# Algorithms for Rationalizability and CURB Sets

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## ABSTRACT

Significant work has been done on computational aspects of solving games under various solution concepts, such as Nash equilibrium, subgame perfect Nash equilibrium, correlated equilibrium, and (iterated) dominance. However, the fundamental concepts of rationalizability and CURB (Closed Under Rational Behavior sets have not, to our knowledge, been studied from a computational perspective. First, for rationalizability we describe an LP-based polynomial algorithm that finds all strategies that are rationalizable against a mixture over a given set of opponent strategies. Then, we describe a series of increasingly sophisticated polynomial algorithms for finding all minimal CURB sets, one minimal CURB set, and the smallest minimal CURB set. Finally, we give theoretical results regarding the relationships between CURB sets and Nash equilibria, showing that finding a Nash equilibrium can be exponential only in the size of the smallest CURB set. We show that this can lead to an arbitrarily large reduction in the complexity of finding a Nash equilibrium. On the downside, we also show that the smallest CURB set can be arbitrarily larger than the supports of the enclosed Nash equilibrium.

# 1. INTRODUCTION

For multi-agent systems, game-theoretic solution concepts help agents choose strategies, help modelers predict system states, and help mechanism designers guarantee properties of the games they create. Significant attention has been given to algorithms for finding equilibria according to the solution concepts of subgame perfect Nash equilibrium (e.g., minimax search and  $\alpha$ - $\beta$ -pruning), Nash equilibrium [1964, 2004, 2005], correlated equilibrium [1989], and more recently, iterative dominance [1988, 2005a] and related concepts [2005b].

Nash equilibrium (under which no agent has incentive to deviate from its mixed strategy given that the other agents do not deviate from theirs) remains the most important point-valued solution concept. However, it has been recently shown that finding a Nash equilibrium, even in two player normal-form games, is PPAD-complete [2005], suggesting that no polynomial-time algorithms exist for the problem.

However, there are other fundamental solution concepts that have certain known advantages over Nash equilibrium, and—as we will show—solutions according to those concepts can be found in polynomial time even in the worst case. Specifically, we will study the concept of *rationalizability* and the concept of the *minimal Closed Under Rational Behavior (CURB) set* [1991] for twoperson normal-form games. A game can have multiple Nash equilibria, but each of those is a point, i.e., a strategy profile. In contrast, in these concepts a solution is a *set* of strategies for each player.

The notion of rationalizability was introduced in [1984] and [1984]. It has by now been used as a robust solution concept in game theory, and in applications such as auctions (e.g., [2003] [2005] [2001]). Its main insight is that rationality restricts players from ever playing strategies that are not best responses given the beliefs they hold about their opponents; strategies are not *rationalizable*. Formally, a strategy is rationalizable if and only if there exists some mixture over opponent strategies for which it is a best response.

Rationalizability is defined from one agent's perspective. CURB sets extend the same idea to multiagent settings. In short, a CURB set consists of a set of pure strategies for each agent so that all of the agents rationalizable strategies are included, given that the other agents only mix over their rationalizable pure strategies. In other words, a CURB set, S, is defined as a set of strategies that contains the best responses to any mixture over itself: if S is CURB and players believe that no strategy outside of S will be played with positive probability by their opponents, then such strategies will indeed not be played by rational players. Formally a CURB set is defined by the following operators.

- β<sub>i</sub>(m): a function that returns player i's best responses to the mixed strategy m.
- M(S): a function that returns all possible mixtures with supports in S.
- β<sub>i</sub>(S): a function that returns player i's best responses to any mixture with supports in S,

$$\beta_i(S) = \bigcup_{m \in M(S)} \beta_i(m)$$

• β(S): the Cartesian product of the sets β<sub>i</sub>(S) over all players, *i*.

$$\beta(S) = \prod_i \beta_i(S)$$

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Under this notation, a set, S, is CURB if  $\beta(S) \subset S$ . The entire game is trivially CURB by this definition. [1991] distinguish a *minimal* CURB set as a CURB set that does not contain any CURB subsets.

The minimal CURB set solution concept has been motivated from several perspectives, including the following:

- As is well known, nonstrict mixed Nash equilibria can be highly unstable because a player is indifferent between (some of) his pure strategies. Strict Nash equilibria would be stable but many games lack such equilibria. Minimal CURB sets are the "nearest set-valued generalization of strict Nash equilibria" (it is the smallest set of strategies that includes all ways of choosing among the indifferences) and a solution according to this concept is guaranteed to exist [1991]<sup>1</sup>.
- Any CURB set can be viewed as a subspace of strategies within which any best-response dynamic (even a bestresponse dynamic of mixed strategies) will stay within. CURB sets have thus been examined as a solution concept that describes the strategy subspace where iteratively adapting agents will eventually settle (e.g., [1995]).
- More recently, Voorneveld *et.al.* have enumerated properties of minimal CURB sets that illustrate the advantages of setbased solution concepts over point-valued concepts such as Nash equilibria [2005].

A fast technique for finding CURB sets in extensive form games by utilizing their additional structure has been presented [2003]. However, the literature to date suggests that finding minimal CURB sets has been prohibitively complex in normal form games (e.g., [2003, 2005]). We present, to our knowledge, the first computational treatment of CURB sets in normal form games. We show that the complexity of finding CURB sets is polynomial even in the worst case.

