

15-780: Graduate AI

Lecture 4. SAT, Reductions

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Admin

HW1



- *Reminder: HW1 is out*
- *Download from course website*
- *We'll provide hardcopies on request*
- *Questions?*



Review

Proofs in FOL



- *Proof by contradiction*
- *Unification, variable substitutions*
- *First-order resolution & factoring*
- *Above is a sound, complete proof system*
 - *Herbrand universe, propositionalizing*
 - *Lifting lemma*

Variations on FOL & proofs



- *Wh-questions (who killed JR?), answer literals*
- *Equality (paramodulation or axiom schema)*
- *Second-order logic*

Knowledge engineering



- *Hierarchies (isa, partOf), inheritance*
- *Fluents*
- *Frame problem*
- *Debugging*



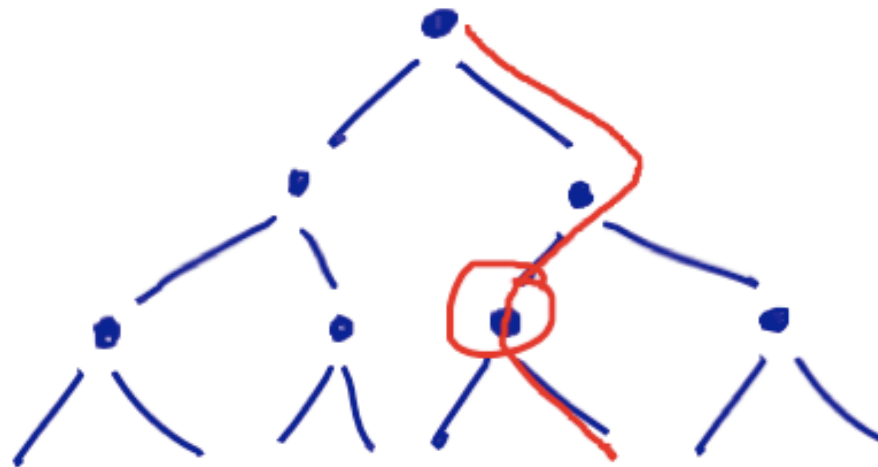
Temporal Logics

QCTL*: a fairly powerful TL



- *Quantified Computation-Tree Logic **
- *FOL + representation of time + quantifiers over time*

Time in QCTL*



- *Statements interpreted relative to a current history and time point (h, w)*
- *E.g., truth of a literal depends on w*

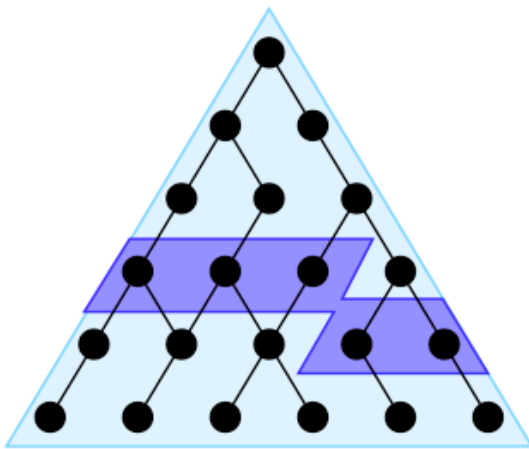
New quantifiers in QCTL*



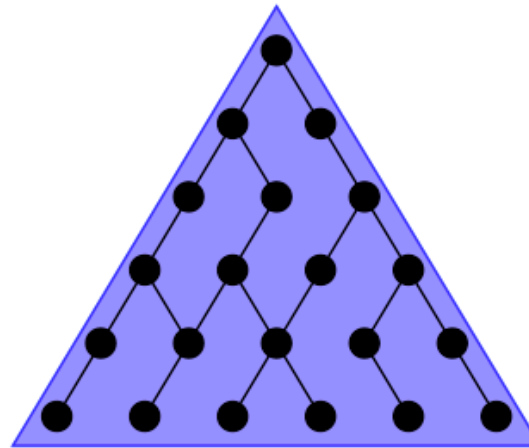
- $A S = \text{“always } S\text{”}$
 - S is true for (h', w) for all h' passing through w
- $P U Q = \text{“}P \text{ until } Q\text{”}$
 - there is some time v in h , with $v > w$, such that P holds for (h, u) for all u with $w < u < v$, and Q holds at (h, v)

