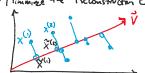
Writer in terms of the first parcial component, called V, here

1) Minimine the Reconstruction Error



$$\vec{V}_{1} = \underset{\vec{V}}{\operatorname{argmin}} \frac{1}{N} \underbrace{\underbrace{\bigvee_{i=1}^{N} d_{i} + \operatorname{argmin}}_{\vec{V}} \frac{1}{N} \underbrace{\underbrace{\bigvee$$

$$= \underset{\overrightarrow{V} \leq t}{\operatorname{agmin}} \frac{1}{|V|} \sum_{i=1}^{N} ||X^{(i)} - (\overrightarrow{V}^T \overrightarrow{X}^{(i)}) \overrightarrow{V}||_{2}^{2}$$

$$||\overrightarrow{V}||_{2} = 1$$

(2) Maximize the Variance

M= N Z=X(i)

$$\overrightarrow{V}_{1} = arg_{MAX} \frac{1}{N} \sum_{i=1}^{N} \left(\begin{array}{c} longth & of vector \\ pay. & of x^{(i)} & onlow \end{array} \right)^{2}$$

= assumex
$$\frac{1}{\sqrt[N]{s.t.}} \sum_{i=1}^{N} \left(\sqrt[N]{x}^{i} \right)^{2}$$
 $\|\sqrt[N]{l}\|_{2} = 1$

