Example Templates

Elly Zoe Winner and Manuela Veloso

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while ((in_current_state (at(v?1:obj v?2:loc)) or
              in_current_state (inside(v?1:obj v?4:rocket))) and
         (in\_goal\_state (at(v?1:obj v?3:loc)) or
              in_goal_state (inside(v?1:obj v?4:rocket)))) do
    if (in_current_state (at(?1:obj ?2:loc)) and
              in\_current\_state (at(?4:rocket ?5:loc))) then
         move(?4:rocket ?5:loc ?2:loc)
    while (in_current_state (at(v?6:obj ?2:loc)) and
              in_current_state (at(?4:rocket ?2:loc)) and
              (in_goal_state (at(v?6:obj v?7:loc)) or
                   in_goal_state (inside(v?6:obj ?4:rocket)))) do
         load(?6:obj ?4:rocket ?2:loc)
    while (in_current_state (inside(v?6:obj ?4:rocket)) and
              in_current_state (at(?4:rocket ?2:loc)) and
              in_goal_state (at(v?6:obj ?2:loc))) do
         unload(?6:obj ?4:rocket ?2:loc)
while (in_current_state (inside(v?1:obj v?2:rocket)) and
         in_current_state (at(v?2:rocket v?3:loc)) and
         in\_goal\_state (at(v?1:obj v?4:loc))) do
    move(?2:rocket ?3:loc ?4:loc)
    while (in_current_state (inside(v?5:obj ?2:rocket)) and
              in_goal_state (at(v?5:obj ?4:loc))) do
         unload(?5:obj ?2:rocket ?4:loc)
\mathbf{while}\;(\mathbf{in\_current\_state}\;(\mathsf{at(v?1:rocket}\;\mathsf{v?2:loc)})\;\mathbf{and}
         in\_goal\_state (at(v?1:rocket v?3:loc))) do
    move(?1:rocket ?2:loc ?3:loc)
```

Table 1: Rocket domain template

Table 2: A simple template that solves all gripper-domain problems involving moving balls from one room to another.