

10-601 Introduction to Machine Learning

Machine Learning Department School of Computer Science Carnegie Mellon University

Hidden Markov Models

Matt Gormley Lecture 20 Mar. 30, 2020

Reminders

- Practice Problems for Exam 2
 - Out: Fri, Mar 20
- Midterm Exam 2
 - Thu, Apr 2 evening exam, details announced on Piazza
- Homework 7: HMMs
 - Out: Thu, Apr 02
 - Due: Fri, Apr 10 at 11:59pm
- Today's In-Class Poll
 - http://poll.mlcourse.org

HMMs: History

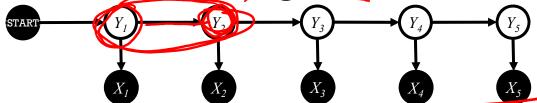
- Markov chains: Andrey Markov (1906)
 - Random walks and Brownian motion
- Used in Shannon's work on information theory (1948)
- Baum-Welsh learning algorithm: late 60's, early 70's.
 - Used mainly for speech in 60s-70s.
- Late 80's and 90's: David Haussler (major player in learning theory in 80's) began to use HMMs for modeling biological sequences
- Mid-late 1990's: Dayne Freitag/Andrew McCallum
 - Freitag thesis with Tom Mitchell on IE from Web using logic programs, grammar induction, etc.
 - McCallum: multinomial Naïve Bayes for text
 - With McCallum, IE using HMMs on CORA

• ...

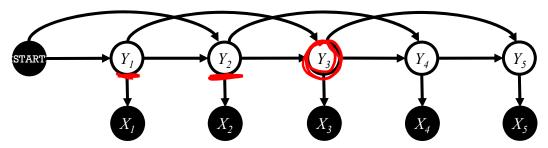


Higher-order HMMs

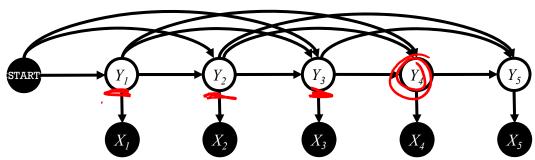
1st-order HMM (i.e. bigram HMM)



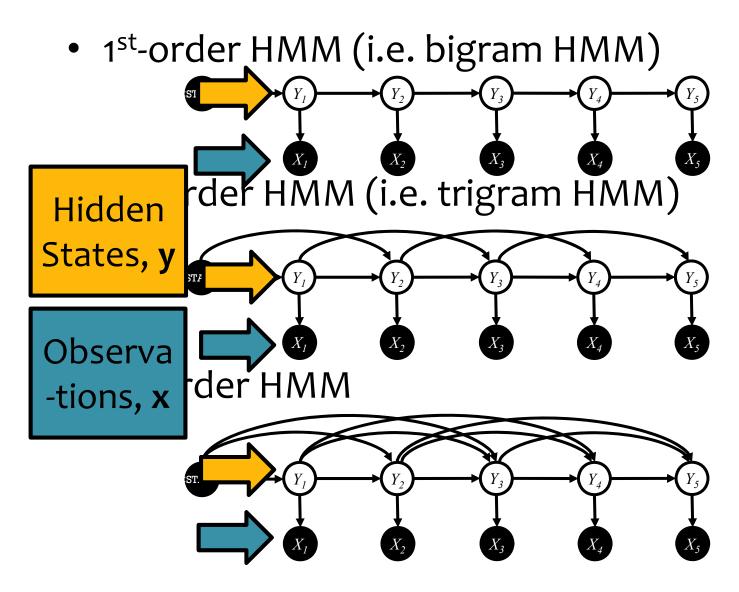
• 2nd-order HMM (i.e. trigram HMM)