The rest of the paper is organized as follows. We present and analyze a family of algorithms which compute, for a two player normal form game, in time polynomial in the total number of pure strategies, the set of all rationalizable strategies, all minimal CURB sets, a single minimal CURB set, and the smallest minimal CURB set. Finally, we discuss additional applications of our results, including the potential of finding minimal CURB sets to bound the computation involved in finding Nash equilibria.

# 2. FINDING RATIONALIZABLE STRATE-GIES

Finding strategies which are rationalizable under specific beliefs (i.e. against a mixture over a given set of opponent strategies) is a problem of interest in its own right, and plays a central role in our computation of CURB sets. In this section, we present a polynomial time procedure, all\_rationalizable, which accomplishes this task.

In 2-player games, iterative removal of strategies strictly dominated by (potentially mixed) strategies finds all rationalizable strategies. However, it cannot distinguish between strategies that are only globally rationalizable and strategies rationalizable under specific beliefs. CURB sets are defined with regard to internally consistent beliefs. Therefore, iterated dominance does not support algorithms for CURB sets. The technique presented in this section does (our all\_rationalizable function conditions on given beliefs).

The algorithm below is for the row player. The column player's algorithm is symmetric. The parameters to the procedure are a set of row player strategies to consider,  $S_r$ , a set of column player strategies they may be played against,  $S_c$ , and the row-player's utility function,  $u_r$ . For each row strategy,  $s_r \in S_r$ , a linear feasibility problem (LFP) (i.e., a linear program with no objective) is constructed to find a mixture,  $p_{s_c}$ , over column player strategies such that  $s_r$  is the row player's best response. The constraints of the LFP ensure that the mixture is valid (sums to 1) and that the row player's utility by playing  $s_r$  against  $p_{s_c}$  is greater than or equal to that of any other strategy in  $S_r$ . If and only if the LFP has a feasible solution,  $s_r$  is added to the set of rationalizable strategies.

**procedure** all\_rationalizable  $(S_r, S_c, u_r)$ 

 $S_r^* \leftarrow \emptyset$ 

for each row strategy,  $s_r \in S_r$  do

let rationalizable  $\leftarrow \top$  iff there exists a feasible solution to the following linear feasibility problem:

find  $p_{s_c}$  such that

$$\sum_{s_c} p_{s_c} = 1 \tag{1}$$

$$\left( \forall s_r' \in S_r / \{s_r\} \right) \quad \sum_{s_c} p_{s_c} u_r(s_r, s_c) \geq \sum_{s_c} p_{s_c} u_r(s_r', s_c)$$

$$(2)$$

if rationalizable then  $S^*_r \leftarrow S^*_r \cup s_r$  return  $S^*_r$ 

The computational complexity of the procedures described in this paper depend on the total number of strategies in the game, which we will denote by n, and the complexity of solving a linear feasibility problem where the number of variables and the number of constraints are bounded by n, which we will denote as LFP(n). Linear feasibility problems can be solved in low-order polynomial time even in the worst case. They are no slower to solve than linear programs (the fastest known algorithms for LFPs are faster, in the worst case, than the fastest known linear programming algorithms [2006]) because linear program solving involves solving a linear feasibility program as the first phase to find a feasible solution, after which the linear program solver needs to still improve that solution to reach an optimum. (In the experiments, we solve the LFP using the simplex algorithm, which has worst-case exponential complexity but is known to outperform polynomial linear programming algorithms in practice.)

PROP. 1. all\_rationalizable returns all rationalizable strategies, and nothing else. It is  $O(n) \times LFP(n)^2$ .

#### 3. FINDING CURB SETS

We now turn our attention to the problem of finding CURB sets. The procedure below finds a minimal set of strategies that both 1) contains a given seed strategy,  $s_r$ , and 2) is CURB. (Note that the returned set is not necessarily a minimal CURB set.) It alternates between the players, calling the all\_rationalizable procedure to identify strategies that have become rationalizable via the addition of opponent strategies. If an iteration passes without strategies being added, the algorithm has converged.

<sup>&</sup>lt;sup>1</sup>A similar set-valued concept is the Set-Nash of Lavi and Nisan [2005], which has been examined for mechanism design but not from an algorithmic perspective. That concept differs from CURB sets in that only strategies which are rationalizable against *pure* opponent strategies within the set are included.

<sup>&</sup>lt;sup>2</sup>We omit some proofs due to limited space.

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\begin{array}{l} \textbf{procedure min_containing_CURB}(s_r, \langle S_r, S_c, u \rangle) \\ S_r^* \leftarrow \{s_r\}, S_c^* \leftarrow \emptyset \\ \texttt{converged} \leftarrow \bot \\ \textbf{while} \neg \texttt{converged do} \\ \texttt{converged} \leftarrow \top \\ \textbf{for } (p, o) \in [(c, r), (r, c)] \ \textbf{do} \\ S_p' \leftarrow \texttt{all_rationalizable}(S_p \setminus S_p^*, S_o^*, u_p) \\ \textbf{if } S_p' \neq \emptyset \ \textbf{then} \\ \texttt{converged} \leftarrow \bot \\ S_p^* \leftarrow S_p^* \cup S_p' \\ \textbf{return sub-game, } G' = \langle S_r^*, S_c^*, u \rangle \end{array}
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PROP. 2. min\_containing\_CURB is  $O(n^2) \times LFP(n)$ .

