

Robust lossy detection using sparse measurements

The regular case

Balakrishnan Narayanaswamy
(Joint work with Rohit Negi and Pradeep Khosla)

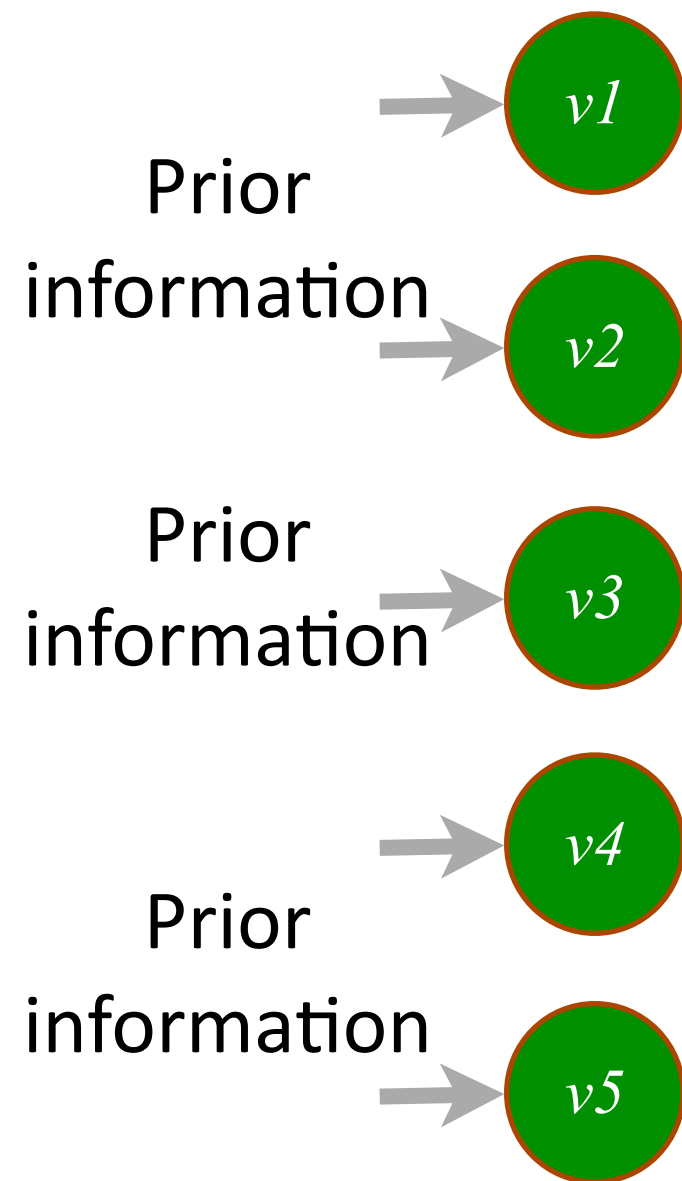
There's Nothing So Practical As a Good Theory
-Kurt Lewin

CarnegieMellon

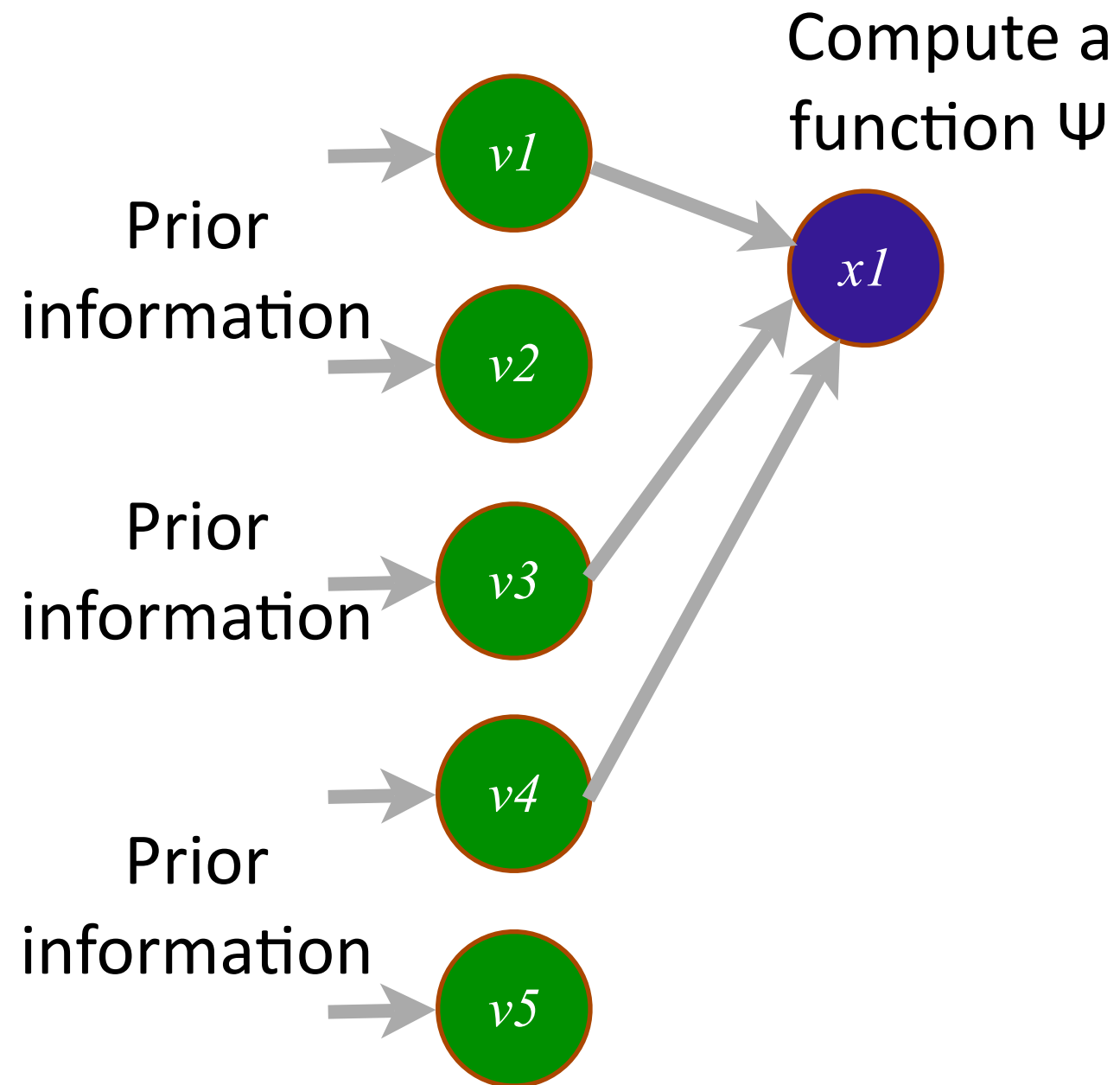


A graphical model for measurements

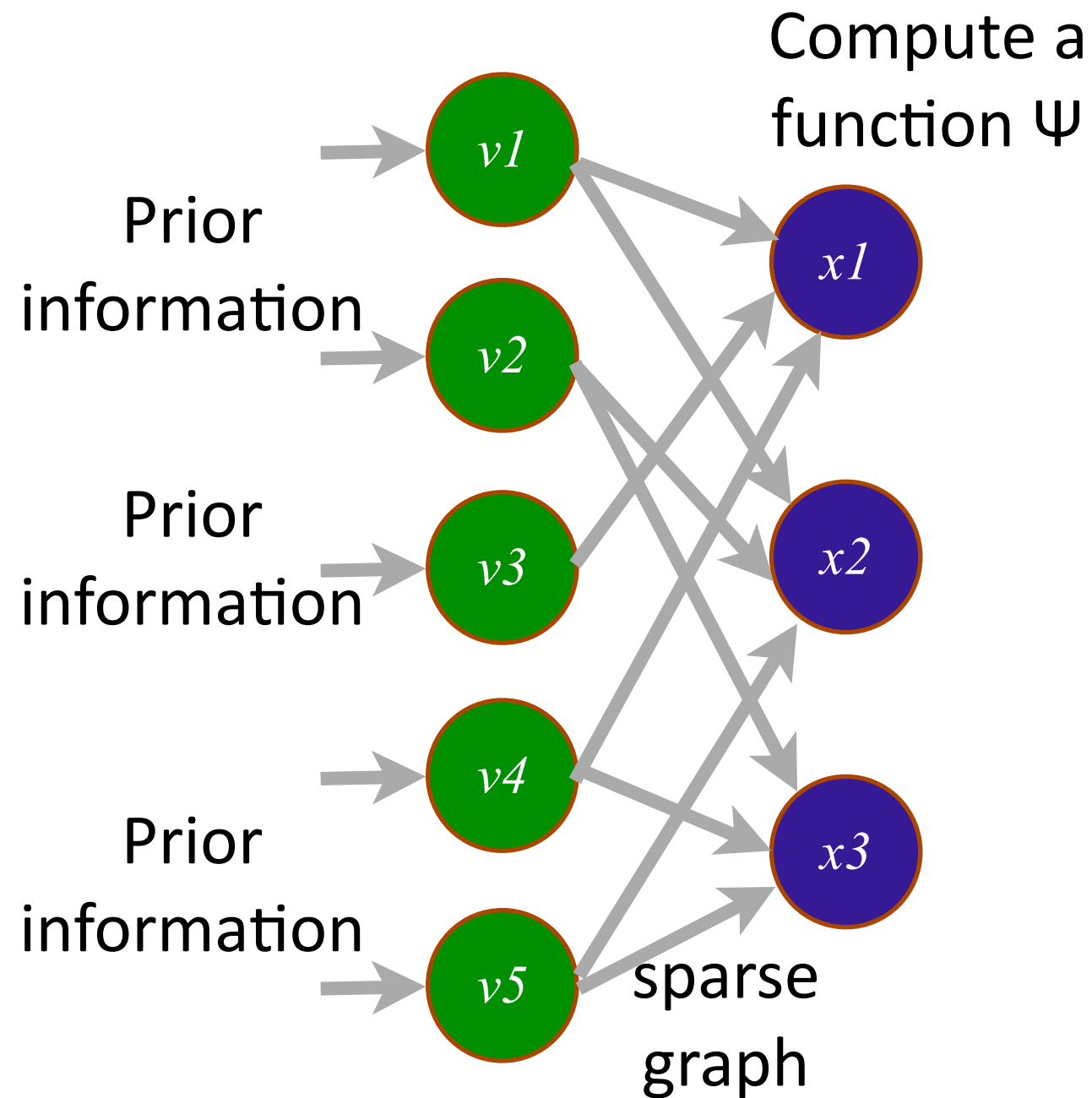
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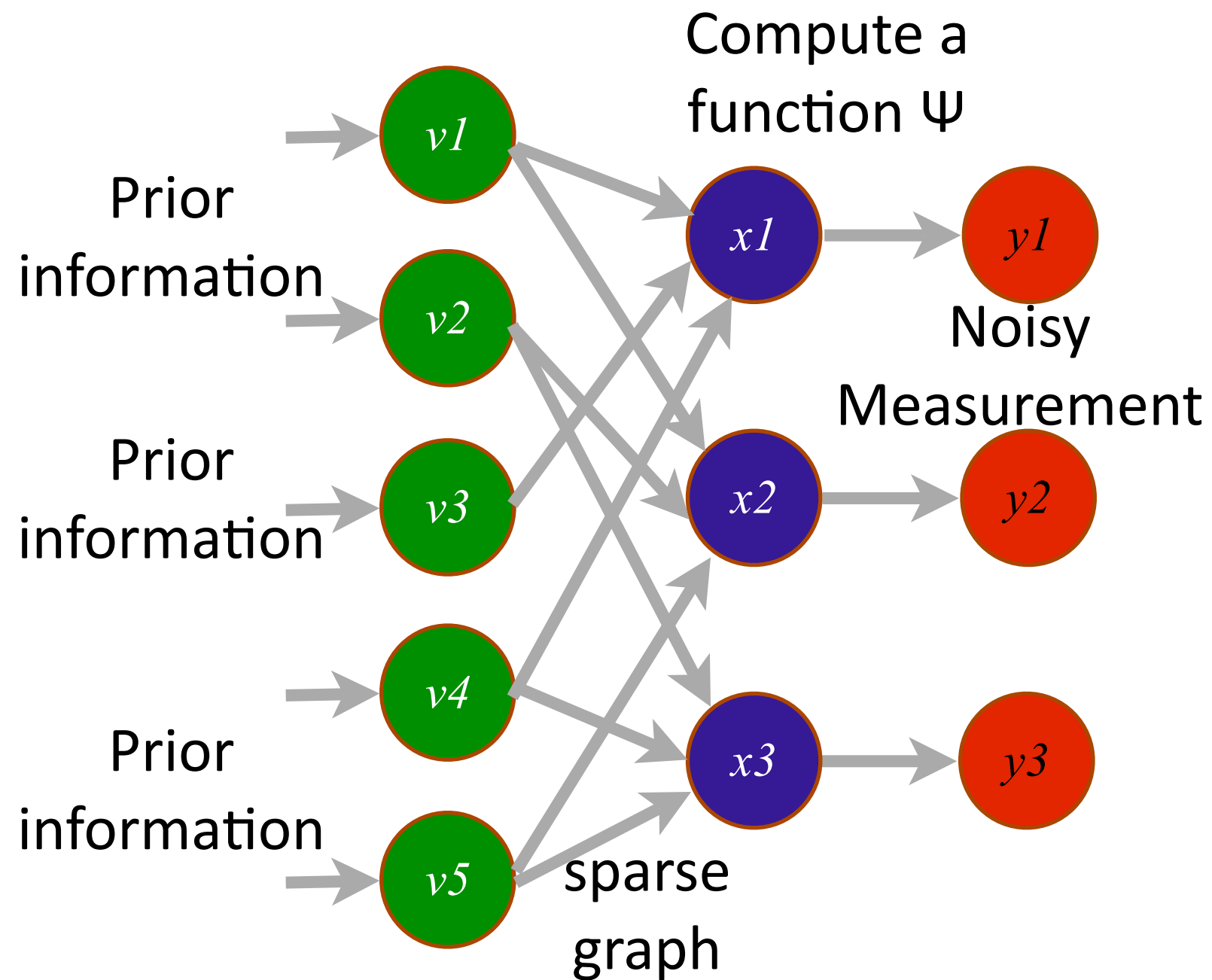
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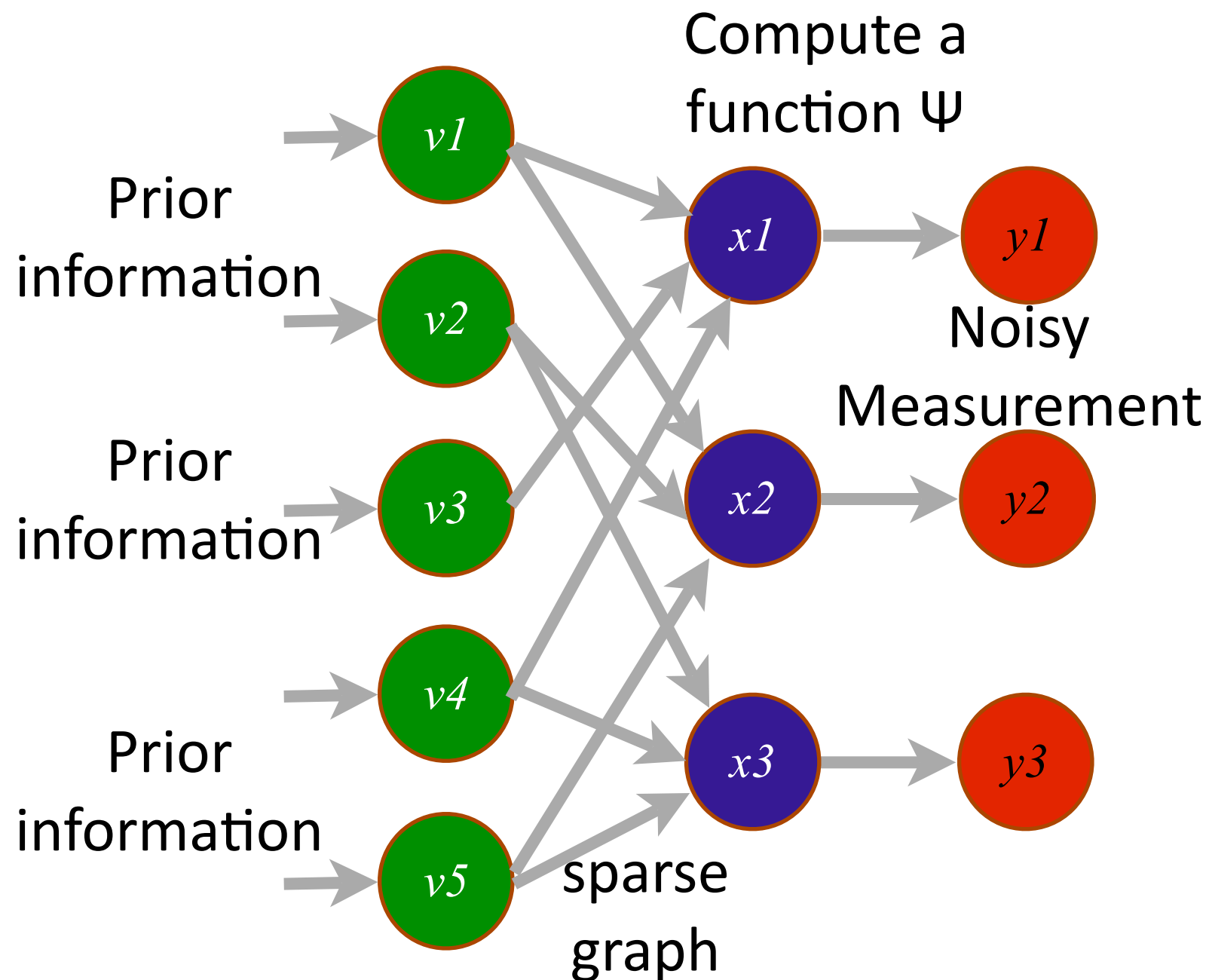
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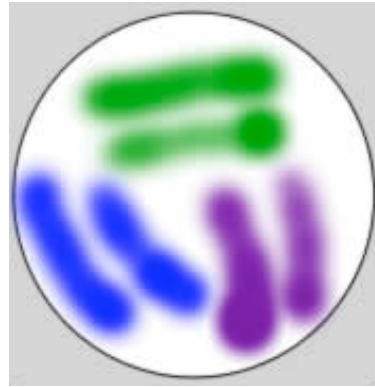