• 3rd-order HMM

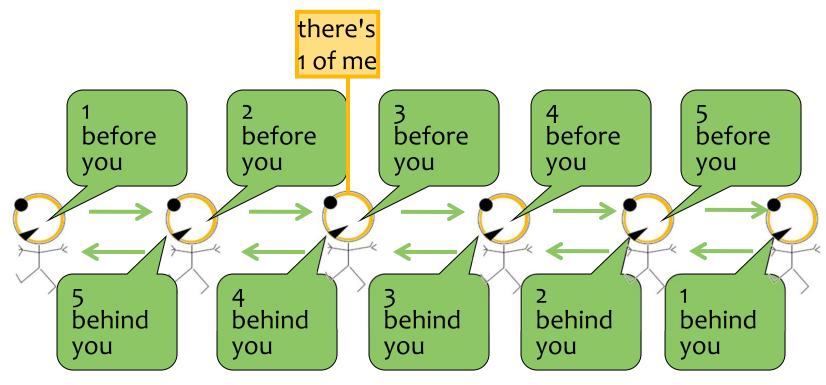


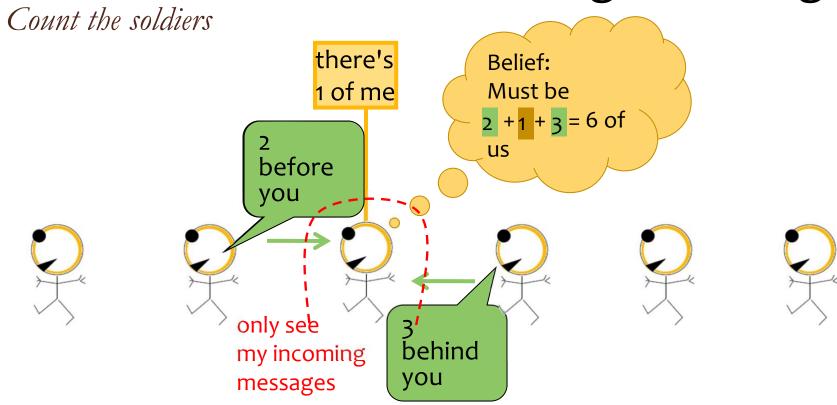
Higher-order HMMs

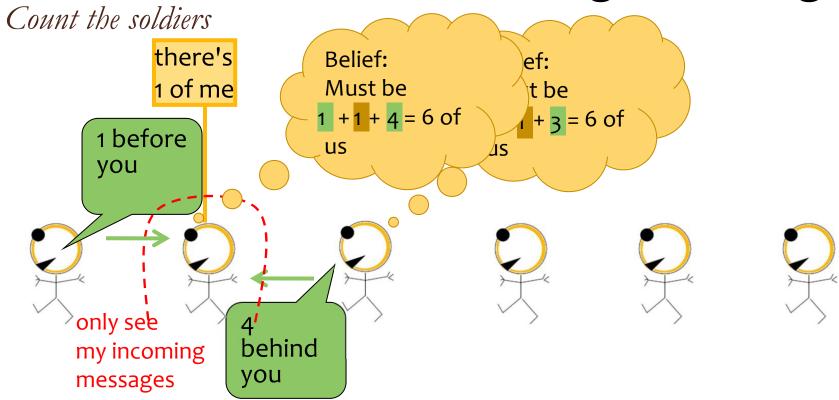


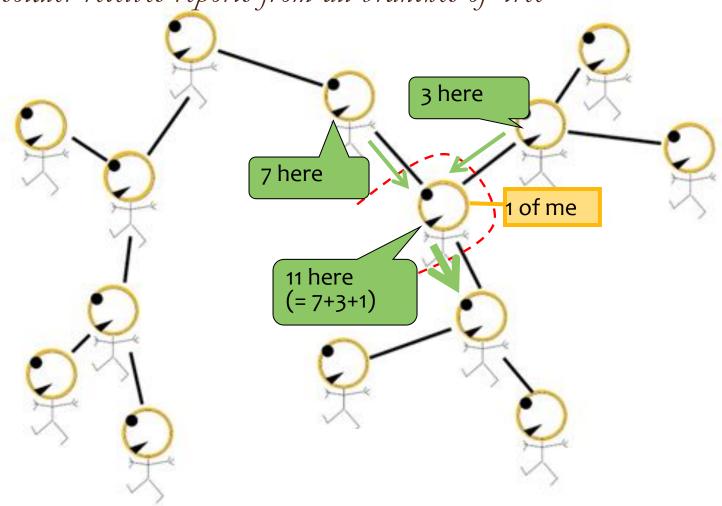
BACKGROUND: MESSAGE PASSING

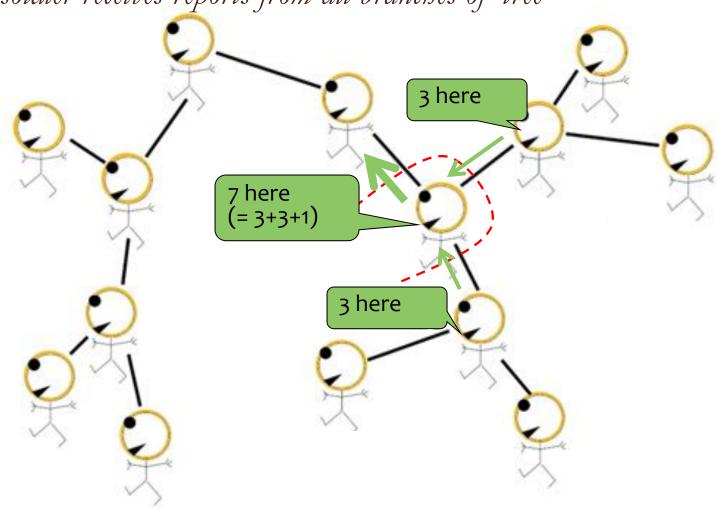
Count the soldiers

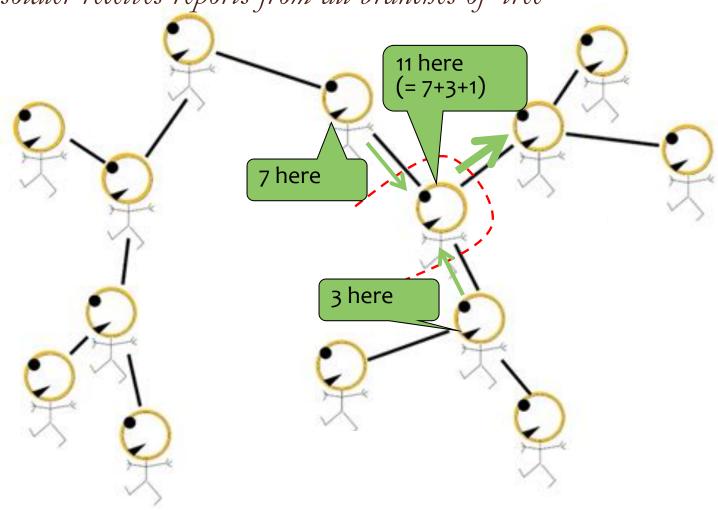


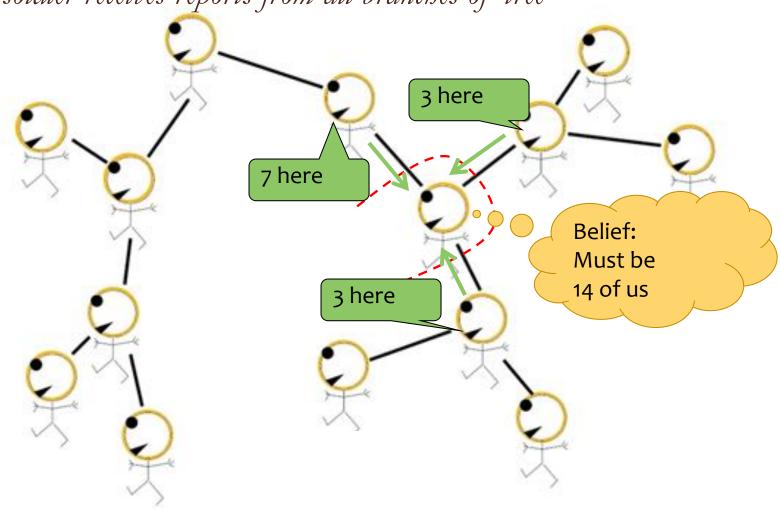


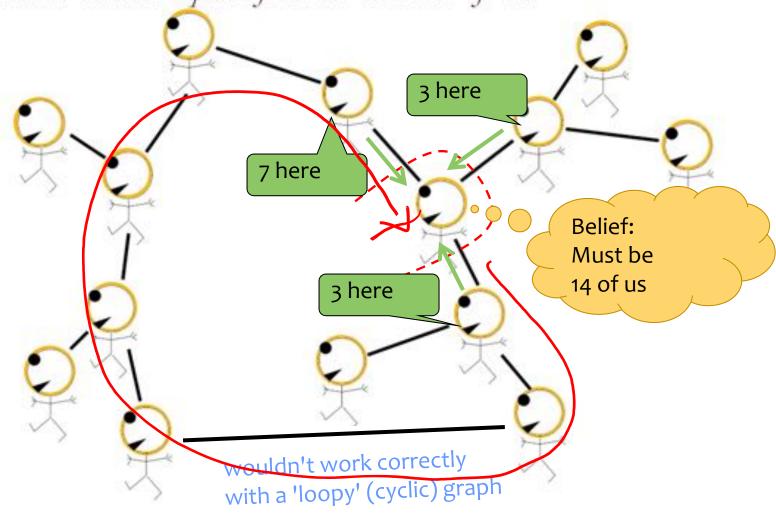












THE FORWARD-BACKWARD ALGORITHM



Question:

True or False: The joint probability of the observations and the hidden states in an HMM is given by:

$$P(\mathbf{X} = \mathbf{x}, \mathbf{Y} = \mathbf{y}) = C_{y_1} \left[\prod_{t=1}^{T} A_{y_t, x_t} \right] \left[\prod_{t=1}^{T-1} B_{y_{t+1}, y_t} \right]$$

Recall:

Emission matrix, **A**, where $P(X_t = k | Y_t = j) = A_{j,k}, \forall t, k$ Transition matrix, **B**, where $P(Y_t = k | Y_{t-1} = j) = B_{j,k}, \forall t, k$ Initial probs, **C**, where $P(Y_1 = k) = C_k, \forall k$

Inference

Question

True or False: The probability of the observations

in an HMM is given by:

Fiven by:
$$P(\mathbf{X} = \mathbf{x}) = \prod_{t=1}^{T} A_{x_t, x_{t-1}} = \sum_{y_t \in \mathcal{Y}_t} P(\mathbf{X} = \mathbf{x}, \mathbf{Y} = \mathbf{Y})$$

Recall:

Emission matrix, **A**, where $P(X_t = k | Y_t = j) = A_{j,k}, \forall t, k$ Transition matrix, **B**, where $P(Y_t = k | Y_{t-1} = j) = B_{j,k}, \forall t, k$ Initial probs, **C**, where $P(Y_1 = k) = C_k, \forall k$

