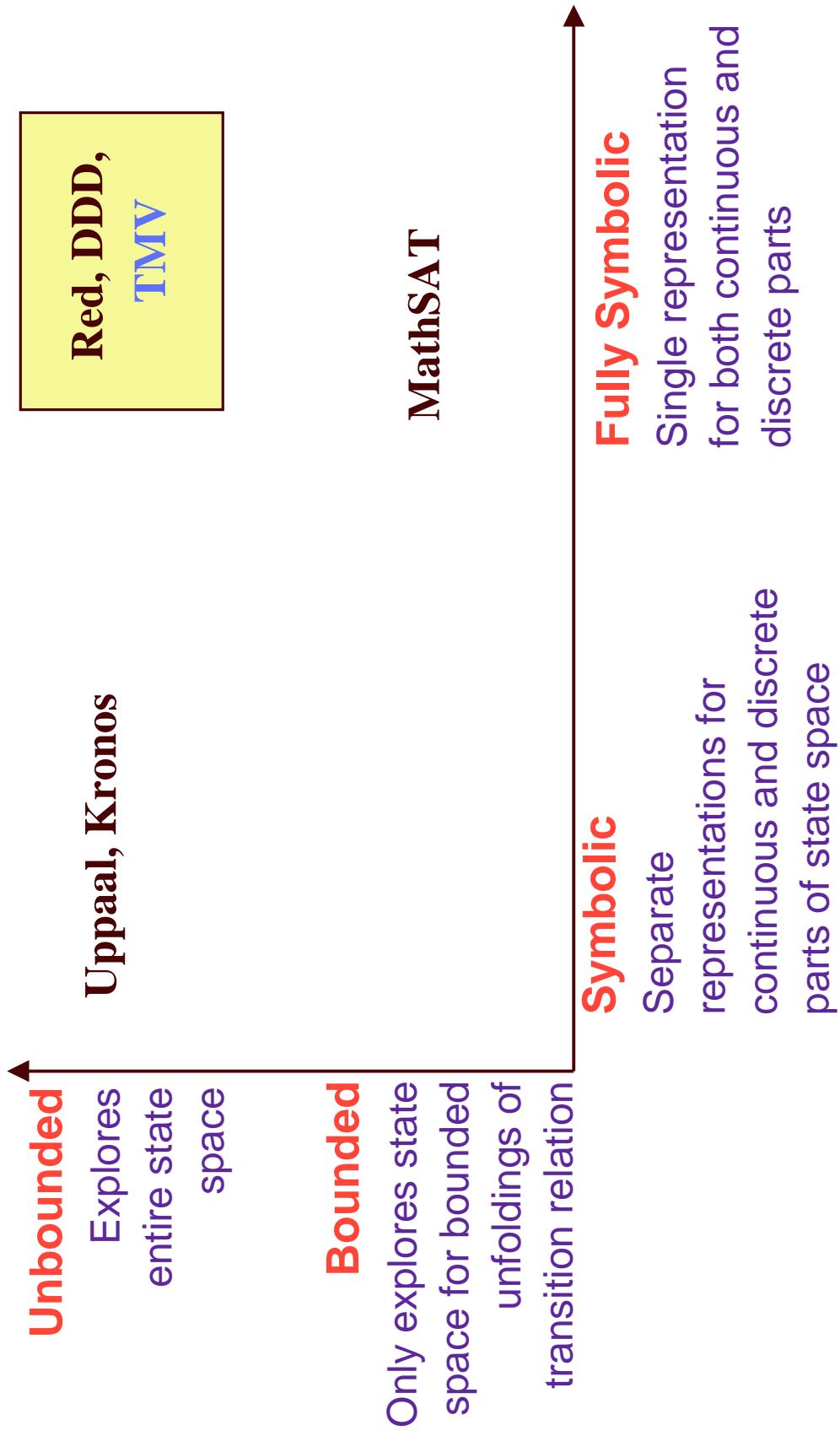
# Timed Automata

Alur, Courcoubetis, & Dill, '90

- A modeling formalism for timed systems
- Generalization of finite automaton with:
  - Non-negative real-valued clock variables
  - Constraints on clocks as guards on states and transitions



