**Analysis of Boolean Functions** 

(CMU 18-859S, Spring 2007)

Lecture 9: Learning Decision Trees and DNFs

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Lecturer: Ryan O'Donnell

Scribe: Suresh Purini

## **1** Two Important Learning Algorithms

We recall the following definition and two important learning algorithms discussed in previous lecture.

**Definition 1.1** Given a collection S of subsets of [n], we say  $f : \{-1, 1\}^n \to \mathbb{R}$  has  $\epsilon$ -concentration on S, if

$$\sum_{S \notin \mathcal{S}} \hat{f}(S)^2 \le \epsilon.$$

**Theorem 1.2** Let C be a class of n-bit functions, such that  $\forall f \in C$ , f is  $\epsilon$ -concentrated on  $S = \{S \subseteq [n] | |S| \leq d\}$ , then the function class C is learnable under the uniform distribution to an accuracy of  $O(\epsilon)$ , with a probability of at least  $1 - \delta$ , in time  $poly(|S|, 1/\epsilon)poly(n) \log(1/\delta)$  using random examples only.

This algorithm is called Low Degree algorithm and was proposed by Linial, Mansour and Nisan in [3]. Refer theorem 5.4 in lecture notes 8.

**Theorem 1.3** Let C be a class of *n*-bit functions, such that  $\forall f \in C$ , f is  $\epsilon$ -concentrated on some collection S. Then the function class C is learnable using membership queries (Goldreich-Levin Algorithm) in  $poly(|S|, 1/\epsilon)poly(n) \log (1/\delta)$  time.

This algorithm is called Kushilevitz-Mansour algorithm [2]. Refer corollary 5.5 in lecture notes 8.

## 2 Learning Decision Trees

A decision tree is a binary tree in which the internal nodes are labeled with variables and the leafs are labeled with either -1 or +1. And the left and right edges corresponding to any internal node is labeled -1 and +1 respectively. We can think of the decision tree as defining a boolean function in the natural obvious way. For example, the decision tree in the figure 1 defines a boolean function whose DNF formula is  $x_1x_2x_3 + x_1\bar{x}_2x_4 + \bar{x}_1x_2$ .

Note that, given any boolean function we can come up with a corresponding decision tree.

Let P be a path in the decision tree. An example of a path in the figure 1 is  $P = (x_1 = -1, x_2 = +1, x_4 = -1)$ .

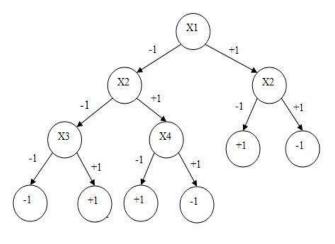


Figure 1:

Let  $\mathbf{1}_P : \{-1, 1\}^n \to \{0, 1\}$  be an indicator function for path P. For example,

 $\mathbf{1}_{P} = \begin{cases} 1 & \text{if } x_{1} = -1, x_{2} = +1, x_{4} = -1 \\ 0 & \text{else} \end{cases}$ 

**Observation 2.1** A boolean function f can be expressed in terms of path functions  $\mathbf{1}_P$ 's, corresponding to various paths in the decision tree of the function f as follows

$$f(x) = \sum_{Paths P} \mathbf{1}_P(x) f(P)$$

where f(P) is the label on the leaf when the function f takes the path P in its decision tree.

**Observation 2.2** Let V be the set of variables occurring in a path function  $\mathbf{1}_P$  and d be the cardinality of the set V. Then the Fourier expansion of  $\mathbf{1}_P$  looks like

$$\sum_{S \subseteq V} \pm 2^{-d} X_S.$$

It is easy to see the proof of the above observation by noting that the Fourier expansion for the path function  $\mathbf{1}_P$ , when  $P = (x_1 = -1, x_2 = +1, x_4 = -1)$ , is  $\mathbf{1}_P = x_1 \overline{x}_2 x_4 = (\frac{1}{2} - \frac{1}{2}x_1)(\frac{1}{2} + \frac{1}{2}x_2)(\frac{1}{2} - \frac{1}{2}x_4)$ .