Inference

Question:

True or False: Suppose each hidden state takes K values. The marginal probability of a hidden state y_t given the observations x is given by:

$$P(Y_t = y_t | \mathbf{X} = \mathbf{x}) = \sum_{j=1}^K B_{j,y_t}$$

Recall:

Emission matrix, **A**, where $P(X_t = k | Y_t = j) = A_{j,k}, \forall t, k$ Transition matrix, **B**, where $P(Y_t = k | Y_{t-1} = j) = B_{j,k}, \forall t, k$ Initial probs, **C**, where $P(Y_1 = k) = C_k, \forall k$

Inference for HMMs

Whiteboard

- Three Inference Problems for an HMM
 - Evaluation: Compute the probability of a given sequence of observations
 - 2. Viterbi Decoding: Find the most-likely sequence of hidden states, given a sequence of observations
 - 3. Marginals: Compute the marginal distribution for a hidden state, given a sequence of observations

Dataset for Supervised Part-of-Speech (POS) Tagging

Data: $\mathcal{D} = \{oldsymbol{x}^{(n)}, oldsymbol{y}^{(n)}\}_{n=1}^N$

Sample 1:	n	flies	p like	an	$\begin{array}{c c} & & \\ & &$
Sample 2:	n	n	v like	d	$ \begin{array}{c c} $
Sample 3:	n	fly	with	n	$ \begin{array}{c c} $
Sample 4:	p	n	you	will	$\begin{cases} y^{(4)} \\ x^{(4)} \end{cases}$

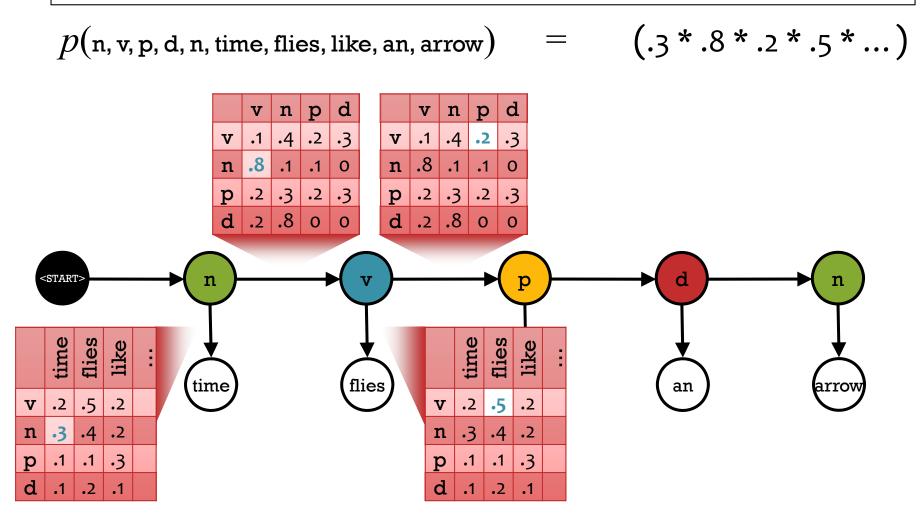
Inference for HMMs

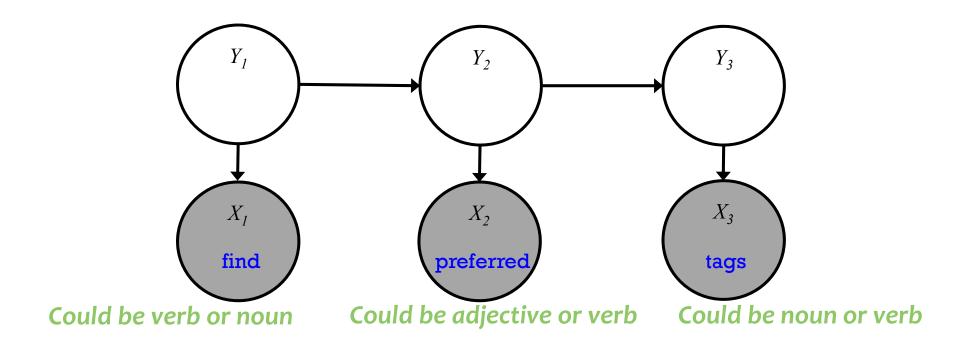
Whiteboard

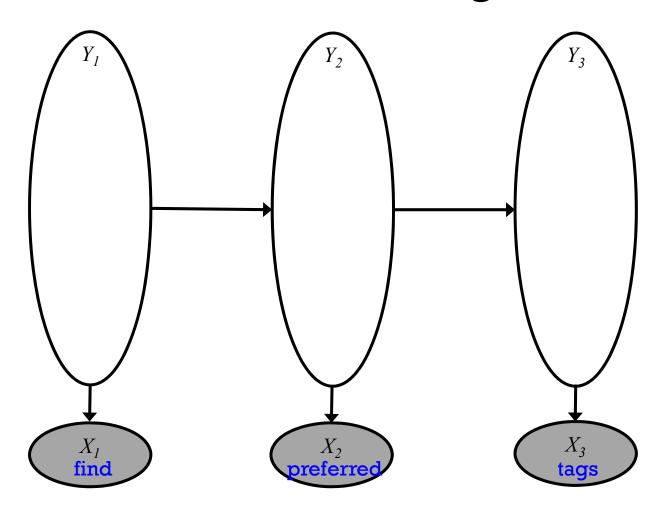
Forward-backward search space

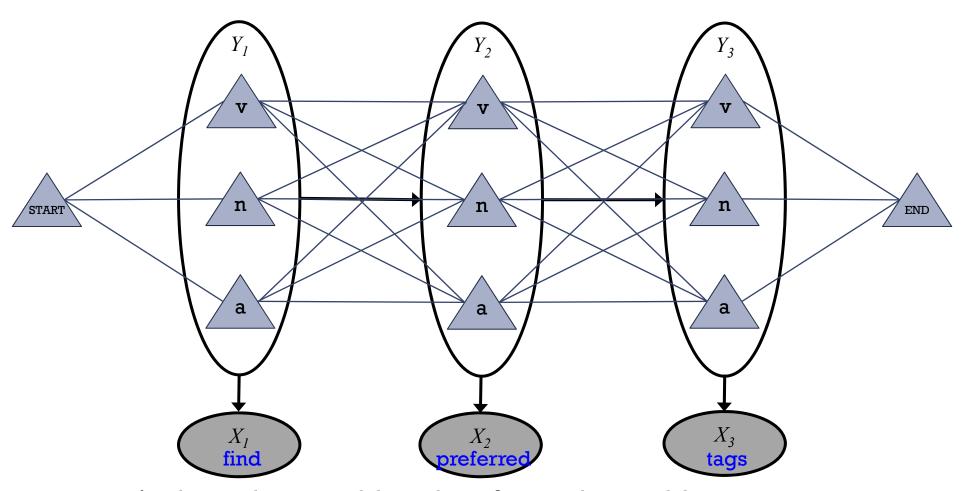
Hidden Markov Model

A Hidden Markov Model (HMM) provides a joint distribution over the the sentence/tags with an assumption of dependence between adjacent tags.