# Timed Model Checking Taxonomy



# Unbounded, Fully Symbolic Model Checking

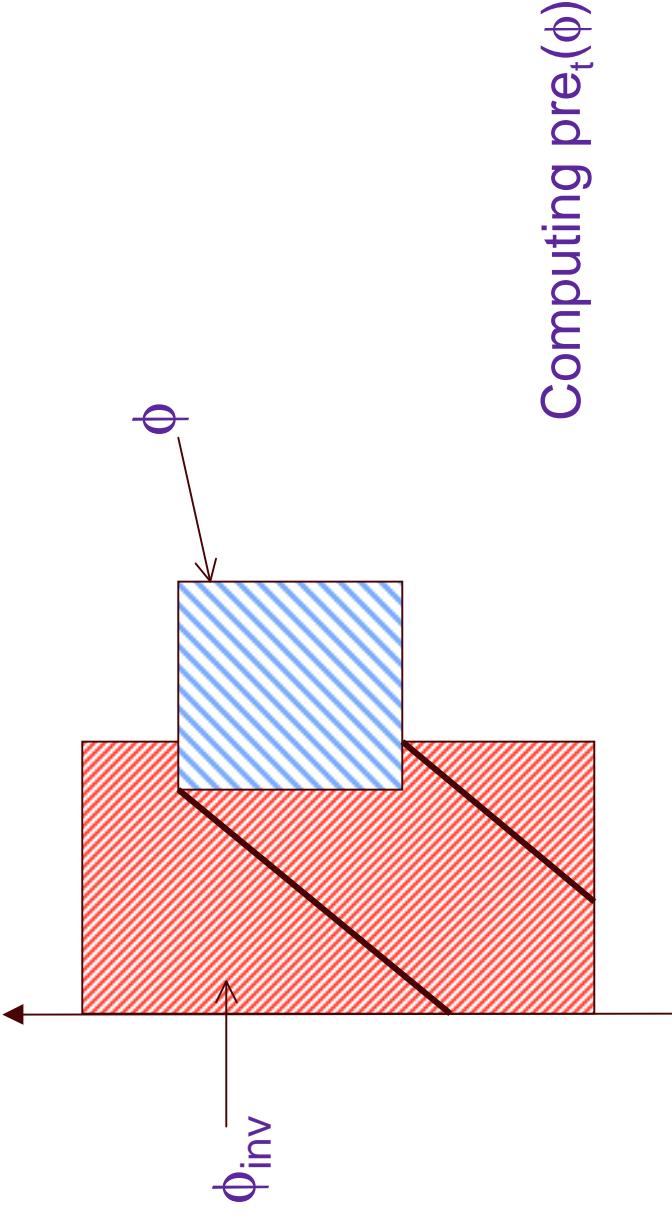
Henzinger, Nicollin, Sifakis, Yovine '94

- **Set of states represented as a formula  $\phi$  in separation logic (SL)**
  - Boolean Combinations ( $\wedge, \vee, \neg$ ) of
    - Boolean variables:  $e_i$
    - Separation Predicates:  $x_i \geq x_j + c, x_i > x_j + c$ 
      - » Also called “difference-bound” or “gap-order” constraints
  - 0 represented as special variable  $x_0$
- **Properties are in Timed CTL\***
- **Two kinds of TCTL\* formulas:**
  - **Reachability properties: Safety and bounded liveness**
    - » E.g. AG (file requested  $\rightarrow$  AF  $\leq_5$  (file received))
  - **Non-reachability properties: Unbounded liveness**
    - » E.g. EG . z:= 0 . F (z = 1) [non-zoneness]

# Pre Operator for Model Checking

- Two ways to reach a set of states  $\phi$ :
  - Let time elapse
    - Only clock variables change, discrete variables remain unchanged
  - Make a discrete transition
    - Some clock variables reset, all others unchanged
    - Discrete state changes as per transition relation
- Pre Operator can be written as
$$\text{pre}(\phi) \triangleq \text{pre}_d(\phi) \vee \text{pre}_t(\phi)$$
  - $\text{pre}_d(\phi)$  is the same as in Boolean model checking
  - $\text{pre}_t(\phi)$  is expressed in Quantified Separation Logic (QSL)

# Timed Pre Operator in QSL



- $\text{pre}_t(\phi) \triangleq \exists \delta \{ \delta \leq x_0 \wedge \phi[\delta / x_0] \wedge \forall \varepsilon (\delta \leq \varepsilon \leq x_0 \wedge \phi_{\text{inv}}[\varepsilon / x_0]) \}$

- $\phi_{\text{inv}}$  is the conjunction of all state guards
- Need quantifier elimination procedure for QSL

# **QSL Quantifier Elimination**

- **Start with QSL formula  $\omega$ , where  $\omega \triangleq \exists X_a \cdot \phi$** 
  - To handle  $\forall X_a \cdot \phi$ , start with  $\exists X_a \cdot \neg \phi$ , and negate the result
- **Quantifier elimination done in 3 phases:**
  1. Translate  $\omega$  to another QSL formula  $\omega'$  where:
    - $\omega'$  has quantifiers only over Boolean variables
    - $\omega$  is equivalent to  $\omega'$
  2. Encode  $\omega'$  as a QBL formula and **eliminate Boolean quantifiers**
  3. Translate the result back to SL
- **Benefit of this method**
  - Unlike other methods, avoids translation to DNF

