



10-301/601 Introduction to Machine Learning

Machine Learning Department
School of Computer Science
Carnegie Mellon University

Regularization + Neural Networks

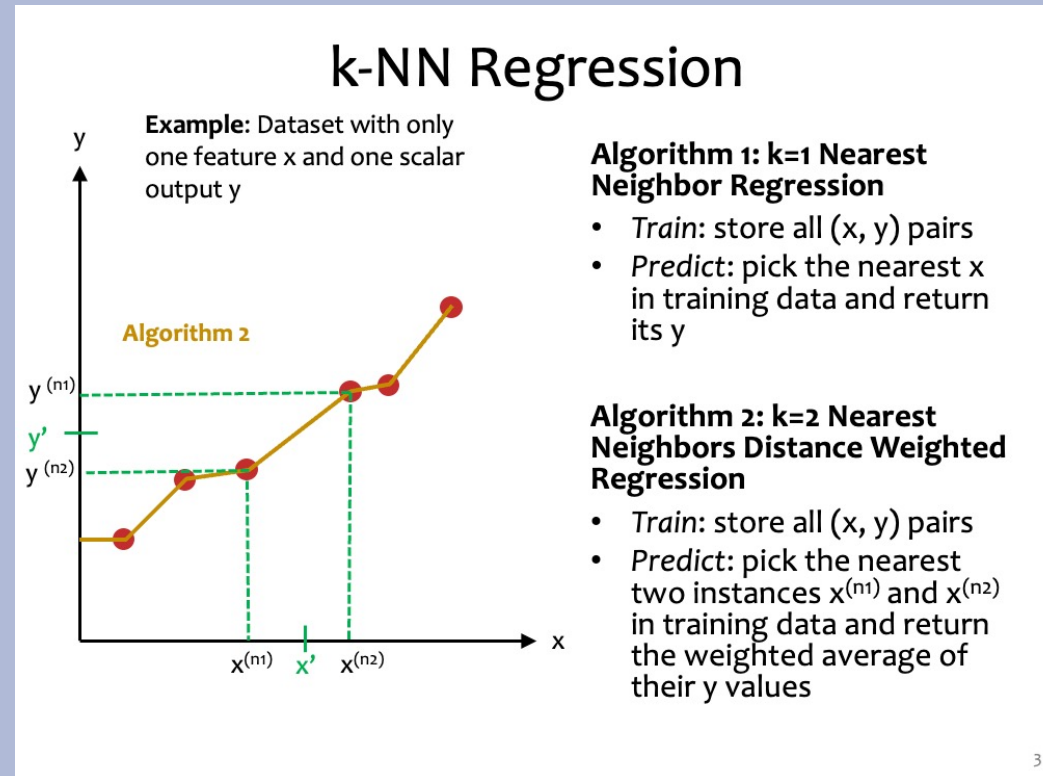
Matt Gormley
Lecture 11
Oct. 3, 2022

Reminders

- **Practice Problems: Exam 1**
- **Exam 1**
 - Tue, Oct 4, 6:30pm – 8:30pm
 - see Piazza for exam location
- **Homework 4: Logistic Regression**
 - Out: Tue, Oct 4
 - Due: Thu, Oct 13 at 11:59pm
- **Be careful to submit to the correct submission slot on Gradescope!**

