system objects shown in red
shared memory shown in magenta
Aperios messages shown in blue
TCP messages shown in green

teammate messages
camera settings
sensor feedback, camera images, motion commands
sensor feedback
joint angles/robot control

shared memory setup messages

log info
comm control

TCPGateway

mainObj
teammate messages
debug info

motion

motion updates

OVirtualRoboComm
camera settings

shMemMgr

WLOut
camera settings

SPOut

debug info

teammate messages
debug info
teammate messages
debug info

debug info
to memory stick

connection requests
debug info
debug info

teammate messages