THM. 1. The min\_containing\_CURB algorithm is correct, that is, the returned set,  $S^*$ , is a minimal set of strategies that both 1) contains the given seed strategy,  $s_r$ , and 2) is CURB.

PROOF. We show that  $S^*$  is CURB by considering its state after min\_containing\_CURB converges. The convergence of the algorithm implies that no strategies outside of  $S^*$  are rationalizable with respect to  $S^*$ . Therefore,  $\beta(S^*) \subset S^*$ , and  $S^*$  is CURB.

To prove that  $S^*$  is the minimal containing CURB set of  $s_r$  (it contains no CURB subsets that include  $s_r$ ), we will use induction on the strategies added to  $S^*$ .

- **Base Case:** Initially  $S^*$  contains only  $s_r$  and  $\beta_c(s_r)$ . At this point,  $S^*$  is trivially the minimal containing CURB set of  $s_r$  because we cannot remove  $s_r$  and removing the column player's best response to  $s_r$  breaks the CURB property.
- Inductive Step: Each time a new strategy s<sup>\*</sup> is added to S<sup>\*</sup> it is necessarily a best response to some mixture, m ∈ M(S<sup>\*</sup>), over the strategies already contained in S<sup>\*</sup>. Since strategies are never removed from S<sup>\*</sup> during the execution of min\_containing\_CURB, m will remain a valid mixture. Therefore, no new strategy s<sup>\*</sup> can be removed from S<sup>\*</sup> without breaking the CURB property.

We will now present three algorithms which use the above procedure to detect minimal CURB sets in a game. To facilitate understanding of these algorithms, we first present the following results regarding CURB set structure.

THM. 2. If each of two intersecting strategy sets is CURB, then their intersection is also CURB.

PROOF. Consider two CURB sets  $S_A$  and  $S_B$  with the nonempty intersection  $S_I$ . For any mixture over strategies in  $S_I$  belonging to (without loss of generality) the row player, there exists a pure strategy which is column player's best response,  $s_c^*$ . Because  $S_A$  is CURB and also contains the row mixture,  $s_c^* \in S_A$ ; likewise  $s_c^* \in S_B$ . Therefore  $s_c^*$  is within their intersection,  $S_I$ .  $\Box$ 

Since the intersection of two CURB sets must be CURB and contained in both sets, we have the following.

COR. 1. Minimal CURB sets cannot overlap (i.e., share any rows or columns).

COR. 2. Each row strategy belongs to at most one minimal CURB set.

Finding All Minimal CURB Sets. The broadest query one can make regarding the minimal CURB set structure of a game is to find all minimal CURB sets. For one, this is useful in the adaptive agent context, to identify regions of strategy space into which learning agents may settle (e.g., [1995]). The all\_MC procedure described below answers this query.

To determine all of the minimal CURB sets, the min\_containing\_CURB procedure can be executed with each row strategy, in turn, as a seed. For the first seed, this call is made with the parameter  $\langle S_r, S_c, u \rangle$  indicating the entire game. However, the result above regarding CURB intersections shows that each of the CURB sets returned by min\_containing\_CURB must contain the minimal containing CURB sets of each of its members. Therefore, we can accelerate future calls by maintaining a map between each strategy and the smallest CURB set in which it has been discovered so far. We use the subgame restricted to that strategy set as the parameter  $\langle S_r, S_c, u \rangle$  when that strategy is used as the seed. Whenever such a call results in a smaller CURB set, we eliminate the previous CURB set from consideration, as it cannot be minimal. Once each strategy has been used as a seed, all\_MC terminates and returns the CURB sets that have not been eliminated.

From the corollary above, the fact that all\_MC executes min\_containing\_CURB on each row strategy, and the fact that no superset CURB sets remain, we have the following.

**PROP.** 3. all\_MC finds all minimal CURB sets, and nothing else. It is  $O(n^3) \times LFP(n)$ .

Finding One Minimal CURB Set. Rather than finding all minimal CURB sets in a game, it may be desirable to quickly find any single minimal CURB set. To complete this query, we can use the min\_containing\_CURB procedure with a random strategy as the seed. Since the discovered CURB set might not be minimal, we recur within it by choosing as a seed a contained strategy that has not yet been used as a seed. We repeat this until all strategies in the current set have been used as seeds, at which point we terminate and return the remaining set. This constitutes the one\_minimal\_CURB algorithm.

If the game has more than one CURB set, one\_MC will be faster than all\_MC because it will never leave the smallest CURB set within which it ever chooses a seed. The exact speed of one\_MC depends on the first seed chosen. If it happens to be in a small CURB set, one\_MC runs faster. In the worst case where the entire game is the only CURB set, one\_MC executes all of the same steps as all\_MC. Due to this fact, and the fact that the returned set has been confirmed to be the minimal containing CURB set for all strategies within it, we have the following.

PROP. 4. one\_MC returns a minimal CURB set, and is  $O(n^3) \times LFP(n)$ .

**Finding the Smallest Minimal CURB Set.** As a different type of query, one may be interested in finding a *smallest* minimal CURB set. This is important, for example, if the CURB set is used for future computations (e.g., for Nash equilibrium finding as we will discuss later in the paper) and the complexity of those future computations increases with the size of the CURB set.