Q&A

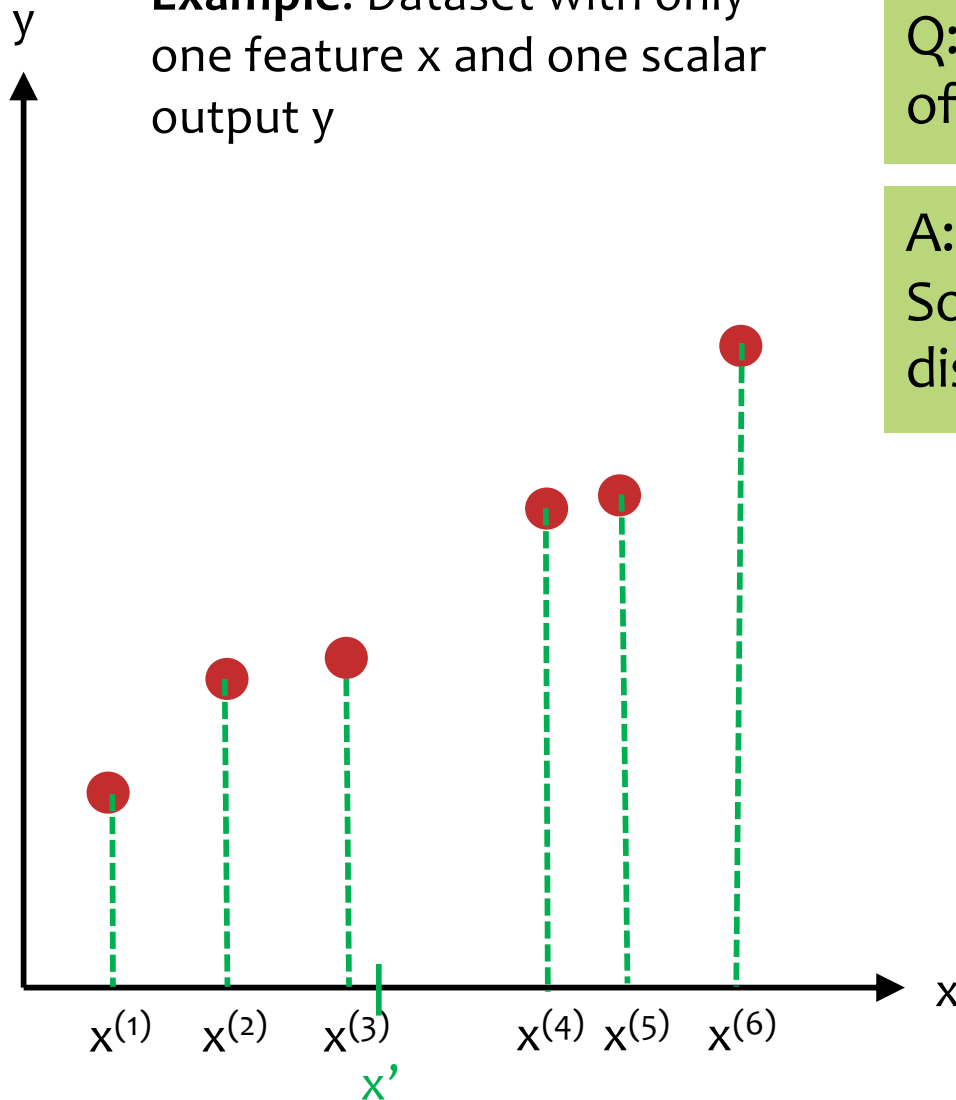
Q: Is this correct?



A: Oops! No.

k-NN Regression

Example: Dataset with only one feature x and one scalar output y



Q: What are the $k=2$ nearest neighbors of the test point x' ?

A: $x^{(2)}$ and $x^{(3)}$.

So the output curve is actually discontinuous!

Algorithm 2: $k=2$ Nearest Neighbors Distance Weighted Regression

- *Train:* store all (x, y) pairs
- *Predict:* pick the nearest two instances $x^{(n1)}$ and $x^{(n2)}$ in training data and return the weighted average of their y values

REGULARIZATION

Overfitting

Definition: The problem of **overfitting** is when the model captures the noise in the training data instead of the underlying structure

Overfitting can occur in all the models we've seen so far:

- Decision Trees (e.g. when tree is too deep)
- KNN (e.g. when k is small)
- Perceptron (e.g. when sample isn't representative)
- Linear Regression (e.g. with nonlinear features)
- Logistic Regression (e.g. with many rare features)