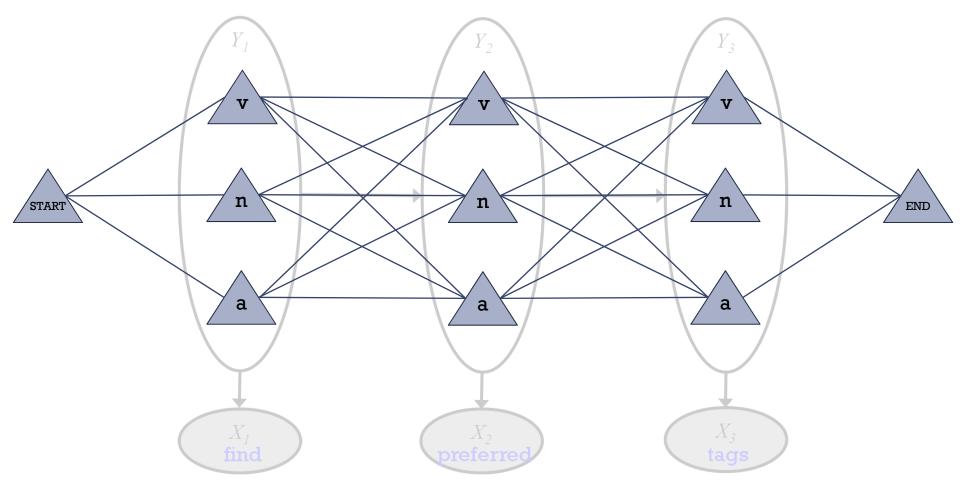




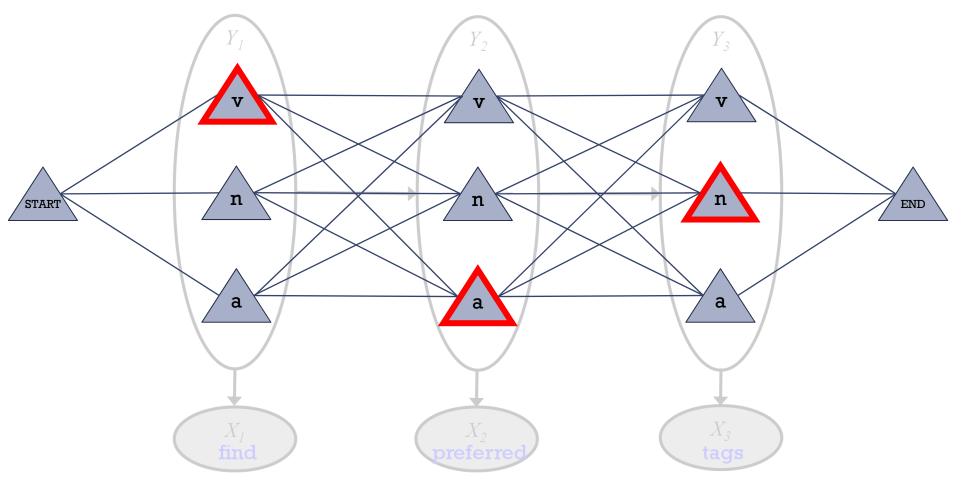




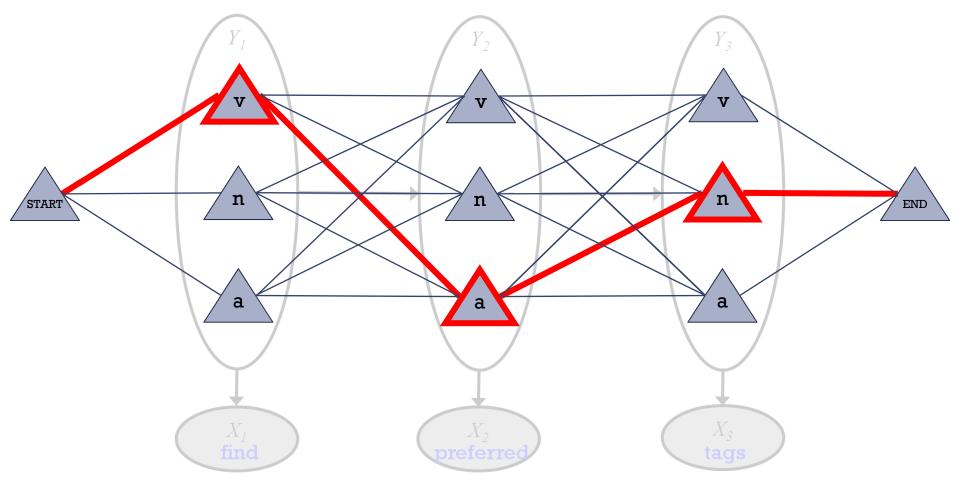
• Let's show the possible values for each variable



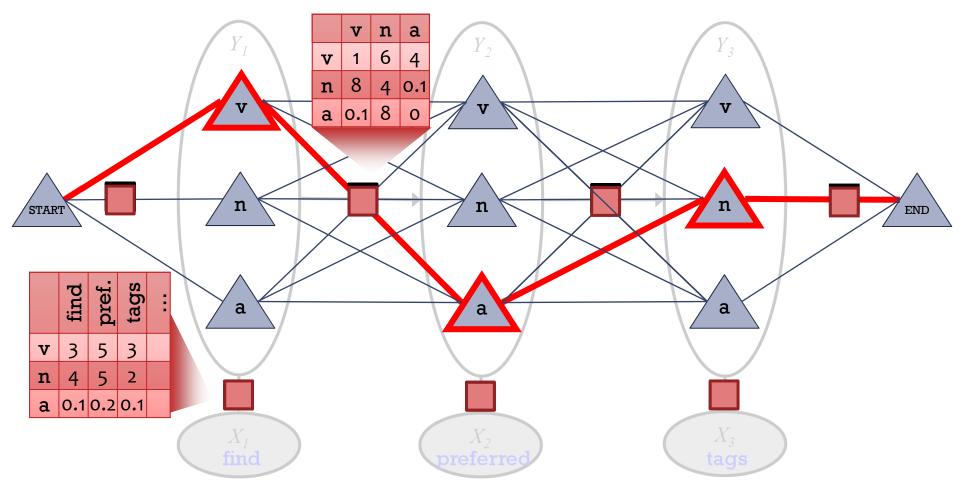
• Let's show the possible values for each variable



- Let's show the possible *values* for each variable One possible assignment

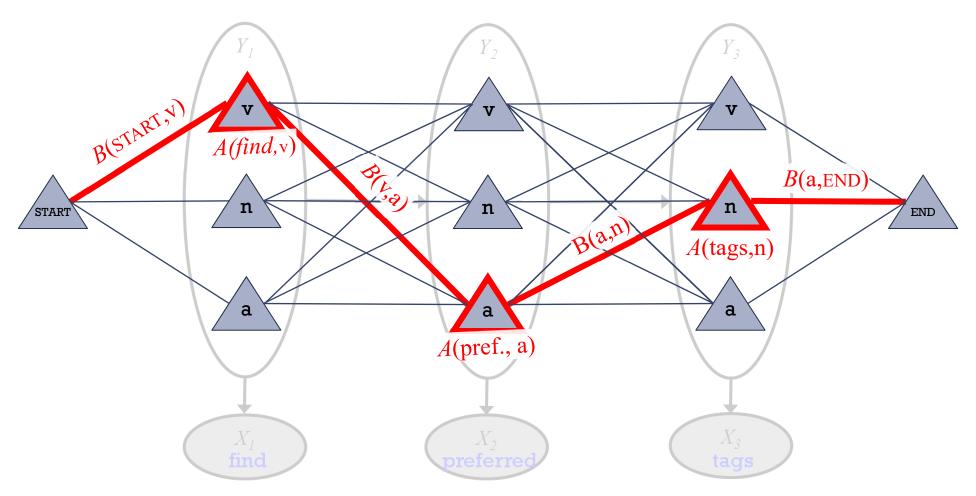


- Let's show the possible values for each variable
- One possible assignment And what the 7 transition / emission factors think of it ...



