

# No quiz today!

# Randomized Algorithms - 2



#### **BLOOM FILTERS - RECAP**

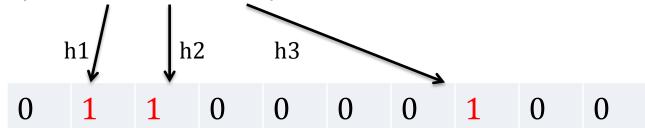


- Interface to a Bloom filter
  - BloomFilter(int maxSize, double p);
  - void bf.add(String s); // insert s
  - bool bd.contains(String s);
    - // If s was added return true;
    - // else with probability at least 1-p return false;
    - // else with probability at most p return true;
  - I.e., a noisy "set" where you can test membership (and that's it)

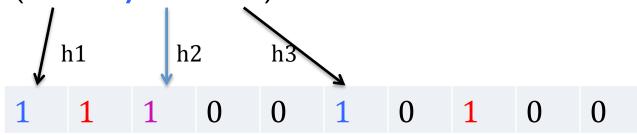




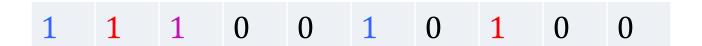
bf.add("fred flintstone"):



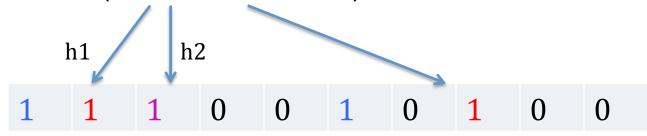
bf.add("barney rubble"):



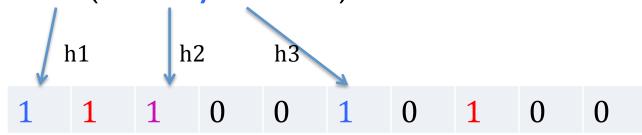




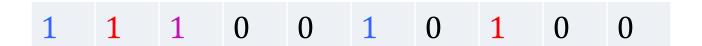
bf.contains ("fred flintstone"):



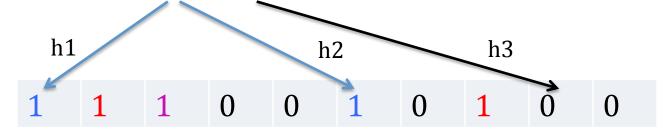
bf.contains("barney rubble"):



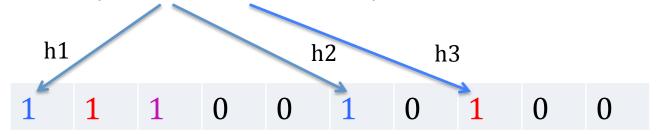




bf.contains("wilma flintstone"):



bf.contains("wilma flintstone"):





#### **Bloom filters - recap**

- An implementation
  - Allocate M bits, bit[0]...,bit[1-M]
  - Pick K hash functions hash(1,2),hash(2,s),....
    - E.g: hash(i,s) = hash(s+ randomString[i])
  - To add string s:
    - For i=1 to k, set bit[hash(i,s)] = 1
  - To check contains(s):
    - For i=1 to k, test bit[hash(i,s)]
    - Return "true" if they're all set; otherwise, return "false"
  - M and K
    - set carefully to obtain right false positive rate
- Sample code and sample applications...



