# Introduction to Human-Robot Interaction V 3.0 Spring 2015

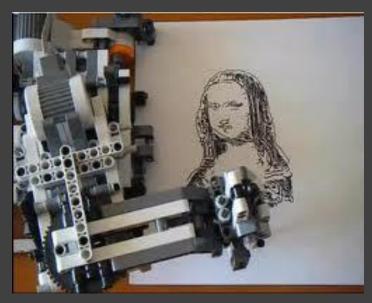
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# People Introductions

- Proposed definitions?
- Key questions when creating HRI system?

• It is an application area





• It is a new field of inquiry





• It is boundary work





# Boundaries shift...



# Small Groups Project boundary and agency

- [What is agency?]
- Identify an existing commercial device that may, in the next decade, be infused with agency and thus become an HRI component.
  - What are the technology enablers?
  - Why agency?
  - Identify a socially dystopian case.

- Our goals
- Our responsibilities
- Your responsibilities
- Evaluation

- Our goals
  - Breadth over depth for your future planning
  - Context relevant to any engineering future
- Our responsibilities
- Your responsibilities
- Evaluation

- Our goals
- Our responsibilities
  - Second year real-time course tweaking
  - Give us suggestions and we will incorporate
- Your responsibilities
- Evaluation

- Our goals
- Our responsibilities
- Your responsibilities
  - Class attendance and active participation
  - Homework
  - Four major group activities, culminating in a final project
  - Written and in-class activity & project presentations
- Evaluation

- Our goals
- Our responsibilities
- Your responsibilities
- Evaluation
  - Participation, homework, projects
  - Effective teamwork
  - Final group presentation

# Syllabus & website tour

(search "16-467 HRI")

# HRI Course Subjects

- Expression and Gaze Perspective-taking
- Proxemics
- Speech
- Perception
- Interaction Design
- Manipulation
- Decision-making
- Mental Models

- Systems Engineering
- Robot Futures & Singularity
- Shared Autonomy
- Exoskeletons & **Assistive Robotics**
- Educational Robotics

# AmaZoogle Home Delivery



# AmaZoogle Tall Poles?

- Expression and Gaze Perspective-taking
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# HRI Project & Homework

 Thematic choices for semester-long focus:

- Trust
- Empathy
- Reliability

# HRI Project & Homework

- Five team milestones
- Homeworks:
  - 1. Project proposal
  - 2. Interaction design spec
  - 3. Automation design x 2
  - 4. Research protocol
- Final Project Execution, Analysis and Presentation

# HRI Study Example

#### No Fair!! An Interaction with a Cheating Robot

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Abstract—Using a humanoid robot and a simple children's game, we examine the degree to which variations in behavior result in attributions of mental state and intentionality. Participants play the well-known children's game "rock-paper-scissors" against a robot that either plays fairly, or that cheats in one of two ways. In the "verbal cheat" condition, the robot announces the wrong outcome on several rounds which it loses, declaring itself the winner. In the "action cheat" condition, the robot changes its gesture after seeing its opponent's play. We find that participants display a greater level of social engagement and make greater attributions of mental state when playing against the robot in the conditions in which it cheats.

Index Terms—Affective & emotional responses, Beliefs about robots, Mental models of robot behavior

object that it has selected. This "nonverbal leakage" is a subtle expression of mental state on the part of the robot. Protosocial responses have also been used to increase the human participants' feeling of engagement, as well as the length of time they fix their attention to a robot [4]. Breazeal [5] uses affective communication to create engagement between naïve participants and a humanoid robot. Mental state attribution may also play a role in studies that observe other phenomena. In their study of humans teaching robots, Kim, Leyzberg, Tsui, and Scassellati found that participants speak more to a robot that has trouble performing a learning task [6].

Simple experiments involving the motion of shapes across

