#### Language and Statistics II

Lecture 17: Discriminative Training, part III

Noah Smith

#### Lecture Overview

- Formal problem from assignment 3
- <del>MIRA</del>
- Kernel for trees and sequences (Collins)
- Discrimative reranking
- Transformation-based learning (if time)

#### HMM as a PCFG

HMM  $H = \langle \Sigma, Q, q_0, F, e:(Q \setminus F) \times \Sigma \rightarrow \mathbb{P}, t:Q \times Q \rightarrow \mathbb{P} \rangle$ PCFG  $G = \langle \Sigma, N, n_0, r:N \times (N \cup \Sigma)^* \rightarrow \mathbb{P} \rangle$ Let:

$$\begin{split} \Sigma &= \Sigma \\ \mathsf{N} &= \mathsf{Q} \\ \mathsf{n}_0 &= \mathsf{q}_0 \\ \mathsf{r}(\mathsf{q}, \langle \mathsf{s}, \mathsf{q}' \rangle) &= \mathsf{e}(\mathsf{q}, \mathsf{s}) \cdot \mathsf{t}(\mathsf{q}, \mathsf{q}') \quad \text{if } \mathsf{q}' \notin \mathsf{F} \\ \mathsf{r}(\mathsf{q}, \langle \mathsf{s} \rangle) &= \mathsf{e}(\mathsf{q}, \mathsf{s}) \cdot \oplus_{\mathsf{q}':\mathsf{q}' \in \mathsf{F}} \mathsf{t}(\mathsf{q}, \mathsf{q}') \end{split}$$

$$\begin{split} C(s_i, i, i) &= 1\\ C(X, i, k) &= \max(\max_Y C(Y, I, k) \times r(X, \langle Y \rangle),\\ \max_{j, Y, Z} C(Y, i, j) \times C(Z, j+1, k) \times r(X, \langle Y, Z \rangle))\\ goal &= C(N_0, 1, |\mathbf{s}|)\\ priority(C(X, i, j)) &= |\mathbf{s}| - (j - i) \end{split}$$

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**Notice:** When binary rule fires, Y is always in  $\Sigma$ .

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**Notice:** When binary rule fires, **Y** is always in  $\Sigma$ .

So j = i.

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**Notice:** When binary rule fires, Y always =  $s_i$ .

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**Notice:** When binary rule fires, Y always =  $s_i$ .

So substitute.

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**Notice:** When binary rule fires, Y always =  $s_i$ .

And  $C(s_i, i, i) = 1$ .

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#### **Notice:** When unary rule fires, Y is always in $\Sigma$ and = $s_i$ .

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**Notice:** C(s<sub>i</sub>, i, i) is unnecessary in general; only used when i = |**s**|.

r(q,  $\langle s, q' \rangle$ ) = e(q, s) · t(q, q') if q' ∉ F r(q,  $\langle s \rangle$ ) = e(q, s) · max<sub>q':q' ∈ F</sub> t(q, q')

 $C(X, |s|, |s|) = r(X, \langle s_{|s|} \rangle)$   $C(X, i, |s|) = \max_{Z} C(Z, i+1, |s|) \times r(X, \langle s_{i}, Z \rangle)$   $goal = C(N_{0}, 1, |s|)$ priority(C(X, i, j)) = |s| - (j - i)

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**Notice:** third term of C(...) is always  $|\mathbf{s}|$ .

 $C(X, |\mathbf{s}|) = r(X, \langle \mathbf{s}_{|\mathbf{s}|} \rangle)$   $C(X, i) = \max_{Z} C(Z, i+1) \times r(X, \langle \mathbf{s}_{i}, Z \rangle)$   $goal = C(N_{0}, 1)$  $priority(C(X, i)) = |\mathbf{s}| - (|\mathbf{s}| - i) = i$ 