# THE COUNT-MIN SKETCH: RECAP

#### Bloom Filter -> Count-min sketch

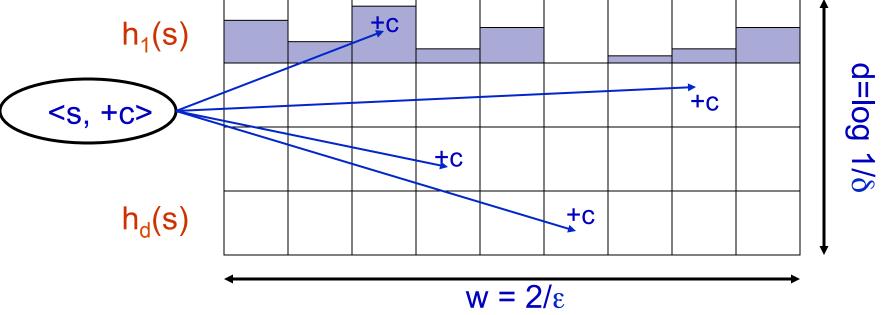


- An implementation
  - Allocate a matrix CM with d rows, w columns
  - Pick d hash functions  $h_1(s), h_2(s),...$
  - To increment counter A[s] for s by c
    - For i=1 to d, set CM[i, hash(i,s)] += c
  - To retrieve value of A[s]:
    - For i=1 to d, retrieve M[i, hash(i,s)]
    - Return minimum of these values
  - Similar idea as Bloom filter:
    - if there are *d* collisions, you return a value that's too large; otherwise, you return the correct value.

Question: what does this look like if d=1?

#### CM Sketch Structure





- Each string is mapped to one bucket per row
- Estimate A[j] by taking  $\min_{k} \{ CM[k,h_{k}(j)] \}$
- Errors are always over-estimates i.e. with prob >  $1-\delta$
- Analysis:  $d=\log 1/\delta$ ,  $w=2/\epsilon \rightarrow error$  is usually less than  $\epsilon ||A||_1$



#### **CM Sketch Guarantees**



- [Cormode, Muthukrishnan' 04] CM sketch guarantees approximation error on point queries less than ε||A||<sub>1</sub> in space O(1/ε log 1/δ)
- CM sketches are also accurate for skewed values---i.e.,
   only a few entries s with large A[s]
  - "Finding heavy hitters"
- Application:
  - finding counts for words x,y that frequently co-occur →
     compute "semantic orientation" of words
  - some others later on
- A disadvantage:
  - CM is harder to tune than Bloom filters





# LOCALITY SENSITIVE HASHING (LSH)





Wait, did he say locality sensitive hash browns?





#### LSH: key ideas

- Goal:
  - map feature vector x to bit vector bx
  - ensure that bx preserves "similarity"