**Proposition 2.3** If  $f : \{-1, 1\}^n \to \{-1, 1\}$  is computable by a depth-d decision tree then

- 1. Fourier expansion of f has degree at most d i.e.,  $\sum_{|S|>d} \hat{f}(S)^2 = 0$ .
- 2. All Fourier coefficients are integer multiples of  $2^{-d}$ .
- 3. The number of nonzero Fourier coefficients is at most  $4^d$ .

**Proof:**(1) follows from observation 2.1. We can observe that all the Fourier coefficients look like  $k2^{-d'}$  for some  $d' \leq d$ , which can be written as  $k2^{d+d'}2^{-d}$ . This proves (2). A depth-*d* decision tree has at most  $2^d$  leaves and hence we have at most  $2^d \cdot 2^d = 4^d$  Fourier coefficients, which proves (3).

**Corollary 2.4** Depth-d decision trees are exactly learnable with random examples in time  $poly(4^d)poly(n) \log (1/\delta)$ .

**Proof:** Use Kushilevitz-Mansour algorithm, with  $\epsilon = \frac{2^{-d}}{4}$  and round each Fourier coefficient estimate to the nearest multiple of  $2^{-d}$ .

**Remark 2.5**  $\log(n)$ -depth decision trees are exactly learnable in polynomial time. This algorithm can be derandomized.

**Observation 2.6** Size-s decision trees are  $\epsilon$ -close to a depth  $\log(s/\epsilon)$  decision trees.

**Proof:**Let *T* be decision tree of size *s* corresponding to boolean function *f*. Consider the decision *T'* obtained from *T* by chopping all paths whose depth is greater than  $\log\left(\frac{s}{\epsilon}\right)$  to  $\log\left(\frac{s}{\epsilon}\right)$ . The decision tree *T'* gives an incorrect value for f(X) only when *X* takes a path of length greater than  $\log\left(\frac{s}{\epsilon}\right)$  in *T*. When we pick *X* at random, this happens with probability  $2^{-\log\left(\frac{s}{\epsilon}\right)} = \frac{\epsilon}{s}$ . Therefore by union bound, we get that  $\Pr_{\mathbf{x}\in\{-1,1\}^n}[T(\mathbf{x})\neq T'(\mathbf{x})] \leq \epsilon$ .

**Corollary 2.7** Size-s decision trees are  $O(\epsilon)$ -concentrated on a collection of size size  $4^{\log(s/\epsilon)} = (s/\epsilon)^2$ .

**Definition 2.8** Given a function  $f : \{-1, 1\}^n \to \mathbb{R}$ , the spectral norm of  $L_1$ -Fourier norm of f is

$$||\hat{f}||_1 = \sum_{S \subseteq [n]} |\hat{f}(S)|$$

**Observation 2.9** If a function f is an AND of literals, then  $||\hat{f}||_1 = 1$ . Refer observation 2.2 for the proof idea.

The following observation follows from the fact  $\forall a, b \in \mathbb{R}, |a+b| \le |a|+|b|$  and |ab| = |a||b|.

#### **Observation 2.10**

- 1.  $||\widehat{f+g}||_1 \le ||\widehat{f}||_1 + ||\widehat{g}||_1$
- 2.  $||\widehat{cf}||_1 = |c|||\widehat{f}||_1$

**Proposition 2.11** If f has a decision tree of size s,  $||\hat{f}||_1 \leq s$ .

**Proof:** 

$$||\hat{f}||_{1} \leq \sum_{Paths P} \widehat{\mathbf{1}_{P}f(P)}$$
$$\leq \sum_{Paths P} \widehat{\mathbf{1}_{P}}$$
$$\leq s$$

**Proposition 2.12** Given any function f with  $||f||_2^2 \leq 1$  and  $\epsilon > 0$ ,  $S = \{S \subseteq [n] ||\hat{f}(S)| \geq \frac{\epsilon}{||\hat{f}||_1}\}$ , then f is  $\epsilon$ -concentrated on S. Note that  $|S| \leq \left(\frac{||\hat{f}||_1}{\epsilon}\right)^2$ .