# Quantifier Elimination Phase 1

Input  $\omega \triangleq \exists x_3 \cdot (x_1 \geq x_3 \vee x_3 \geq x_1+2) \wedge x_0 \geq x_3 - 5 \wedge x_3 \geq x_2$



Boolean encoding  $\phi_{\text{bool}}$

$$(e_{1,3}^{\geq,0} \vee e_{3,1}^{\geq,2}) \wedge e_{0,3}^{\geq,-5} \wedge e_{3,2}^{\geq,0}$$



Transitivity constraints  $\phi_{\text{cons}}$

$$\begin{aligned} (e_{1,3}^{\geq,0} \wedge e_{3,2}^{\geq,0}) &\Rightarrow (x_1 \geq x_2) \\ \wedge (e_{3,1}^{\geq,2} \wedge e_{0,3}^{\geq,-5}) &\Rightarrow (x_0 \geq x_1-3) \\ \wedge (e_{0,3}^{\geq,-5} \wedge e_{3,2}^{\geq,0}) &\Rightarrow (x_0 \geq x_2-5) \end{aligned}$$



Generate QSL formula  $\omega'$

$$\exists e_{1,3}^{\geq,0}, e_{3,1}^{\geq,2}, e_{0,3}^{\geq,-5}, e_{3,2}^{\geq,0}. [\phi_{\text{bool}} \wedge \phi_{\text{cons}}]$$

# Quantifier Elimination Phase 2 & 3

Generate QBL formula  $\rho$  from  $\omega'$

$$\exists \mathbf{e}_{1,3}^{\geq,0}, \mathbf{e}_{3,1}^{\geq,2}, \mathbf{e}_{0,3}^{\geq,-5}, \mathbf{e}_{3,2}^{\geq,0}.$$
$$[\phi_{\text{bool}} \wedge (\mathbf{e}_{1,3}^{\geq,0} \wedge \mathbf{e}_{3,2}^{\geq,0} \Rightarrow \mathbf{e}_{1,2}^{\geq,0}) \wedge$$
$$\underline{(\mathbf{e}_{3,1}^{\geq,2} \wedge \mathbf{e}_{0,3}^{\geq,-5} \Rightarrow \mathbf{e}_{0,1}^{\geq,-3})} \wedge (\mathbf{e}_{0,3}^{\geq,-5} \wedge \mathbf{e}_{3,2}^{\geq,0}) \Rightarrow \mathbf{e}_{0,2}^{\geq,-5}]$$



Eliminating quantifiers from  $\rho$  yields

$$(\mathbf{e}_{1,2}^{\geq,0} \wedge \mathbf{e}_{0,2}^{\geq,-5}) \vee (\mathbf{e}_{0,1}^{\geq,-3} \wedge \mathbf{e}_{0,2}^{\geq,-5})$$



Translating back to separation logic

$$(x_1 \geq x_2 \wedge x_0 \geq x_2 - 5) \vee (x_0 \geq x_1 - 3 \wedge x_0 \geq x_2 - 5)$$

# Special Class of QSL formulas

- Consider QSL formulas of the form:

$$\exists \varepsilon \cdot \{ \varepsilon \leq x_0 \wedge \phi [\varepsilon / x_0] \}$$

- Recall that  $x_0$  stands for 0

- We can do quantifier elimination more efficiently, generating fewer quantified Boolean variables

- Can similarly handle  $\exists \varepsilon \cdot \{ \varepsilon \geq x_0 \wedge \phi [\varepsilon / x_0] \}$

- Half of all quantifier elimination operations
  - Experimentally, leads to 10X-20X speedup

# Preliminary Results

- Fischer's timed mutual exclusion protocol, for increasing numbers of processes
- Results for non-reachability formula (non-zoneness)
  - Timed Model Verifier (TMV): Our model checker
    - Uses a BDD package (CUDD) as a QBL solver
    - Kronos & Red are the only other model checkers that can handle non-reachability properties

| Number of Processes | Kronos Time (sec.) | Red Time (sec.) | TMV Time (sec.) | TMV (peak nodes) |
|---------------------|--------------------|-----------------|-----------------|------------------|
| 3                   | 0.03               | 0.28            | 0.24            | 28               |
| 4                   | 0.23               | 1.30            | 0.44            | 39               |
| 5                   | 1.98               | 5.05            | 0.80            | 54               |
| 6                   | *                  | 17.80           | 2.15            | 69               |
| 7                   | *                  | 57.95           | 6.61            | 88               |

# Publications & Future Work

- **Work will appear at CAV 2003**
  - Details in technical report CMU-CS-03-117
- **Ongoing & Future Work:**
  - Using a SAT-based QBL solver
  - Improving current BDD-based implementation
  - Applications to real-world benchmarks
  - Investigating other applications
    - Convergence checking for bounded model checking of timed automata
    - Theorem proving
    - Hybrid systems