Derived quantifiers

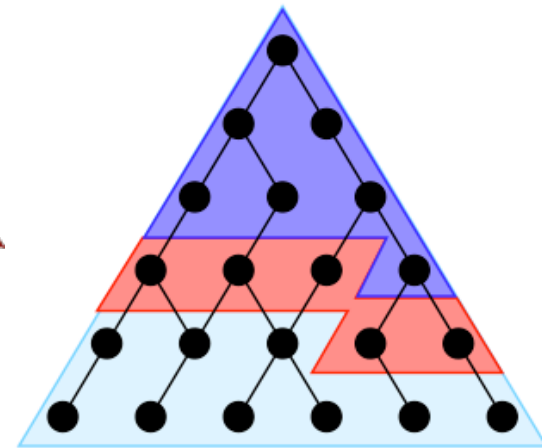
- $F P = \text{“in the future, } P\text{”} = T U P$
 - *also called “finally, P ”*
- $G P = \text{“globally, } P\text{”} = P U F$
- $E P = \text{“possibly, } P\text{”} = \neg A \neg P$
 - *labeled E for existential*



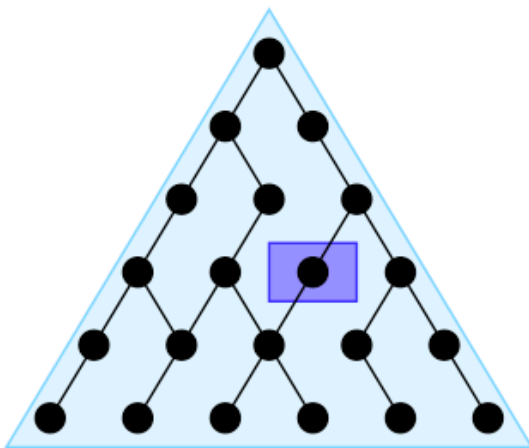
AF **P**



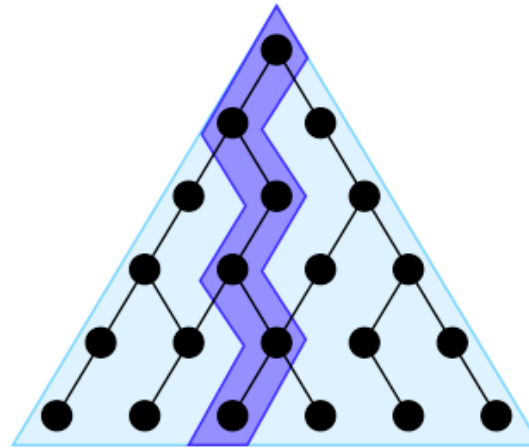
AG **P**



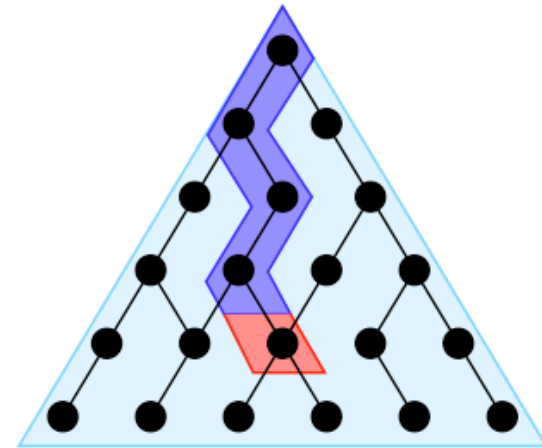
A [**P** **U** **q**]



EF **P**



EG **P**



E [**P** **U** **q**]

image credit: Alessandro Artale

Incompleteness for QCTL*



- *Theorem: the set of valid formulas of QCTL* is not recursively enumerable, even if we restrict to formulas with at most two variables and only unary or 0-ary predicates.*

I Hodgkinson, F Wolter, M Zakharyashev. Decidable and undecidable fragments of first-order branching temporal logics. Proc. 17th Annual IEEE Symposium on Logic in Computer Science (LICS 2002), pp. 393–402.

