Known Errors

The following errors in the second edition have been called to my attention.

- Back cover: Andrew Pitts’s affiliation is printed as “University of Cambridge University Press” rather than “University of Cambridge.” (This is the only mistake that is not under my control!)

- Page 4: In the description of abt’s, operators with no children should also be deemed “leaves.”


- Page 82, Section 10.3: the definition of the recursor should be

\[
\text{iter}\{\langle z, e_0 \rangle; x'; \langle s(x' \cdot 1), [x' \cdot 1, x' \cdot r/x, y]e_1 \rangle \}(e).
\]

- Page 88, first paragraph: replace “induction” by “inductive”.

- Page 90, “which” in the abstract syntax should be “ifnull”, consistently with the concrete syntax.

- Page 107, \(u_1, \ldots, u_n\) should be \(u_1, \ldots, u_m\).

- Page 140, Rule (16.4a): the type label on the \(\lambda\) should be \(\tau_1\), not \(\tau\).

- Page 147, line 13: “identification convention”, not “identification covnention”.

- Page 154, and Exercise 1: the type of \(\text{emp}\) should be \(\forall t : T.q[t]\).

- Page 152, line -8: \(\langle bs, fs' \rangle\) should be \(\text{just}(\langle f, \langle bs, fs' \rangle \rangle)\).
• Page 162, line 3: “In other words $e$ is defined to be . . .” should be “In other words $f$ is defined to be . . .”

• Page 171: “fucntion” should be “function.”

• Page 191, dynamics of application: either a by-name or by-value interpretation is possible.

• Page 191, Rule (22.4h): 0 should be $z$.

• Page 191, Rule (22.4i): $n + 1$ should be $s(n)$.

• Page 193, Section 22.2: “berepresented” should be “be represented”.

• Page 219, paragraph 2: should read: “serve as behavioral specifications”.

• Page 228, Section 25.3: “$\Phi_1 \vdash a \in_\tau \phi$” should be “$\Phi_1 \vdash e \in_\tau \phi.$”

• Page 261, Rule (29.3a): Conclusion should be $e \triangleright e$ initial.

• Page 265, Exercises 29.4 and 29.5 are orphaned: the modal formulation of exceptions is no longer presented in the text.

• Page 267, Section 30.1: $\tau \cont \cont$ should be $\tau' \cont \cont$.

• Page 268, rule 30.2: the premise should read “$k \div \tau$.”

• Page 288, Section 32.5: “…the name of the fluid…”

• Page 291, Section 33.1: “A dynamic class is a symbol that is generated…”

• Page 292, last paragraph: Revised per online edition to clarify discussion of disequality of names.

• Page 294, line 11: $\text{isin}[a](e;x,e_1;e_2)$ should be $\text{isin}[a](e;y,e_1;e_2)$ to align the variable name $y$ with its definition to follow.

• Page 298, Exercises 33.3 and 33.4 depend on Exercises 29.4 and 29.5, which rely on the modal formulation of exceptions.

• Page 314, first display equation: the printed edition inexplicably has

$$\tau \cap \triangleq \tau \cmd \times (\text{nat} \rightarrow \text{nat} \cmd)$$

which instead should be

$$\tau \cap \triangleq \tau \cmd \times (\tau \rightarrow \tau \cmd).$$

• Page 344, start of paragraph 2: should read: “finite mapping of the task names”.

2
• Pages 344-5: Rule 37.10(b) should have a premise \( \neg(e_2 \text{ val}) \) to prevent needless repetition. Rule 37.10(c) should send \( a_1 \) to \( e_1(e_2) \) in the result state, not to the senseless substitution instance.

• Page 366, Section 39.4, displayed example at end should be

• Page 380, displayed program has a missing use of \( \text{cmd} \), should be

\[
\begin{align*}
\text{fix loop: } & \tau \text{ cmd is cmd } (x \leftarrow \text{acc}; \text{match } x \text{ as } a \cdot y \rightarrow \text{ret } \text{ow} \rightarrow \text{emit}(x); \text{do loop})
\end{align*}
\]

• Page 381, Rules 4.10. There is no execution rule for \( \text{sync(never)} \), so that the intended, but unstated, progress theorem fails. A solution is to introduce a new action, say \( \# \), representing synchronization on the never-occurring event, and to add the execution rule

\[
\text{sync(never)} \xrightarrow{\#} \Sigma \text{ sync(never)}.
\]

The same correction applies to \( \text{DA} \), which also has a null event.

• Page 387, Rule 41.2(b): Premise \( \Gamma \vdash e_1: \tau_1 \text{ cmd } w \) should be \( \Gamma \vdash e_1: \text{cmd}[w](\tau_1) w \).

• Page 389, Rule 41.6a: The process “\( \text{run( } m \text{ )} \)” should be “\( \text{run( at[w](m))} \)” to record the site of the spawned process.