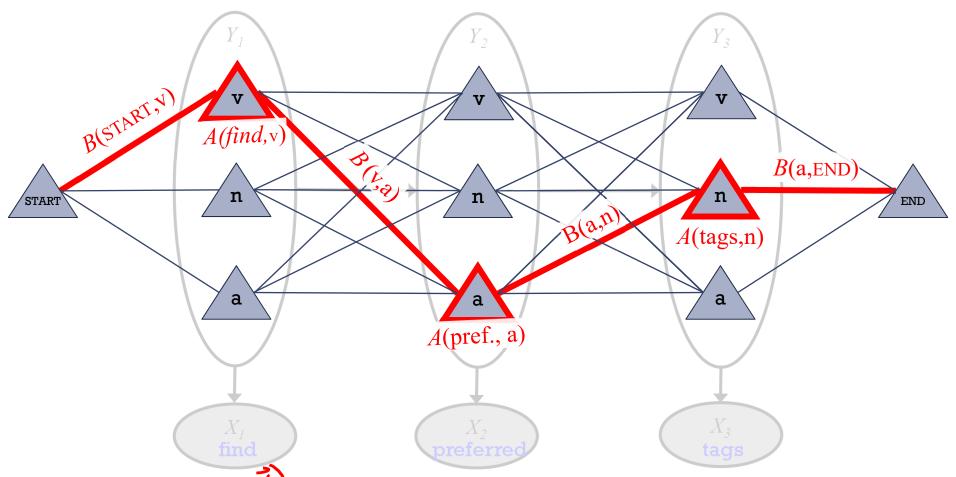
- Let's show the possible values for each variable
- One possible assignment And what the 7 transition / emission factors think of it ...

Viterbi Algorithm: Most Probable Assignment

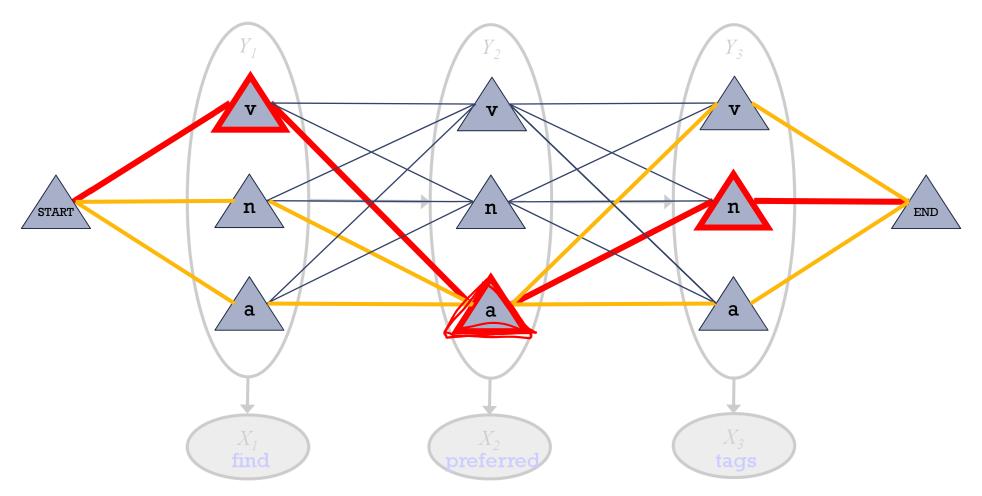


- So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/Z) * product of 7 numbers$
- Numbers associated with edges and nodes of path
- Most probable assignment = path with highest product

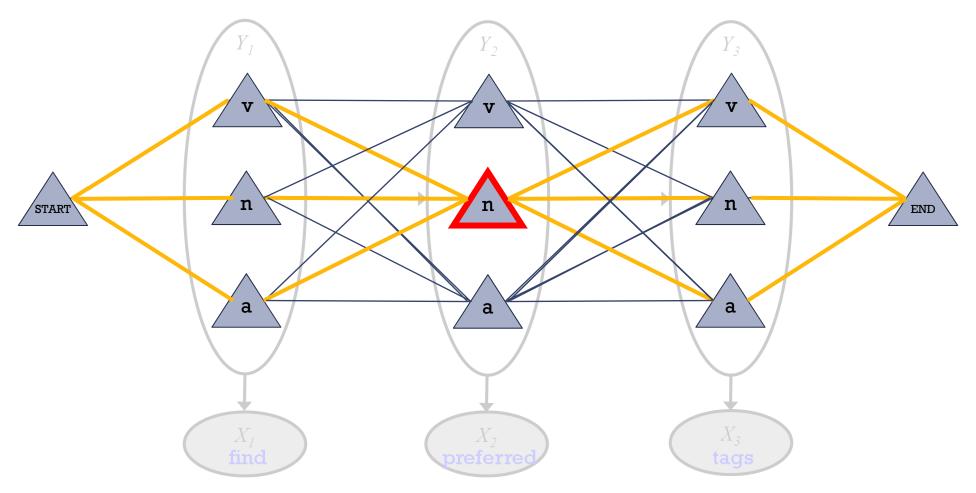
Viterbi Algorithm: Most Probable Assignment



• So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/Z) * \text{ product weight of one path}$

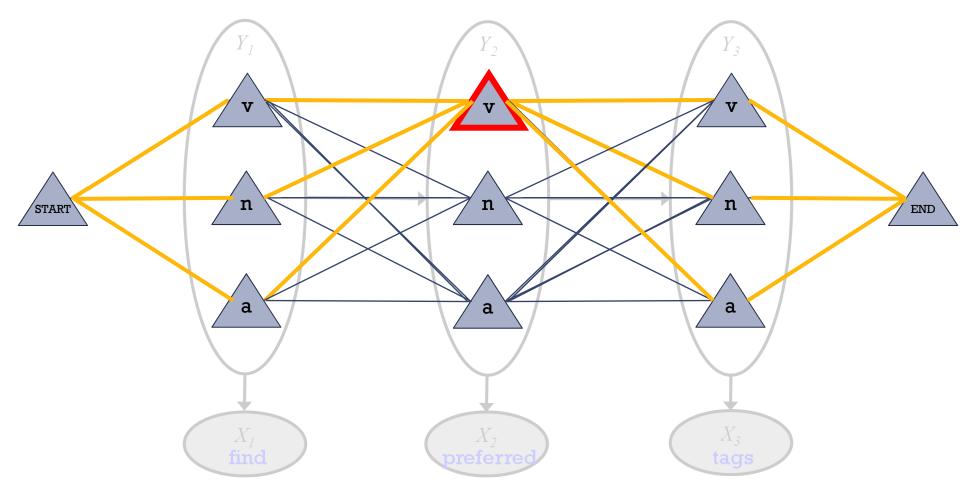


- So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/\mathbf{Z}) * \text{product weight of one path}$
- Marginal probability $p(Y_2 = a)$ \Rightarrow = (1/Z) * total weight of all paths through