When can we reconstruct the input from the noisy, sparse measurements ?

The need for population wide genetic screening

The need for population wide genetic screening

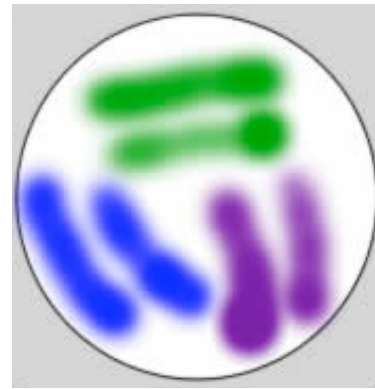
Diploid



Two Homologous copies of
each chromosome

The need for population wide genetic screening

Diploid

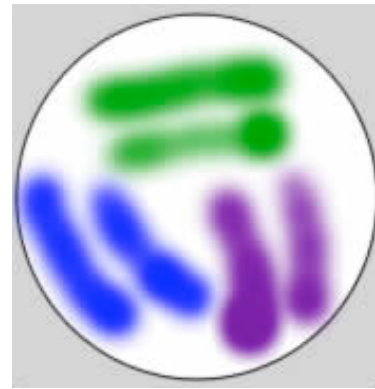


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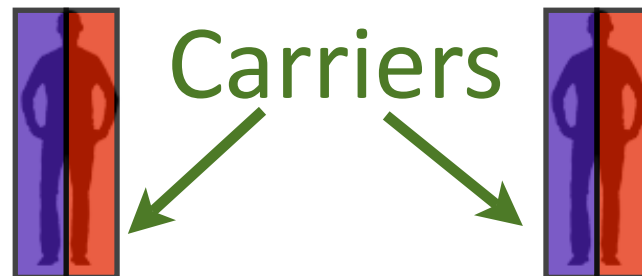
Sickle-cell anemia,
Albinism, Cystic Fibrosis,
Tay-Sachs Disease,
Gaucher's Disease