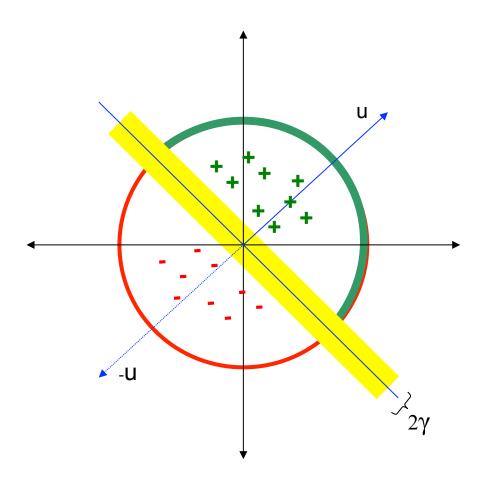


# **Random Projections**



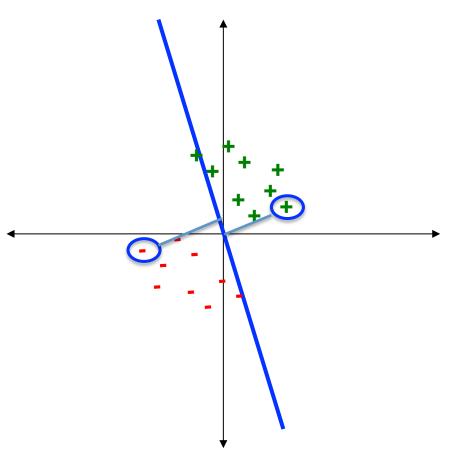


## Random projections





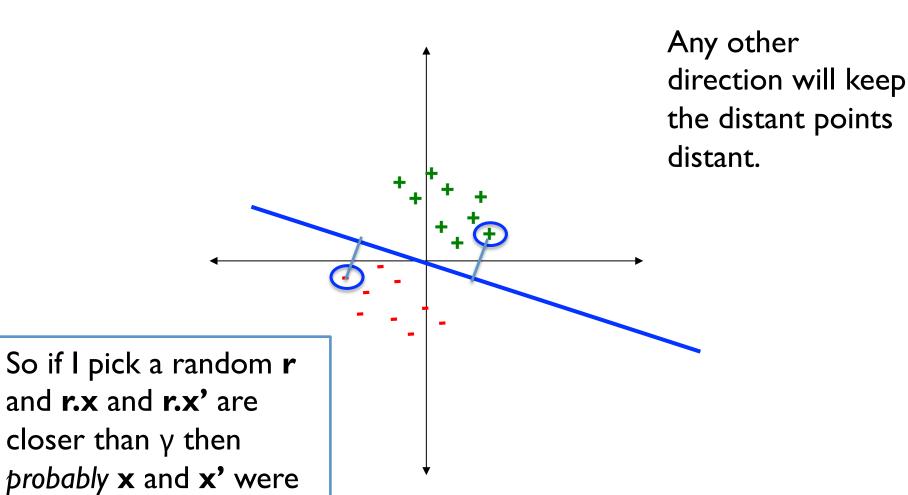
## **Random projections**



To make those points "close" we need to project to a direction orthogonal to the line between them



#### Random projections



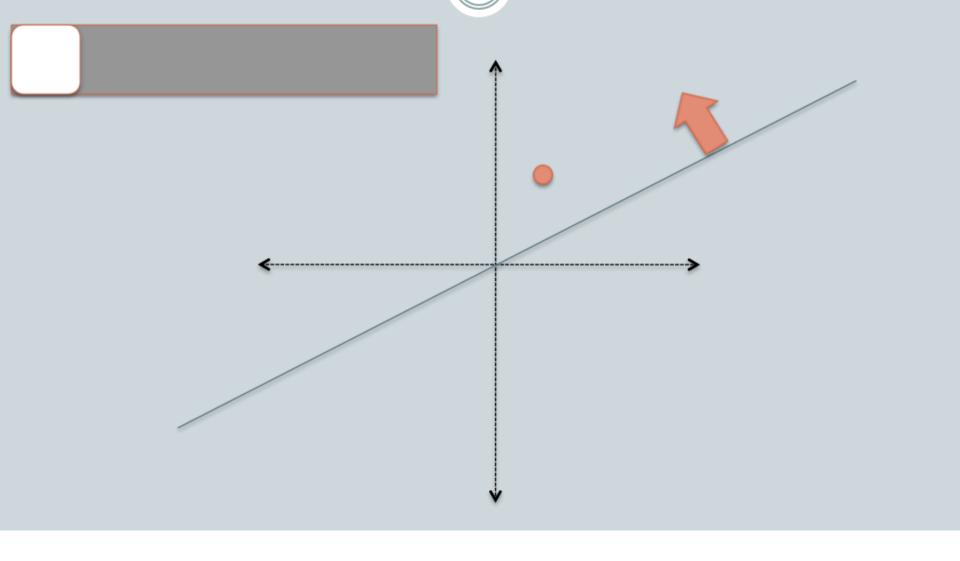
close to start with.