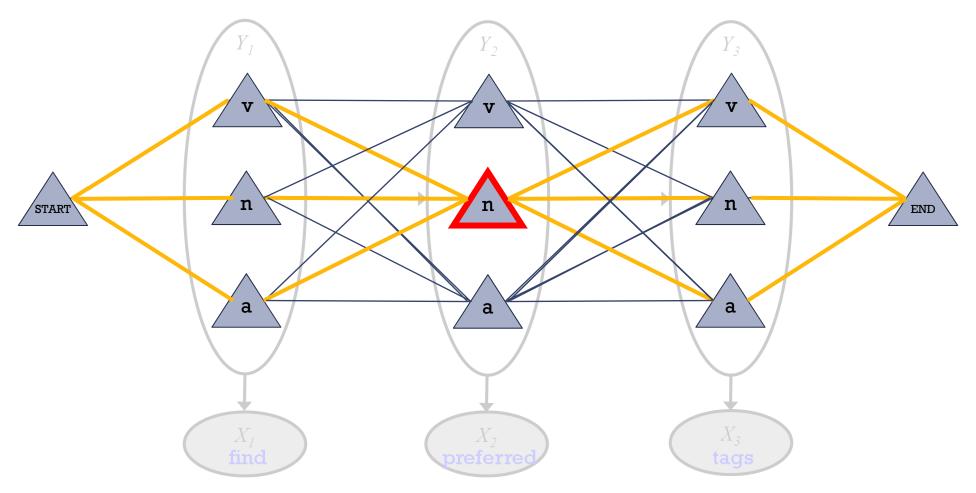
• So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/\mathbf{Z}) * \text{product weight of one path}$

• Marginal probability $p(Y_2 = n)$ = (1/Z) * total weight of all paths through n



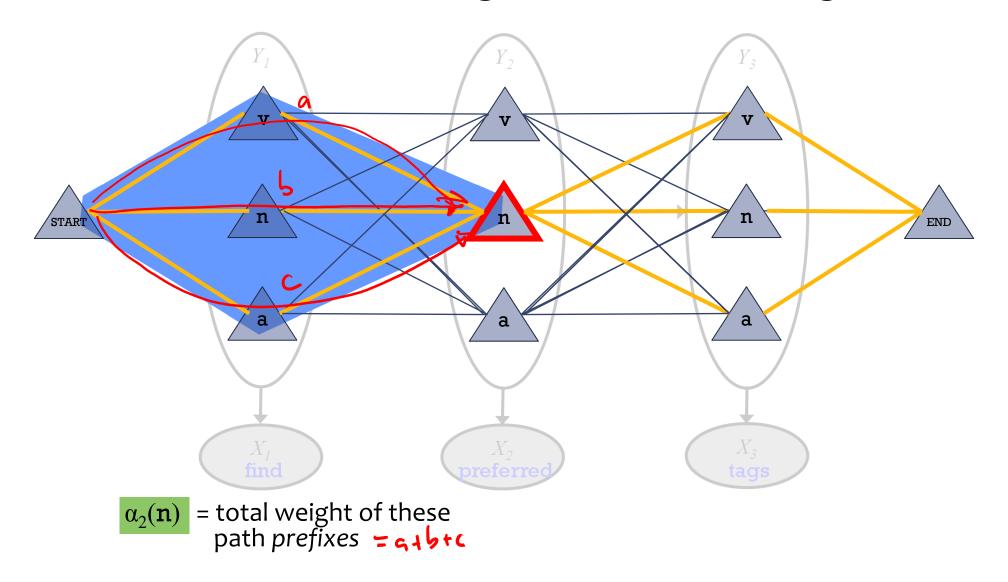
• So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/\mathbf{Z}) * \text{product weight of one path}$

• Marginal probability $p(Y_2 = v)$ = (1/Z) * total weight of all paths through

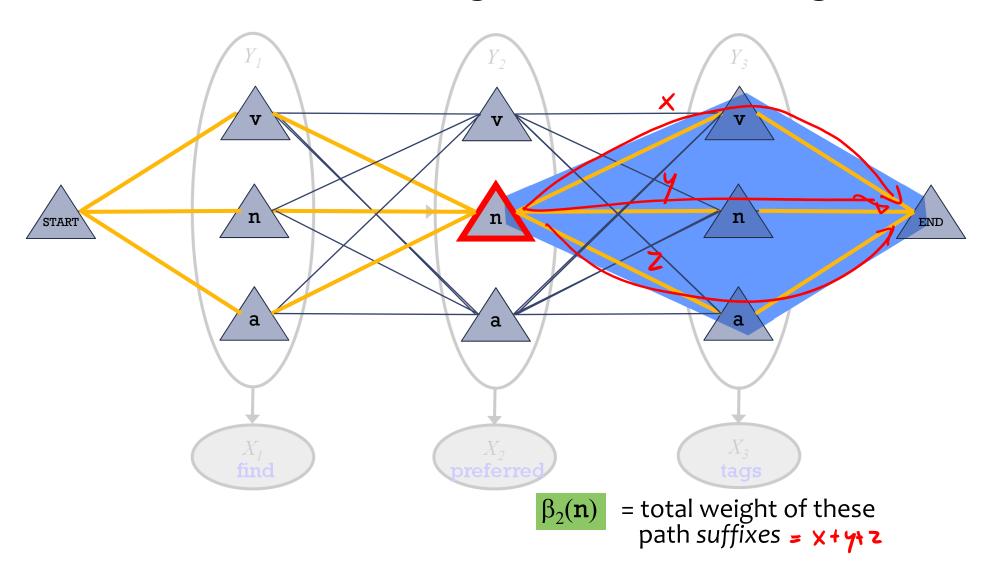


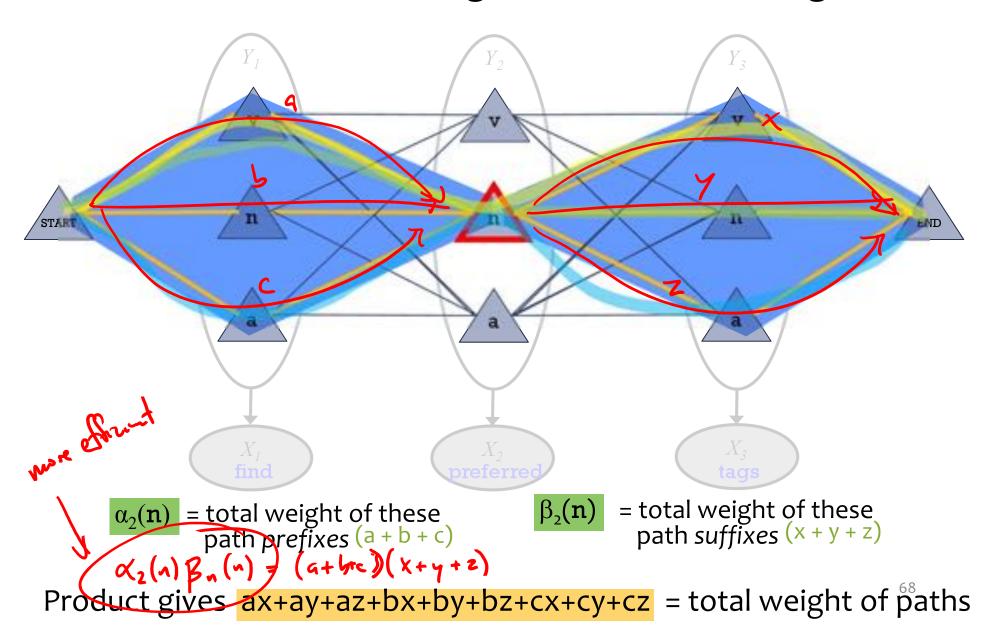
• So $p(\mathbf{v} \mathbf{a} \mathbf{n}) = (1/\mathbf{Z}) * \text{product weight of one path}$

• Marginal probability $p(Y_2 = n)$ = (1/Z) * total weight of all paths through n



(found by dynamic programming: matrix-vector products)

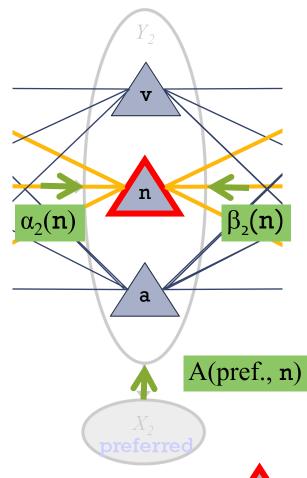




Oops! The weight of a path through a state also includes a weight at that state.

