Division of Labor in Ant Colonies

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What is division of labor? (cont.)

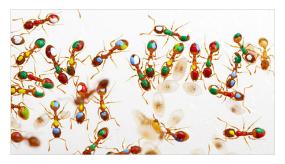
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Contributions

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- ▶ A very general mathematical formulation for the phenomenon of division of labor in ant colonies.
- A distributed algorithm that quickly reaches a near optimal task allocation and imposing only minimal assumptions on the capabilities of individual ants.

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- ▶ A set *T* of tasks.

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- ▶ For task $\tau \in T$, ant $a \in A$ and time $t \in \mathbb{R}_{\geq 0}$:
 - $d(\tau,t)$ is the total energy demand for task τ at time t.
 - $e(\tau, a, t)$ is the energy that can be supplied by ant a if engaged at task τ at time t.

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▶ Observe that by definition $A = Y(\tau, t) \cup I(t)$.

• $w(\tau,t) = \sum_{a \in Y(\tau,t)} e(\tau,a,t)$ is the energy supplied to task τ at time t.

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- ▶ $q(\tau,t) = d(\tau,t) w(\tau,t)$, if negative represents a surplus of energy at task τ , if positive represents a deficit of energy at task τ , and if zero then the task τ is in equilibrium.
- An *optimal* task assignment is one that minimizes $\sum_{\tau \in T} q(\tau, t)^2$

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We consider synchronous model where time proceeds in lock-step rounds $1, 2, \ldots$, and for the duration of each round $i \in \mathbb{N}$ each ant $a \in A$ works at task y(a, i).

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- ▶ Recall that $q(\tau,i) = d(\tau,i) w(\tau,i)$ is the difference between the energy demand for task τ at round i and the energy supplied for task τ at round i.
- For each task $\tau \in T$ ants can sense only a binary feedback function $f(\tau, i)$ where:

$$f(\tau, i) = \begin{cases} +1 & q(\tau, i) \ge 0, \\ -1 & q(\tau, i) < 0. \end{cases}$$

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- ► Intuition: Given sufficient memory, ants could use a randomized binary-search-like strategy, guided by the function f, to reach the optimal division of labor.
- Idea 1: Offload the burden of memory from the individuals to the colony.
- Idea 2: Let ants use a response-threshold strategy to pick tasks, and allow them to specialize.

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Algorithm Details

▶ Each ant stores a task $currentTask \in T \cup \{\bot\}$ and a potential table $\varrho[\tau]$.

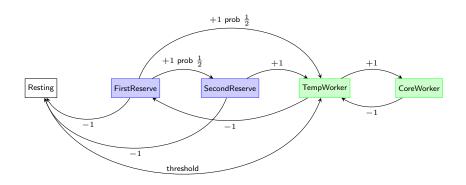
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- ▶ Each ant stores a task $currentTask \in T \cup \{\bot\}$ and a potential table $\varrho[\tau]$.
- ▶ Initially ants start in the RESTING state with $currentTask = \bot$ and a potential of zero for every task $\forall \tau \in T, \varrho[\tau] = 0$.

Algorithm Details

- ▶ Each ant stores a task $currentTask \in T \cup \{\bot\}$ and a potential table $\varrho[\tau]$.
- ▶ Initially ants start in the Resting state with $currentTask = \bot$ and a potential of zero for every task $\forall \tau \in T, \varrho[\tau] = 0$.
- ► Ants can be in one of the five states RESTING, FIRSTRESERVE, SECONDRESERVE, TEMPWORKER and COREWORKER.