19

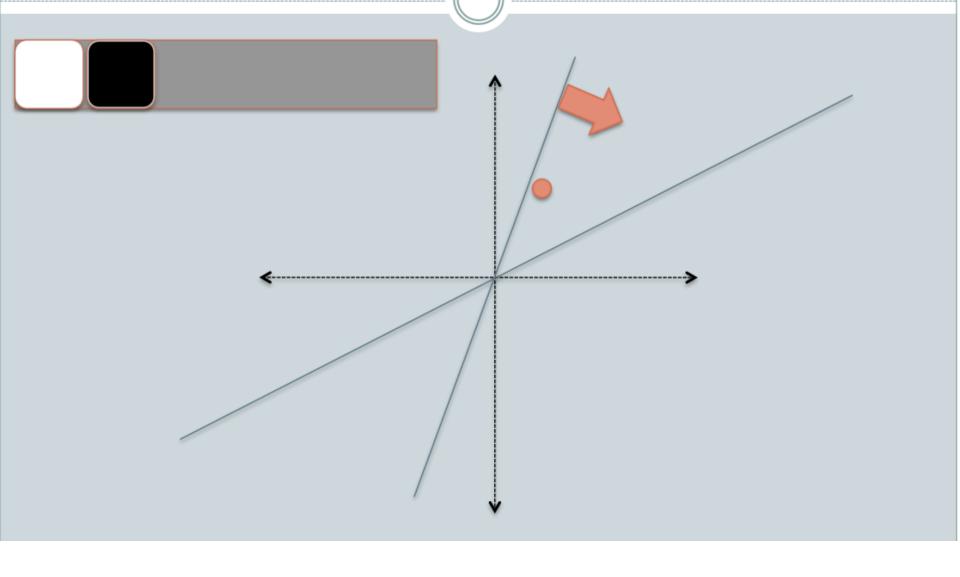


#### LSH: key ideas

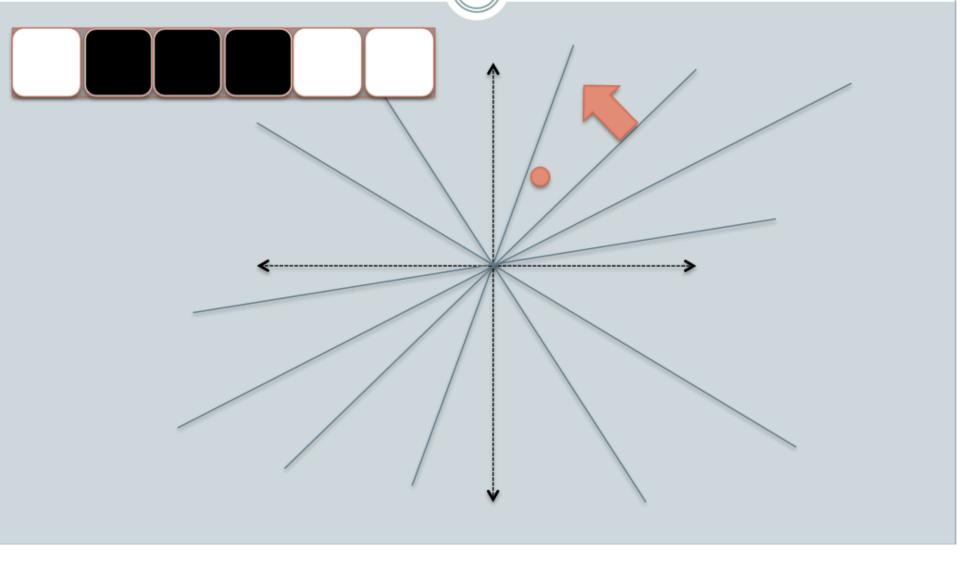
- Goal:
  - map feature vector x to bit vector bx
  - ensure that bx preserves "similarity"
- Basic idea: use random projections of x
  - Repeat many times:
    - Pick a random hyperplane r by picking random weights for each feature (say from a Gaussian)
    - Compute the inner product of r with x
    - Record if x is "close to"  $r(r.x \ge 0)$ 
      - the next bit in bx
    - Theory says that is x' and x have small cosine distance then bx and bx' will have small Hamming distance