We find the smallest minimal CURB set using a pseudoparallelization of all\_MC, wherein we expand a candidate set only when it is one of the smallest currently available. First, we construct a candidate set for each row strategy containing only that strategy. We insert the sets into a priority queue where sets containing the fewest strategies receive highest priority. We repeatedly pop the smallest candidate set from the queue and add all the rationalizable strategies to that set using all\_rationalizable. If new strategies were added, the resulting set is inserted back into the queue, and prioritized based on its new size. The algorithm terminates when a candidate set is removed from the queue that fails to admit any new rationalizable strategies. That set is returned, and it is a smallest minimal CURB set. We call this algorithm small\_MC.

The smallest CURB set in any game must be minimal, and all other candidates in the queue are of size greater or equal to the returned set. The complexity of small\_MC is bounded by the total number of strategies in the smallest CURB set, which we denote by  $n_{SC}$ . Since each call to all\_rationalizable must add at least one strategy until small\_MC terminates, we have the following.

PROP. 5. small\_MC returns a minimal CURB set that is a smallest minimal CURB set in the game, and it is  $O(n_{SC} n^2) \times LFP(n)$ .

#### **3.1** Experimental Results

We examined the runtime performance of our algorithms on two game distributions provided by the *GAMUT* instance generators [2004]: *random games*, and *covariant games*. Figure 1 shows how each minimum CURB finding algorithm scales with game size on a dataset of over 1000 random, square normal form games with total number of strategies *n* between 20 and 80. small\_MC is faster than all\_MC. This is consistent with their *O*-complexities, considering that many random games have small CURB sets. While the *O*-complexity of one\_MC and all\_MC is the same, experimentally one\_MC is faster because it only needs to find one minimal CURB set. (On any game with more than one minimal CURB set, one\_MC is faster than all\_MC.)

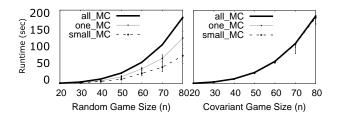


Figure 1: Scalability of our algorithms in game size (the curves on the right overlap).

We observed that the performance illustrated on random games in Figure 1 was typical of that of many other instance distributions provided by the *GAMUT* instance generators as well. However, to show potentially differing performance, we also experimented with the covariant game class, in which payoffs for both players are drawn from the same distribution with a specified covariance. In our experiments we used a covariance parameter of -0.5. That class and that setting have been shown to be particularly challenging for Nash equilibrium finding (with the Lemke-Howson algorithm and the Porter-Nudelman-Shoham algorithm) [2004]. Figure 1 shows that the all\_MC algorithm scales similarly on random and covariant games, while the other two algorithms lose their relative speed advantages when applied to the covariant class.

Most random games have small smallest CURB sets (in fact, often sets of size 2, i.e., pure-strategy equilibria), and those that do not, tend to have very large smallest CURB sets (Figure 2). On the other hand, covariant games tend to have almost no small smallest CURB sets and often have large smallest CURB sets. (This is consistent with the observed hardness of these games for support enumeration-based Nash equilibrium finding algorithms that try to find equilibria with small supports first [2004].) The disparity explains the lowered performance on covariant games for both the two minimal CURB finding algorithms, which are affected by the size of the smallest minimal CURB set.

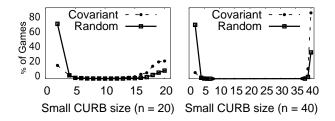


Figure 2: Distribution of Smallest CURB set size in random and covariant (r = -0.5) games, where n = 20 and n = 40(3,000 games for each distribution and value of n).

To better understand how the minimal CURB finding algorithms scale with the size of the smallest CURB set, we bucketed the n = 20 games from above according to the size of the smallest CURB set. (For n = 40 games the buckets for medium sized small CURB sets were nearly empty, making it impossible for us to estimate mean runtimes with sufficient accuracy.) Figure 3 plots the average runtime for each bucket. On games with very small CURB sets, small\_MC is fastest, but it is outperformed by both one\_MC and all\_MC as the smallest CURB set grows. The surprising average-case efficiency of the latter two algorithms is due to their leveraging of information across calls to min\_containing\_CURB with different seeds. Because small\_MC performs all the searches in parallel, this information is unavailable.

The results shown in Figure 1 are unintuitive because most random and covariant games have tiny CURB sets, which are the special case under which small\_MC outperforms one\_MC. If smallness of CURB sets were known in advance, one could use small\_MC to accomplish the task of one\_MC more efficiently, but generally this is slower. To get the best of both, one can timeslice between the two algorithms. The runtime of this hybrid is at most twice the runtime of the faster of the two (plus the length of a slice and the slicing overhead).

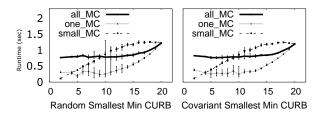


Figure 3: Average runtime on games were n = 20, with varying smallest CURB set sizes.

## 4. CURB SETS AND NASH EQUILIBRIA

Both minimal CURB sets and Nash equilibria model strategy subspaces which are mutually reinforced given the rationality of agents and their common knowledge. A CURB set with only one row and one column strategy is *necessarily* a pure strategy Nash equilibrium. Furthermore, any minimal CURB set contains the supports for at least one Nash equilibrium in mixed strategies [1991]. We observe that this result suggests a secondary use for finding minimal CURB sets: our algorithms can be used to preprocess a game so that a Nash equilibrium finding algorithm needs to only operate on a minimal CURB set rather than the entire game. This can yield an arbitrarily large reduction of the search space, as Theorem 3(a) will show.