**Notice:** third term of C(...) is always  $|\mathbf{s}|$ .

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#### **Equivalent to Back-Viterbi!**

$$\begin{split} &C(X, |\mathbf{s}|) = r(X, \langle s_{|\mathbf{s}|} \rangle) \\ &C(X, i) = \max_{Z} C(Z, i+1) \times r(X, \langle s_{i}, Z \rangle) \\ &goal = C(N_{0}, 1) \\ &priority(C(X, i)) = i \end{split}$$

 $\mathbf{r}(\mathbf{q}, \langle \mathbf{s} \rangle) = \mathbf{e}(\mathbf{q}, \mathbf{s}) \cdot \max_{\mathbf{q}': \mathbf{q}' \in \mathsf{F}} \mathbf{t}(\mathbf{q}, \mathbf{q}')$ 

#### Kernels and Dual Weights

 Recall that a kernel is a way of implicitly expanding our feature set by replacing the dot-product with new function of two vectors.

$$K(\mathbf{f}(x,y),\mathbf{f}(x',y')) = \mathbf{f}'(x,y) \cdot \mathbf{f}'(x',y')$$

 Recall also that dual formulation of linear models uses "support vectors" (sparse in SVMs, but holds for most parameter estimation methods):

$$\mathbf{w} = \sum_{i} \sum_{y' \in \text{GEN}(y_i)} \alpha_{i,y'} (\mathbf{f}(x_i, y')) \qquad K(\mathbf{f}(x, y), \mathbf{w}) = \sum_{i} \sum_{y' \in \text{GEN}(y_i)} \alpha_{i,y'} K(\mathbf{f}(x, y), \mathbf{f}(x_i, y'))$$

#### **Specialized Kernels**

- The kernel function *K* is just a measure of similarity.
  - Higher = more similar.
- A function of two objects (any objects!) is a kernel if it equates to taking a dot product in some feature space.
- Let's reason backwards ...

– What feature spaces would we like?

#### Tree Kernels (Collins and Duffy, 2002)

- The feature vector implied by the use of a CFG is a vector of **rule counts**.
- Implied kernel:

$$K(\tau_1, \tau_2) = \sum_{r \in G} \operatorname{count}(r; \tau_1) \times \operatorname{count}(r; \tau_2)$$

- Rules are just "bits" of structure.
- Scaling up: what if we could match up all subtree types?

#### Subtree Features



2 (A (C B)) 1 (A ((C D A) B) 1 (C (D A)) 1 (A ((C D A) (B w)) 1 (D x) 1 (A ((C (D x) A) B) 1 (C y) 1 (A ((C (D x) A) (B w)) 1 (B z) 1 (A ((C D (A C B)) 1 (B w) (B w)) 0 (D (B B) 1 (A ((C (D x) (A C B)) 0 (A (B C) (B w)) 0 (B (C C) 1 (A ((C (D x) (A (C y) (B z))) (B w))

#### "All Subtrees"

- Not a new idea.
  - Bod (1998 and before): "data-oriented parsing"
    - many tricks required not efficient
  - Goodman (1996): convert DOP model to an approximating PCFG
- Collins and Duffy (2002): can implement this as a kernel!
  - Avoid the Really Big feature representation.
  - Train using discriminative methods.
- Note: subtrees contain full rules; can't break just anywhere.

#### The All-Subtrees Kernel

$$K(\tau_{1},\tau_{2}) = \sum_{\tau} \operatorname{count}(\tau;\tau_{1}) \times \operatorname{count}(\tau;\tau_{2})$$

$$= \sum_{\tau} \left( \sum_{\tau_{1} \subseteq \tau_{1}} \delta(\tau,\tau_{1}) \right) \left( \sum_{\tau_{2} \subseteq \tau_{2}} \delta(\tau,\tau_{2}) \right)$$

$$= \sum_{\tau_{1}^{i} \subseteq \tau_{1}} \sum_{\tau_{2}^{i} \subseteq \tau_{2}} \sum_{\tau} \delta(\tau,\tau_{1}) \delta(\tau,\tau_{2})$$

$$= \sum_{n_{1}^{i} \subseteq \tau_{1}} \sum_{n_{2}^{j} \subseteq \tau_{2}} \left[ \# \text{ of matching subtrees rooted at } n_{1}^{i}, n_{2}^{j} \right]$$
Summing over nodes in the two trees!