**Proof:** 

$$\begin{split} \sum_{S \notin \mathcal{S}} \hat{f}(S)^2 &\leq \max_{S \notin \mathcal{S}} |\hat{f}(S)| \left[ \sum_{S \notin \mathcal{S}} |\hat{f}(S)| \right] \\ &\leq \max_{S \notin \mathcal{S}} |\hat{f}(S)| \left[ \sum_{S \notin \mathcal{S}} |\hat{f}(S)| + \sum_{S \in \mathcal{S}} |\hat{f}(S)| \right] \\ &\leq \frac{\epsilon}{||\hat{f}||_1} \cdot ||\hat{f}||_1 \\ &\leq \epsilon \end{split}$$

**Corollary 2.13** Any class of functions  $C = \{f | ||f||_2^2 \le 1 \text{ and } ||\hat{f}||_1 \le s\}$  is learnable with random examples in time  $poly(s, \frac{1}{\epsilon})$ .

Let us now consider functions which are computable by decision trees where nodes branch on arbitrary parities of variables. Figure 2 contains an example of a function computable by decision tree on the parity of the various subsets of variables. Another example is parity function which is computable by a depth-1 parity decision tree.

**Proposition 2.14** If a function  $f : \{-1, 1\}^n \to \{-1, 1\}$  is expressible as a size-s decision tree on parities, then  $||\hat{f}||_1 \leq s$ .

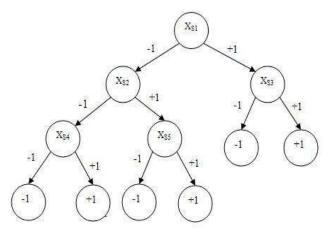


Figure 2:

**Proof:**Let  $\mathbf{1}_P$  be an  $\{0, 1\}$ -indicator function for a path P in the decision tree. Let the path  $P = (X_{S_1} = b_1, \dots, X_{S_d} = b_d)$ , i.e., we get the path P by taking the edges labeled  $b_1, \dots, b_d \in \{-1, 1\}$  starting from the root node. We have

$$\mathbf{1}_P = (\frac{1}{2} + \frac{1}{2}b_1 X_{S_1}) \cdots (\frac{1}{2} + \frac{1}{2}b_d X_{S_d})$$

It can be seen that  $||\widehat{\mathbf{1}_P}||_1 = 1$ . Since  $f(x) = \sum_{Paths P} \mathbf{1}_P(x) f(P)$ , we have  $||\widehat{f}||_1 \leq s$ .  $\Box$ 

**Definition 2.15** An AND of parities is called a coset.

**Remark 2.16** If a function  $f : \{-1, 1\}^n \to \{-1, 1\}$  is expressible as  $\sum_{i=1}^s \pm \mathbf{1}_{P_i}$ , where  $P_i$ 's are cosets then  $||\hat{f}||_1 \leq s$ .

**Remark 2.17** Proposition 2.14 implies that we can learn all parity functions in  $poly(\frac{1}{\epsilon})$  time. Observe that we cannot see this result straightforward from the usual decision trees on parity functions.

**Theorem 2.18** [1] If a function  $f : \{-1, 1\}^n \to \{-1, 1\}$  with  $||\hat{f}||_1 \leq s$ , then

$$f = \sum_{i=1}^{2^{2^{O(s^4)}}} \pm \mathbf{1}_{P_i}$$

where  $P_i$ 's are cosets.