Simplified State Machine



$$\forall \tau \in T, \varrho[\tau] \leftarrow \begin{cases} 0 & \text{if } f(\tau, i) < 0\\ \min(\varrho[\tau] + 1, 3) & \text{if } f(\tau, i) > 0 \end{cases}$$

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candidate \leftarrow \{ \tau \in T \mid \varrho[\tau] = 3 \}
if candidate \neq \emptyset then
      with probability \frac{1}{2} do
             \forall \tau \in T, \rho[\tau] \leftarrow 0
             currentTask \leftarrow random candidate task
             state \leftarrow TempWorker
       end with
end if
```

case state = TempWorker

```
case state = TempWorker if f(currentTask, i) < 0 then state \leftarrow FirstReserve
```

```
 \begin{aligned} \mathbf{case} \ & \mathbf{state} = \mathbf{TEMPWORKER} \\ & \mathbf{if} \ f(currentTask,i) < 0 \ \mathbf{then} \\ & \mathbf{state} \leftarrow \mathbf{FIRSTRESERVE} \\ & \mathbf{else} \\ & \mathbf{state} \leftarrow \mathbf{COREWORKER} \\ & \mathbf{end} \ \mathbf{if} \end{aligned}
```

```
case state = TempWorker if f(currentTask, i) < 0 then state \leftarrow FirstReserve else state \leftarrow CoreWorker end if case state = CoreWorker
```

```
case state = TEMPWORKER
   if f(currentTask, i) < 0 then
      state \leftarrow FIRSTRESERVE
   else
      state \leftarrow COREWORKER
   end if
case state = COREWORKER
   if f(currentTask, i) < 0 then
      state ← TEMPWORKER
   end if
end case
```

case state = FIRSTRESERVE

```
case state = FIRSTRESERVE if f(currentTask, i) < 0 then state \leftarrow RESTING else
```

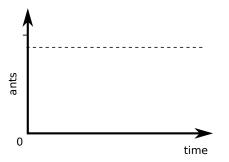
```
case state = FIRSTRESERVE
   if f(currentTask, i) < 0 then
       state \leftarrow Resting
   else
       with probability \frac{1}{2} do
          state \leftarrow TempWorker
       otherwise
          state ← SECONDRESERVE
       end with
   end if
```

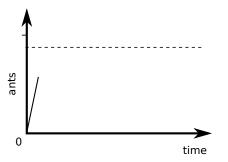
```
case state = FIRSTRESERVE
   if f(currentTask, i) < 0 then
      state ← RESTING
   else
      with probability \frac{1}{2} do
         state ← TEMPWORKER
      otherwise
         state ← SECONDRESERVE
      end with
   end if
case state = SECONDRESERVE
```

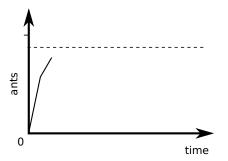
```
case state = FIRSTRESERVE
   if f(currentTask, i) < 0 then
      state ← RESTING
   else
      with probability \frac{1}{2} do
         state ← TempWorker
      otherwise
         state ← SECONDRESERVE
      end with
   end if
case state = SECONDRESERVE
   if f(currentTask, i) < 0 then
      state ← RESTING
```

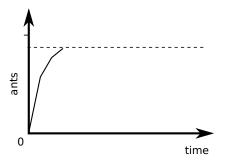
```
case state = FIRSTRESERVE
   if f(currentTask, i) < 0 then
      state ← RESTING
   else
      with probability \frac{1}{2} do
         state ← TEMPWORKER
      otherwise
         state ← SecondReserve
      end with
   end if
case state = SECONDRESERVE
   if f(currentTask, i) < 0 then
      state ← Resting
   else
      state ← TEMPWORKER
   end if
```

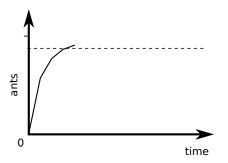
end case

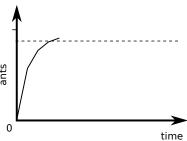


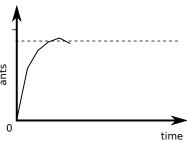


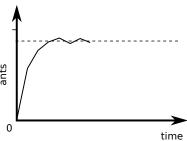


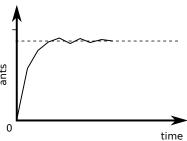


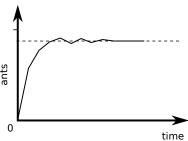




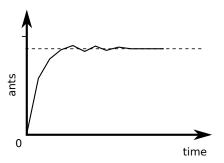








▶ **Theorem:** After $O(\log n)$ rounds, with high probability, ants reach an optimal task allocation.



Questions?