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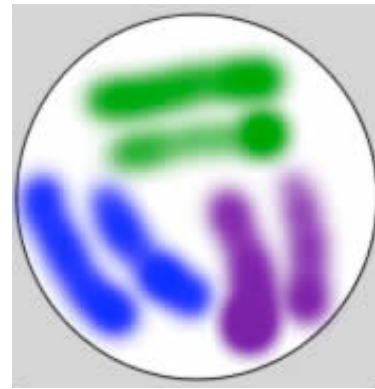
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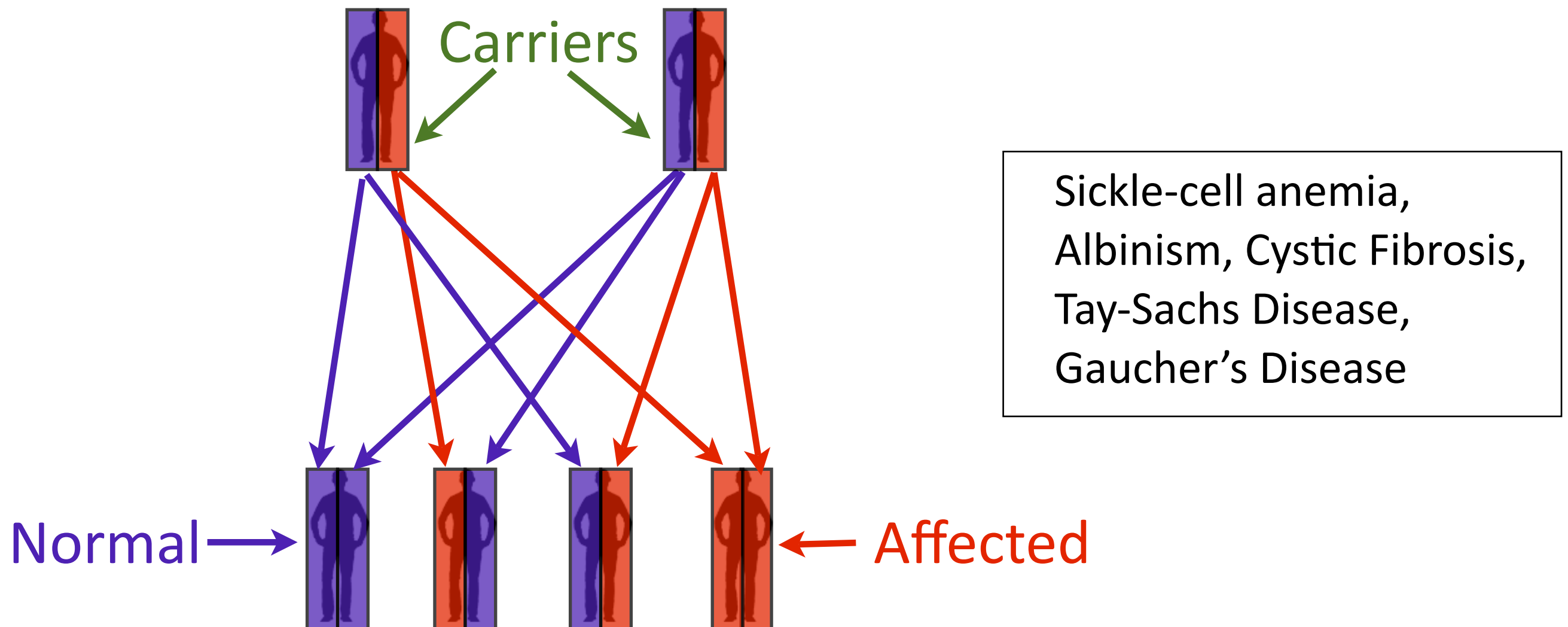
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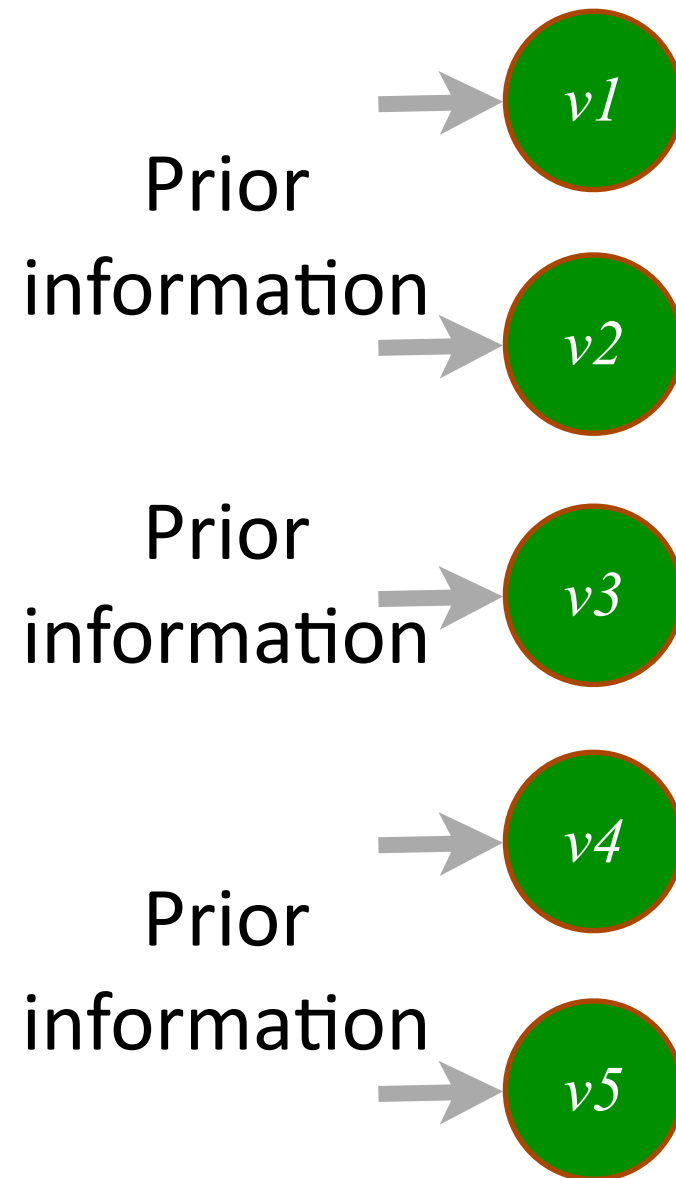
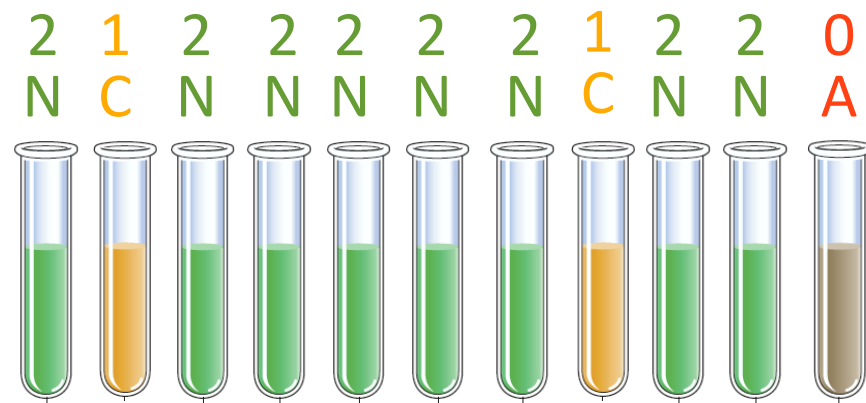
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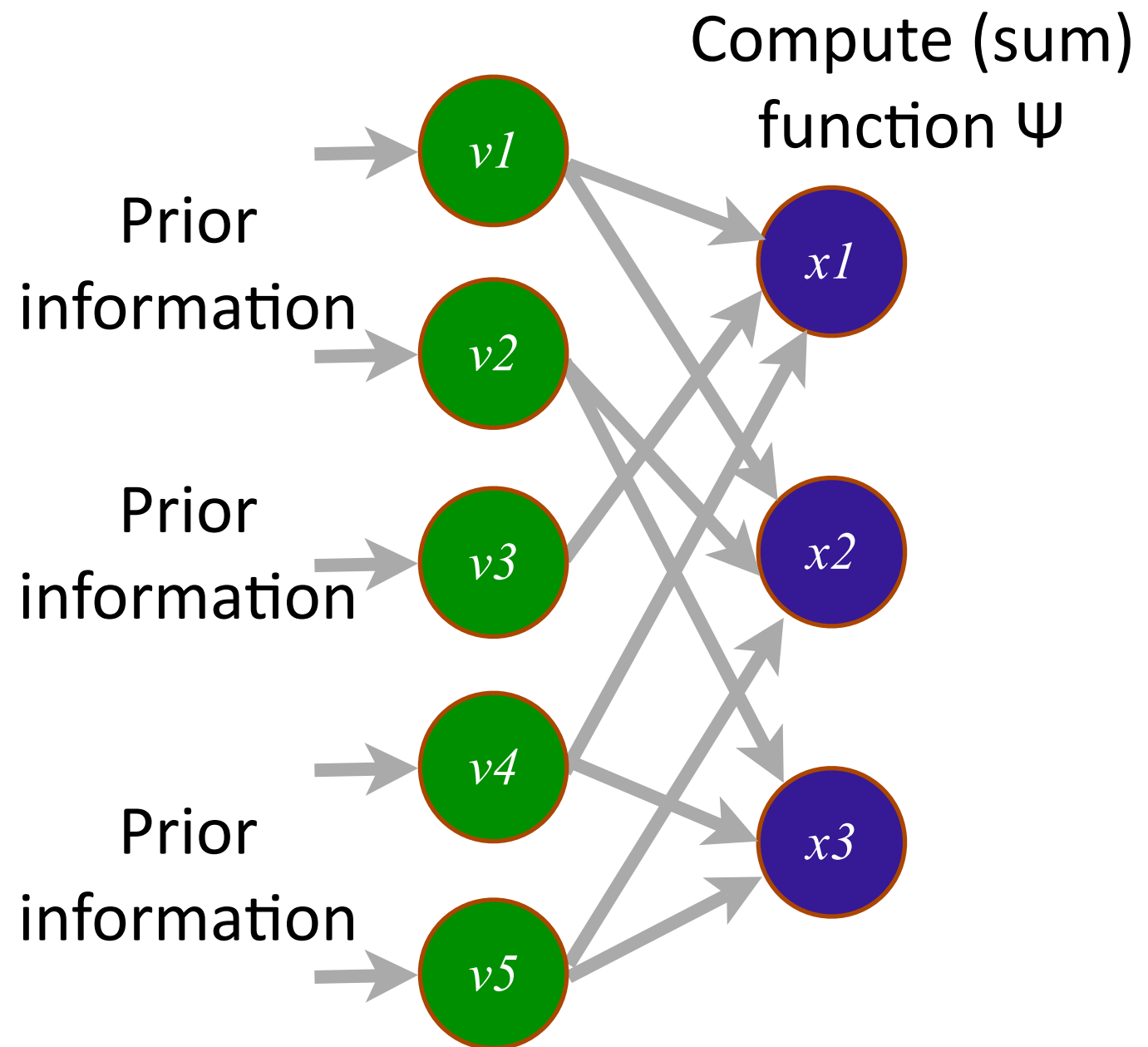
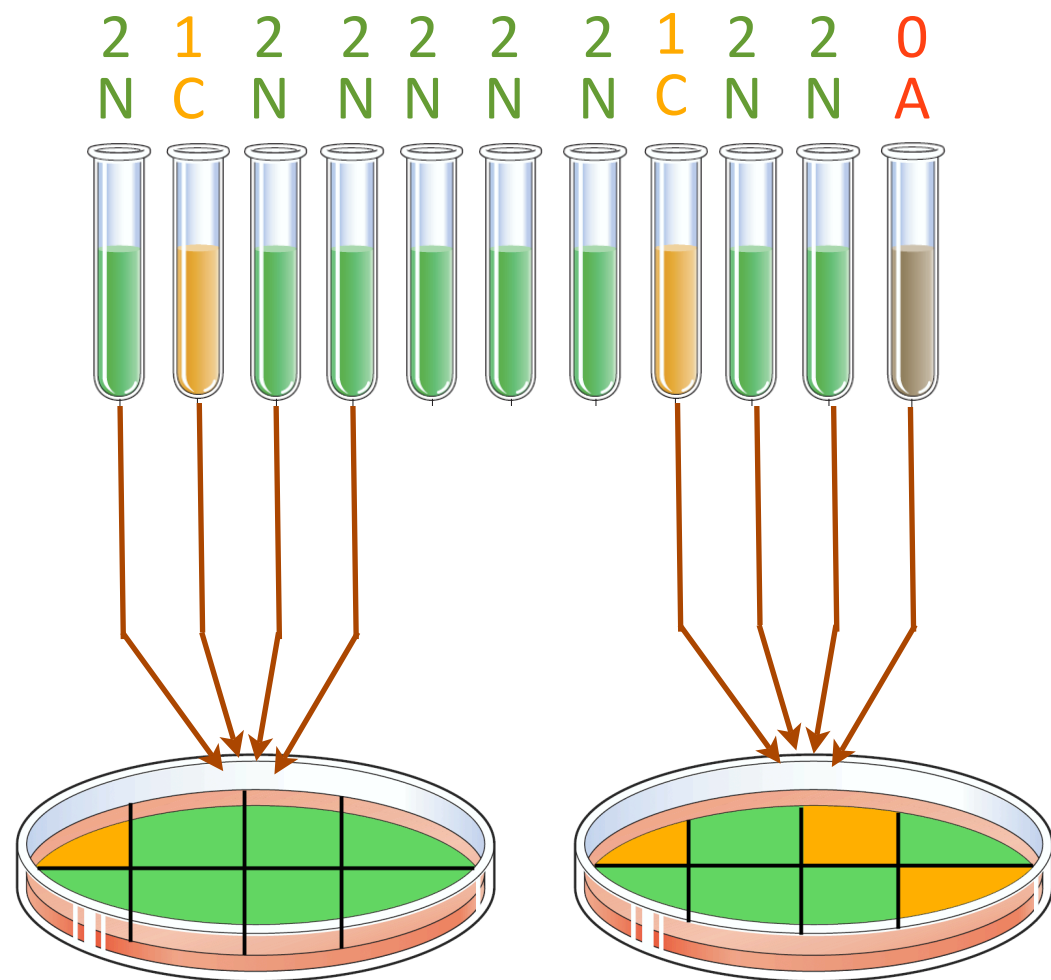
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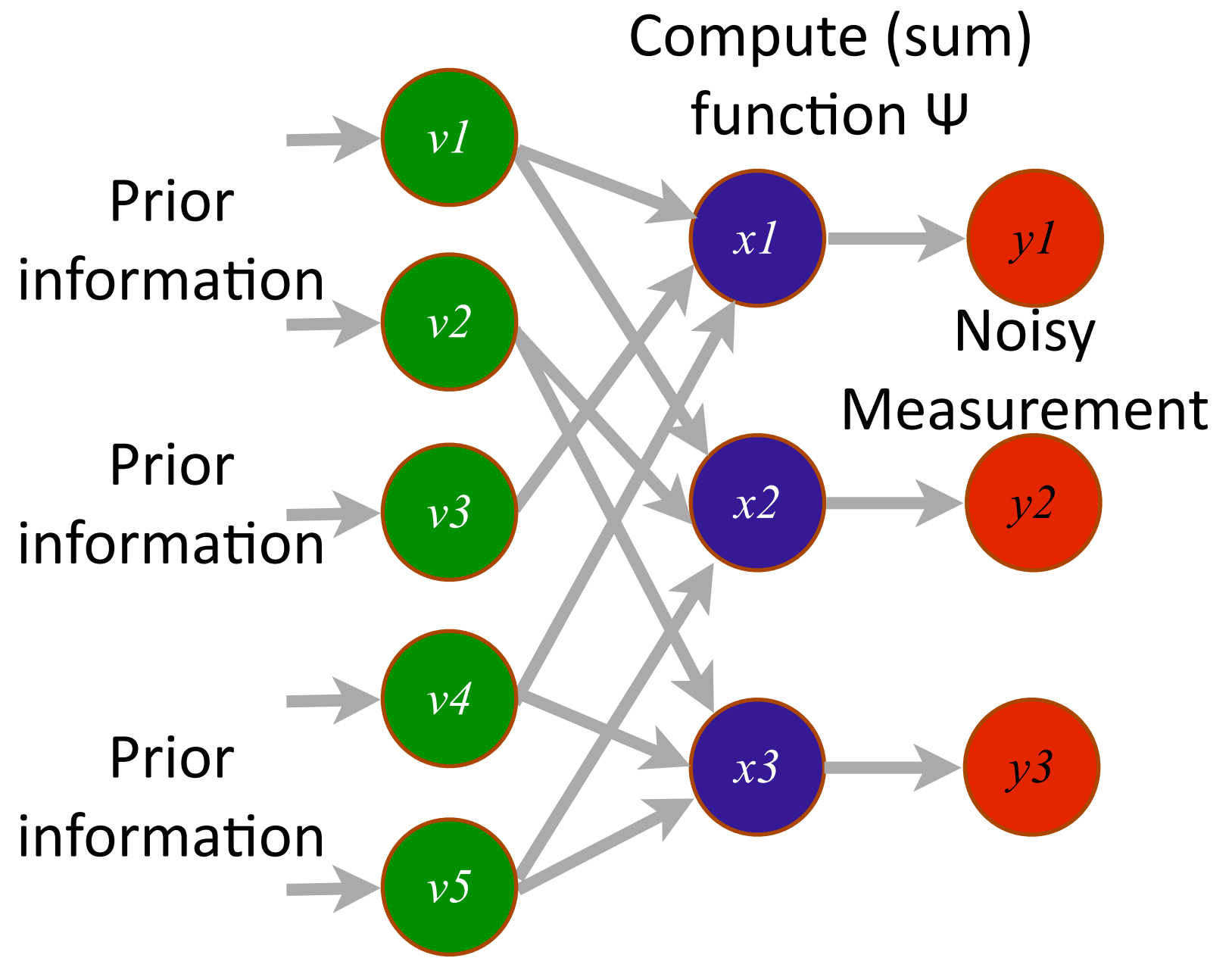
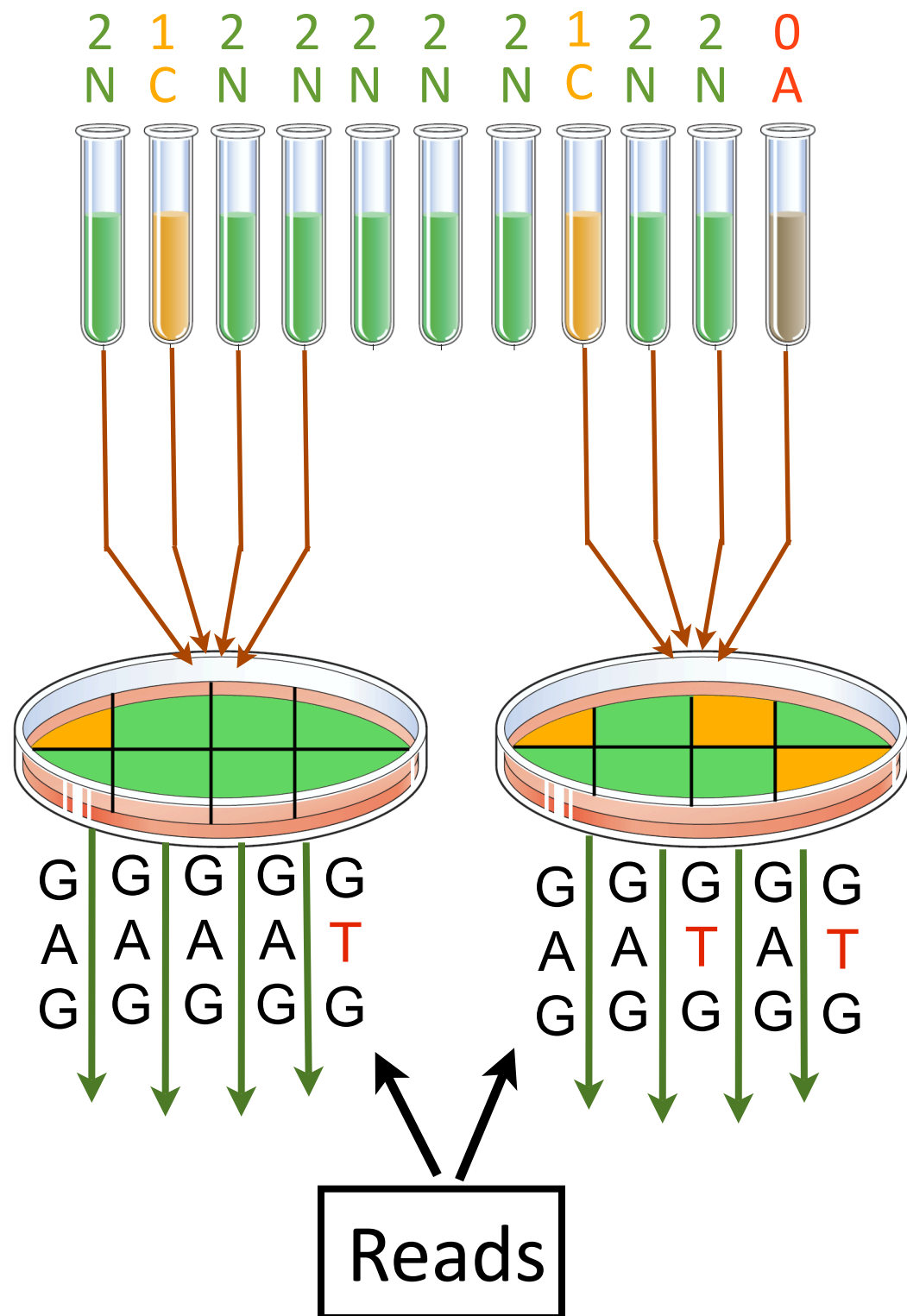
Pooling designs as a sparse graphical model