Intuition



- *The length of a single future is countably infinite, and the set of all futures is uncountably infinite*
- *QCTL* quantifies over uncountable sets*
- *FOL only can quantify over countable sets*
 - *e.g., no FOL translation of AFP*



SAT

Satisfiability



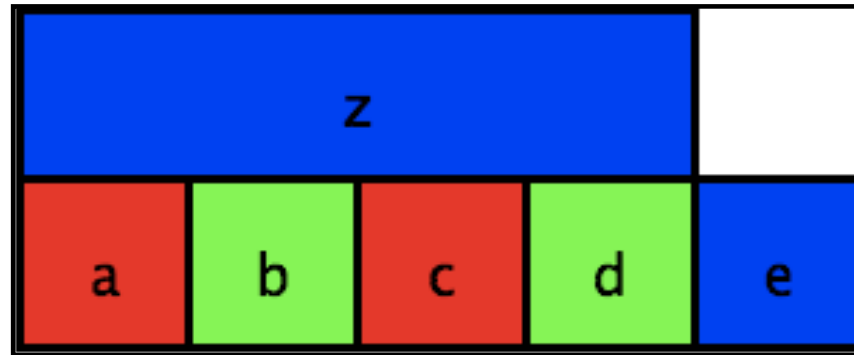
- *SAT is the problem of determining whether a given propositional logic sentence is satisfiable*
- *A **decision problem**: given an instance, answer yes or no*
- *A fundamental problem in CS*

SAT is a general problem



- *Many other useful decision problems reduce to SAT*
- *Informally, if we can solve SAT, we can solve these other problems*
- *So a good SAT solver is a good AI building block*

Example decision problem



- *k-coloring: can we color a map using only k colors in a way that keeps neighboring regions from being the same color?*

Example decision problem



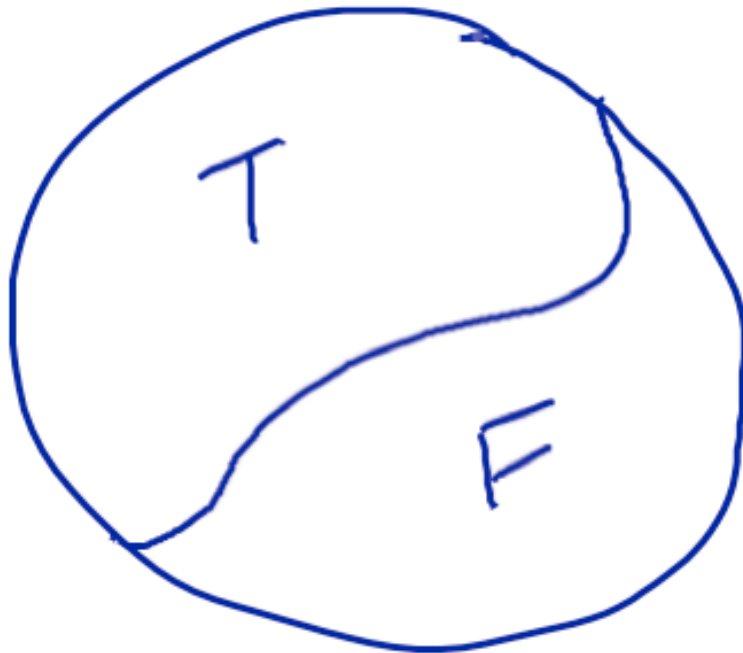
- *Propositional planning: given a list of operators (w/ preconditions, effects), can we apply operators in some order to achieve a desired goal?*
- *Have cake & eat it too example*
- *We'll see later how to represent as SAT*

Reduction

- *Loosely, “A reduces to B” means that if we can solve B then we can solve A*
- *More formally, A, B are decision problems (instances $\mapsto$ truth values)*
- *A reduction is a poly-time function f such that, given an instance a of A*
 - *$f(a)$ is an instance of B, and*
 - *$A(a) = B(f(a))$*