The most common prior preprocessing technique for Nash equilibrium finding, iterated removal of dominated strategies, attempts to eliminate strategies that cannot be played with any probability in any Nash equilibrium [1988], [1993]. The same is true of a recent preprocessing technique, the generalized eliminability method [2005b]. One comparative advantage of minimal CURB set-based elimination is that it can eliminate strategies that are played in some equilibria, while guaranteeing that the resulting set still contains the supports of at least one equilibrium.

Our CURB set-based preprocessor can reduce search space size by an arbitrary amount (i.e. to a CURB set of almost any dimension) even on games where no prior preprocessing technique can eliminate anything.

THM. 3. For any  $r \ge 2$ ,  $c \ge 2$  and r', c' such that  $1 < r' \le r$ and  $1 < c' \le c$  (or r' = c' = 1), there exists at least one  $r \times c$ normal-form game, where

- a) the game has an  $r' \times c'$  smallest CURB set.
- *b)* iterated elimination of dominated strategies (even domination by mixed strategies) cannot eliminate any strategies,
- c) the recent recursive preprocessing technique (that can eliminate strategies that belong to some equilibrium as long as some other equilibrium remains) [2006 ] cannot eliminate any strategies, and
- d) if  $r' + c' \leq \frac{r+c}{2}$  (i.e., the smallest CURB set is not huge), the general eliminability method [2005b] cannot eliminate any strategies. (Even if the smallest CURB set is huge, the general eliminability technique cannot eliminate more strategies than our CURB set-based technique.)

PROOF. We first present the following family,  $\Gamma$ , of games. Let  $\Gamma_{r'c'}$  denote such a game of size  $r' \times c'$ . The following generator produces such a game where  $r', c' \geq 2$ . Assign the payoffs  $u(s_{r_1}, s_{c_1}) = u(s_{r_2}, s_{c_2}) = (0, 1)$  and  $u(s_{r_1}, s_{c_2}) = u(s_{r_2}, s_{c_1}) = (1, 0)$ . Then, for  $i \in [2, r' - 1]$ , set  $u(s_{r_{i+1}}, s_{c_1}) = (\frac{r'-i}{r'}, 1)$  and  $u(s_{r_{i+1}}, s_{c_2}) = (\frac{i}{r'}, 0)$ . Next, for  $j \in [2, c' - 1]$ , set  $u(s_{r_1}, s_{c_{j+1}}) = (0, \frac{c'-j}{c'})$  and  $u(s_{r_2}, s_{c_{j+1}}) = (1, \frac{j}{c'})$ . For all payoffs still unassigned, set  $u(s_{r_i}, s_{c_j}) = (-i, -j)$ .

For example, the game  $\Gamma_{3,4}$  is as follows.

$\Gamma_{3,4}$	$s_{c_1}$	$s_{c_2}$	$s_{c_3}$	$s_{c_4}$
$s_{r_1}$	0,1	1,0	$0, \frac{1}{2}$	$0, \frac{1}{4}$
$s_{r_2}$	1,0	0,1	$1, \frac{1}{2}$	$1, \frac{3}{4}$
$s_{r_3}$	$\frac{1}{3}, 1$	$\frac{2}{3},0$	-3,-3	-3,-4

Any game generated in this way has a Nash equilibrium where the row player mixes between his first two strategies and the column player mixes among all his strategies. It also has an equilibrium where the column player mixes between his first two strategies and the row player mixes among all his. Thus, every strategy in  $\Gamma_{r'c'}$  is part of some equilibrium. Additionally each column strategy is a best response to a mixture over the first two row strategies (and, to any column strategy, one of those two is a best response), and vice versa. Thus,  $\Gamma_{r'c'}$  has a single minimal CURB set and it includes the entire game.

We now construct an  $r \times c$  game with a minimally CURB  $r' \times c'$ subset by putting the game  $\Gamma_{r'c'}$  in the top left and the game  $\Gamma_{(r-r')(c-c')}$  in the bottom right. All other payoffs are set to negative random noise. The resulting game is irreducible by (iterated) dominance and by general eliminability because every strategy participates in some Nash equilibrium. The game is irreducible by the recursive preprocessor because the row player's payoffs are distinct within each column and the column player's payoffs are distinct within each row. (If  $\Gamma_{r'c'}$  is the *smallest* minimal CURB set and  $r' + c' > \frac{r+c}{2}$ , we instead construct a game by starting with  $\Gamma_{r'c'}$ and including additional row and column strategies that are neither dominated nor part of any minimal CURB set. It is easy to generate such strategies, but they might not be part of any Nash equilibrium. Thus the general eliminability method may be able to eliminate those additional strategies.)