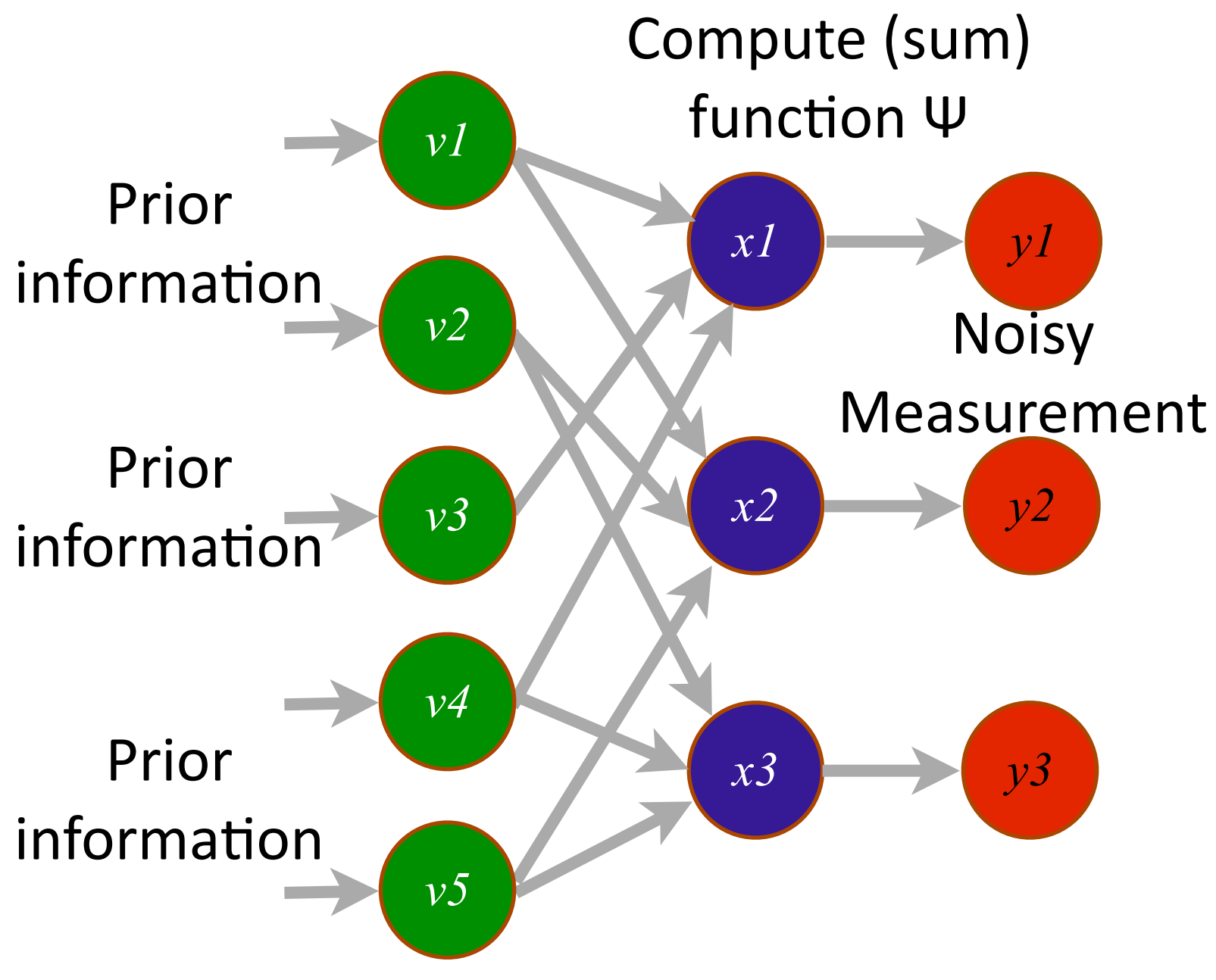
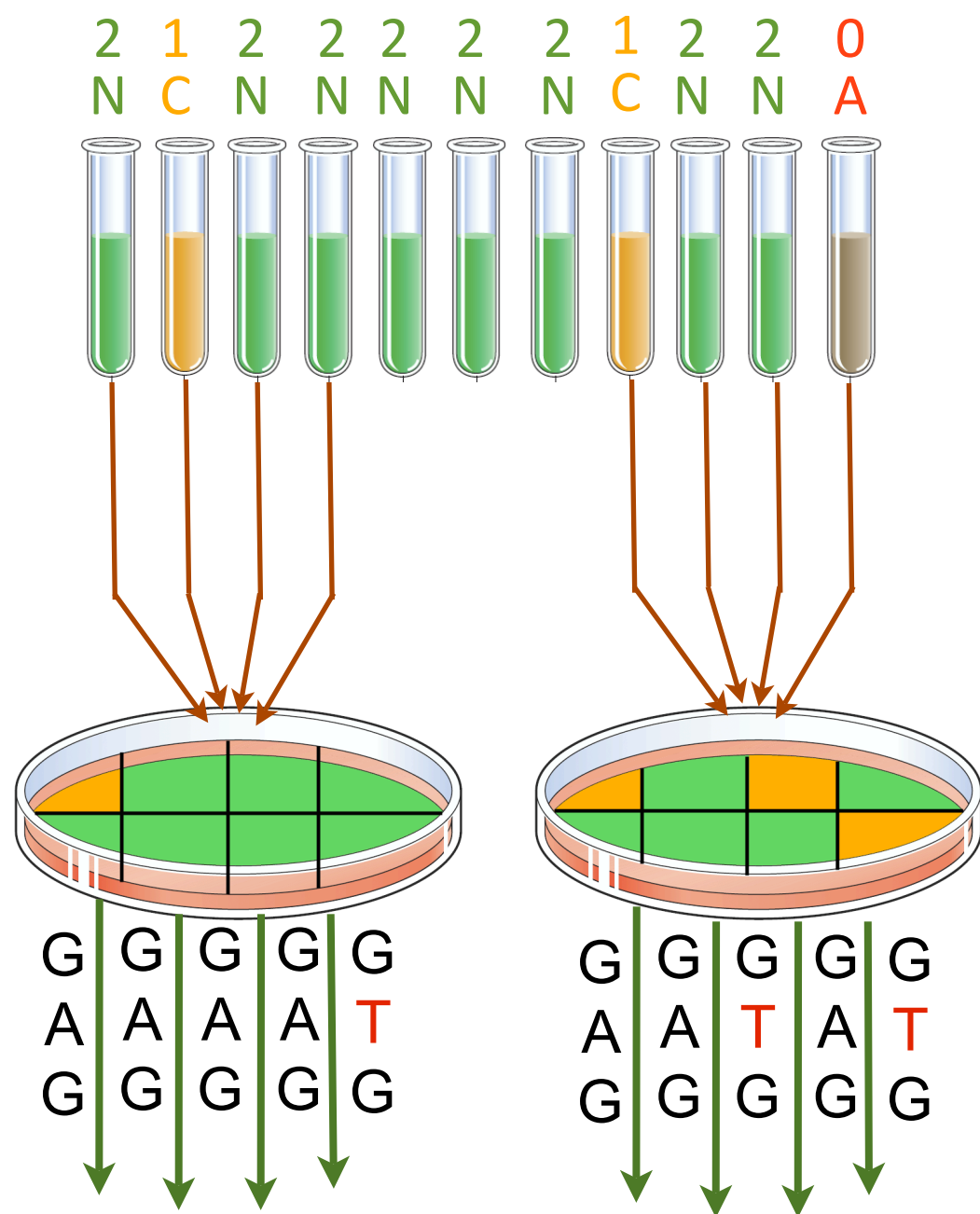
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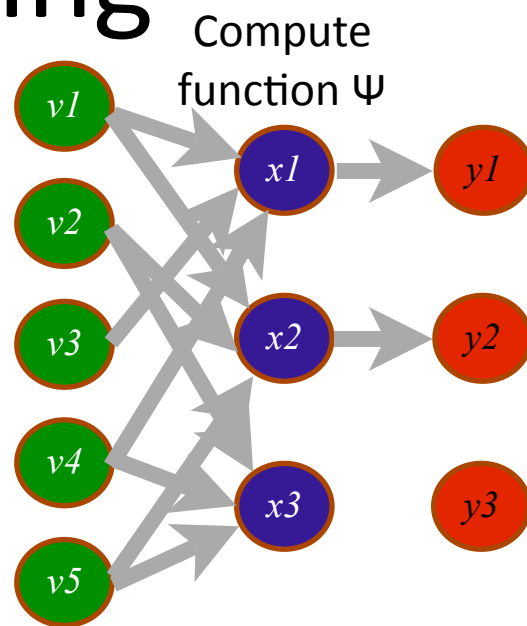
Pooling designs as a sparse graphical model



Sparse regular pooling designs due to practical constraints

Connections to many interesting problems/applications

- Group Testing
- Compressed sensing
- Sensor networks
- LT codes / LDGM codes
- Multi-user detection
- Modeling the olfactory system



Connections to many interesting problems/applications

- Group Testing

Ψ is OR function

Input/Output binary

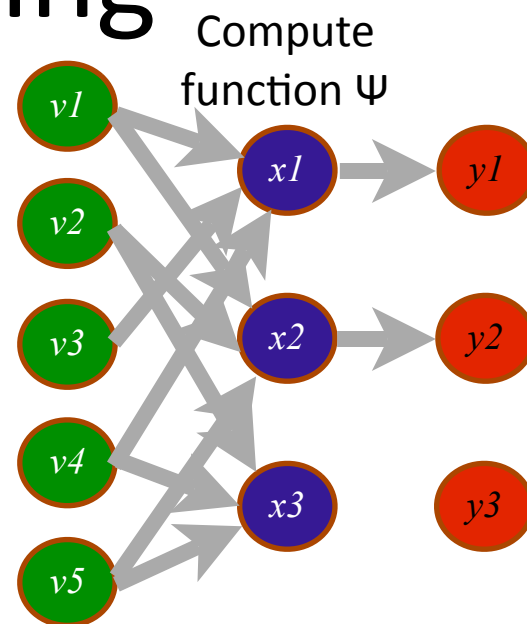
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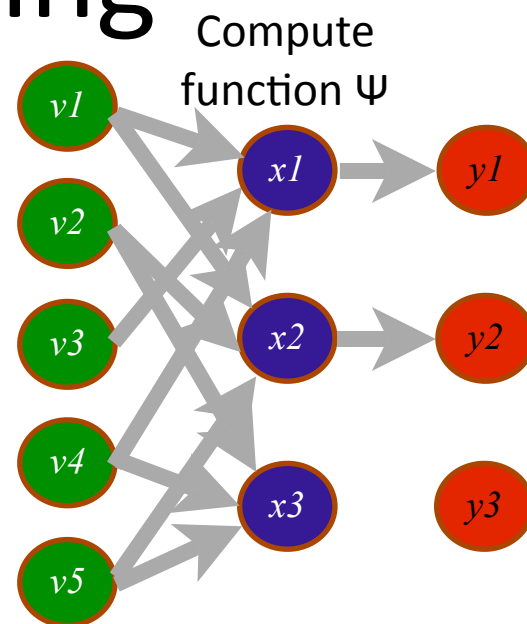


Connections to many interesting problems/applications

- Group Testing

Ψ is OR function
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- General functions Ψ
- Non-binary inputs and outputs

- Info. Theoretic
- Focus on noise
- Graph Structure
- Probabilistic priors

$$\text{Rate } R = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$

The capacity of sparse, regular measurements

Theorem : A rate R is achievable (for an allowable distortion D) if,

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The capacity of sparse, regular measurements

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$$R < C_{LB}(D) = \min_{\lambda: Dis(\lambda) > D} \frac{T(\lambda)}{[H(\lambda) - H(\gamma)]}$$

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For sparse, regular measurement structures

$$T(\lambda) = -H(Y|V) + cH(\lambda) + \inf_{\kappa: \text{sparse graph constraints}} -H(\kappa) - \sum_{a,b,o} \kappa(a,b) P_{y|v}(o|a) \log P_{y|v}(o|b)$$

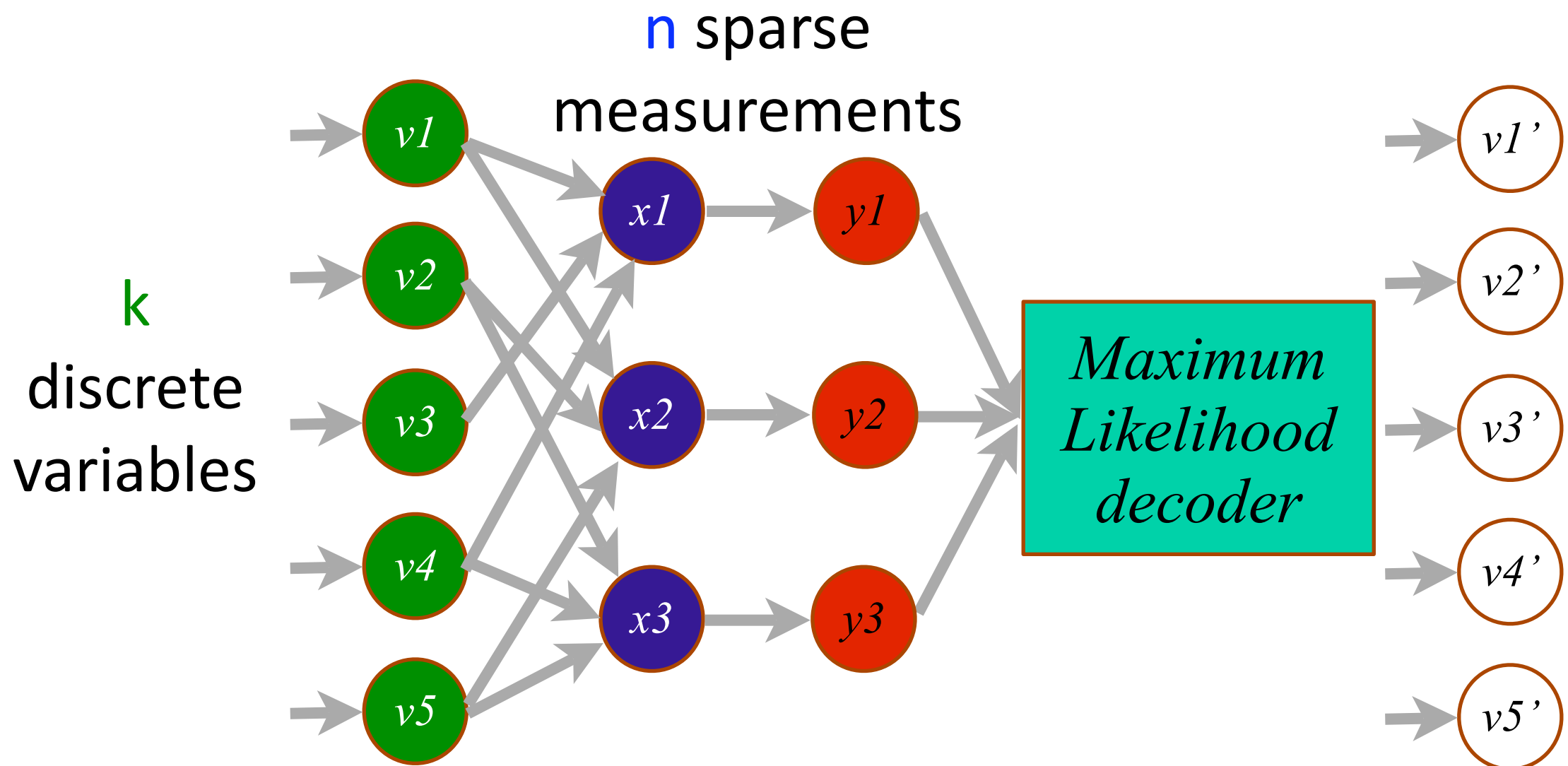
Outline

- Application : Pooling Designs for genetic screening
- Related Problems
- Information theoretic formulation
- Intuition
- Illustration of the result