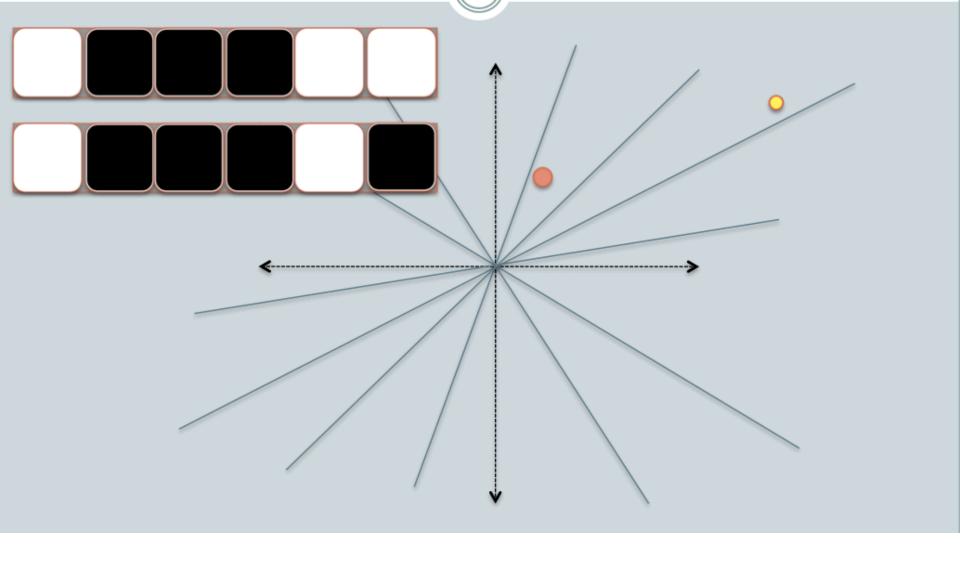
[Slides: Ben van Durme]



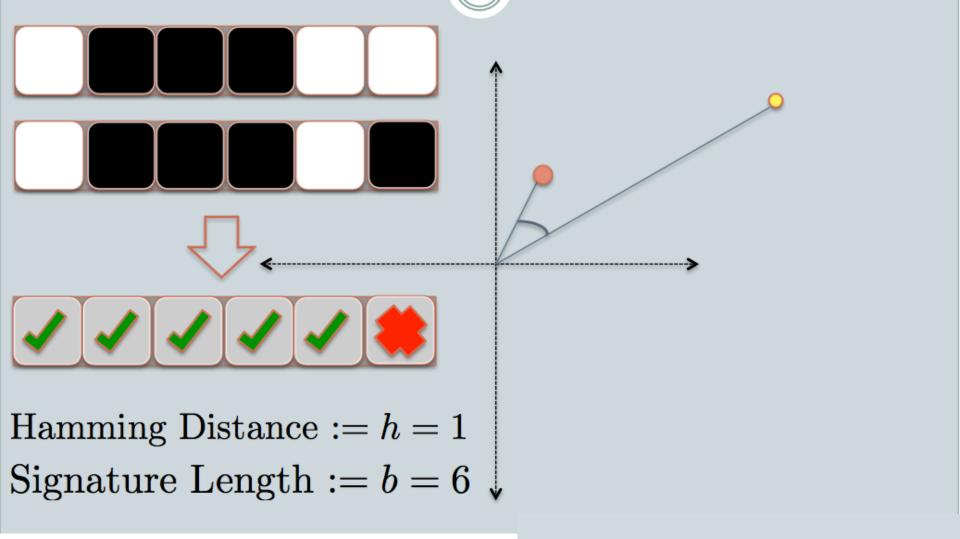
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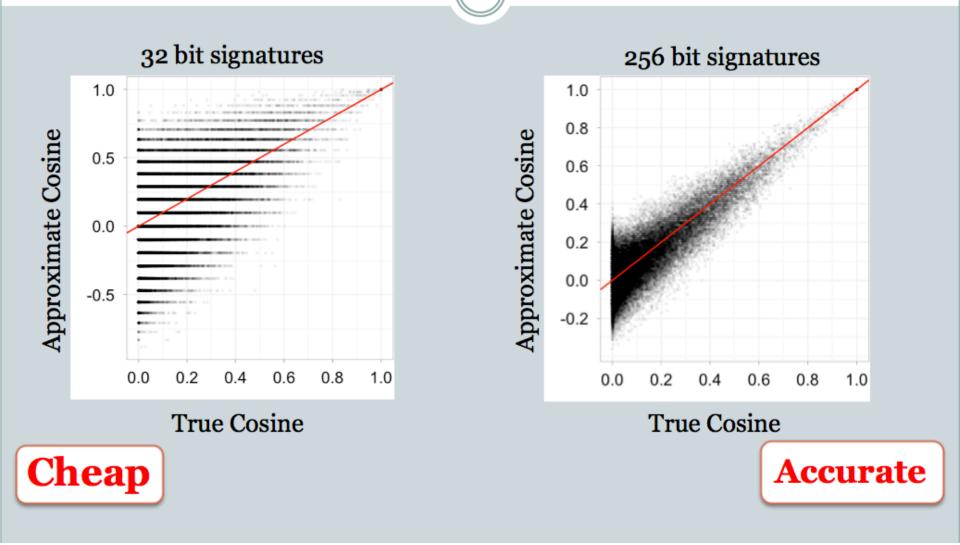
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$$\cos(\theta) pprox \cos(rac{h}{b}\pi)$$
[Slides: Ben van Durme]  $\frac{1}{6}\pi$ )
$$= \cos(rac{h}{b}\pi)$$