However, three factors curb the promise of minimal CURB set algorithms as powerful preprocessors for Nash equilibrium finding. First, the fastest Nash equilibrium finding algorithms, while requiring exponential time in the worst case, tend to run faster than (at least the current implementations of) the CURB set finding algorithms on many instance distributions. Second, by Theorem 3(a), the smallest CURB set can be arbitrarily large (up to the size of the entire game, in which case the preprocessor does not eliminate any strategies from consideration). Third, even after the smallest minimal CURB set has been identified, the remaining search space (CURB set size) can be arbitrarily larger than the size of the supports of a contained Nash equilibrium:

THM. 4. A Nash equilibrium with supports consisting of two strategies for each player can be the only Nash equilibrium in an arbitrarily large minimal CURB set.

PROOF. Consider the following family of games that contain large minimal CURB sets and small-support equilibria. For any integer k > 0, we define the game  $\Omega_k$  as follows. As in the previous proof, assign the payoffs  $u(s_{r_1}, s_{c_1}) = u(s_{r_2}, s_{c_2}) = (0, 1)$  and  $u(s_{r_1}, s_{c_2}) = u(s_{r_2}, s_{c_1}) = (1, 0)$ . Then, for  $i \in [3, 2 + k]$ ,

- $u(s_{r_i}, s_{c_1}) = (-\infty, \epsilon), u(s_{r_1}, s_{c_i}) = (\epsilon, -\infty),$
- $u(s_{r_i}, s_{c_i}) = (0, 0),$
- $u(s_{r_i}, s_{c_{i-1}}) = (1 + \epsilon, 0), u(s_{r_{i-1}}, s_{c_i}) = (0, 1 + \epsilon)$ , and
- for all j > i + 1 and  $j \le 2 + n$ ,

$$u(s_{r_i}, s_{c_i}) = (0, -\infty)$$
, and  $u(s_{r_i}, s_{c_i}) = (-\infty, 0)$ 

For example, the game  $\Omega_2$  is as follows.

$\Omega_2$	$s_{c_1}$	$s_{c_2}$	$s_{c_3}$	$s_{c_4}$
$s_{r_1}$	0,1	1,0	$\epsilon, -\infty$	$\epsilon, -\infty$
$s_{r_2}$	1,0	0,1	$0,1+\epsilon$	$0,-\infty$
$s_{r_3}$	$-\infty,\epsilon$	$1+\epsilon,0$	0,0	$0,1+\epsilon$
$s_{r_4}$	$-\infty,\epsilon$	$-\infty, 0$	$1+\epsilon,0$	0,0

PROP. 6.  $\Omega_k$  has a single minimal CURB set and it includes the entire game.

PROP. 7. In  $\Omega_k$ , the only Nash equilibrium is the the strategy profile where  $s_{r_1}$ ,  $s_{r_2}$ ,  $s_{c_1}$  and  $s_{c_2}$  are each played with probability  $\frac{1}{2}$ .

This completes the proof of the theorem.  $\Box$ 

The above results mean that minimal CURB set algorithms do not always help in Nash equilibrium finding because the smallest CURB set can be arbitrarily large (Theorem 3(a)) and it can be arbitrarily loose around an enclosed Nash equilibrium (Theorem 4). However, on any game instance that has a small CURB set *or* a relatively tight minimal CURB set<sup>3</sup>, and on which standard equilibrium-finding algorithms run very slowly, our technique should yield a drastic speed improvement for Nash equilibrium finding (the worst-case complexity of our preprocessor is polynomial, while any equilibrium-finding algorithm has superpolynomial run-time (unless PPAD=P)).

Furthermore, the existence of the polynomial-time algorithm for detecting a game's smallest CURB set (small\_MC) allows us to offer the following theoretical result of potential general interest.

THM. 5. The complexity of finding a single Nash equilibrium for a two-player normal form game is super-polynomial only in the size of the game's smallest CURB set. (If PPAD=P, then it is not super-polynomial in anything.)

# 5. CONCLUSIONS AND FUTURE RE-SEARCH

We presented the first algorithms for rationalizability and CURB sets, two important set-valued solution concepts for normal-form games. Our algorithms find all rationalizable strategies for a given support of opponent's strategies, all minimal CURB sets (all\_MC), one minimal CURB set (one\_MC), and a smallest minimal CURB set (small\_MC), all in polynomial time. The CURB algorithms use techniques such as dovetailing with a priority queue, and exploiting information across overlapping CURB sets, to further improve speed.

Experiments on random games showed that small\_MC is the fastest, one\_MC is second, and all\_MC is the slowest of the three. On covariant games, the speed advantage of the former two disappears. The runtime of the algorithms is affected by the size of the smallest CURB set. On games with small CURB sets, small\_MC performed significantly better than the others, but the others (especially one\_MC) performed better on games containing only large CURB sets.

We also examined the potential for using our algorithms as preprocessors for Nash equilibrium finding algorithms. We proved that our technique can eliminate an arbitrarily large portion of the game from consideration while guaranteeing that the remaining strategies contain a Nash equilibrium. This is the case even on games where prior preprocessing techniques are powerless.

On the downside, we showed that the smallest CURB set can be arbitrarily large and/or arbitrarily loose. Furthermore, on many distributions, current Nash equilibrium finding algorithms run faster on average than the CURB set algorithms.