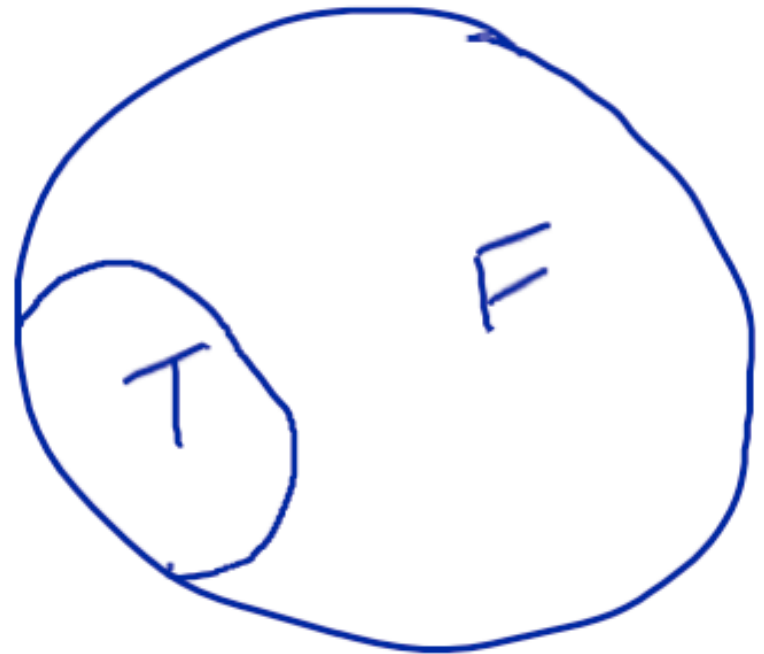
Reduction picture

Problem A



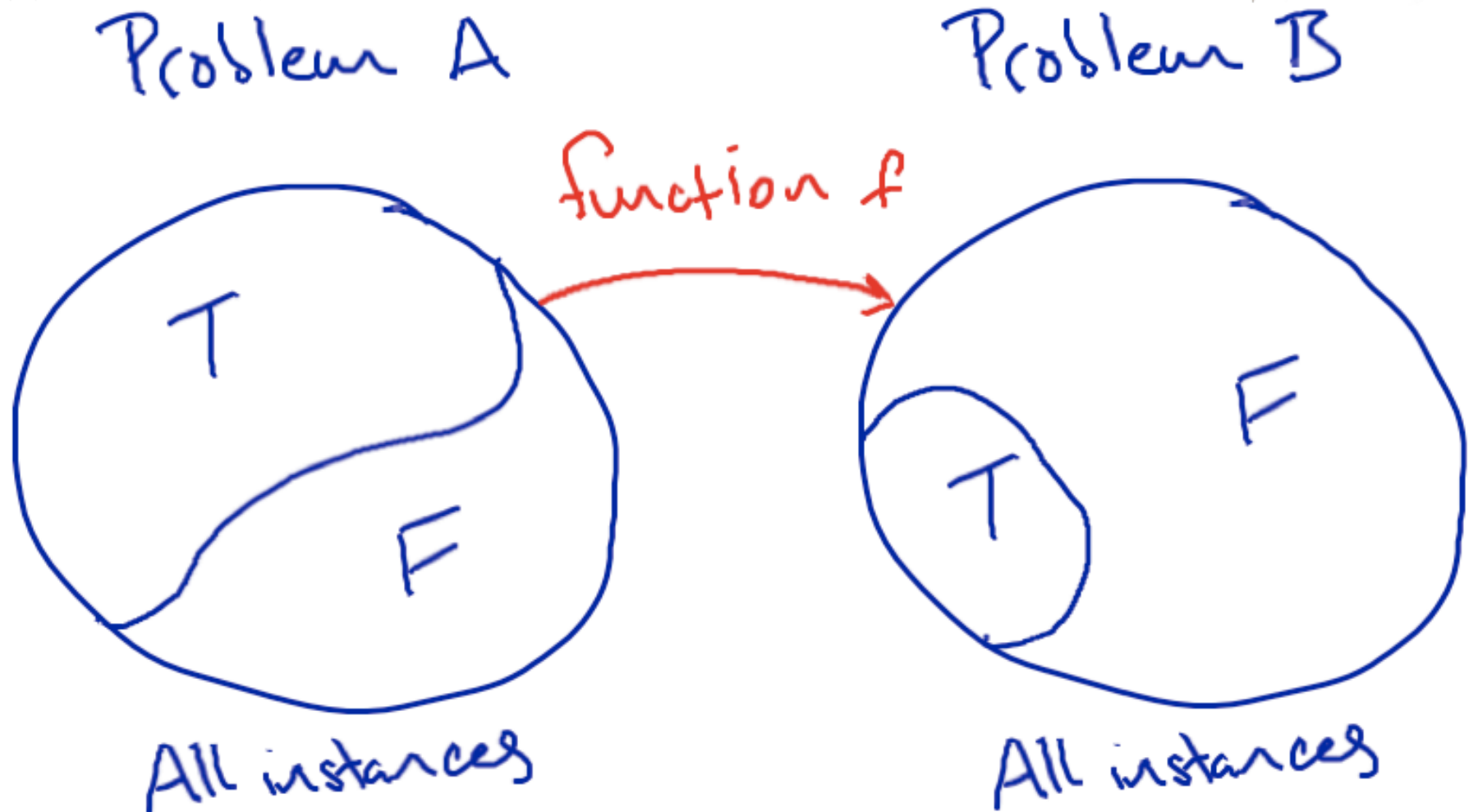
All instances

Problem B