# 3 Learning DNFs

**Proposition 3.1** If f has a size-s DNF formula, it is  $\epsilon$ -close to a width- $\log(\frac{s}{\epsilon})$  DNF.

**Proof:**Let the function  $f : \{-1, 1\}^n \to \{-1, 1\}$  has a size-*s* DNF. Drop all the terms whose width is larger than  $\log(\frac{s}{\epsilon})$  from the DNF of f and let the new DNF represents the function f'. If we look at a particular term in the DNF of f whose width is greater than  $\log(\frac{s}{\epsilon})$ , then the probability that a randomly chosen  $x \in \{-1, 1\}$  sets it to -1 (or 1 if we look at f as boolean function from  $\{0, 1\}^n$  to  $\{0, 1\}$ ) is at most  $2^{-\log(\frac{s}{\epsilon})} = \frac{\epsilon}{s}$ . Since there are at most s terms in the DNF, we have that  $\mathbf{Pr}_{\mathbf{x}} [f(\mathbf{x}) \neq f'(\mathbf{x})] \leq \epsilon$  by union bound.  $\Box$ 

**Proposition 3.2** If a function  $f : \{-1, 1\}^n \to \{-1, 1\}$  has a width w DNF, then  $\mathbb{I}(f) \leq 2w$ .

**Proof:**Left as an exercise.

**Corollary 3.3** If a function  $f : \{-1, 1\}^n \to \{-1, 1\}$  has a width w DNF, then f is  $\epsilon$ -concentrated on a  $S = \{S \mid |S| \leq \frac{2w}{\epsilon}\}$ . Thus the function f can be learnable in  $n^{O(\frac{w}{\epsilon})}$ .

In the rest of the class, we shall prove the following theorem making use of Hastad's switching lemma.

**Theorem 3.4** DNF's of width w are  $\epsilon$ -concentrated on degree up to  $O(w \log(\frac{1}{\epsilon}))$ .

**Remark 3.5** Observe that we are replacing the  $\frac{1}{\epsilon}$ -factor with  $\log(\frac{1}{\epsilon})$ -factor on the maximum degree of the Fourier coefficients.

**Definition 3.6** A random restriction with \*-probability  $\rho$  on [n] is a random pair  $(\mathbf{I}, \mathbf{X})$  where  $\mathbf{I}$  is a random subset of [n] chosen by including each coordinate with probability  $\rho$  independently and  $\mathbf{X}$  is a random string from  $\{-1, 1\}^{|\overline{\mathbf{I}}|}$ .

Given a function  $f : \{-1,1\}^n \to \{-1,1\}$ , we shall write  $f_{\mathbf{X}\to\bar{\mathbf{I}}} : \{-1,1\}^{|\mathbf{I}|} \to \mathbb{R}$  for a restriction of f. If the function f is computable by a width w DNF, then after a random restriction with \*-probability  $\rho = \frac{1}{10w}$ , with very high probability,  $f_{\mathbf{X}\to\bar{\mathbf{I}}} : \{-1,1\}^{|\mathbf{I}|} \to \mathbb{R}$  has a O(1)-depth decision tree. The reason for this is intuitively that in each term of the DNF,  $\frac{1}{10}$  variables survive the random restriction on an average. Thus resulting in a a constant depth decision tree. This intuition is formalized in the following lemma due to Hastad.

**Theorem 3.7** (*Hastad's Switching Lemma*) Let  $f : \{-1,1\}^n \to \{-1,1\}$  be a width w computable DNF. When we apply a random restriction on the function f with \*-probability  $\rho$ , then

$$\Pr_{(\mathbf{I},\mathbf{X})}[\textit{DT-depth}(f_{\mathbf{X}\to\bar{\mathbf{I}}})>d] \leq (5\rho w)^d$$