Motivation: Regularization

- **Occam's Razor:** prefer the simplest hypothesis
- What does it mean for a hypothesis (or model) to be **simple**?
 1. small number of features (**model selection**)
 2. small number of “important” features (**shrinkage**)

Regularization

- **Given** objective function: $J(\theta)$
- **Goal** is to find: $\hat{\theta} = \underset{\theta}{\operatorname{argmin}} J(\theta) + \lambda r(\theta)$
- **Key idea:** Define regularizer $r(\theta)$ s.t. we tradeoff between fitting the data and keeping the model simple
- **Choose form of $r(\theta)$:**
 - Example: q-norm (usually p-norm): $\|\theta\|_q = \left(\sum_{m=1}^M |\theta_m|^q \right)^{\frac{1}{q}}$

q	$r(\theta)$	yields parameters that are...	name	optimization notes
0	$\ \theta\ _0 = \sum \mathbb{1}(\theta_m \neq 0)$	zero values	L0 reg.	no good computational solutions
1	$\ \theta\ _1 = \sum \theta_m $	zero values	L1 reg.	subdifferentiable
2	$(\ \theta\ _2)^2 = \sum \theta_m^2$	small values	L2 reg.	differentiable

Regularization Examples

Add an **L2 regularizer** to Linear Regression (aka. Ridge Regression)

$$\begin{aligned} J_{\text{RR}}(\boldsymbol{\theta}) &= J(\boldsymbol{\theta}) + \lambda \|\boldsymbol{\theta}\|_2^2 \\ &= \frac{1}{N} \sum_{i=1}^N \frac{1}{2} (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)})^2 + \lambda \sum_{m=1}^M \theta_m^2 \end{aligned}$$

Add an **L1 regularizer** to Linear Regression (aka. LASSO)

$$\begin{aligned} J_{\text{LASSO}}(\boldsymbol{\theta}) &= J(\boldsymbol{\theta}) + \lambda \|\boldsymbol{\theta}\|_1 \\ &= \frac{1}{N} \sum_{i=1}^N \frac{1}{2} (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)})^2 + \lambda \sum_{m=1}^M |\theta_m| \end{aligned}$$

Regularization Examples

Add an **L2 regularizer** to Logistic Regression

$$\begin{aligned} J'(\boldsymbol{\theta}) &= J(\boldsymbol{\theta}) + \lambda \|\boldsymbol{\theta}\|_2^2 \\ &= \frac{1}{N} \sum_{i=1}^N -\log p(y^{(i)} \mid \mathbf{x}^{(i)}, \boldsymbol{\theta}) + \lambda \sum_{m=1}^M \theta_m^2 \end{aligned}$$

Add an **L1 regularizer** to Logistic Regression

$$\begin{aligned} J'(\boldsymbol{\theta}) &= J(\boldsymbol{\theta}) + \lambda \|\boldsymbol{\theta}\|_1 \\ &= \frac{1}{N} \sum_{i=1}^N -\log p(y^{(i)} \mid \mathbf{x}^{(i)}, \boldsymbol{\theta}) + \lambda \sum_{m=1}^M |\theta_m| \end{aligned}$$