[Slides: Ben van Durme]



#### LSH applications

- Compact storage of data
  - and we can still compute similarities
- LSH also gives very fast approximations:
  - approx nearest neighbor method
    - just look at other items with **bx'=bx**
    - also very fast nearest-neighbor methods for Hamming distance
  - very fast clustering
    - cluster = all things with same **bx** vector

# Online Generation of Locality Sensitive Hash Signatures

Benjamin Van Durme and Ashwin Lall







DENISON UNIVERSITY



#### LSH algorithm

- Naïve algorithm:
  - Initialization:
    - For i=1 to outputBits:
      - For each feature f:» Draw r(f,i) ~ Normal(0,1)
  - -Given an instance x
    - For i=1 to outputBits:

```
LSH[i] = sum(\mathbf{x}[f]*r[i,f]) for f with non-zero weight in \mathbf{x}) > 0 ? 1 : 0
```

Return the bit-vector LSH



### LSH algorithm

- But: storing the *k classifiers* is expensive in high dimensions
  - -For each of 256 bits, a dense vector of weights for every feature in the vocabulary
- Storing seeds and random number generators:
  - -Possible but somewhat fragile



#### LSH: "pooling" (van Durme)

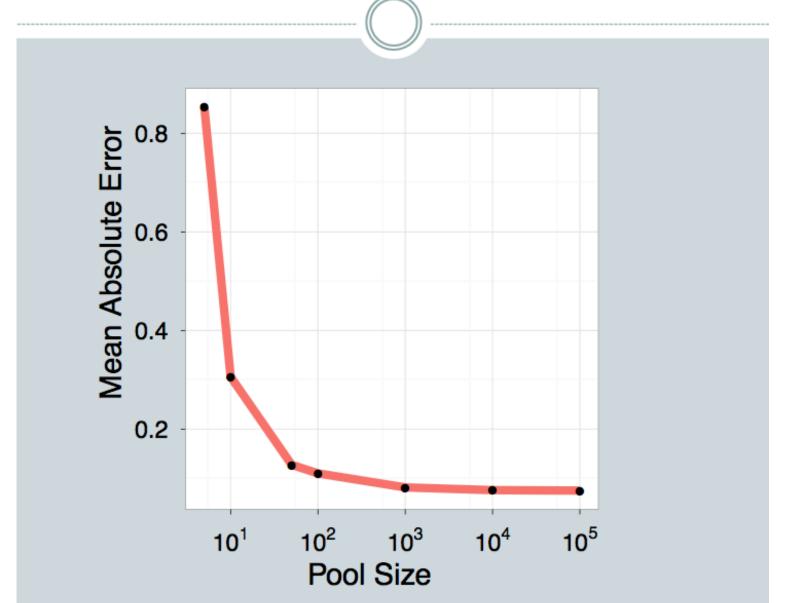
- Better algorithm:
  - Initialization:
    - Create a pool:
      - Pick a random seed s
      - For i=1 to poolSize:» Draw pool[i] ~ Normal(0,1)
    - For i=1 to outputBits:
      - Devise a random hash function hash(i,f):» E.g.: hash(i,f) = hashcode(f) XOR randomBitString[i]
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LSH[i] = sum(
x[f] * pool[hash(i,f) % poolSize] for f in x) > 0 ? 1 : 0
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## The Pooling Trick







