# Recitation 5 <br> Neural Networks 

## 10-301/10-601: Introduction to Machine Learning

2022-10-14

## 1 Matrix Calculus

Consider $\mathbf{x} \in \mathbb{R}^{p}, \mathbf{y} \in \mathbb{R}^{r}, \mathbf{z} \in \mathbb{R}^{n}$ where $\mathbf{z}=g(\mathbf{y})$, and $\mathbf{y}=f(\mathbf{x})$. We want to derive $d \mathbf{z} / d \mathbf{x}$ (a vector form of the scalar chain rule).

1. If $\mathbf{x}, \mathbf{y}$, and $\mathbf{z}$ were all scalars, what would $d z / d x$ be?

## Shape matching:

2. Fill in the following shapes:

$$
\frac{d \mathbf{y}}{d \mathbf{x}}: \quad \frac{d \mathbf{z}}{d \mathbf{y}}: \quad \frac{d \mathbf{z}}{d \mathbf{x}}:
$$

3. Therefore, the correct derivative is

$$
\frac{d \mathbf{z}}{d \mathbf{x}}=
$$

Generalizing a single element: The more rigorous method of computing such derivatives is by computing the scalar derivative for a single element, then generalizing this to all elements by turning the scalar form into a matrix form.
4. Fill in the single element:

$$
\frac{d z_{k}}{d x_{i}}=
$$

## 2 Forward Propagation



Figure 1: Neural Network For Example Questions

Forward Propagation is the process of calculating the value of your loss function, given data, weights and activation functions. Given the input data $\mathbf{x}$, we can transform it by the given weights, $\boldsymbol{\alpha}$, then apply the corresponding activation function to it and finally pass the result to the next layer. Forward propagation does not involve taking derivatives and proceeds from the input layer to the output layer.

Network Overview Consider the neural network with one hidden layer shown in Figure 2. The input layer consists of 2 features $\mathbf{x}=\left[x_{1}, x_{2}\right]^{T}$, the hidden layer has 3 nodes with output $\mathbf{z}=\left[z_{1}, z_{2}, z_{3}\right]^{T}$, and the output layer is a scalar $\hat{y}$. We also add a bias to the input, $x_{0}=1$ and the output of the hidden layer $z_{0}=1$, both of which are fixed to 1 .
$\boldsymbol{\alpha}$ is the matrix of weights from the inputs to the hidden layer and $\boldsymbol{\beta}$ is the matrix of weights from the hidden layer to the output layer. $\alpha_{j, i}$ represents the weight going to the node $z_{j}$ in the hidden layer from the node $x_{i}$ in the input layer (e.g. $\alpha_{1,2}$ is the weight from $x_{2}$ to $z_{1}$ ), and $\boldsymbol{\beta}$ is defined similarly. We will use a tanh activation function for the hidden layer and no activation for the output layer.

Network Details Equivalently, we define each of the following.
The input:

$$
\begin{equation*}
\mathbf{x}=\left[x_{0}, x_{1}, x_{2}\right]^{T} \tag{1}
\end{equation*}
$$

Linear combination at the first (hidden) layer:

$$
\begin{equation*}
a_{j}=\sum_{i=0}^{2} \alpha_{j, i} \cdot x_{i}, \forall j \in\{1, \ldots, 3\} \tag{2}
\end{equation*}
$$

Activation at the first (hidden) layer:

$$
\begin{align*}
z_{j} & =\tanh \left(a_{j}\right)=\frac{e^{a_{j}}-e^{-a_{j}}}{e^{a_{j}}+e^{-a_{j}}}, \forall j \in\{1, \ldots, 3\}  \tag{3}\\
\mathbf{z} & =\left[z_{0}, z_{1}, z_{2}, z_{3}\right]^{T} \tag{4}
\end{align*}
$$

Linear combination at the second (output) layer:

$$
\begin{equation*}
\hat{y}=\sum_{j=0}^{3} \beta_{j} \cdot z_{j} \tag{5}
\end{equation*}
$$

Here we fold in the bias term $\alpha_{j, 0}$ by thinking of $x_{0}=1$, and fold in $\beta_{0}$ by thinking of $z_{0}=1$.