• Page 390, Theorems 41.2 and 41.3, the transition judgments should be \( p \xrightarrow{a@w} \Sigma p' \); the “\( w \)” should be above the transition arrow, not below it.

• Page 437, last paragraph: strike “obviously reflexive.” Reflexivity is exactly Theorem 46.13.

• Page 438, Section 46.1, definition of a congruence: require only that the relations be partial equivalence relations (symmetric and transitive, not necessarily reflexive).

• Page 442, proof of Lemma 46.16: Add “By Definition 46.8 and Lemma 46.11 . . . .” for clarity.

• Page 447, Section 47.3, “the following rule”.

• Page 448, Section 47.3, should be “. . . it is enough to show that \( \dot{\gamma}(e_1) \sim \tau \dot{\gamma}(e'_1), . . . .”

• Page 456, Section 48.2, statement and proof of Lemma 48.3, \( \Delta, t \) should be \( \Delta, t \) type.

• Page 459, Section 48.3, proof of Lemma 48.8: second \( \rho \) should be \( \rho' \):

\[
d'[\rho'] \cong [\rho'/t]\dot{\delta}(\tau_2) e'[\rho'].
\]
• Page 462, line 8: the second occurrence of ρ should be ρ’.

• Rules 12.9, 12.10a, 12.11a, and 12.11b revised to correct errors in premises.

\[
( v v . ( V_0 \otimes V_1 ) ) \otimes U \rightarrow^{\Sigma} ( v v . V_1 \otimes V_2 ) \otimes U \equiv v v . ( V_1 \otimes V_2 \otimes U ) .
\]

**Improvements**

The following changes improve the presentation in the text.

• Various places: ensure uniform use of “statics” and “dynamics” rather than “static semantics” and “dynamic semantics.”

• Chapter 11 and elsewhere: replace \texttt{abort(e)} by \texttt{case e \{ \}} to avoid the implication that “abort” causes a run-time fault, which it does not (and can not!).

• Page 130, the dynamics is specified to be lazy, though it is possible to specify both eager and lazy semantics using optional premises and rules. The rules given in Figure 1 do so.

• Chapter 40 Concurrent Algol. The dynamics specifies \textit{synchronous} communication, in which an emit of a message does not terminate until the message has been received. An \textit{asynchronous} dynamics may be specified by making the alterations given in Figure 2. These rules define an asynchronous send process, and re-define the dynamics of emit to create such a process.

• Section 33.2. It would be more suggestive to write \texttt{inref(e_1;e_2)} in place of \texttt{mk(e_1;e_2)} to stress its role as the dynamic analogue of \texttt{in[a](e)}, much as \texttt{getref(e)} is the dynamic analogue of \texttt{get[a]} for assignables.

**Acknowledgements**

Thanks to Carlo Angiuli, Stephanie Balzer, Peter Brattveit Bock, Corwin de Boor, Jordan Brown, Karl Crary, Jan Hoffmann, Muhammed Hussein Nasroliahput, Shawn Rashid, Selva Samuel, Stephanie Weirich, James R. Wilcox, Haoxuan (Aaron) Yue, Fangyi Zhou, Jake Zimmerman.
\[
\begin{align*}
&e \mapsto e' \\
&\text{fold}\{t.\tau\}(e) \mapsto \text{fold}\{t.\tau\}(e') \\
&e_2 \mapsto e'_2 \\
&\text{rec}\{t.\tau\}(x.e_1; e_2) \mapsto \text{rec}\{t.\tau\}(x.e_1; e'_2) \\
&\text{map}^+\{t.\tau\}(y.\text{rec}\{t.\tau\}(x.e_1; y))(e_2)/x|e_1 \\
&\text{gen}\{t.\tau\}(x.e_1; e_2) \mapsto \text{gen}\{t.\tau\}(x.e_1; e'_2) \\
&e \mapsto e' \\
&\text{unfold}\{t.\tau\}(e) \mapsto \text{unfold}\{t.\tau\}(e') \\
&\text{map}^+\{t.\tau\}(y.\text{gen}\{t.\tau\}(x.e_1; y))(e_2/x)|e_1 \\
\end{align*}
\]

Figure 1: Eager-or-Lazy Dynamics for Inductive and Coinductive Types

\[
\begin{align*}
&\Sigma e : \text{clsfd} \quad e \mapsto e' \\
&\Sigma!e \mapsto e'_\Sigma \\
&\Sigma !e \mapsto 1 \\
&\Sigma e \mapsto e'_\Sigma \\
&e \mapsto e' \\
&\text{emit}(e) \mapsto \text{ret}(\nothing) \otimes !e \\
\end{align*}
\]

Figure 2: Asynchronous Dynamics for Concurrent Algol