#### **Dynamic Program**

$$\Delta(n_1^i, n_2^j) = \begin{cases} 0 & \text{if different productions at roots} \\ 1 & \text{if same production and preterminal roots} \\ \prod_k \left(1 + \Delta(n_1^{\text{kid}(i,k)}, n_2^{\text{kid}(j,k)})\right) & \text{if same production and not preterminal roots} \end{cases}$$

Thought question: what's the runtime?









matches at (higher) C: 2 matches at (higher) B: 1

$$\Delta(\mathsf{A}_{1,4}, \, \mathsf{A}_{1,4}) = (1 + \Delta(\mathsf{C}_{1,3}, \, \mathsf{C}_{1,3})) \times (1 + \Delta(\mathsf{B}_{4,4}, \, \mathsf{B}_{4,4})) = 6$$

#### NB

- Labeled sequences are trees, too.
  - As we saw!
- So you can define an "all-fragments" kernel for labeled sequences in exactly the same way.
- Try it!

## Problem with the Dual Representation

- Decoding for parsing and tagging models usually involves dynamic programming (max-times).
  - For that, we need **w**.
  - Need to convert back to the primal.
- How many different  $\alpha$ ?
  - Exponential! (Size of  $\Sigma_i GEN(x_i)$ .)

$$\mathbf{w} = \sum_{i} \sum_{y' \in \text{GEN}(y_i)} \alpha_{i,y'} (\mathbf{f}(x_i, y')) \qquad K(\mathbf{f}(x, y), \mathbf{w}) = \sum_{i} \sum_{y' \in \text{GEN}(y_i)} \alpha_{i,y'} K(\mathbf{f}(x, y), \mathbf{f}(x_i, y'))$$

#### **Discriminative Reranking**

- Reduce the size of GEN.
- Use a base model to propose a list of the top *N* structures.
  - Usually done approximately until 2005.
  - Goodman (1999): *N*-best semiring (not efficient)
  - Huang and Chiang (2005): general solution to N-best lists for (max-plus) dynamic programming algorithms.
- Train a model to discriminate **correct** structure from other top-*N* structures.

#### **Discriminative Reranking**

- Collins (2000):
  - Exp-loss evaluated
  - Log-loss defined, not tested (more expensive)
- See Riezler et al. (2002) and Charniak and Johnson (2005) for log-loss results.
- Don't need kernels for this!
  - Still unclear how easily we can mix kernels with log-loss.
- Great way to throw in features that are too expensive to put into a dynamic programming algorithm.

# Everything That's Old is New Again

- Brill (1992): "transformation-based learning"
- No model and no weights.
- Transformation: a rule that modifies the structure.
  - E.g., "if the word is *dog* and the word before it is *the*, tag the word NOUN."
  - Think of these as "find-replace" operators.
- What is learned?
  - A sequence of deterministic transformations.
- Applied to tagging, NER, parsing, ...
- Application: apply transformations in sequence.
   Really fast!
- Training ...

#### **TBL** Training

- Specify all rule templates.
- Apply baseline to training data.
- $L = \langle \rangle$
- Iterate until performance decreases on dev set:
  - Choose the rule R that increases net accuracy by the most (if it exists; else quit). (Expensive search!)
  - Add the rule to the end of L.
  - Apply R to the training data.
- Return L.

Notes:

This is a greedy learner.

Error rate on training data is **guaranteed** to decrease until termination.

#### Recap of Discriminative Methods: Attacking Error Directly

- Linear separation and the perceptron
- Conditional estimation, Boosting, Maximum Margin training
  - 0-1 loss, log-loss, exp-loss, hinge loss
- Lagrange duality
- Support vector machines
- Kernels
  - Tree kernels
- Reranking
- Transformation-based learning

#### Next Time ...

#### Unsupervised learning: models gone wild!