Loss We will use Squared error loss, $\ell(\hat{y}, y)$ :

$$
\begin{equation*}
\ell(\hat{y}, y)=\frac{1}{2}(\hat{y}-y)^{2} \tag{6}
\end{equation*}
$$

We initialize the network weights as:

$$
\begin{aligned}
& \boldsymbol{\alpha}=\left[\begin{array}{lll}
0 & 1 & 2 \\
2 & 1 & 0 \\
0 & 2 & 0
\end{array}\right] \\
& \boldsymbol{\beta}=\left[\begin{array}{llll}
0 & 1 & 2 & 2
\end{array}\right]
\end{aligned}
$$

For the following questions, we use $y=3$.

1. Why and how do we include a bias term in the input and in the hidden-layer?
2. Why do we need to use nonlinear activation functions in our neural net?

## 3. Scalar Form:

- Given $x_{1}=1, x_{2}=2$, What are the values of $a$ ?

$$
\begin{aligned}
& a_{1}=\sum_{i=0}^{2} \alpha_{1, i} x_{i}= \\
& a_{2}=\sum_{i=0}^{2} \alpha_{2, i} x_{i}= \\
& a_{3}=\sum_{i=0}^{2} \alpha_{3, i} x_{i}=
\end{aligned}
$$

- Given $z_{1}=0, z_{2}=1, z_{3}=0$ calculate $\hat{y}, l$

4. Vector Form: Find the vector form of forward computation, given $\mathbf{x}$ is a column vector.

## 3 Diagrams

1. For the following function $f$, create the computational graph using the conventions defined in lecture.

$$
f(x, y, z)=\frac{\sin (x y)}{z}+\frac{e^{x z}}{x y}
$$

2. For the following neural network, draw the corresponding computational graph. Assume that all hidden units use the tanh function as the activation function and that the loss is mean squared error. Provide the shape of all parameters defined in the computational graph. Assume the weights for the first layer and second layers are respectively the matrices $\boldsymbol{\alpha}$ and $\beta$.


## 4 Backward Propagation



Figure 2: Neural Network For Example Questions (same as Figure 1)
Given a Neural Network and a corresponding loss function $J(\theta)$, backpropagation gives us the gradient of the loss function with respect to the weights of the neural network. The method is called backward propagation because we calculate the gradients of the final layer of weights first, then proceed backward to the first layer. In a simple neural network with one hidden layer, the partial derivatives that we need for learning are $\frac{\partial \ell}{\partial \alpha_{i j}}$ and $\frac{\partial \ell}{\partial \beta_{k j}}$, and we need to apply chain rule recursively to obtain these. Note that in implementation, it is easier to use matrix/vector forms to conduct computations.

1. Many gradients are calculated in back propagation. Which of these gradients are used to update the weights? Do not include intermediate value(s) used to calculate these gradient(s).
2. Scalar Form: Given $x_{1}=1, x_{2}=2$, what are the values of $\frac{\partial \ell}{\partial \beta_{1}}, \frac{\partial \ell}{\partial \alpha_{1,1}}$ ?

Hint: Derive expressions for $\frac{\partial \ell}{\partial \beta_{i}}$ and $\frac{\partial \ell}{\partial \alpha_{i, j}}$ first, then substitute in values.
For convenience, the computation graph for the neural network is displayed below:


Figure 3: Computation graph for the neural network in Figure 2

Hint: $\frac{\partial \tanh (x)}{\partial x}=1-\tanh (x)^{2}$
Table 1: tanh values

| x | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\tanh (x)$ | 0.76159 | 0.96403 | 0.99505 | 0.99933 | 0.99991 | 0.99999 | 0.99999 | 0.99999 | 0.99999 |

$$
\frac{\partial \ell}{\partial \beta_{i}}=\frac{\partial \ell}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial \beta_{i}}
$$

$$
\frac{\partial \ell}{\partial \beta_{1}}=
$$

$$
\frac{\partial \ell}{\partial \alpha_{i, j}}=\frac{\partial \ell}{\partial \hat{y}} \frac{\partial \hat{y}}{\partial z_{i}} \frac{\partial z_{i}}{\partial a_{i}} \frac{\partial a_{i}}{\partial \alpha_{i, j}} \quad \frac{\partial \ell}{\partial \alpha_{1,1}}=
$$

3. Vector Form: What are the values of $\frac{\partial \ell}{\partial \boldsymbol{\beta}}, \frac{\partial \ell}{\partial \boldsymbol{\alpha}}$ ?