Regularization

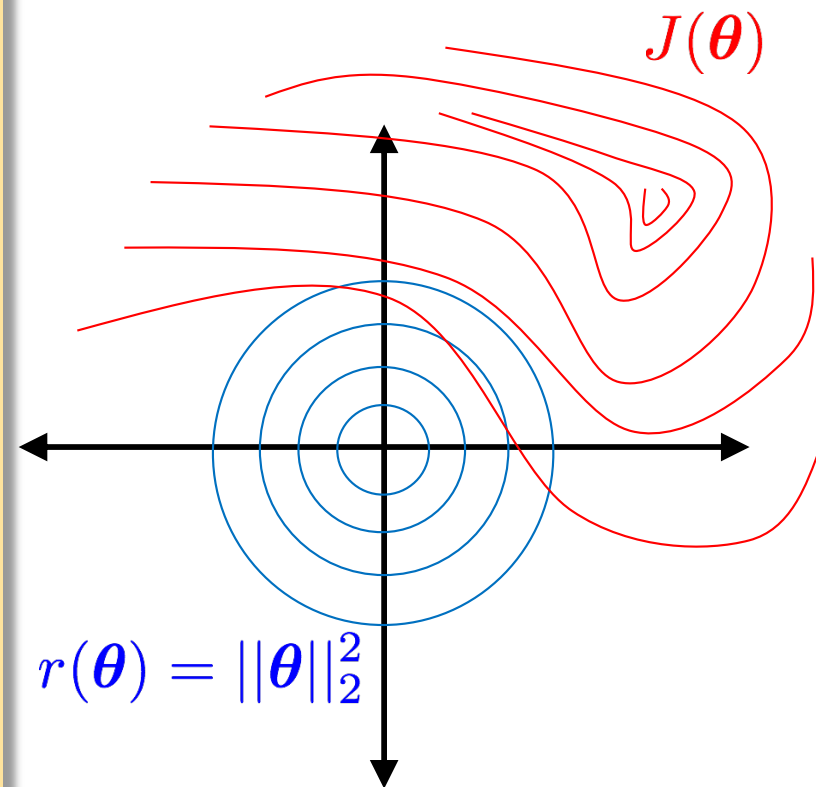
Question:

Suppose we are minimizing $J'(\theta)$ where

$$J'(\theta) = J(\theta) + \lambda r(\theta)$$

As λ increases, the minimum of $J'(\theta)$ will...

- A. ...move towards the midpoint between $J(\theta)$ and $r(\theta)$
- B. ...move towards the minimum of $J(\theta)$
- C. ...move towards the minimum of $r(\theta)$
- D. ...move towards a theta vector of positive infinities
- E. ...move towards a theta vector of negative infinities
- F. ...stay the same



Regularization

Whiteboard

- Why does L2 regularization lead to small numbers and L1 regularization lead to zeros?

Regularization

Don't Regularize the Bias (Intercept) Parameter!

- In our models so far, the bias / intercept parameter is usually denoted by θ_0 -- that is, the parameter for which we fixed $x_0 = 1$
- Regularizers always avoid penalizing this bias / intercept parameter
- Why? Because otherwise the learning algorithms wouldn't be invariant to a shift in the y-values