## LSH: key ideas: pooling

- Advantages:
  - with pooling, this is a compact re-encoding of the data
    - you don't need to store the r's, just the pool

# Locality Sensitive Hashing (LSH) in an On-line Setting

# LSH: key ideas: online computation

- Common task: distributional clustering
  - for a word w, x(w) is sparse vector of words that co-occur with w
  - -cluster the w's

$$\vec{v} \in \mathbb{R}^d$$



$$\vec{r_i} \sim N(0,1)^d$$

$$h_i(\vec{v}) = \begin{cases} 1 & \text{if } \vec{v} \cdot \vec{r_i} \ge 0, \\ 0 & \text{otherwise.} \end{cases}$$

if 
$$\vec{v} = \Sigma_j \vec{v}_j$$
  
then  $\vec{v} \cdot \vec{r}_i = \Sigma_j \vec{v}_j \cdot \vec{r}_i$ 

Break into local products

Online 
$$h_{it}(\vec{v}) = \begin{cases} 1 & \text{if } \Sigma_j^t \vec{v}_j \cdot \vec{r}_i \ge 0, \\ 0 & \text{otherwise.} \end{cases}$$

### **Algorithm 1** Streaming LSH Algorithm



#### **Parameters:**

- m: size of pool
- d: number of bits (size of resultant signature)
- s: a random seed
- $h_1, ..., h_d$ : hash functions mapping  $\langle s, f_i \rangle$  to  $\{0, ..., m-1\}$ INITIALIZATION:
- 1: Initialize floating point array  $P[0, \ldots, m-1]$
- 2: Initialize H, a hashtable mapping words to floating point arrays of size d
- 3: **for**  $i := 0 \dots m 1$  **do**
- 4: P[i] := random sample from N(0, 1), using s as seed

#### ONLINE:

- 1: for each word w in the stream do
- 2: **for** each feature  $f_i$  associated with w **do**
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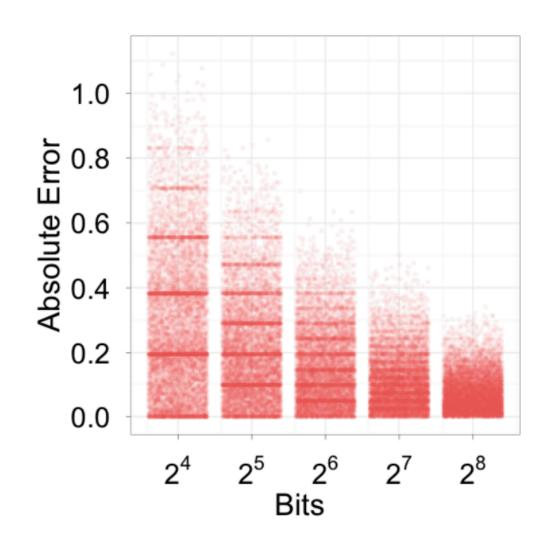
#### SIGNATURE COMPUTATION:

- 1: for each  $w \in H$  do
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- Corpus: 700M+ tokens, 1.1M distinct bigrams
- For each, build a feature vector of words that co-occur near it, using on-line LSH
- Check results with 50,000 actual vectors





### Closest based on true cosine

#### London

Milan<sub>.97</sub>, Madrid<sub>.96</sub>, Stockholm<sub>.96</sub>, Manila<sub>.95</sub>, Moscow<sub>.95</sub> ASHER<sub>0</sub>, Champaign<sub>0</sub>, MANS<sub>0</sub>, NOBLE<sub>0</sub>, come<sub>0</sub> Prague<sub>1</sub>, Vienna<sub>1</sub>, suburban<sub>1</sub>, synchronism<sub>1</sub>, Copenhagen<sub>2</sub>

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Closest based on 32 bit sig.'s



## Locality Sensitive Hashing (LSH) and Pooling Random Values



### LSH algorithm

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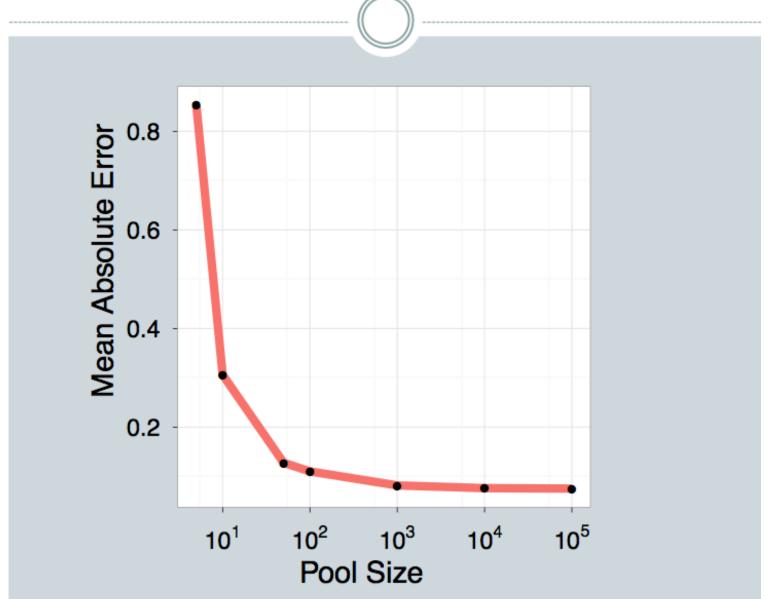
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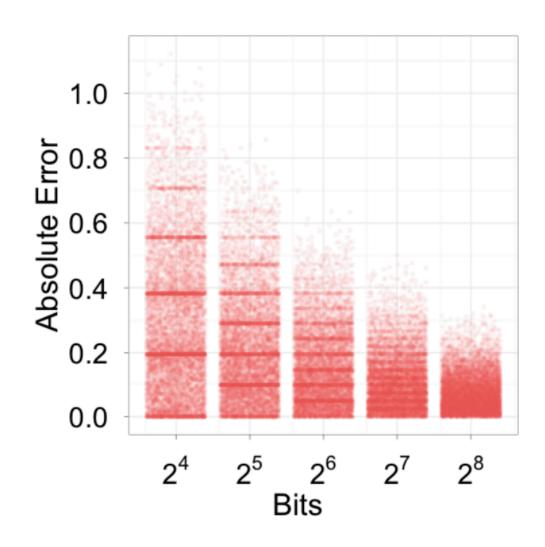
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### Points to review

- APIs for:
  - Bloom filters, CM sketch, LSH
- Key applications of:
  - Very compact noisy sets
  - Efficient counters accurate for *large* counts
  - Fast approximate cosine distance
- Key ideas:
  - Uses of hashing that allow collisions
  - Random projection
  - Multiple hashes to control Pr(collision)
  - Pooling to compress a lot of random draws