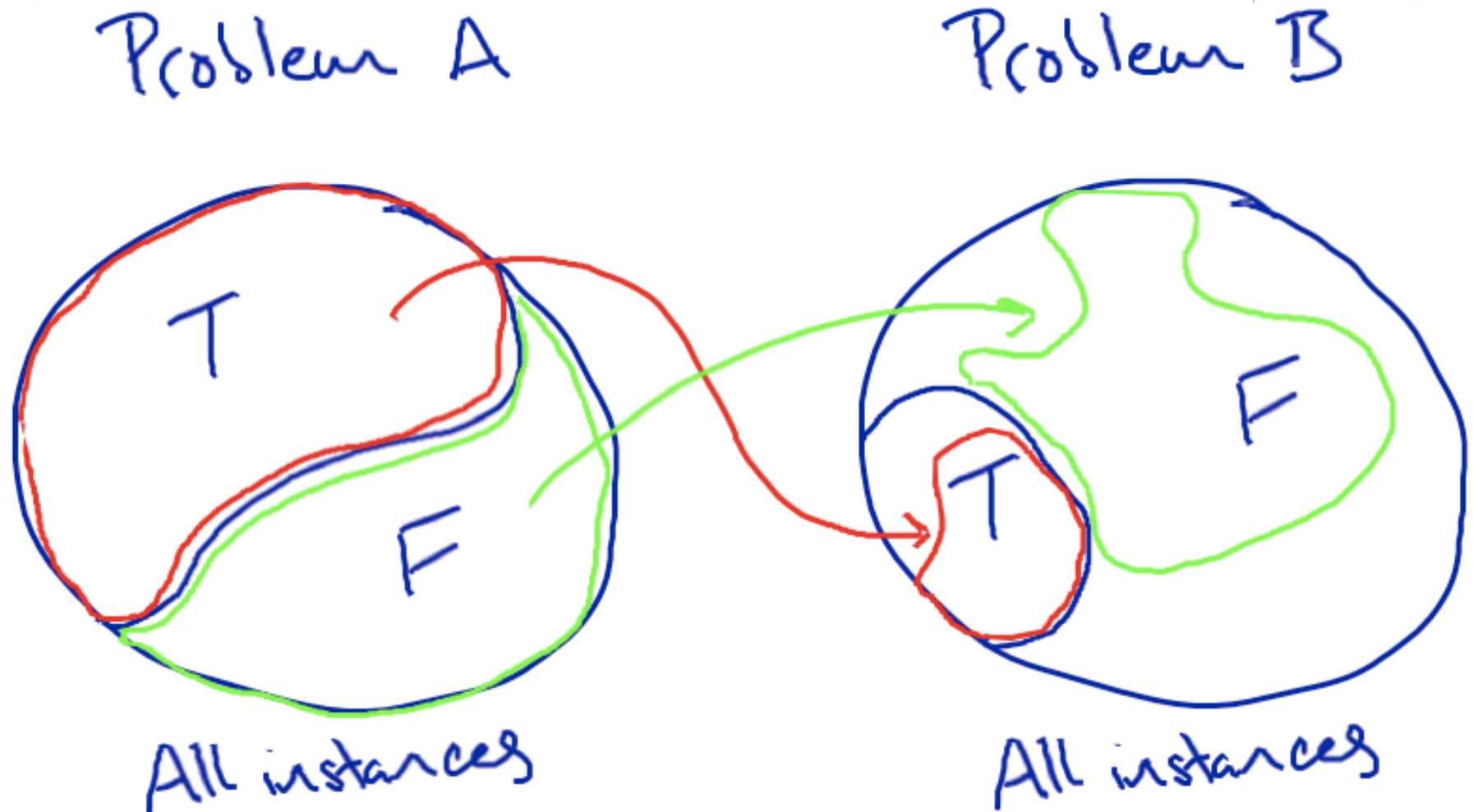


All instances

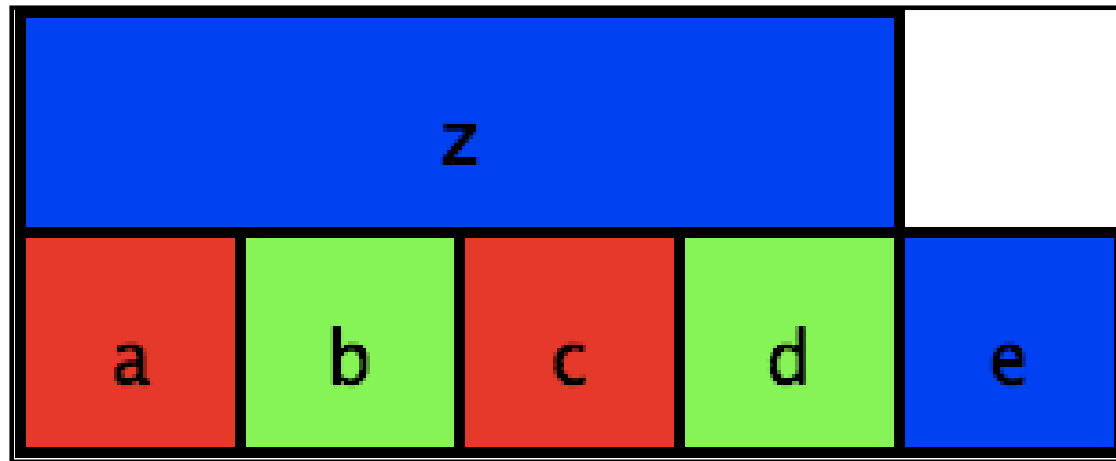
Reduction picture



Reduction picture



Back to example