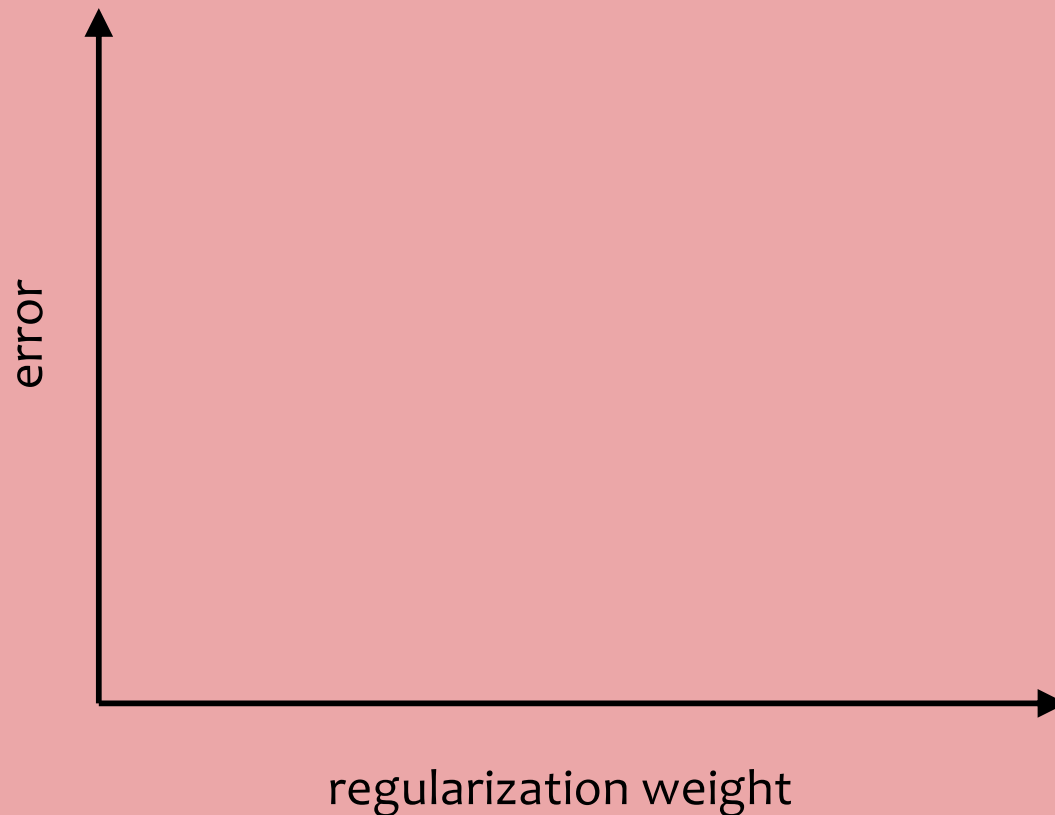
Whitening Data

- It's common to *whiten* each feature by subtracting its mean and dividing by its variance
- For regularization, this helps all the features be penalized in the same units
(e.g. convert both centimeters and kilometers to z-scores)

Regularization Exercise

In-class Exercise

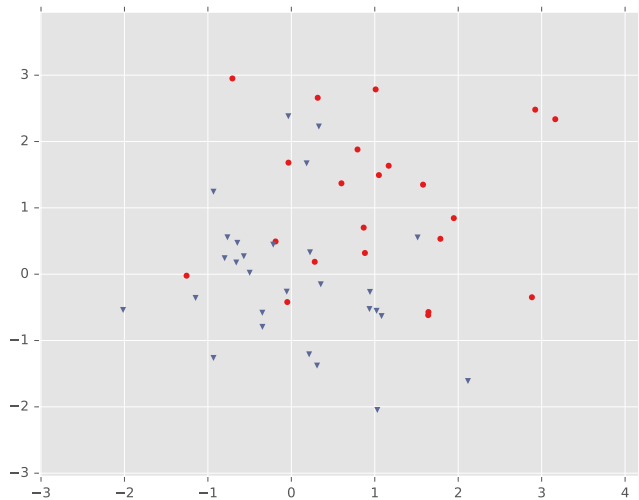
1. Plot train error vs. regularization weight (cartoon)
2. Plot validation error vs . regularization weight (cartoon)



