

Multiobjective Optimization

- Multiple independent, often competing, objectives
- If there is no clear preference, goal is a *Pareto set* of unrankable solutions -- not a single optimal solution

Pareto Optimality

Pareto Dominance:

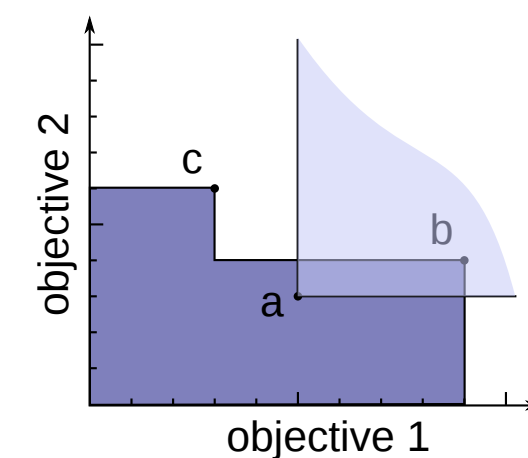
$$a, b \in \mathbb{R}^k$$

$$a \succ b \text{ iff } (\forall i \in 1 \dots k, a_i \geq b_i) \wedge (\exists j \in 1 \dots k | a_j > b_j)$$

$$a \sim b \text{ iff } \neg(a \prec b) \wedge \neg(a \succ b)$$

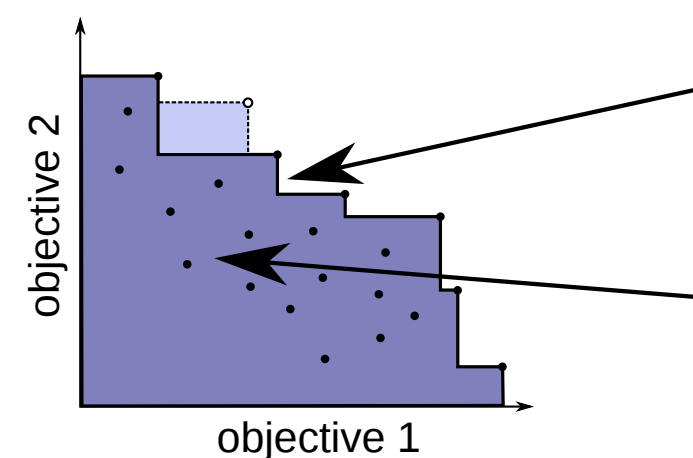
Pareto optimal subset of a set of points P:

$$\text{PAR}(P) = \{p \in P | \forall q \in P, (p \sim q) \vee (p \succ q)\}$$



$$a \prec b, a \sim c, b \sim c$$

Pareto Front Hypervolume



Pareto optimal subset forms **Pareto front** in objective space

Hypervolume of Pareto front: region in objective space dominated by points in the Pareto front

Existing Methods

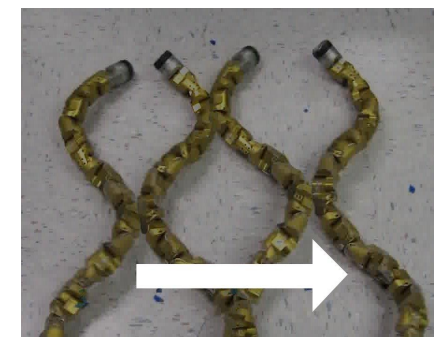
NISE [1]: fast approximate solutions; only for linear functions;

Simplex methods [2]: exact solutions, only for linear functions

NSGA-II [3]: Gold standard for nonlinear functions; GA based, takes thousands of samples