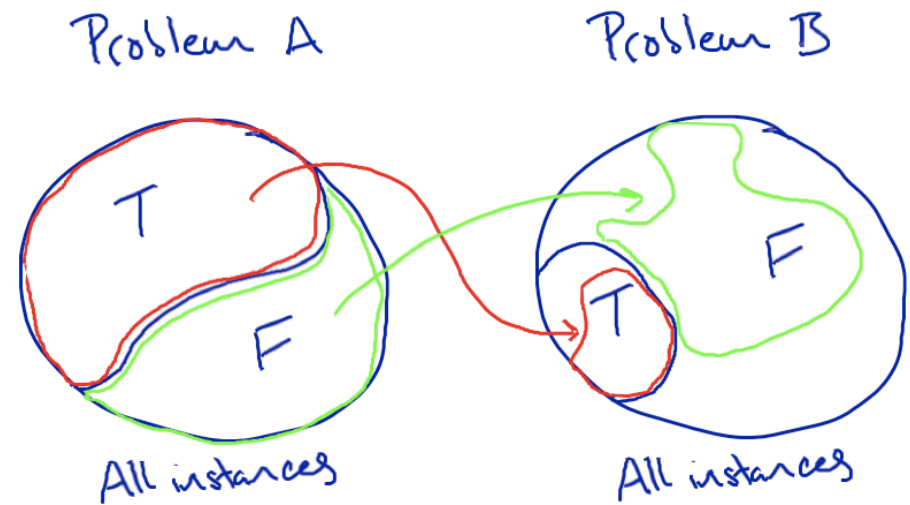


- *Each square must be red, green, or blue*
- *Adjacent squares can't both be red (similarly, green or blue)*