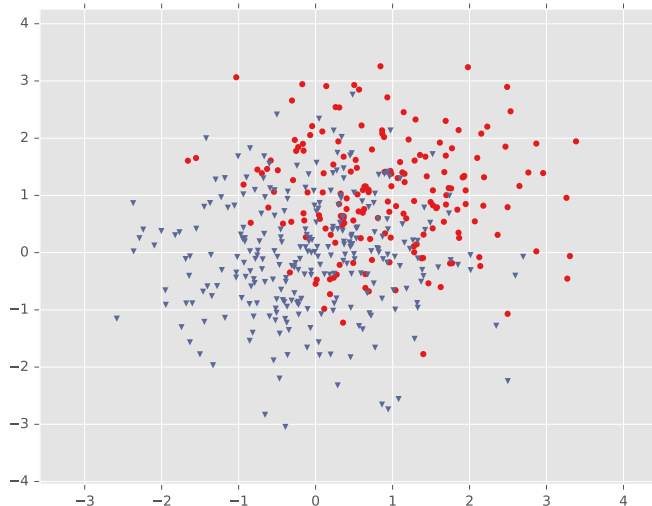
REGULARIZATION EXAMPLE: LOGISTIC REGRESSION

Example: Logistic Regression

Training
Data

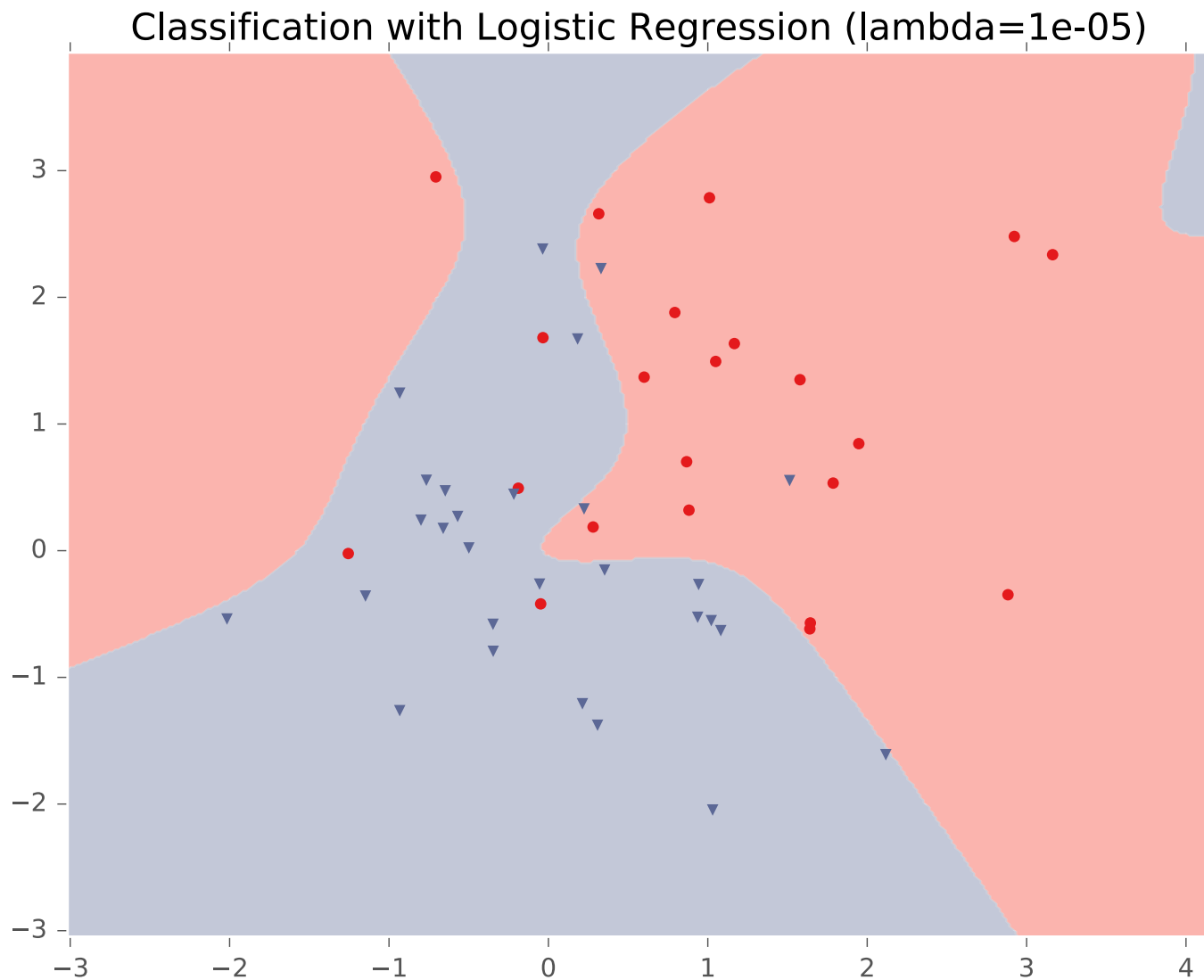


Test
Data

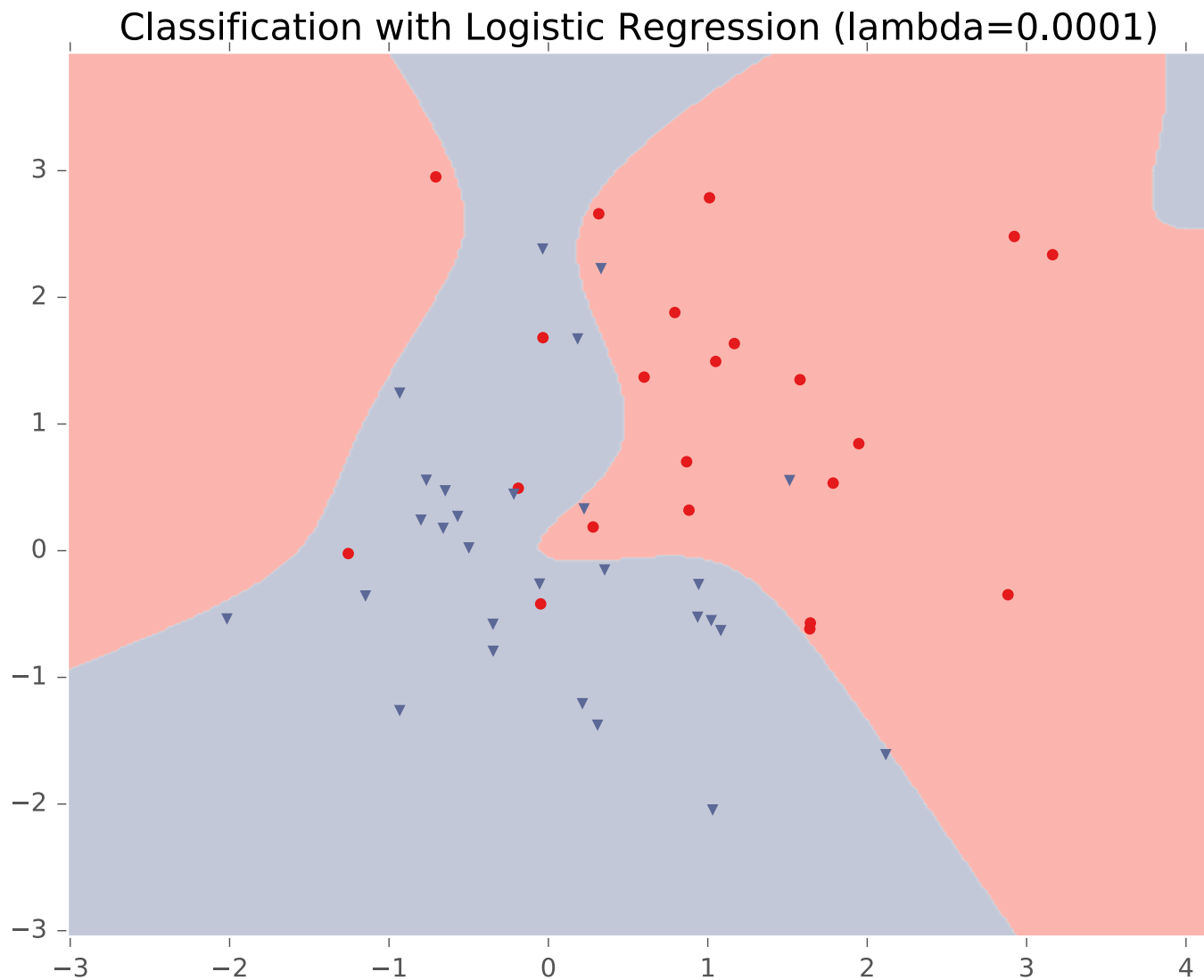


- For this example, we construct **nonlinear features** (i.e. feature engineering)
- Specifically, we add **polynomials up to order 9** of the two original features x_1 and x_2
- Thus our classifier is **linear** in the **high-dimensional feature space**, but the decision boundary is **nonlinear** when visualized in **low-dimensions** (i.e. the original two dimensions)