Applications

- Fast snake robot locomotion with a stable head camera view



- Animal Behavior modeling
- Engineering design
- Spacecraft trajectories

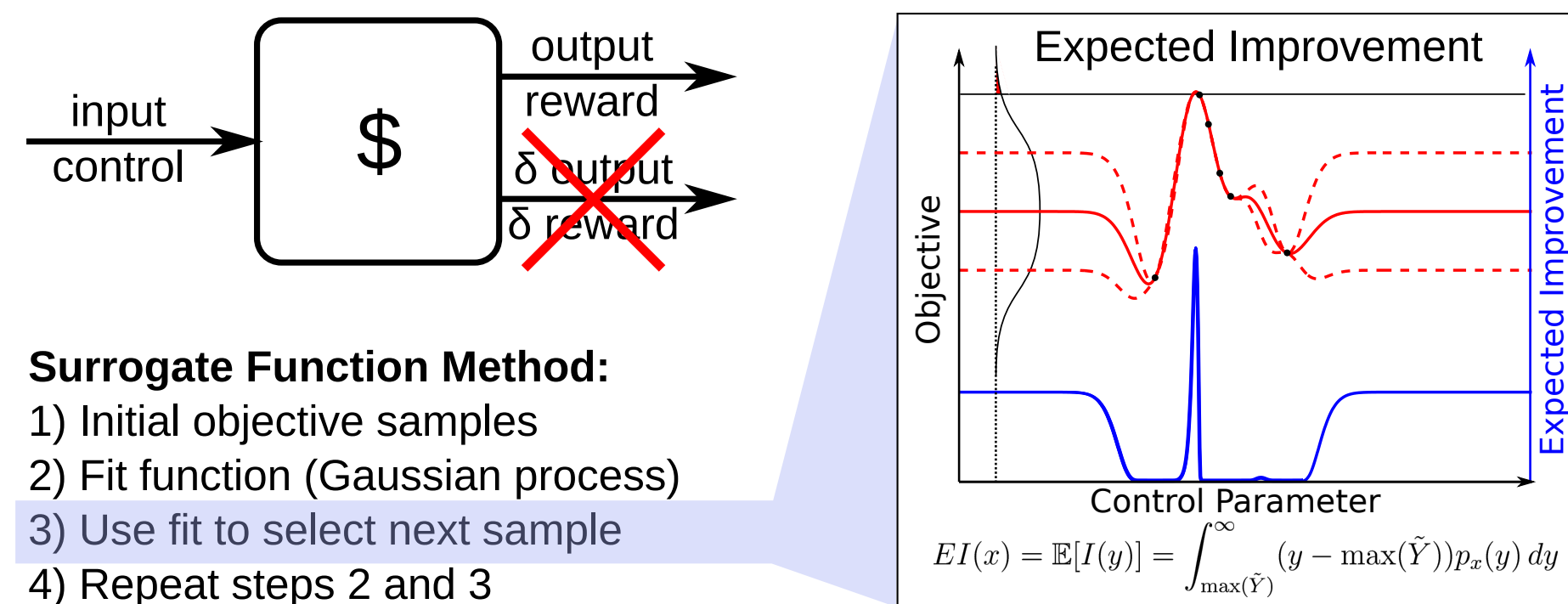
Expensive Multiobjective Optimization: Problem Definition

Goal: Given a budget of experiments (samplings of the objective functions), sequentially sample the objectives to obtain a set which has the highest hypervolume.

Parameter space: $X \subset \mathbb{R}^m$
Objectives: $\{f^1, f^2, \dots, f^k\}, k \geq 2, f^i: X \rightarrow \mathbb{R}$
Sample locations: $\{x_1, x_2, \dots, x_n | x_i \in X\}$
Objective evaluations at X: $\tilde{Y} = \{f^i(x_j)\}$

Goal: Choose x_i sequentially to maximize $\text{HV}(\text{PAR}(\tilde{Y}))$

Bayesian Approach to Expensive Black-Box Optimization



Prior Extensions to Multiple Objectives

Common: Aggregate objectives, and treat problem as a single objective

ParEGO [4]: Current state of the art; optimizes random aggregate each step

Keane [5]: Approximation to method described below

Multiobjective Optimization using Expected Improvement in Hypervolume

Work in objective space to focus on quantity we are maximizing -- hypervolume

Updated Algorithm Outline:

- 1) Initial objective samples
- 2) Fit functions (GPs)
- 3) Next sample: $\text{argmax}_x \text{EIHV}(x)$
- 4) Repeat steps 2 and 3

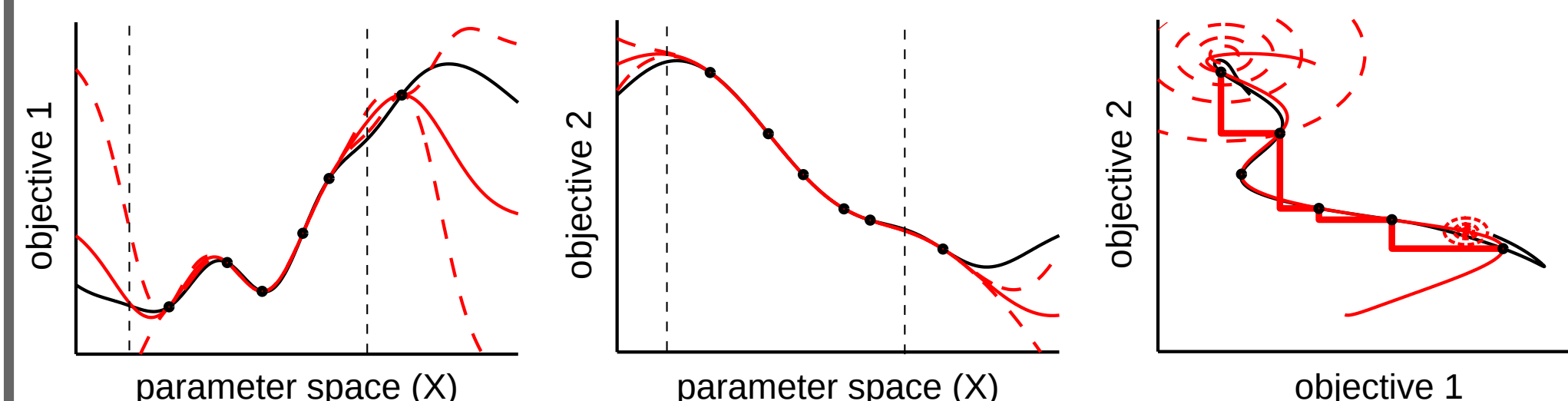
Define improvement as:

$$\text{IHV}(y) = \text{HV}(\tilde{Y} \cup y) - \text{HV}(\tilde{Y})$$

Update selection metric (see [6]) to:

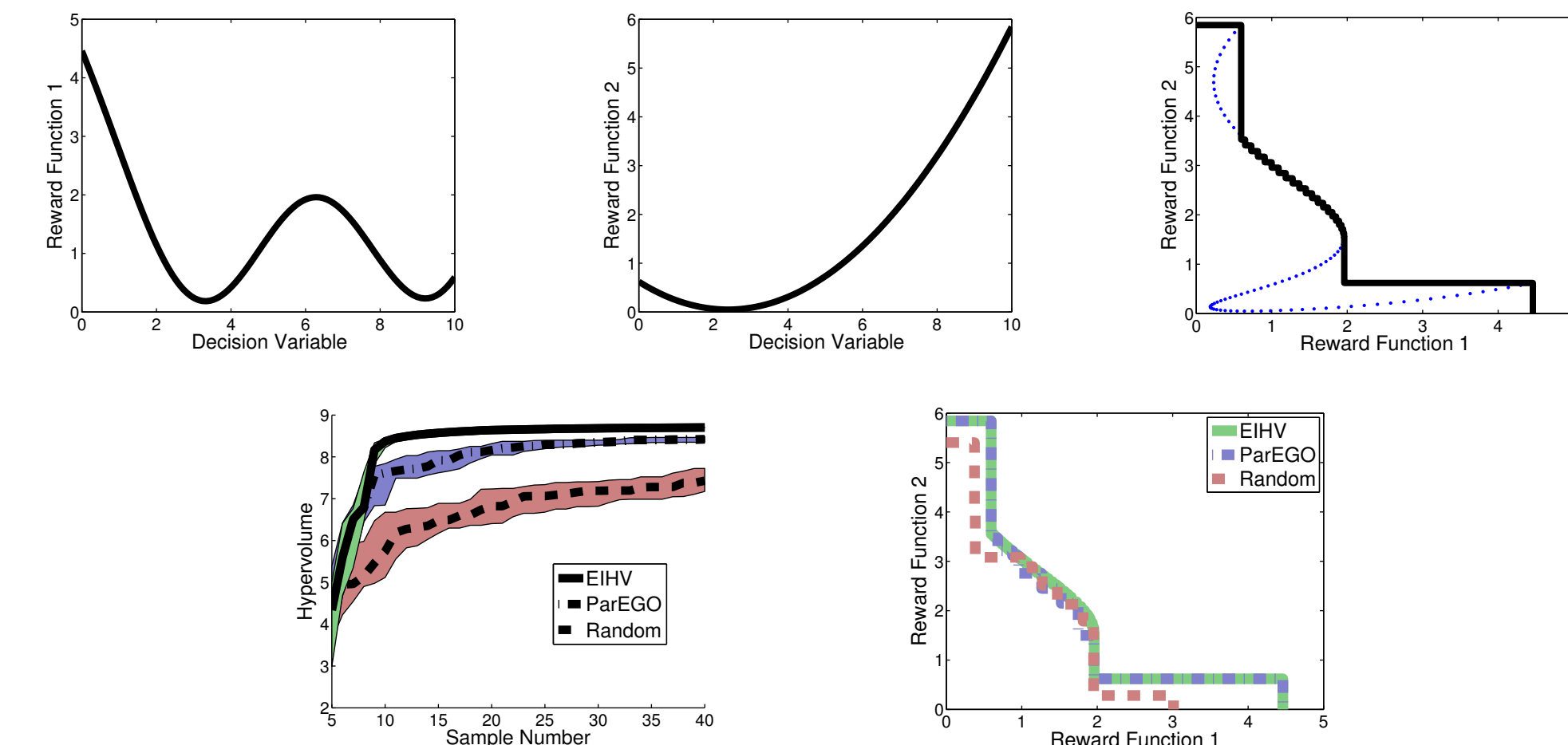
$$\text{EIHV}(x) = \mathbb{E}[\text{IHV}(y)] = \int \dots \int_{\mathbb{R}^k} (\text{IHV}(y) p_x(y^1) \dots p_x(y^k)) dy^1 \dots dy^k$$