However, we showed that finding a Nash equilibrium is superpolynomial *only* in the size of the smallest CURB set of the game. Taken together with our CURB set algorithms that are polynomial even in the worst case, and the fact that Nash equilibrium finding algorithms are super-polynomial in the worst case (unless PPAD=P), this indicates that our preprocessing techniques will yield a drastic speed improvement on hard games that have a small *or* a relatively tight minimal CURB set. As we showed, games with these two properties do exist; future research involves determining whether such games occur naturally. The CURB set definition is for any number of players. In this paper we considered the two-player case. For a larger number of players, the obstacle is finding rationalizable strategies quickly as a subroutine. The mathematical program we use is of degree d where the number of players is d + 1; for two players it is an LFP but for three players it is already quadratic. Our CURB set algorithms can be trivially generalized to any number of players. Even the generalized versions only make a polynomial number of calls to the all\_rationalizable subroutine. Therefore, if future research finds polynomial algorithms for finding rationalizable strategies for more than two players in polynomial time, then our generalized CURB set algorithms are also polynomial time.

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<sup>&</sup>lt;sup>3</sup>If the game has a relatively tight CURB set, a Nash equilibrium can be found quickly by enumerating strategies of the CURB to be left out from the supports.

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# 8. APPENDIX

**PROP.** 1. all\_rationalizable returns all rationalizable strategies, and nothing else. It is  $O(n) \times LFP(n)$ .

**PROOF.** For any strategy to be rationalizable, by definition, there must be a mixture over opponent strategies for which that strategy is a best response. By inspection, the linear program in all\_rationalizable will return true iff such a mixture exists. Since all\_rationalizable runs this program on all strategies, and includes them in the return set only if the linear program is feasible, it must be correct. Since the linear program is executed once for each strategy, and the size of the linear program is bounded by n, all\_rationalizable has complexity as shown.  $\Box$ 

**PROP.** 2. min\_containing\_CURB is  $O(n^2) \times LFP(n)$ .

PROOF. Every two calls made to all\_rationalizable must add a strategy to the return set, or else min\_containing\_CURB must terminate. Since at most n strategies can be added this way, the complexity of min\_containing\_CURB is  $O(n^2) \times \text{LFP}(n)$ .

THM. 1. The min\_containing\_CURB procedure is correct, that is, the returned set,  $S^*$ , is a minimal set of strategies that both 1) contains the given seed strategy,  $s_r$ , and 2) is CURB.

Proof in main text.

THM. 2. If each of two intersecting strategy sets is CURB, then their intersection is also CURB.

#### Proof in main text.

COR. 1. Minimal CURB sets cannot overlap (i.e., share any rows or columns).

PROOF. Consider minimal CURB sets  $S_A$  and  $S_B$  which share non-empty overlap  $S_C$ . By the containment theorem,  $S_C$  must also be CURB. Since, by the definition of intersection,  $S_C \subset S_A$ , this contradicts our predicate that  $S_A$  is minimal.  $\Box$ 

COR. 2. Each row strategy belongs to at most one minimal CURB set.

PROOF. This is trivially true from Corollary 1.  $\Box$ 

**PROP.** 3. all\_MC finds all minimal CURB sets, and nothing else. It is  $O(n^3) \times LFP(n)$ .

PROOF. By Corollary 1, the minimal CURB set for any strategy must either equal or be contained by any other CURB set in which the strategy is found. Therefore Theorem 1 holds even when min\_containing\_CURB is called on a smallest CURB set in which a strategy has been found so far. By this and Corollary 2, the main loop of all\_MC must discover all minimal CURB sets in the game. Since any CURB set which is not minimal must have contained one of the minimal CURB sets discovered, it is removed when the smaller CURB set is discovered (or not added if the smaller set was previously discovered). Therefore all\_MC returns all, and only minimal CURB sets. In the worst case, all\_MC must call min\_containing\_CURB n times, with the full game as a parameter, giving time complexity  $O(n^3) \times LFP(n)$ .

**PROP.** 4. one\_MC returns a minimal CURB set, and is  $O(n^3) \times LFP(n)$ .

PROOF. If there are no other minimal CURB sets, then the entire game is minimally CURB and will be therefore returned, according to Proposition 3. If there are any other minimal CURB sets, one of them will be discovered when a strategy inside it is used as a seed. In the worst case (when the whole game is minimally CURB), one\_MC must call min\_containing\_CURB n times, with the full game as a parameter, giving time complexity  $O(n^3) \times LFP(n)$ .

PROP. 5. small\_MC returns a minimal CURB set that is a smallest minimal CURB set in the game, and it is  $O(n_{SC} n^2) \times LFP(n)$ .

PROOF. At the time small\_MC terminates, all\_rationalizable has been called on all row and column strategies in the set, with no new rationalizable strategies being discovered. Therefore, the returned set is CURB. Since all other candidate sets on the queue must be as large, or larger than the returned set, (and future exploration can only add strategies to these sets) this set is at least as small as the smallest CURB set in the game. The smallest CURB set must also be a minimal CURB set.

Whenever a candidate set is fathomed, at least one new strategy must be added or small\_MC will terminate. Since there are n candidate sets, and  $n_{SC}$  strategies in returned set, at most  $n \times n_{SC}$  sets have been fathomed at termination. Each examination of a candidate set involves a call to all\_rationalizable the complexity of small\_MC is as given.

