

Robotic Motion Planning: Probabilistic Primer

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Experiments and outcomes

- Experiment: Flip a Coin
- Outcome: Heads or Tails

- Experiment: Person's temperature in class now
- Outcome: a scalar

- Event Subset of possible outcomes $E \subset S$

Probability

- $\Pr(E)$: Probability of an event E occurring when an experiment is conducted
- \Pr maps \mathcal{S} to unit interval

$$\Pr(\text{heads}) = 0.5, \Pr(\text{tails}) = 0.5$$

$$\Pr(\text{heads} \cup \text{tails}) = 1$$

1. $0 \leq \Pr(E) \leq 1$ for all $E \subset \mathcal{S}$.
2. $\Pr(\mathcal{S}) = 1$.
3. $\sum_i \Pr(E_i) = \Pr(E_1 \cup E_2 \cup \dots)$ for any countable disjoint collection of sets E_1, E_2, \dots . This property is known as *sigma additivity*. In particular, we have $\sum_{i=1}^n \Pr(E_i) = \Pr(E_1 \cup E_2 \cup \dots \cup E_n)$.
4. $\Pr(\emptyset) = 0$.
5. $\Pr(E^c) = 1 - \Pr(E)$, where E^c denotes the complement of E in \mathcal{S} .
6. $\Pr(E_1 \cup E_2) = \Pr(E_1) + \Pr(E_2) - \Pr(E_1 \cap E_2)$.

Dependence

- Independent: $\Pr(E_1 \cap E_2) = \Pr(E_1)\Pr(E_2)$
- Conditional Probability:
 - If E_1 and E_2 are independent, then $\Pr(E_1|E_2) = \Pr(E_1)$
 - Bayes Rule

$$\Pr(E_1|E_2) = \frac{\Pr(E_2|E_1)\Pr(E_1)}{\Pr(E_2)}.$$

More Bayes Rule

$$p(a | b) = \frac{p(b | a) p(a)}{p(b)}$$

$$p(a | b, c) = \frac{p(b | a, c) p(a | c)}{p(b | c)}$$

Total Probability

Discrete

$$\begin{aligned} p(a) &= \sum_i p(a \wedge b_i) \\ &= \sum_i p(a | b_i) p(b_i) \end{aligned}$$

Continuous

$$p(a) = \int p(a | b) p(b) db$$

it follows that:

$$p(a | b) = \int p(a | b, c) p(c | b) dc$$

Random Variable

- A mapping from events to a real number $X : \mathcal{S} \rightarrow \mathbb{R}$
- Examples
 - Discrete: heads or tails, number of heads for repeated flips
 - Continuous: temperature
- Random Vector: $X : \mathcal{S} \rightarrow \mathbb{R}^n$

Distribution

- Any statement one can make about a random variable
- Cumulative Distribution Function (CDF): $F_X(a) = \Pr(X \leq a)$
- Probability _____ Function (P_F):

- Discrete: Mass (PMF)

$$f_X(a) = \Pr(X = a)$$

- Continuous: Density (PDF)

$$\Pr(a \leq X \leq b) = \int_{x=a}^b f_X(x) dx$$

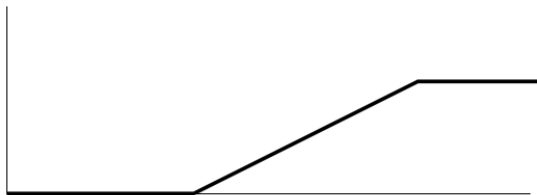
Note that $\Pr((X = a)) = \int_{x=a}^a f_X(x) dx = 0$

Uniform Distribution

CDF

$$U(x; a, b) = \begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & a \leq x \leq b \\ 1 & x \geq b \end{cases}$$

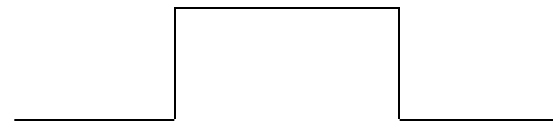
$$Pr(a' \leq x \leq b') = U(b'; a, b) - U(a'; a, b)$$



PDF

$$u(x; a, b) = \begin{cases} 0 & x < a \\ \frac{1}{b-a} & a \leq x \leq b \\ 0 & x \geq b. \end{cases}$$

$$Pr(a' \leq x \leq b') = \int_{x=a'}^{b'} u(x; a, b) dx$$



Expected Value

- PMF

$$E(X) = \sum_i x_i f_X(x_i)$$

PDF

$$E(X) = \int_{x \in \mathbb{R}^n} x f_X(x) dx$$

$$E(aX + bY) = aE(X) + bE(Y)$$

$E(X)$ with \bar{X}

Variance and Co-variance

- Variance: $\sigma^2 = E((X - \bar{X})^2)$
Or σ_i^2 for X_i
- Co-Variance $\sigma_{ij} = E((X_i - \bar{X}_i)(X_j - \bar{X}_j))$
 $\sigma_{ij} = 0$. X_i and X_j are independent
- Co-Variance Matrix $P_X = E((X - \bar{X})(X - \bar{X})^T)$
 σ_i^2 Diagonal terms
 σ_{ij} Off-Diagonal Terms

Gaussians

$$f_X(x) = \frac{1}{\sqrt{(2\pi)^n |P_X|}} e^{-\frac{1}{2}(x-\bar{X})^T P_X^{-1}(x-\bar{X})}$$

$P_X \in \mathbb{R}^{n \times n}$

$\bar{X} \in \mathbb{R}^n$ is the mean vector