**Theorem 3.8** Let f be computable by a width-w DNF. Then  $\forall d \geq 5$ ,

$$\sum_{|U| \ge 20 dw} \hat{f}(u)^2 \le 2^{-d+1}.$$

**Proof:**Let  $(\mathbf{I}, \mathbf{X})$  be a random restriction with  $\rho = \frac{1}{10w}$ . We know from Hastad's switching lemma  $f_{\mathbf{X} \to \bar{\mathbf{I}}}$  has a depth greater than d with a probability less than  $2^{-d}$ . Hence the following sum is nonzero (and less than 1) with a probability less than  $2^{-d}$ .

$$\sum_{S \subseteq I, |S| > d} \hat{f}_{\mathbf{X} \to \overline{\mathbf{I}}}(S)^2$$

Therefore, we have

$$2^{-d} \geq \mathbf{E}_{(\mathbf{X},\mathbf{I})} \left[ \sum_{\substack{S \subseteq I \\ |S| > d}} \hat{f}_{\mathbf{X} \to \overline{\mathbf{I}}}(S)^2 \right]$$

$$= \mathbf{E}_{\mathbf{I}} \left[ \mathbf{E}_{\mathbf{X} \in \{-1,1\}^{|\overline{\mathbf{I}}|}} \left[ \sum_{\substack{S \subseteq \mathbf{I} \\ |S| > d}} \hat{f}_{\mathbf{X} \to \overline{\mathbf{I}}}(S)^2 \right] \right]$$

$$= \mathbf{E}_{\mathbf{I}} \left[ \sum_{\substack{S \subseteq \mathbf{I} \\ |S| > d}} \mathbf{E}_{S \subseteq \mathbf{I}, \mathbf{X} \in \{-1,1\}^{|\overline{\mathbf{I}}|}} \left[ F_{S \subseteq \mathbf{I}}(\mathbf{X})^2 \right] \right] (\operatorname{Recall} F_{S \subseteq I}(x) = \hat{f}_x(S))$$

$$= \mathbf{E}_{\mathbf{I}} \left[ \sum_{\substack{S \subseteq \mathbf{I} \\ |S| > d}} \sum_{T \subseteq \overline{\mathbf{I}}} \widehat{F}_{S \subseteq \mathbf{I}}(T)^2 \right]$$

$$= \mathbf{E}_{\mathbf{I}} \left[ \sum_{\substack{S \subseteq \mathbf{I} \\ |S| > d}} \sum_{T \subseteq \overline{\mathbf{I}}} \widehat{f}(S \cup T)^2 \right]$$

$$= \sum_{U} \widehat{f}(U)^2 \mathbf{Pr}_{\mathbf{I}} [|U \cap \mathbf{I}| > d]$$

Suppose  $|U| \ge 20dw$ , then  $|U \cap \mathbf{I}|$  is binomially distributed with mean  $20dw\rho = 2d$ . Using Chernoff bound, we get that  $\mathbf{Pr}_{\mathbf{I}}[|U \cap \mathbf{I}| > d] \le \frac{1}{2}$ , when  $d \ge 5$ . Therefore we have the

$$\begin{split} \sum_{U} \hat{f}(U)^{2} \Pr_{\mathbf{I}} \left[ |U \cap \mathbf{I}| > d \right] &\leq 2^{-d} \\ \sum_{\substack{U \\ |U| \ge 20dw}} \hat{f}(U)^{2} \frac{1}{2} &\leq 2^{-d} \\ \sum_{\substack{U \\ |U| \ge 20dw}} \hat{f}(U)^{2} &\leq 2^{-d+1} \\ |U| \ge 20dw \end{split}$$

**Remark 3.9** By putting  $dw = w \log(\frac{1}{\epsilon})$ , we get the theorem 3.4

**Further References** Yishay Mansour's survey paper[4] also contains some of the ideas in this lecture notes.

## References

- [1] B. Green and T. Sanders. A quantitative version of the idempotent theorem in harmonic analysis. *ArXiv Mathematics e-prints*, Nov. 2006.
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