THM. 3. For any  $r \ge 2$  and  $c \ge 2$ , there exists  $r \times c$  normal-form games, where

- a) the smallest CURB set can be of any shape  $1 \times 1$  or  $r' \times c'$ (s.t.  $1 < r' \le r$  and  $1 < c' \le c$ ),
- *b) iterated elimination of dominated strategies (even domination by mixed strategies) cannot eliminate any strategies,*

- c) the recent recursive preprocessing technique (that **can** eliminate strategies that belong to some equilibrium as long as some other equilibrium remains) [2006 ] cannot eliminate any strategies, and
- d) if  $r' + c' \leq \frac{r+c}{2}$  (i.e., the smallest CURB set is not huge), the general eliminability method [2005b] cannot eliminate any strategies. (Even if the smallest CURB set is huge, the general eliminability technique cannot eliminate more strategies than our CURB set-based technique.)

#### Proof in main text.

THM. 4. A Nash equilibrium with supports consisting of two strategies for each player can be the only Nash equilibrium in an arbitrarily large minimal CURB set.

#### Proof in main text.

PROP. 6.  $\Omega_k$  has a single minimal CURB set and it includes the entire game.

PROOF.  $s_{r_1}, s_{r_2}, s_{c_1}, s_{c_2}$  must be included in some minimal CURB set, as they each form best responses to each other in the subgame containing them, and this subgame admits no pure strategy NE. To prove that all other strategies in the game are also in the minimal CURB set, we introduce the following Lemma.

LEMMA 1. For i > 2 the row (column) player's strategy  $s_{r_i}$ ( $s_{c_i}$ ) is a best response to the column (row) player's strategy  $s_{c_{i-1}}$ ( $s_{r_{i-1}}$ ). The best response to the row (column) player's edge strategy  $s_{r_{n+2}}$  ( $s_{c_{n+2}}$ ) is  $s_{c_1}$  ( $s_{r_1}$ ).

Lemma 1 holds based on the construction of the  $\Omega$  game, the strategies in question provide  $\epsilon$  more utility than any others. Based on this Lemma, we can see that when i = 3, the row (column) player's strategy  $s_{r_3}$  ( $s_{c_3}$ ) is a best response to the column (row) player's second strategy. This forces the third strategy of each player into the minimal CURB set containing the first two strategies of each player, and inductively each additional strategy is added in the same way.  $\Box$ 

**PROP.** 7. In  $\Omega_k$ , the only Nash equilibrium is the the strategy profile where  $s_{r_1}$ ,  $s_{r_2}$ ,  $s_{c_1}$  and  $s_{c_2}$  are each played with probability  $\frac{1}{2}$ .

PROOF. Suppose that this is not the case, i.e. there exists a mixture,  $m_r^*$ , over the rows  $M_r^*$ , comprising the row player's profile in a Nash equilibrium, and  $s_{r1} \notin M_r^*$ . Along with our assumption, the definition of NE implies that there must exist a mixture,  $m_c^*$ , over columns  $M_c^*$  such that  $\beta_r(m_c^*) = M_r^*$  and  $\beta_c(m_r^*) = M_c^*$ . Since  $s_{r1}$  is not in  $M_r^*$  by assumption, there exists i > 1 such that  $s_{r_i}$  is the lowest numbered support in  $M_r^*$ , and the definition of  $\Omega$  specifies the outcome,  $u(s_{r_i}, s_{c_j}) = (0, -\infty)$ , when j > i + 1.

The column player's NE supports cannot contain any such  $s_{c_j}$ , because placing any positive probability on this strategy will lead to an expected payoff of  $-\infty$  and playing the pure strategy  $s_{c_1}$  provides guaranteed payout of at least 0. If we exclude these strategies,  $s_{c_{i+1}}$  (the highest remaining column strategy) is the only remaining strategy, other than  $s_{c_1}$ , which provides non-zero utility against mixtures on rows  $\geq i$ . In other words, it dominates all column strategies on the row player's supports  $M_r^*$ , aside from one:  $s_{c_1}$ .

Since dominated strategies cannot be played in equilibrium,  $M_c^*$  is constrained to a subset of  $\{s_{c_1}, s_{c_{i+1}}\}$ . If  $M_c^*$  contains  $s_{c_1}, M_r^*$  must not include any  $s_{r_j}$  with j > 2, due to the  $-\infty$  expected payoff of any mixture including such strategies (as discussed above).

In this case, the only remaining possible row NE mixture is the pure strategy  $s_{r_2}$ , the best response to which is  $s_{c_3}$ . Since, by Corollary 2,  $\Omega^n$  has no pure NE, this cannot constitute and equilibrium, contradicting our assumption. Alternatively, if  $M_c^*$  does not include  $s_{c_1}$ , then  $m_c^*$  must be the pure strategy  $s_{c_{i+1}}$ , and Lemma 2 provides a pure strategy best response to any pure strategy with i > 2. This would, again, form a pure strategy NE, which we have shown does not exist.

The reasoning in this proof can also be inverted to show that a contradiction is caused by the assumption that  $M_c^*$  does not contain  $s_{c_1}$ .

THM. 5. The complexity of finding a single Nash equilibrium for a two-player normal form game is super-polynomial only in the size of the game's smallest CURB set. (If PPAD=P, then it is not super-polynomial in anything.)

PROOF. This is clear given the existence of the polynomial time small\_MC algorithm for finding the smallest minimal CURB in a game, and the fact that every minimal CURB set contains the support for at least one Nash equilibrium [1991].  $\Box$