Analogs : channel coding + rate distortion

$$\text{Rate } R = k/n = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$

$$\text{Distortion} = (1/k) \text{ Hamming Distance}(v, v')$$



An Information theory for measurements

$$\text{Rate } R = k/n = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$

Distortion = $(1/k)$ Hamming Distance(v, v')

Error if Distortion $> D$

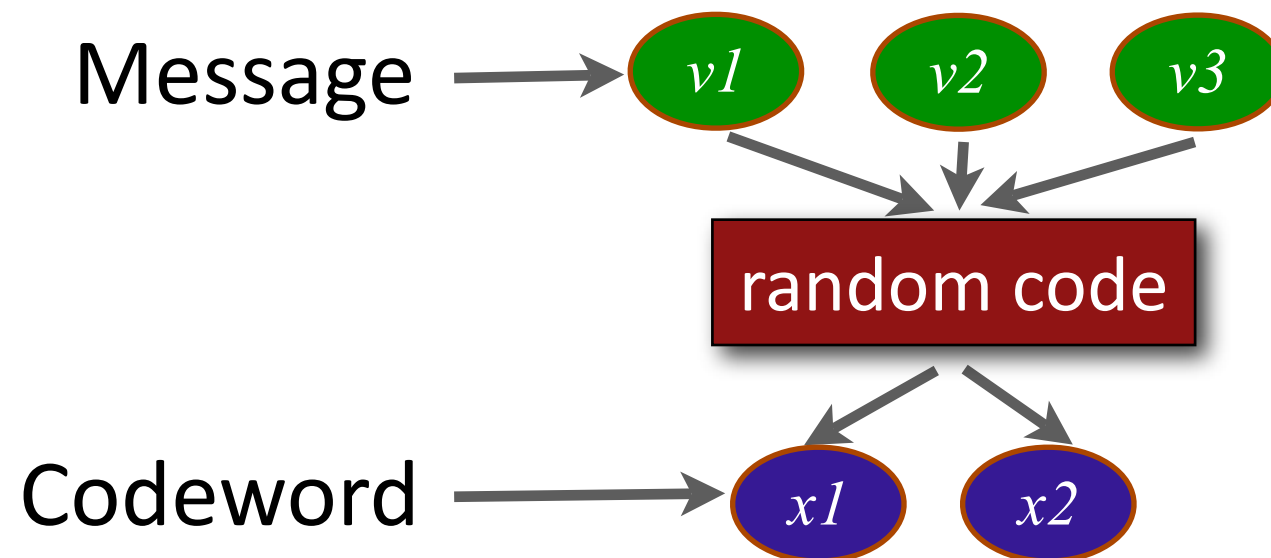
Capacity : $C(D)$: Maximum R such that
 $\Pr(\text{Error}) \rightarrow 0$ as $n \rightarrow \infty$

We lower bound the Capacity : $C_{LB}(D)$

Outline

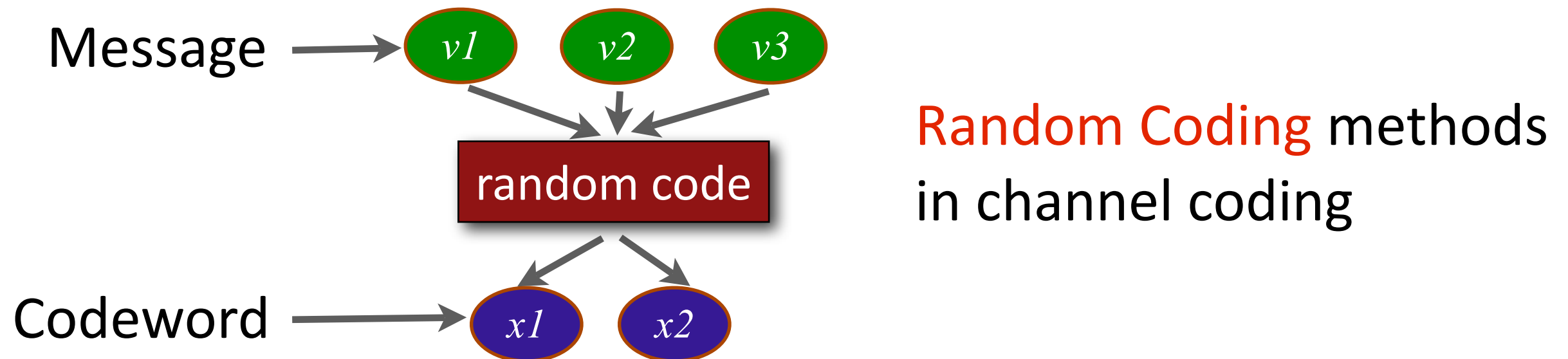
- Application : Pooling Designs for genetic screening
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Insight : Parallels to coding theory + rate distortion



Random Coding methods
in channel coding

Insight : Parallels to coding theory + rate distortion



Can we develop a random measurement argument ?

A proof using random measurements

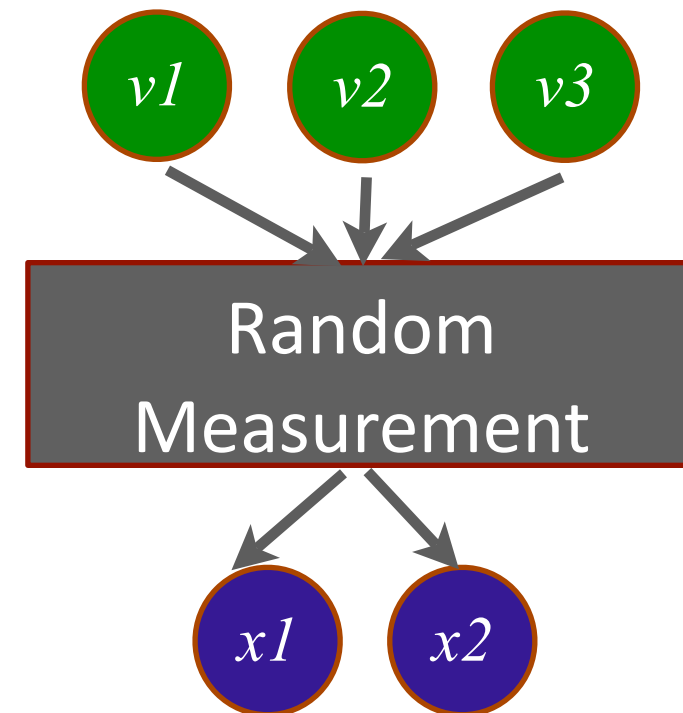
Random measurement configuration

→ generates codebook

Random
Measurement

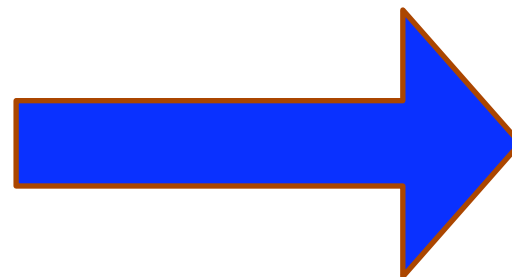
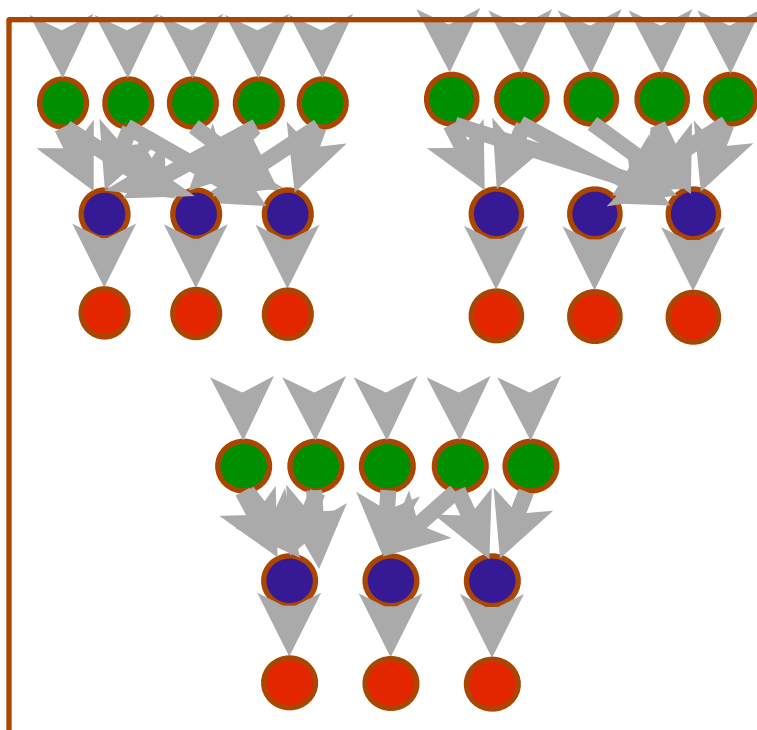
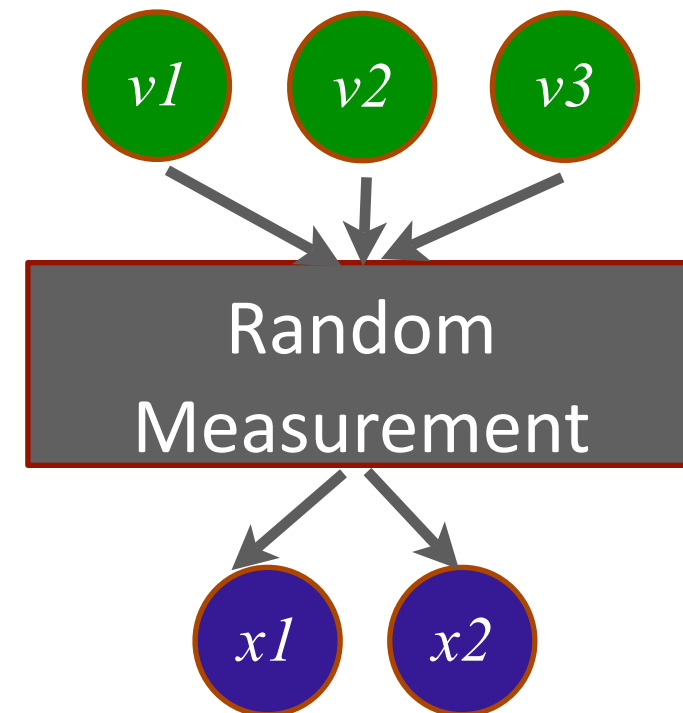
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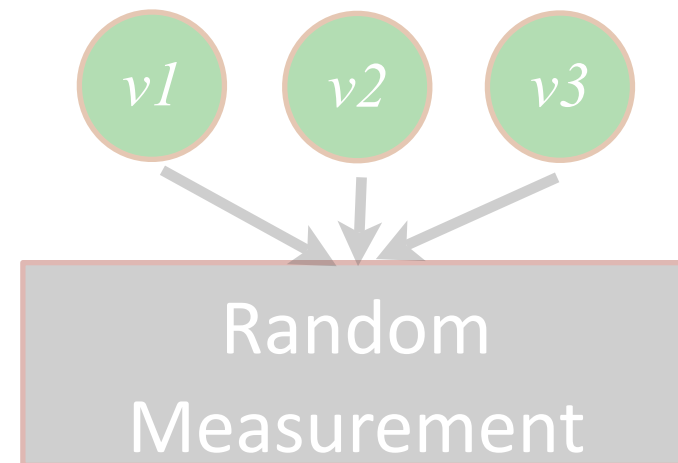


Average Error

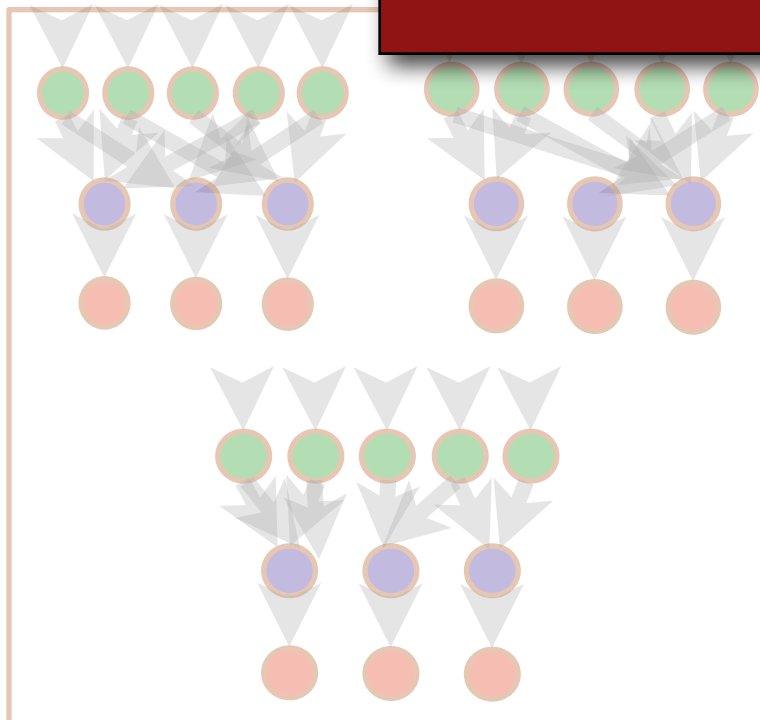
If average error $\rightarrow 0$, then
for some configuration error $\rightarrow 0$

A proof using random measurements

Random measurement configuration
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Choose measurement structure
not codewords!