Projecting GP regression into objective space for EIHV calculation:

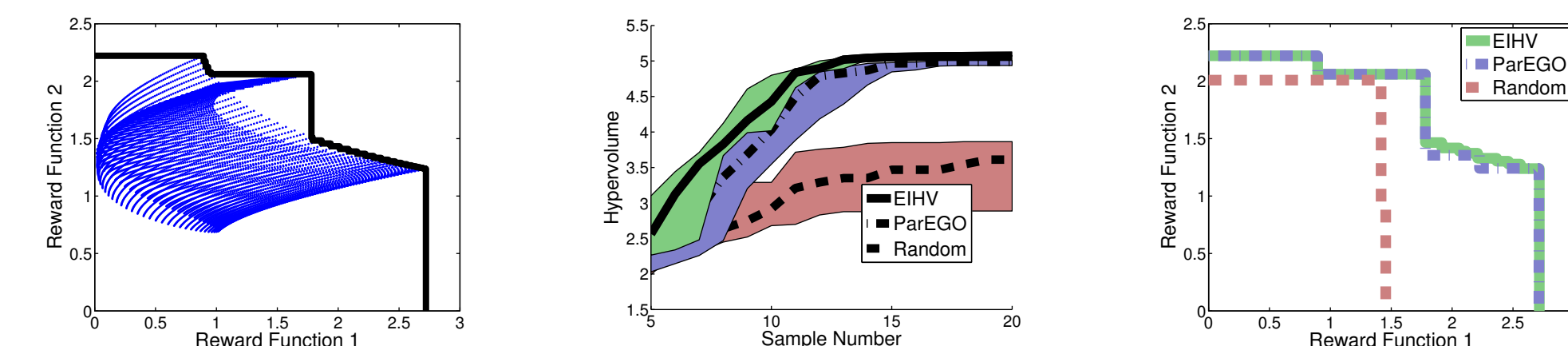


Results

1-D test problem

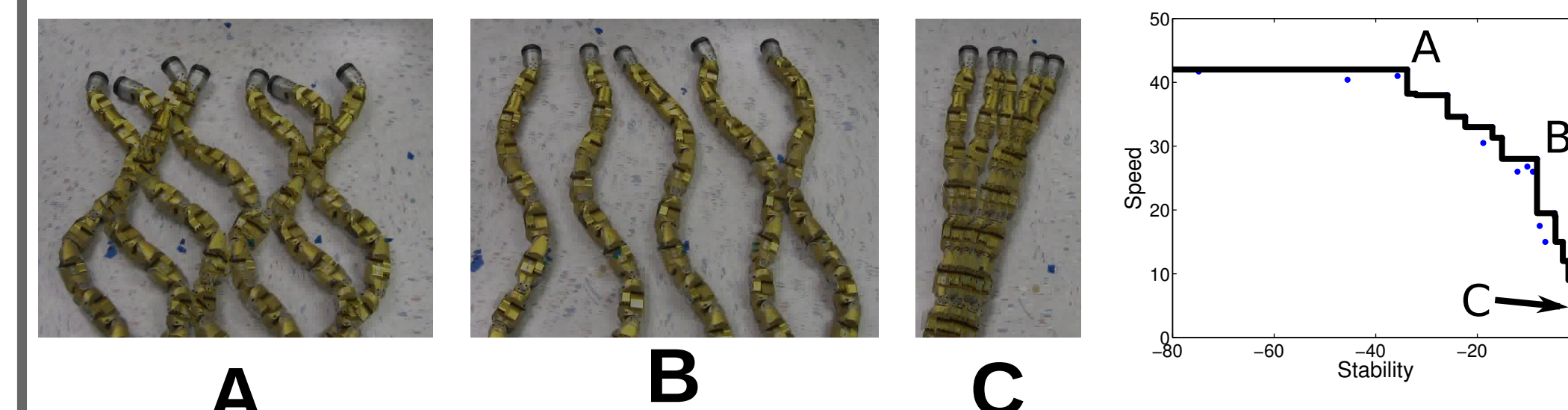


2-D test problem



Each algorithm ran 20 times for each problem.
Median and middle 50% of results shown.

Snake robot: speed vs. head stability



25 experiments; searched over head amplitude and offset parameters

Conclusions

- EIHV provides direct extension of EI to multiobjective problems
- Empirically produces better distribution over the Pareto front than ParEGO
- Demonstrated results on robotic snake

Future Work

- Better handling of noisy function evaluations
- Developing convergence guarantees and rates
- Discover upper dimensionality bound