So $\alpha(\mathbf{n}) \cdot \beta(\mathbf{n})$ isn't enough.

The extra weight is the opinion of the emission probability at this variable.



"belief that $Y_2 = \mathbf{n}$ "

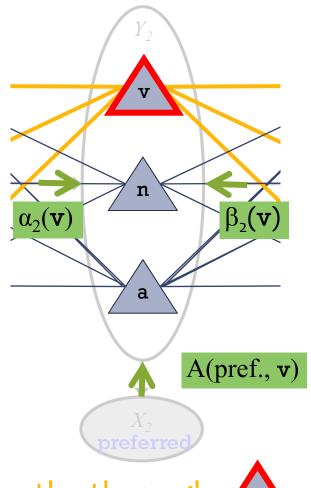
total weight of all paths through



$$= \alpha_2(\mathbf{n})$$

$$\alpha_2(\mathbf{n})$$
 A(pref., \mathbf{n}) $\beta_2(\mathbf{n})$

$$\beta_2(n)$$



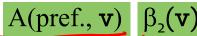
"belief that $Y_2 = \mathbf{v}$ "

"belief that $Y_2 = \mathbf{n}$ "

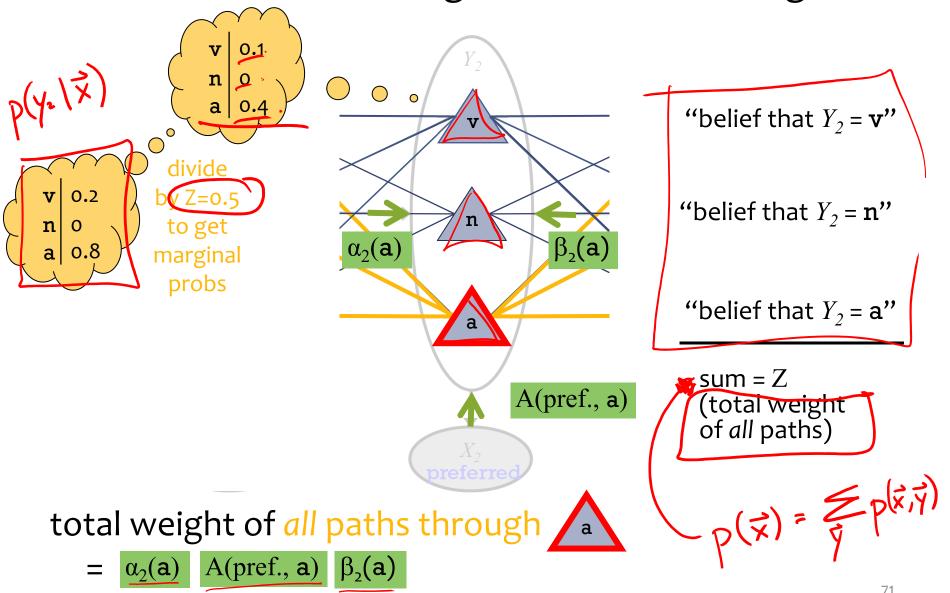
total weight of all paths through



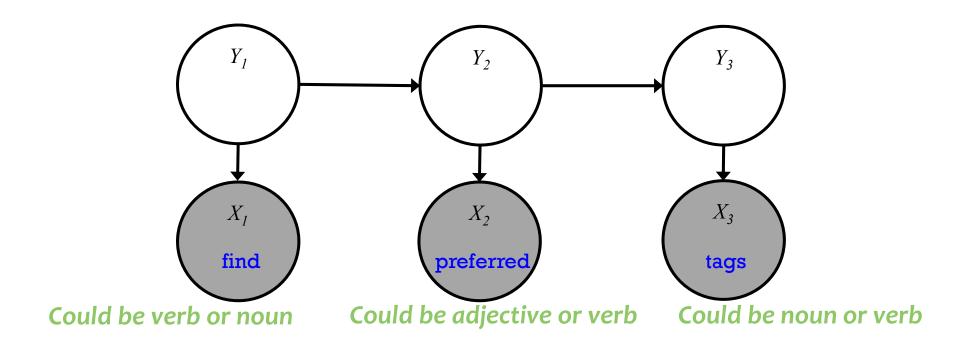
$$= \alpha_2(\mathbf{v})$$







Forward-Backward Algorithm



Inference for HMMs

Whiteboard

- Derivation of Forward algorithm
- Forward-backward algorithm
- Viterbi algorithm

Forward-Backward Algorithm

Define:
$$\alpha_{\xi}(k) \triangleq p(x_1, ..., x_{\xi}, y_{\xi} = k)$$
 $\beta_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi+1}, ..., x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi}, y_{\xi} = k)$

Define: $\alpha_{\xi}(k) \triangleq p(x_{\xi}$

Derivation of Forward Algorithm

Definition:
$$X_{\xi}(k) \stackrel{\geq}{=} p(x_1, ..., x_{\xi}, y_{\xi} = k)$$

Derivation:
$$X_{T}(END) = p(x_1, ..., x_{T}, y_{T} = END)$$

$$= p(x_1, ..., x_{T}, y_{T}) p(y_{T}) \stackrel{\wedge}{=} by \text{ def } df \text{ joint}$$

$$= p(x_{T}|y_{T}) p(x_{1}, ..., x_{T-1}, y_{T}) p(y_{T}) \stackrel{\wedge}{=} by \text{ def. } df \text{ joint}$$

$$= p(x_{T}|y_{T}) p(x_{1}, ..., x_{T-1}, y_{T}) \stackrel{\wedge}{=} by \text{ def. } df \text{ joint}$$

$$= p(x_{T}|y_{T}) \stackrel{\wedge}{=} p(x_{1}, ..., x_{T-1}, y_{T-1}, y_{T}) \stackrel{\wedge}{=} by \text{ def. } df \text{ joint}$$

$$= p(x_{T}|y_{T}) \stackrel{\wedge}{=} p(x_{1}, ..., x_{T-1}, y_{T-1}, y_{T-1}) p(y_{T-1}) \stackrel{\wedge}{=} by \text{ def. } df \text{ af joint}$$

$$= p(x_{T}|y_{T}) \stackrel{\wedge}{=} p(x_{1}, ..., x_{T-1}, y_{T-1}) p(y_{T}|y_{T-1}) p(y_{T-1}) \stackrel{\wedge}{=} by \text{ def. } df \text{ joint}$$

$$= p(x_{T}|y_{T}) \stackrel{\wedge}{=} p(x_{1}, ..., x_{T-1}, y_{T-1}) p(y_{T}|y_{T-1}) \stackrel{\wedge}{=} by \text{ def. } df \text{ joint}$$

$$= p(x_{T}|y_{T}) \stackrel{\wedge}{=} p(x_{1}, ..., x_{T-1}, y_{T-1}) p(y_{T}|y_{T-1}) \stackrel{\wedge}{=} by \text{ def. } df \text{ of } x_{\xi}(k)$$