Average Error

If average error $\rightarrow 0$, then
for some configuration error $\rightarrow 0$

Union Bounding : Gallager-Fano bounding technique

$$\begin{aligned} Pr(\text{error} | \mathbf{v} \text{ is true}) &= Pr(\text{Decode to } \mathbf{v}' \text{ s.t. } \text{distortion}(\mathbf{v}, \mathbf{v}') > D \mid \mathbf{v} \text{ is true}) \\ &\leq \sum_{\mathbf{v}' \neq \mathbf{v}} Pr(\text{Decode to } \mathbf{v}' \mid \mathbf{v} \text{ is true}) \end{aligned}$$

Exponential number of terms !!!

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Exponential number of terms !!!

Group terms into polynomial number of groups g using symmetry

$$\begin{aligned} Pr(\text{error} | \mathbf{v} \text{ is true}) &\leq \sum_g (\text{number of } \mathbf{v}' \text{ in } g) Pr(\text{Decode to } \mathbf{v}' \text{ in } g \mid \mathbf{v} \text{ is true}) \\ &\leq |g| \max_g (\text{number of } \mathbf{v}' \text{ in } g) Pr(\text{Decode to } \mathbf{v}' \text{ in } g \mid \mathbf{v} \text{ is true}) \end{aligned}$$

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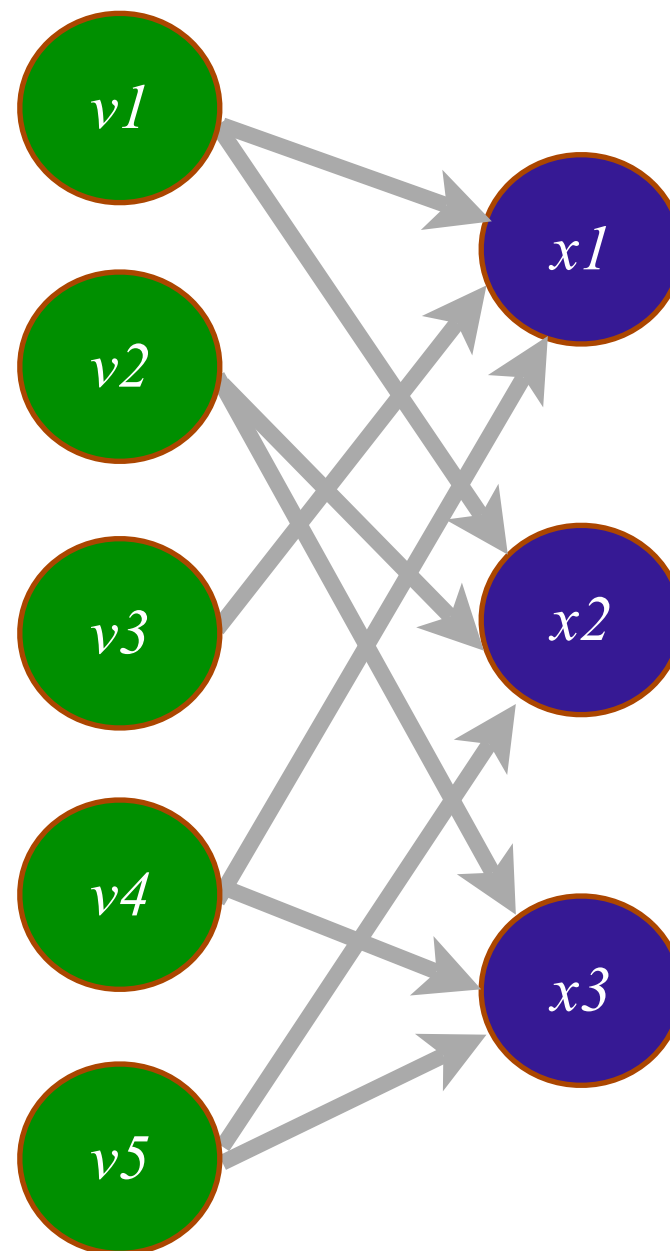
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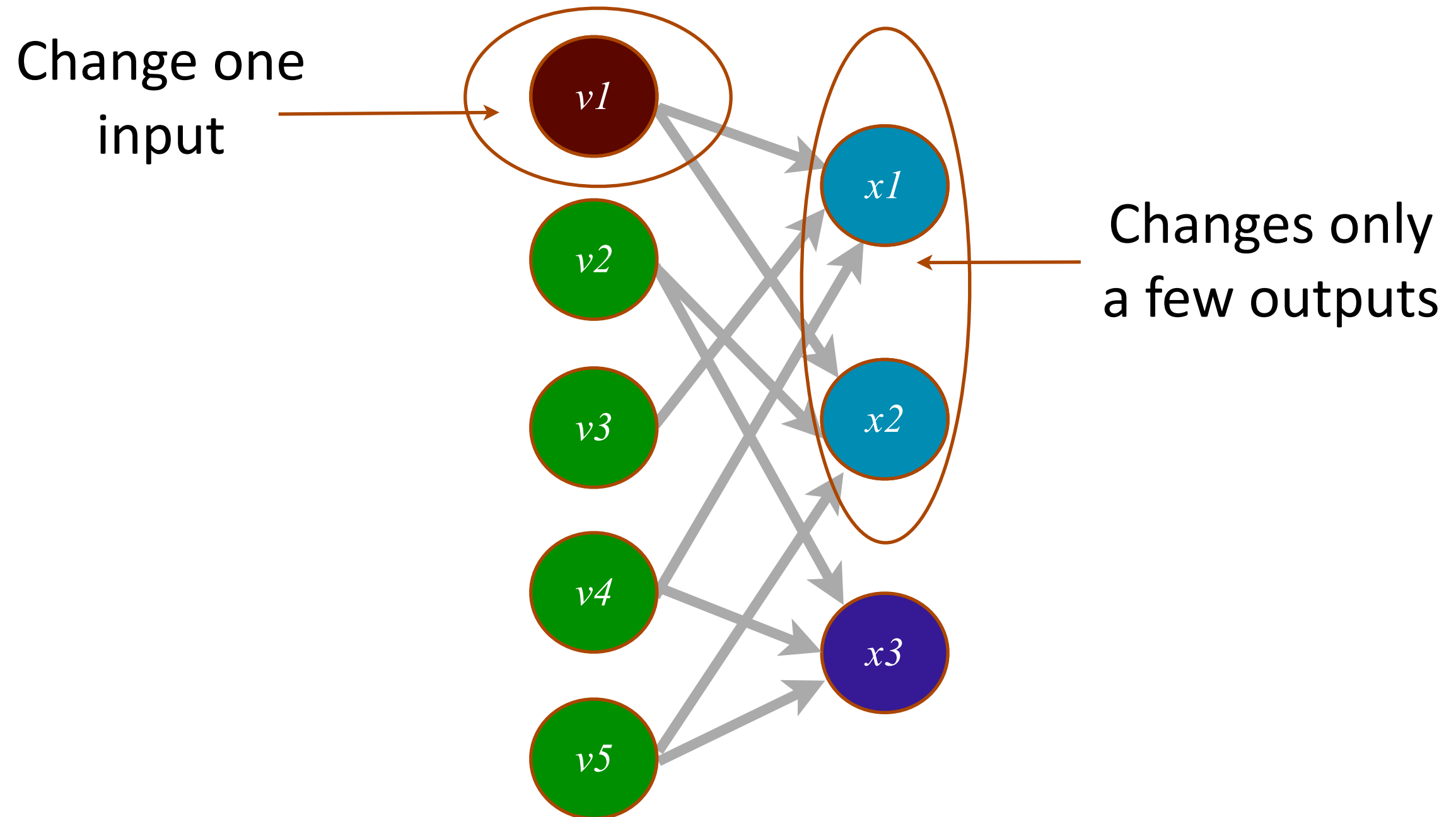
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Easy when the codewords are i.i.d !

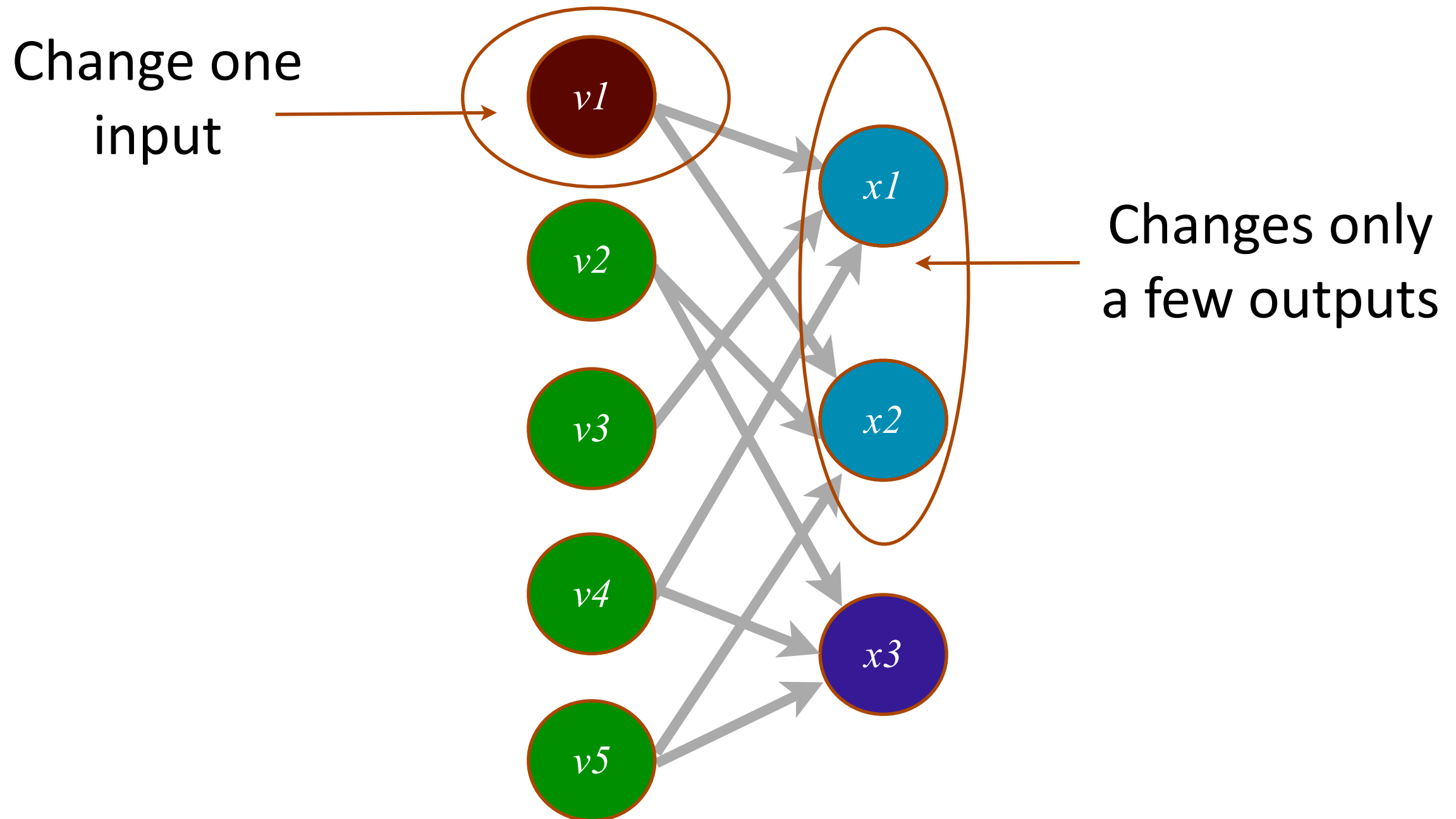
Complication - Loss of Symmetry : Non-i.i.d codewords



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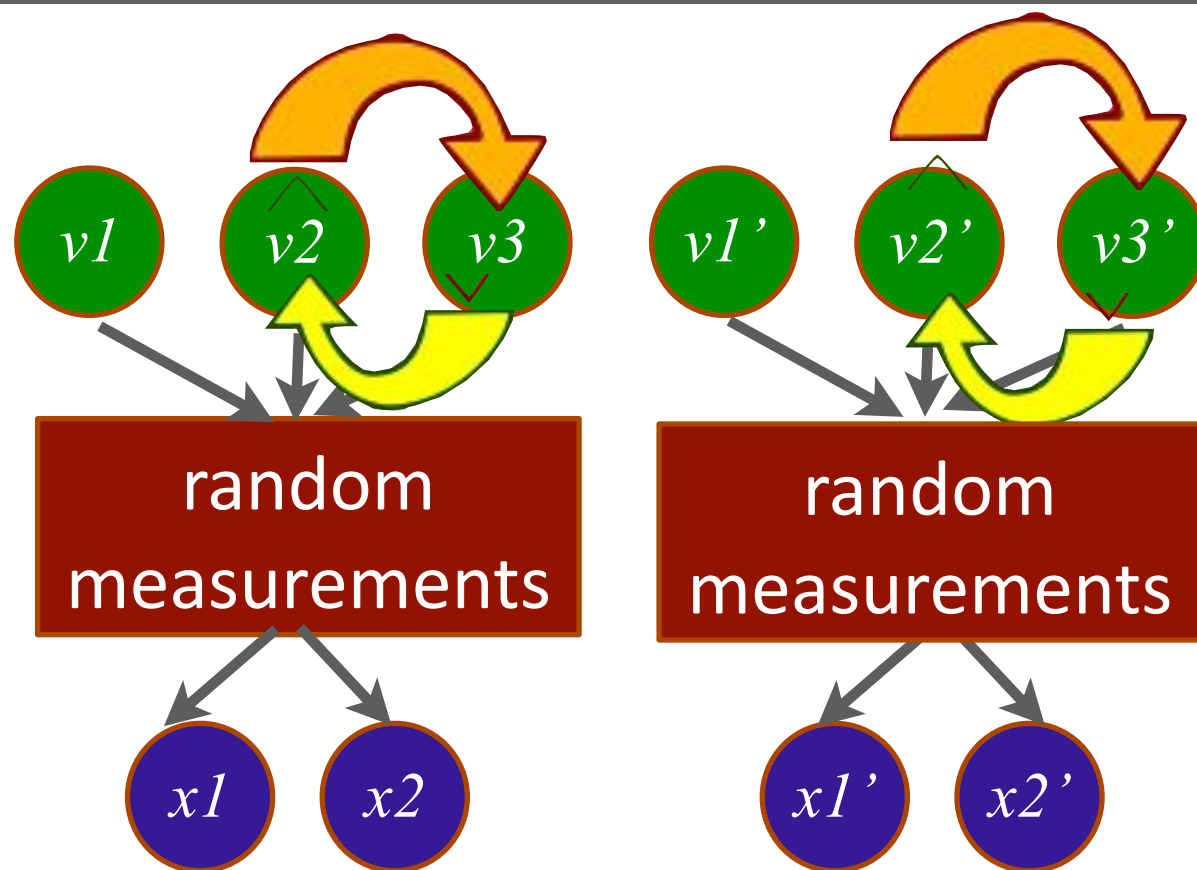


