

Lecture 22: Optimal Set Disjointness lower bound and applications

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1 Recap

- Last class

- $R(DISJ) = \Omega(\sqrt{n})$, where $DISJ(x, y) = \wedge_i NAND(x_i, y_i)$. Achieved this bound by using product distribution.
- Hellinger Distance: $\Delta_{Hel}^2(p, q) = 1 - \sum_x \sqrt{p(x)q(x)}$.
- $\Delta_{Hel}^2(p, q) \leq \Delta_{TV}(p, q) \leq \sqrt{2}\Delta_{Hel}(p, q)$

- Today

- $R(DISJ) = \Omega(n)$

2 $\Omega(n)$ DISJ bound

The high level idea is to find a distribution on the inputs, which gives a distribution on the transcript, and finding a way to get individual NANDs from the transcript.

2.1 Input distribution

The strings $(x_1, y_1) \dots (x_n, y_n)$ will be independent across the n coordinates, but each (x_i, y_i) are correlated.

Let $\sigma \in \{A, B\}^n$.

(x_i, y_i) is sampled independently from η_A if $\sigma_i = A$ and from η_B if $\sigma_i = B$, where:

$$\begin{aligned} \eta_A(1, 0) = \eta_A(0, 0) = 1/2, \eta_A(x, 1) = 0 \\ \eta_B(0, 1) = \eta_B(0, 0) = 1/2, \eta_B(1, x) = 0 \end{aligned}$$

(In a sense, σ_i defines “who is active” for the i th bit.)

2.2 Bounding protocol information

Now suppose a protocol Π communicates with less than δn bits for some constant δ and errs with probability at most $1/2 - \varepsilon$. We can bound $I(X, Y; \Pi) \leq H(\Pi) \leq \delta n$, where we also use Π to refer to the transcript of this protocol. Also, $I(X, Y; \Pi) \geq \sum_1^n I(X_k, Y_k; \Pi)$. Putting these together gives

$$\mathbb{E}_{k \text{ uniform}} [I(X_k, Y_k; \Pi)] \leq \delta$$

So far nothing we have done depends on σ . Since the above is true for fixed σ , it is true for distributional σ . Thus we have

$$\begin{aligned} &\implies \mathbb{E}_{\sigma_{unif}} \mathbb{E}_k I(X_k, Y_k; \Pi) \leq \delta \\ &\implies \mathbb{E}_k \mathbb{E}_{\sigma} I(X_k, Y_k; \Pi) \leq \delta \end{aligned}$$

Thus there is a fixed k such that $\mathbb{E}_{\sigma} I(X_k, Y_k; \Pi) \leq \delta$. We can decompose σ into coordinates; define $\sigma_{-k} := (\sigma_1, \dots, \sigma_{k-1}, \sigma_{k+1}, \dots, \sigma_n)$. Continuing,

$$\begin{aligned} &\implies \mathbb{E}_{\sigma_{-k}} \mathbb{E}_{\sigma_k} I(X_k, Y_k; \Pi) \leq \delta \\ &\implies \text{fixed } \sigma_{-k} \text{ such that } \mathbb{E}_{\sigma_k} I(X_k, Y_k; \Pi) \leq \delta \\ &\implies I(X_k, Y_k; \Pi | \sigma_k = A) + I(X_k, Y_k; \Pi | \sigma_k = B) \leq 2\delta \end{aligned}$$

Intuitively, the protocol does not carry much information about x_k, y_k , which will give a contradiction if we try to compute NAND as the protocol should.

2.3 Computing NAND(x,y)

Alice and Bob receive 1 bit $x, y \in \{0, 1\}$ and want to compute $\text{NAND}(x, y)$ using Π . Set $X_k = x, Y_k = y$, sample X_{-k}, Y_{-k} randomly from $\sigma_{-k}, \eta_A, \eta_B$.

Run Π on (X, Y) and note that $\text{DISJ}(X, Y) = \text{NAND}(x, y)$. By definition of protocol Π , Alice and Bob compute $\text{NAND}(x, y)$ with error at most $1/2 - \epsilon$. Call this whole NAND protocol π .

By what we showed before,

$$\begin{aligned} &I((X_k, Y_k); \pi(X_k, Y_k) | (X_k, Y_k) \sim \eta_A) + I((X_k, Y_k); \pi(X_k, Y_k) | (X_k, Y_k) \sim \eta_B) \leq 2\delta \\ &\implies I(Z; \pi(Z, 0)) + I(Z; \pi(0, Z)) \leq 2\delta \end{aligned}$$

where Z is uniform at random in $\{0, 1\}$.