Back to example

- $(a_r \vee a_g \vee a_b) \wedge (b_r \vee b_g \vee b_b) \wedge (c_r \vee c_g \vee c_b) \wedge (d_r \vee d_g \vee d_b) \wedge (e_r \vee e_g \vee e_b) \wedge (z_r \vee z_g \vee z_b)$
- $(\neg a_r \vee \neg b_r) \wedge (\neg a_g \vee \neg b_g) \wedge (\neg a_b \vee \neg b_b)$
- $(\neg a_r \vee \neg z_r) \wedge (\neg a_g \vee \neg z_g) \wedge (\neg a_b \vee \neg z_b)$
- ...

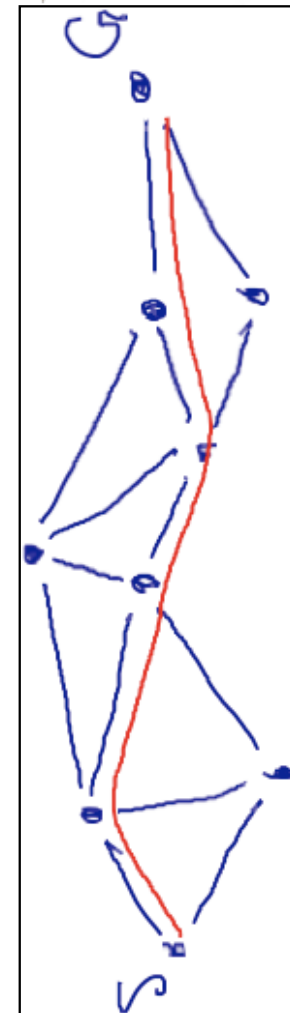
Direction of reduction



- *If A reduces to B:*
 - *if we can solve B, we can solve A*
 - *so B must be at least as hard as A*
- *Trivially, can take an easy problem and reduce it to a hard one*

Not-so-useful reduction

- *Path planning reduces to SAT*
- *Variables: is edge e in path?*
- *Constraints:*
 - *exactly 1 path-edge touches start*
 - *exactly 1 path-edge touches goal*
 - *either 0 or 2 touch each other node*



More useful: reduction to 3SAT

- *We saw that decision problems can be reduced to SAT*
 - *is CNF formula satisfiable?*
- *Can reduce even further, to 3SAT*
 - *is 3CNF formula satisfiable?*
- *Useful if reducing SAT/3SAT to another problem (to show other problem hard)*

SAT reduces to 3SAT

- *Must get rid of long clauses*
- *E.g., $(a \vee \neg b \vee c \vee d \vee e \vee \neg f)$*
- *Replace with*

$$(a \vee \neg b \vee x) \wedge (\neg x \vee c \vee y) \wedge (\neg y \vee d \vee z) \wedge (\neg z \vee e \vee \neg f)$$

NP-completeness



- *S. A. Cook in 1971 proved that many useful decision problems reduce back and forth to SAT*
 - *showed how to simulate poly-size-memory computer w/ (very complicated, but still poly-size) SAT problem*
- *Equivalently, SAT is exactly as hard (in theory at least) as these other problems*

S. A. Cook. The complexity of theorem-proving procedures, Proceedings of ACM STOC'71, pp. 151-158, 1971.

Cost of reduction



- *Complexity theorists often ignore little things like constant factors (or even polynomial factors!)*
- *So, is it a good idea to reduce your decision problem to SAT?*
- *Answer: sometimes...*

Cost of reduction

- *SAT is well studied $\Rightarrow$ fast solvers*
- *So, if there is an efficient reduction, ability to use fast SAT solvers can be a win*
 - *e.g., 3-coloring*
 - *another example later (SATplan)*
- *Other times, cost of reduction is too high*
 - *usu. because instance gets bigger*
 - *will also see example later (MILP)*

Choosing a reduction



- *May be many reductions from problem A to problem B*
- *May have **wildly** different properties*
 - *e.g., solving transformed instance may take seconds vs. days*