Complication - Loss of Symmetry : Non-i.i.d codewords

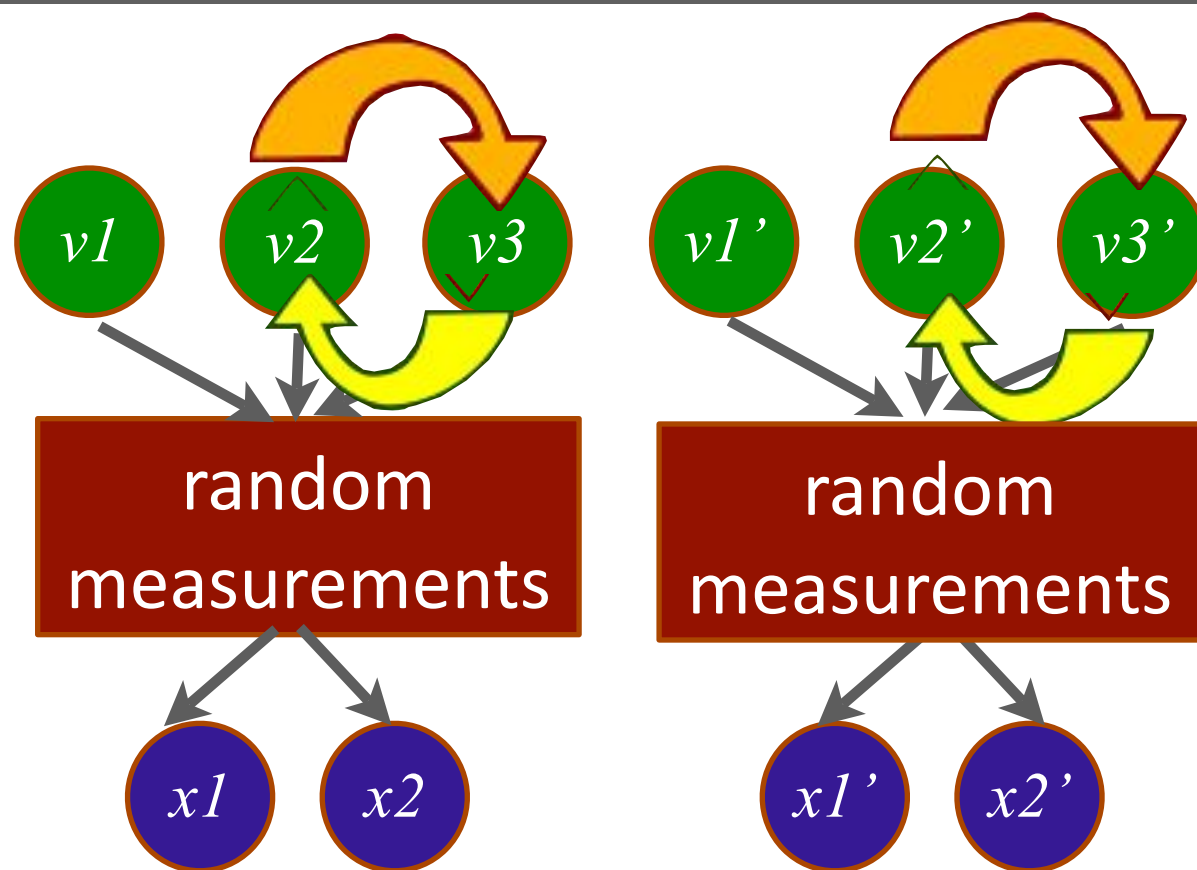


Classical proof doesn't work !

Reintroducing Symmetry: Permutation invariant measurement ensembles



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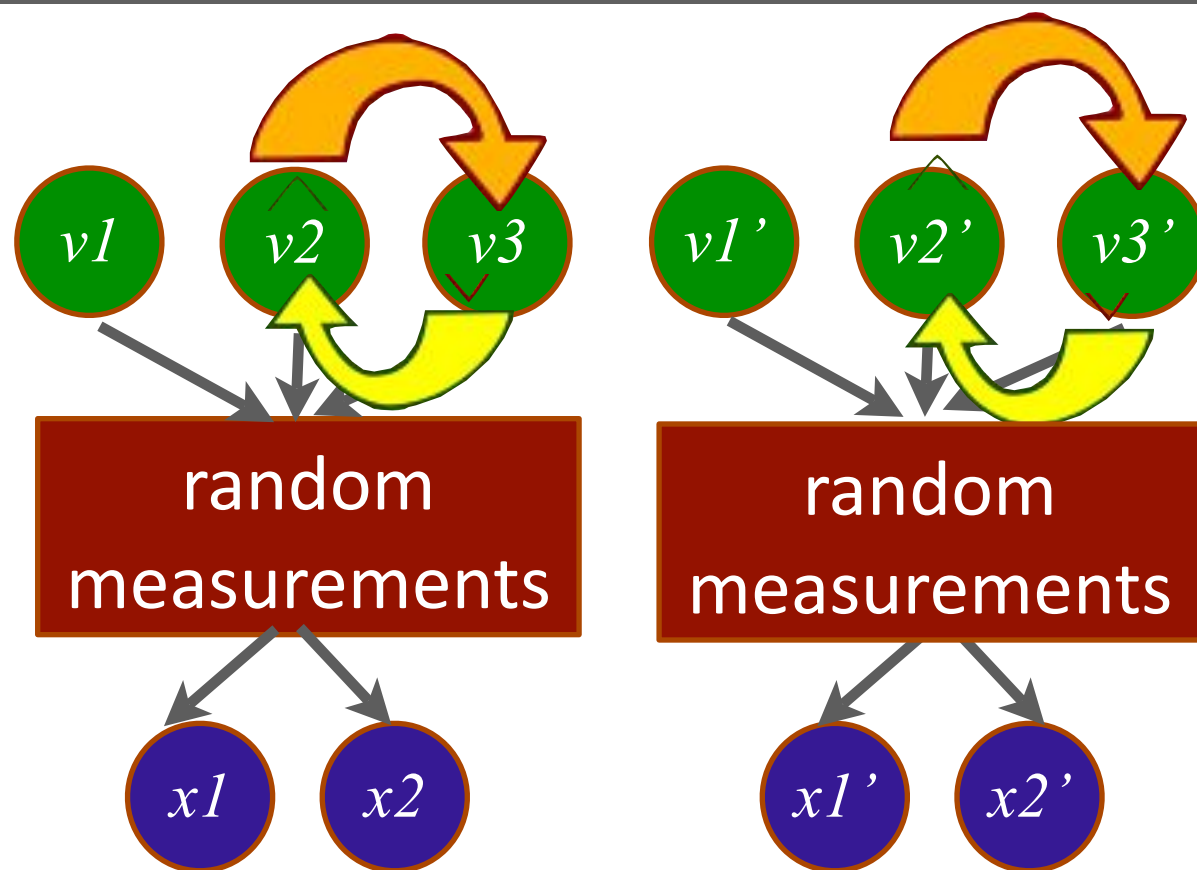


$P_{\mathbf{v}}(\mathbf{X})$
depends only on the type γ of \mathbf{v}



γ [1/2 1/2]

Reintroducing Symmetry: Permutation invariant measurement ensembles



$$P_{\mathbf{v}}(\mathbf{X})$$

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$$Q_{\mathbf{v}', \mathbf{v}}(\mathbf{X}' | \mathbf{X})$$

depends only on the joint type λ of \mathbf{v} and \mathbf{v}'

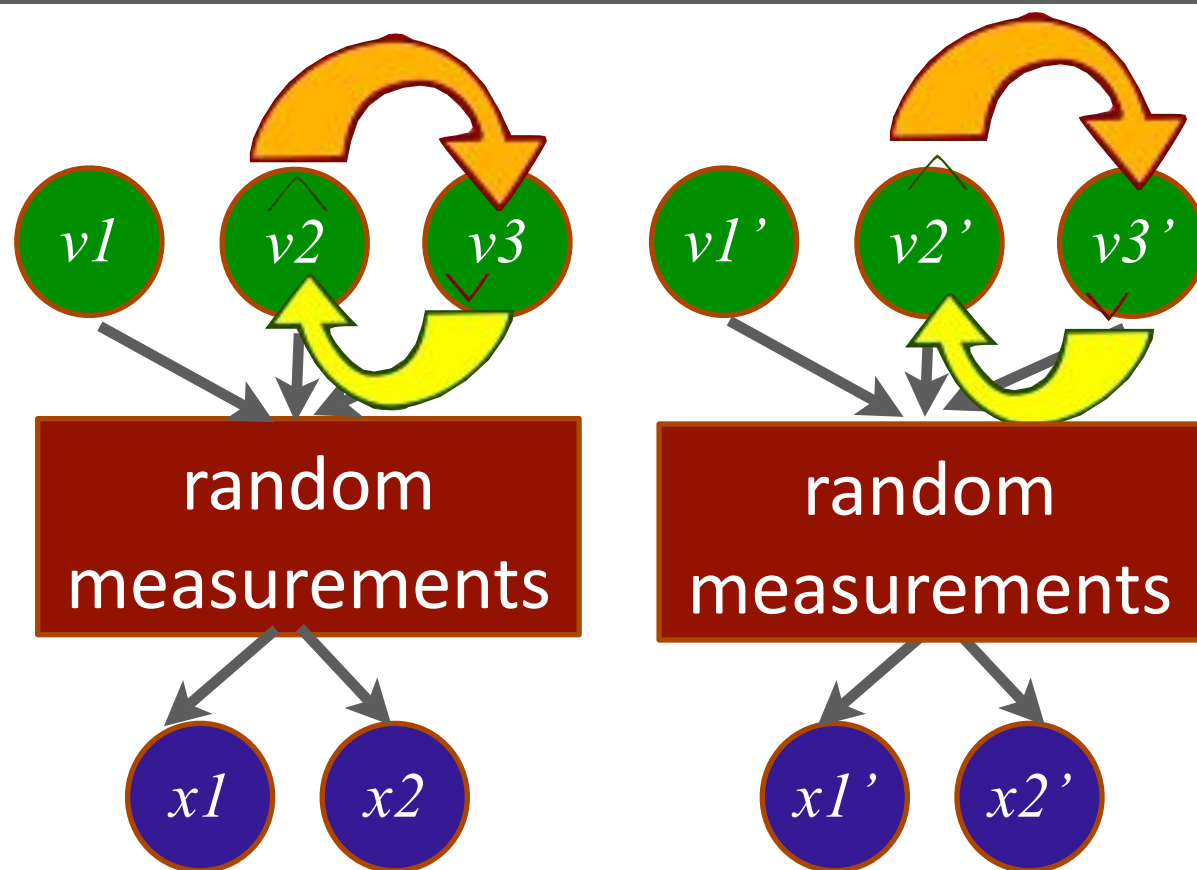


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λ [1/4 1/4 1/4 1/4]

Reintroducing Symmetry: Permutation invariant measurement ensembles



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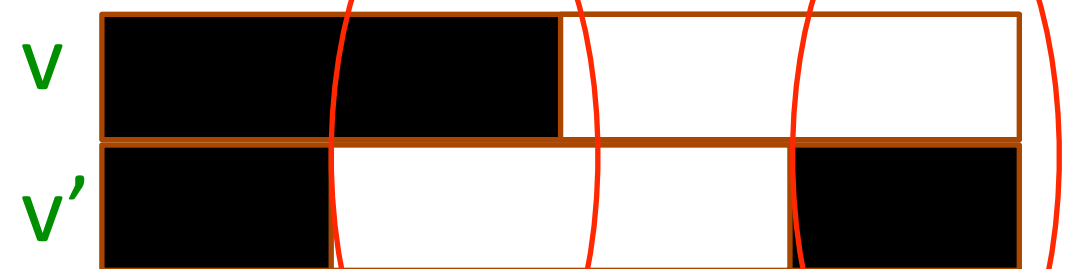
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Distortion



γ [1/2 1/2]



λ [1/4 1/4 1/4 1/4]

Using the symmetry

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$$Pr(\text{Decode to } \mathbf{v}' \text{ in } g \mid \mathbf{v} \text{ is true})$$

Depends only on $P_{\mathbf{v}}(\mathbf{X})$ and $Q_{\mathbf{v}', \mathbf{v}}(\mathbf{X}' | \mathbf{X})$ i.e γ and λ

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Use the joint types λ as the symmetry groups g

$$= Pr(\text{Decode to } \mathbf{v}' \text{ at } \lambda \mid \mathbf{v} \text{ is true})$$

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Only a polynomial number of joint types λ

Some combinatorics and some large deviations

Number of \mathbf{v}' at $\lambda \leq 2^k[H(\lambda) - H(\gamma)]$

Method of types

Some combinatorics and some large deviations

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Method of types

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Large deviations for sparse regular measurements

$$\frac{1}{N} \log \left(\frac{P(\mathbf{y}|\mathbf{v})}{E [P(\mathbf{y}|\mathbf{v})]} \right) \rightarrow T(\lambda)$$