Recall from Problem Set 1, Problem 6 that

$$I(Z, \pi(Z, 0)) \geq \frac{1}{2} [\Delta_{TV}^2(\pi(Z, 0), \pi(0, 0)) + \Delta_{TV}^2(\pi(Z, 0), \pi(1, 0))]$$

where $\Delta_{TV}(p, q) = \frac{1}{2} \sum_x |p(x) - q(x)| = \max_{S \subseteq \text{supp}(p)} |p(S) - q(S)|$. Coming this with Cauchy-Schwartz and the Triangle Inequality gives

$$\begin{aligned} I(Z; \pi(Z, 0)) + I(Z; \pi(0, Z)) &\geq \frac{1}{2} [\Delta_{TV}^2(\pi(Z, 0), \pi(0, 0)) + \Delta_{TV}^2(\pi(Z, 0), \pi(1, 0)) \\ &\quad + \Delta_{TV}^2(\pi(0, Z), \pi(0, 0)) + \Delta_{TV}^2(\pi(0, Z), \pi(0, 1))] \\ &\geq \frac{1}{8} (\Delta_{TV}(\pi(Z, 0), \pi(0, 0)) + \Delta_{TV}(\pi(Z, 0), \pi(1, 0)) \\ &\quad + \Delta_{TV}(\pi(0, Z), \pi(0, 0)) + \Delta_{TV}(\pi(0, Z), \pi(0, 1))) \\ &\geq \frac{1}{8} [\Delta_{TV}(\pi(0, 0), \pi(1, 0)) + \Delta_{TV}(\pi(0, 0), \pi(0, 1))]^2 \\ &\geq \frac{1}{8} \Delta_{TV}^2(\pi(1, 0), \pi(0, 1)) \end{aligned}$$

Actually, we could have worked directly with the Hellinger distance using:

Exercise: $I(Z, f(Z)) \geq \Delta_{Hel}^2(f(0), f(1))$ where f is any randomized function.

This exercise gives the bound

$$\begin{aligned}
2\delta &\geq I(Z, \pi(Z, 0)) + I(Z, \pi(0, Z)) \\
&\geq \frac{1}{2} \Delta_{Hel}^2(\pi(1, 0), \pi(0, 1)) \\
&= \frac{1}{2} \Delta_{Hel}^2(\pi(0, 0), \pi(1, 1)) \\
&= \frac{1}{4} \Delta_{TV}^2(\pi(0, 0), \pi(1, 1))
\end{aligned}$$

where the last equality is the lemma we showed last class. Now this is interesting because NAND is different on (0, 0) and (1, 1). In particular,

$$\Delta_{TV}(\pi(0, 0), \pi(1, 1)) \geq |\Pr(\pi(0, 0) = 0) - \Pr(\pi(1, 1) = 0)| \geq 2\varepsilon$$

Putting the last few inequalities together gives $2\delta \geq \varepsilon^2 \implies \delta \geq \frac{\varepsilon^2}{2}$. This implies $R_{1/2-\varepsilon}(DISJ) \geq \frac{\varepsilon^2}{2}n$, completing the proof.

In fact, it was recently showed that $R_{1/2-\varepsilon}(DISJ) = \Omega(\varepsilon n)$ (Braverman, Moitra '12)

3 Application: Moments in the streaming model

Setting: We have a sequence a_1, a_2, \dots, a_m . $a_i \in [n]$ arrives as a stream. For all i , $f_i := |\{j \in [m], a_j = i\}|$ (frequency).

Goal: Compute $\max_i f_i$. Not very hard (might want to compute other moments but turns out ∞ moment is hardest).

Challenge: Use as little memory as possible. Obviously we can do it in linear memory, can we do better?

Theorem 1. *Any streaming algorithm needs $\Omega(n)$ memory.*

Proof. We will reduce from DISJ. Given (x, y) to DISJ and streaming algorithm A , we can construct a protocol for computing DISJ:

Alice maps x to the stream $a_x = \{i \mid x_i = 1\}$. She runs A on a_x , and sends the state of A to Bob. Bob continues the execution of A with sequence $b_y = \{i \mid y_i = 1\}$. Then the output $\max_i f_i$ is 1 if $DISJ(x, y) = 1$, and 2 if $DISJ(x, y) = 2$.

The communication cost of this protocol is the memory footprint of A , which must be $\Omega(n)$ by the bound on DISJ. Note that this shows A can't even estimate the answer probabilistically. \square

4 Information Cost

Def: $IC_{ext}(\Pi, \mu) = I_{(X, Y) \sim \mu}(X, Y; \Pi)$, referring to the information cost for an external observer.

We can also define a similar idea about what Alice and Bob learn about each other's input from Π :

Def: $IC(\Pi, \mu) = I(\Pi; Y|X) + I(\Pi; X|Y)$, where $(X, Y) \sim \mu$.