Viterbi Algorithm

Define:
$$\omega_{\xi}(k) \triangleq \max_{y_1, \dots, y_{t-1}, y_{t-1}, y_t = k} p(x_1, \dots, x_t, y_1, \dots, y_{t-1}, y_t = k)$$

"backparks" $\longrightarrow b_{\xi}(k) \triangleq \alpha_{fg} \max_{x_1, \dots, x_t, y_1, \dots, y_{t-1}, y_t = k} p(x_1, \dots, x_t, y_1, \dots, y_{t-1}, y_t = k)$

Assume $y_0 = START$

① Initialize $\omega_0(START) = 1$ $\omega_0(k) = 0$ $\forall k \neq START$

② For $t = 1, \dots, T$:

For $k = 1, \dots, K$:

 $\omega_{t}(k) = \sum_{j \in \{1, \dots, K\}} p(x_t | y_t = k) \omega_{k-1}(j) p(y_t = k | y_{t-1} = j)$
 $b_{t}(k) = \sum_{j \in \{1, \dots, K\}} p(x_t | y_t = k) \omega_{k-1}(j) p(y_t = k | y_{t-1} = j)$

③ Compute Most Probable Assignment

 $\hat{y}_T = b_{T+1}(END)$
For $t = T-1, \dots, 1$
 $\hat{y}_t = b_{t+1}(\hat{y}_{t+1})$

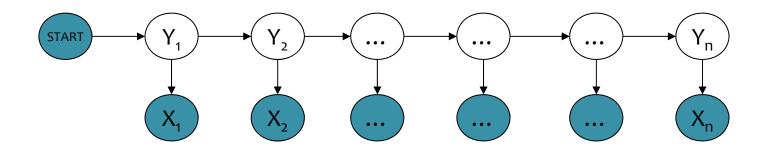
Thick pointer"

Inference in HMMs

What is the **computational complexity** of inference for HMMs?

- The naïve (brute force) computations for Evaluation, Decoding, and Marginals take exponential time, O(K^T)
- The forward-backward algorithm and Viterbi algorithm run in polynomial time, O(T*K²)
 - Thanks to dynamic programming!

Shortcomings of Hidden Markov Models



- HMM models capture dependences between each state and only its corresponding observation
 - NLP example: In a sentence segmentation task, each segmental state may depend not just on a single word (and the adjacent segmental stages), but also on the (nonlocal) features of the whole line such as line length, indentation, amount of white space, etc.
- Mismatch between learning objective function and prediction objective function
 - HMM learns a joint distribution of states and observations P(Y, X), but in a prediction task, we need the conditional probability P(Y|X)

MBR DECODING

Inference for HMMs

- Three Inference Problems for an HMM
 - Evaluation: Compute the probability of a given sequence of observations
 - 2. Viterbi Decoding: Find the most-likely sequence of hidden states, given a sequence of observations
 - Marginals: Compute the marginal distribution for a hidden state, given a sequence of observations
 - 4. MBR Decoding: Find the lowest loss sequence of hidden states, given a sequence of observations (Viterbi decoding is a special case)

Minimum Bayes Risk Decoding

- Suppose we given a loss function l(y', y) and are asked for a single tagging
- How should we choose just one from our probability distribution p(y|x)?
- A minimum Bayes risk (MBR) decoder h(x) returns the variable assignment with minimum **expected** loss under the model's distribution

$$egin{aligned} h_{m{ heta}}(m{x}) &= \underset{\hat{m{y}}}{\operatorname{argmin}} & \mathbb{E}_{m{y} \sim p_{m{ heta}}(\cdot | m{x})}[\ell(\hat{m{y}}, m{y})] \\ &= \underset{\hat{m{y}}}{\operatorname{argmin}} & \sum_{m{y}} p_{m{ heta}}(m{y} \mid m{x})\ell(\hat{m{y}}, m{y}) \end{aligned}$$

Minimum Bayes Risk Decoding

$$h_{m{ heta}}(m{x}) = \mathop{\mathrm{argmin}}_{\hat{m{y}}} \; \mathbb{E}_{m{y} \sim p_{m{ heta}}(\cdot | m{x})}[\ell(\hat{m{y}}, m{y})]$$

Consider some example loss functions:

The θ -1 loss function returns 1 only if the two assignments are identical and 0 otherwise:

$$\ell(\hat{\boldsymbol{y}}, \boldsymbol{y}) = 1 - \mathbb{I}(\hat{\boldsymbol{y}}, \boldsymbol{y})$$

The MBR decoder is:

$$h_{\boldsymbol{\theta}}(\boldsymbol{x}) = \underset{\hat{\boldsymbol{y}}}{\operatorname{argmin}} \sum_{\boldsymbol{y}} p_{\boldsymbol{\theta}}(\boldsymbol{y} \mid \boldsymbol{x}) (1 - \mathbb{I}(\hat{\boldsymbol{y}}, \boldsymbol{y}))$$
$$= \underset{\hat{\boldsymbol{y}}}{\operatorname{argmax}} p_{\boldsymbol{\theta}}(\hat{\boldsymbol{y}} \mid \boldsymbol{x})$$

which is exactly the Viterbi decoding problem!

Minimum Bayes Risk Decoding

$$h_{m{ heta}}(m{x}) = \operatorname*{argmin}_{\hat{m{y}}} \; \mathbb{E}_{m{y} \sim p_{m{ heta}}(\cdot | m{x})}[\ell(\hat{m{y}}, m{y})]$$

Consider some example loss functions:

The **Hamming loss** corresponds to accuracy and returns the number of incorrect variable assignments:

$$\ell(\hat{\boldsymbol{y}}, \boldsymbol{y}) = \sum_{i=1}^{V} (1 - \mathbb{I}(\hat{y}_i, y_i))$$

The MBR decoder is:

$$\hat{y}_i = h_{\boldsymbol{\theta}}(\boldsymbol{x})_i = \underset{\hat{y}_i}{\operatorname{argmax}} \ p_{\boldsymbol{\theta}}(\hat{y}_i \mid \boldsymbol{x})$$

This decomposes across variables and requires the variable marginals.

Learning Objectives

Hidden Markov Models

You should be able to...

- Show that structured prediction problems yield high-computation inference problems
- 2. Define the first order Markov assumption
- 3. Draw a Finite State Machine depicting a first order Markov assumption
- 4. Derive the MLE parameters of an HMM
- 5. Define the three key problems for an HMM: evaluation, decoding, and marginal computation
- 6. Derive a dynamic programming algorithm for computing the marginal probabilities of an HMM
- 7. Interpret the forward-backward algorithm as a message passing algorithm
- 8. Implement supervised learning for an HMM
- 9. Implement the forward-backward algorithm for an HMM
- 10. Implement the Viterbi algorithm for an HMM
- 11. Implement a minimum Bayes risk decoder with Hamming loss for an HMM