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Large deviations for sparse regular measurements

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Introduce tilting distributions

$$\Pr(\text{Decode to } \mathbf{v}' \text{ at } \lambda \mid \mathbf{v} \text{ is true}) \leq 2^{-nT(\lambda)}$$

Result : Lower Bound on Capacity

$$\text{Rate } R = k/n = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$

A rate R is achievable for a joint type λ is

$$R < \frac{T(\lambda)}{[H(\lambda) - H(\gamma)]}$$

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A rate R is achievable for a distortion D if

$$R < C_{LB}(D) = \min_{\lambda: Dis(\lambda) > D} \frac{T(\lambda)}{[H(\lambda) - H(\gamma)]}$$

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For sparse, regular measurement structures

$$T(\lambda) = -H(Y|V) + cH(\lambda) + \inf_{\kappa : \text{sparse graph constraints}} -H(\kappa) - \sum_{a,b,o} \kappa(a,b) P_{y|v}(o|a) \log P_{y|v}(o|b)$$

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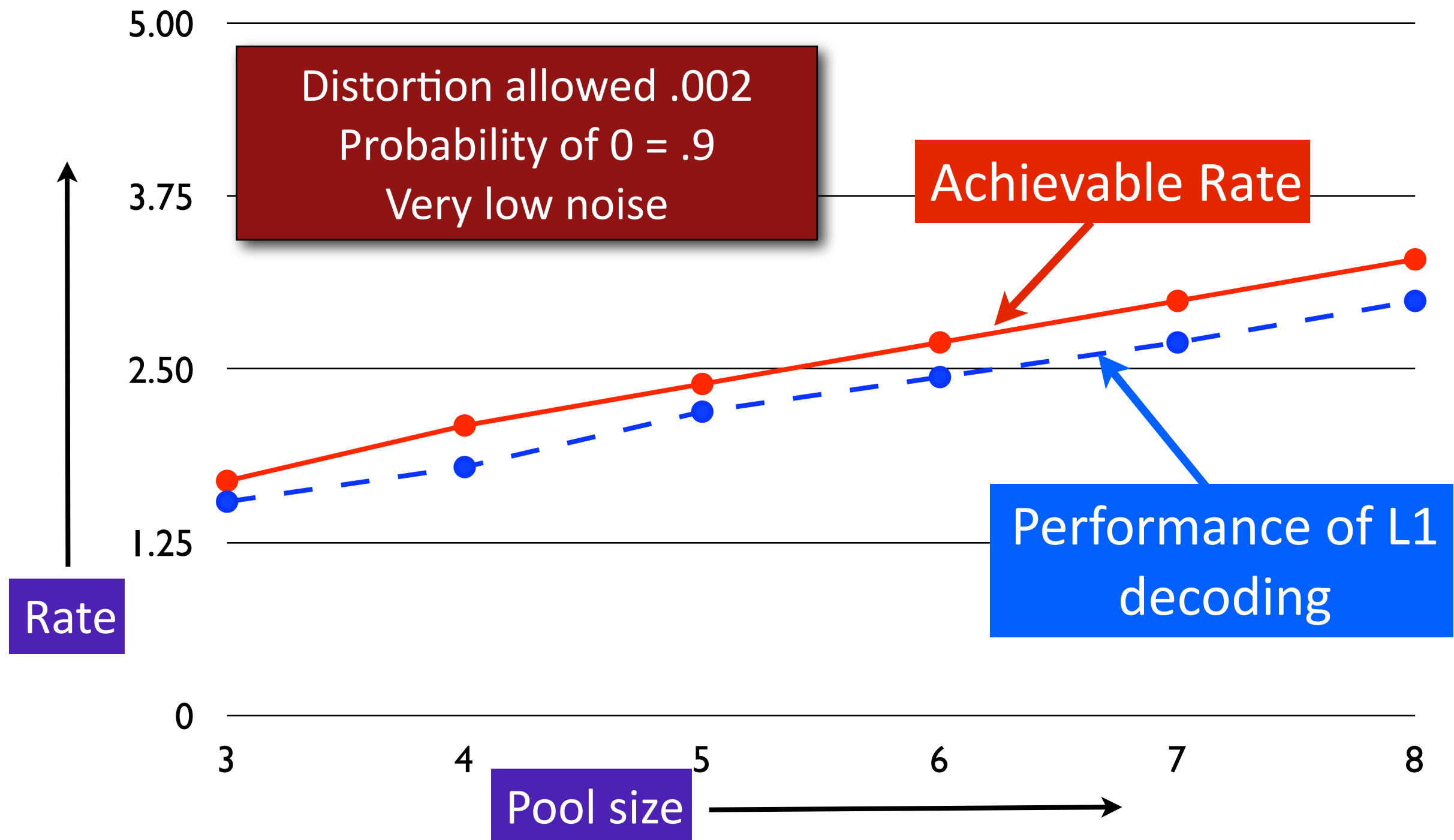
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Outline

- Application : Pooling Designs for genetic screening
- Related Problems
- Information theoretic formulation
- Intuition
- **Illustration of the result**

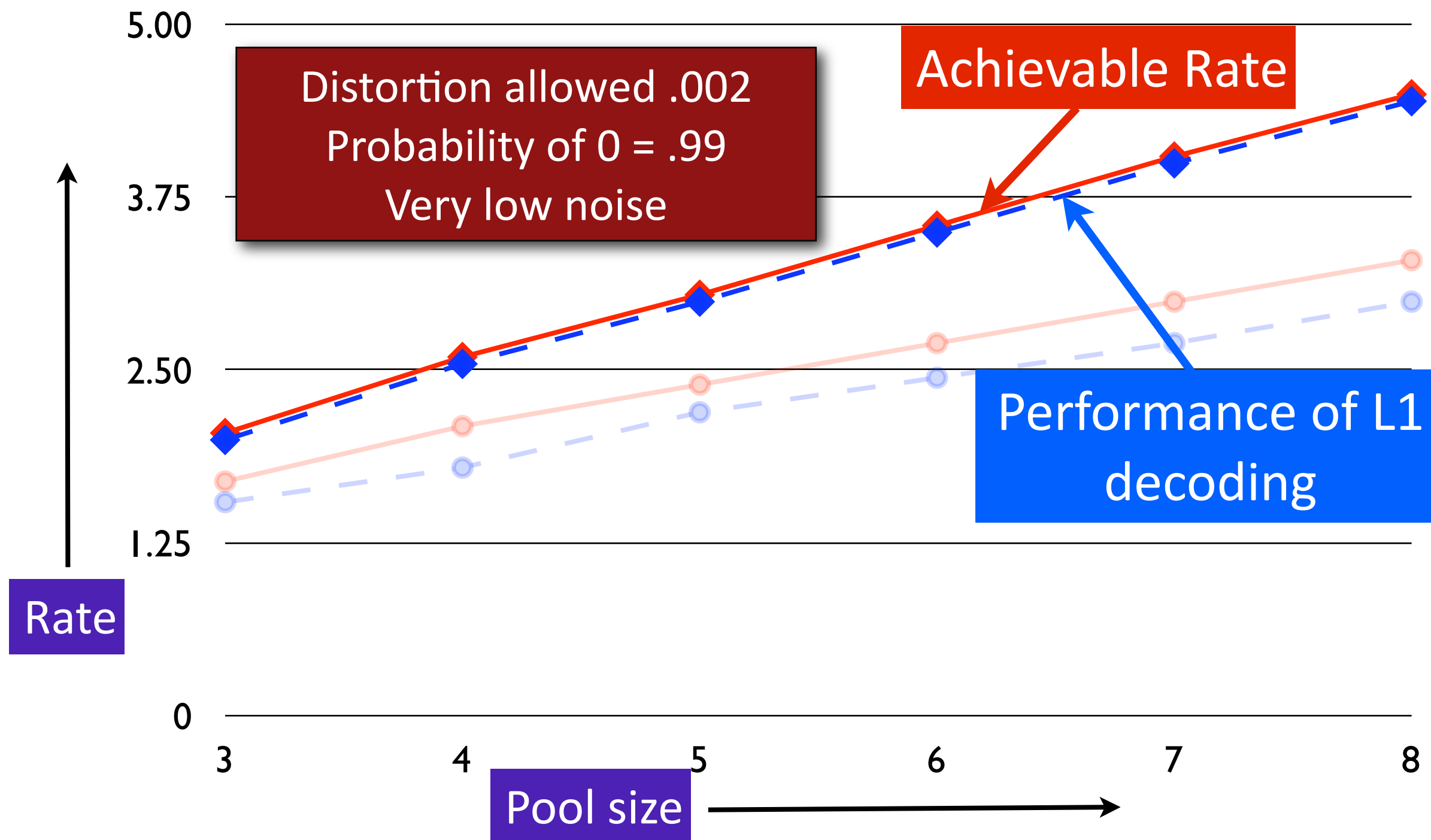
Capacity predicts performance of practical decoder

$$\text{Rate } R = \frac{k}{n} = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$



Excellent agreement for very sparse priors

$$\text{Rate } R = \frac{k}{n} = \frac{\text{\# of inputs}}{\text{\# of measurements}}$$



Insights

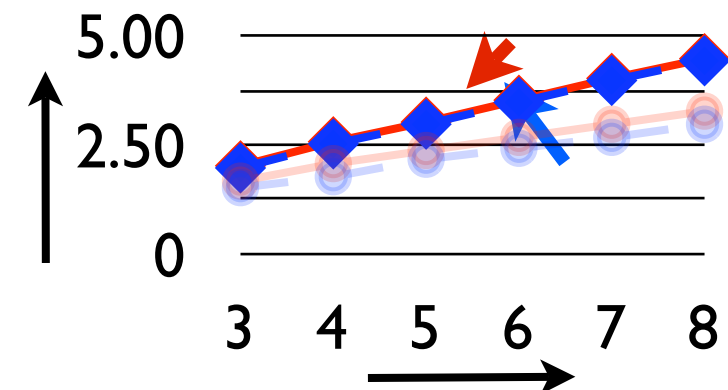
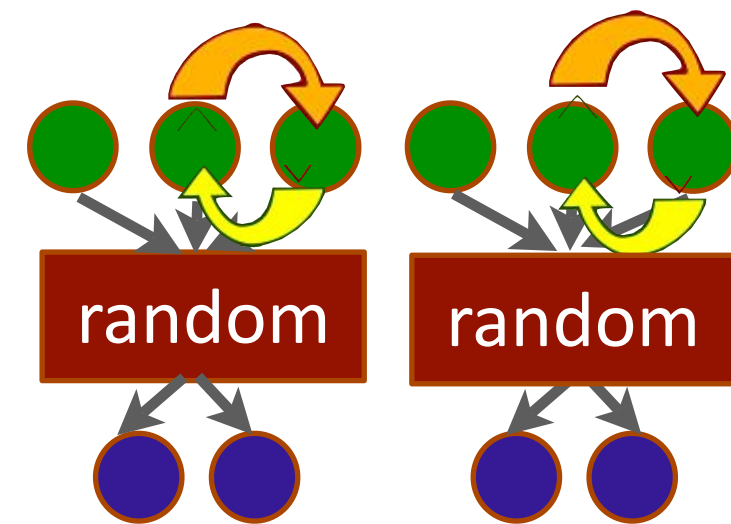
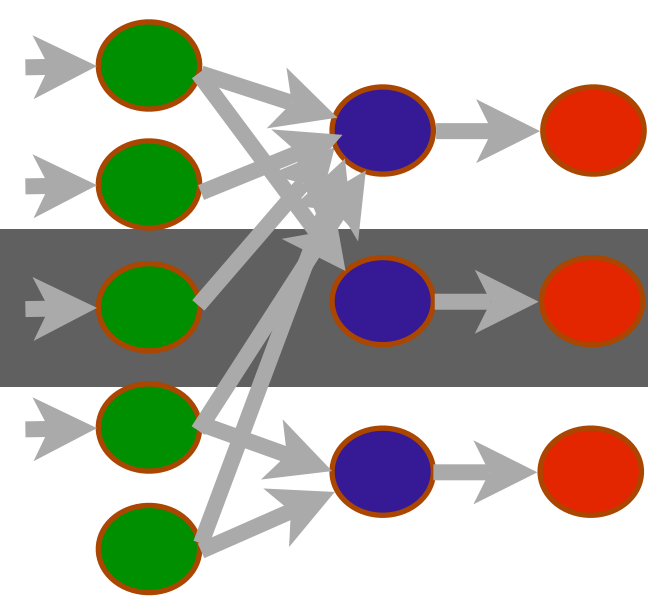
1. Analog between measurements and communication/coding

2. Random Measurements Argument

3. Symmetry through permutation invariance

4. Method of Types + Large Deviation

5. Tightness/Relevance of the result



More combinatorics

Suppose all pools are of size c

All inputs are in alphabet of size L

δ Type/distribution over L^c with marginals γ

K Joint type/distribution over (L^c, L^c) with
marginals λ

More combinatorics

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$$P_m(\vec{Z}) = P^{\vec{\gamma}, \vec{\delta}} = \begin{cases} 2^{-ncH(\vec{\gamma})} & \vec{\delta} \text{ consistent with } \vec{\gamma} \\ 0 & \text{otherwise} \end{cases}$$

$$P_{m,m'}(\vec{Z}, \vec{Z}') = P^{\vec{\lambda}, \vec{\kappa}} = \begin{cases} 2^{-ncH(\vec{\lambda})} & \vec{\kappa} \text{ consistent with } \vec{\lambda} \\ 0 & \text{otherwise} \end{cases}$$

The capacity of sparse, regular measurements

Theorem : A rate R is achievable (for an allowable distortion D) if,

$$R < C_{LB}(D) = \min_{\lambda: Dis(\lambda) > D} \frac{T(\lambda)}{[H(\lambda) - H(\gamma)]}$$

For sparse, regular measurement structures

$$T(\lambda) = -H(Y|V) + cH(\lambda) + \inf_{\kappa: \text{sparse graph constraints}} -H(\kappa) - \sum_{a,b,o} \kappa(a,b) P_{y|v}(o|a) \log P_{y|v}(o|b)$$