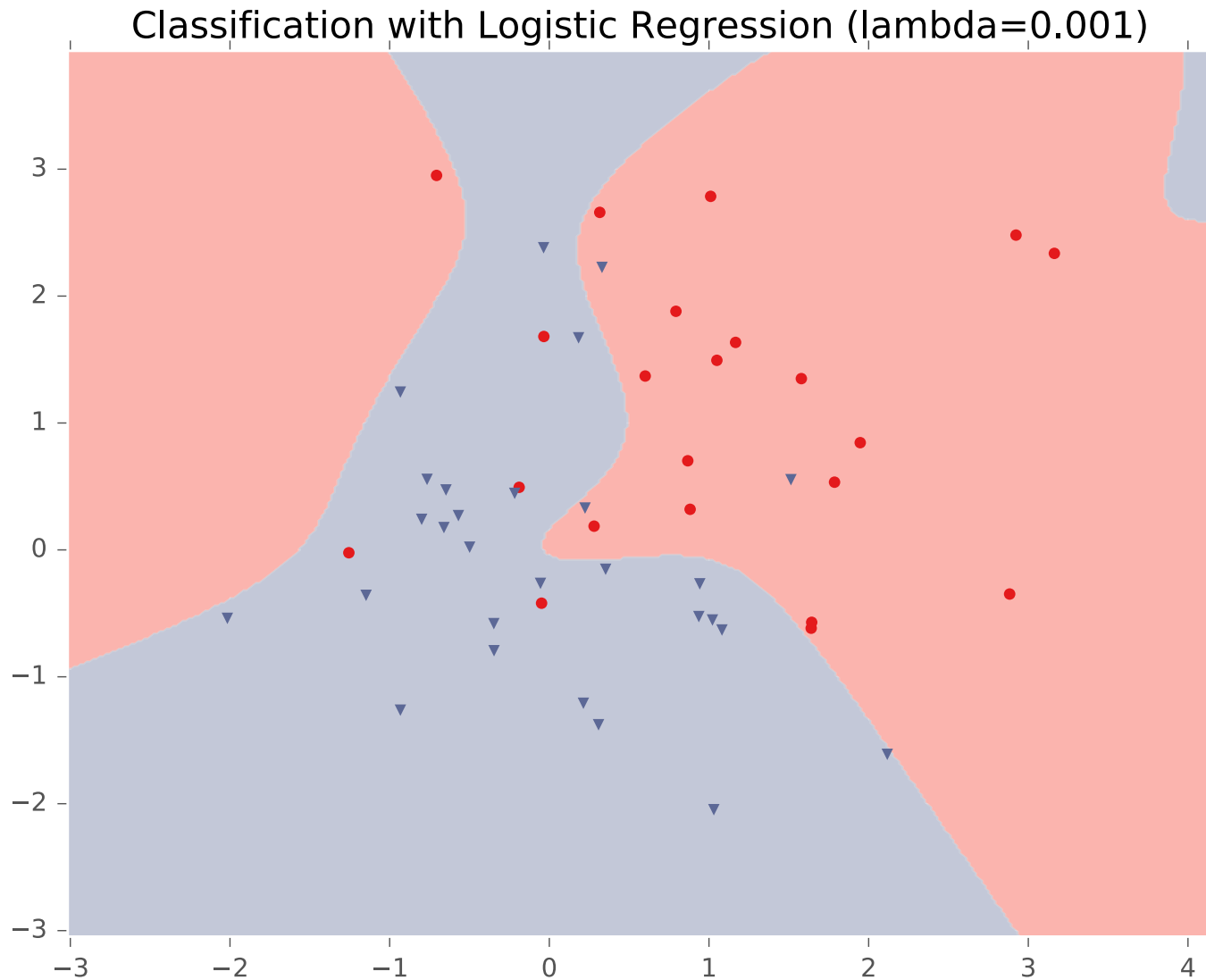
Example: Logistic Regression



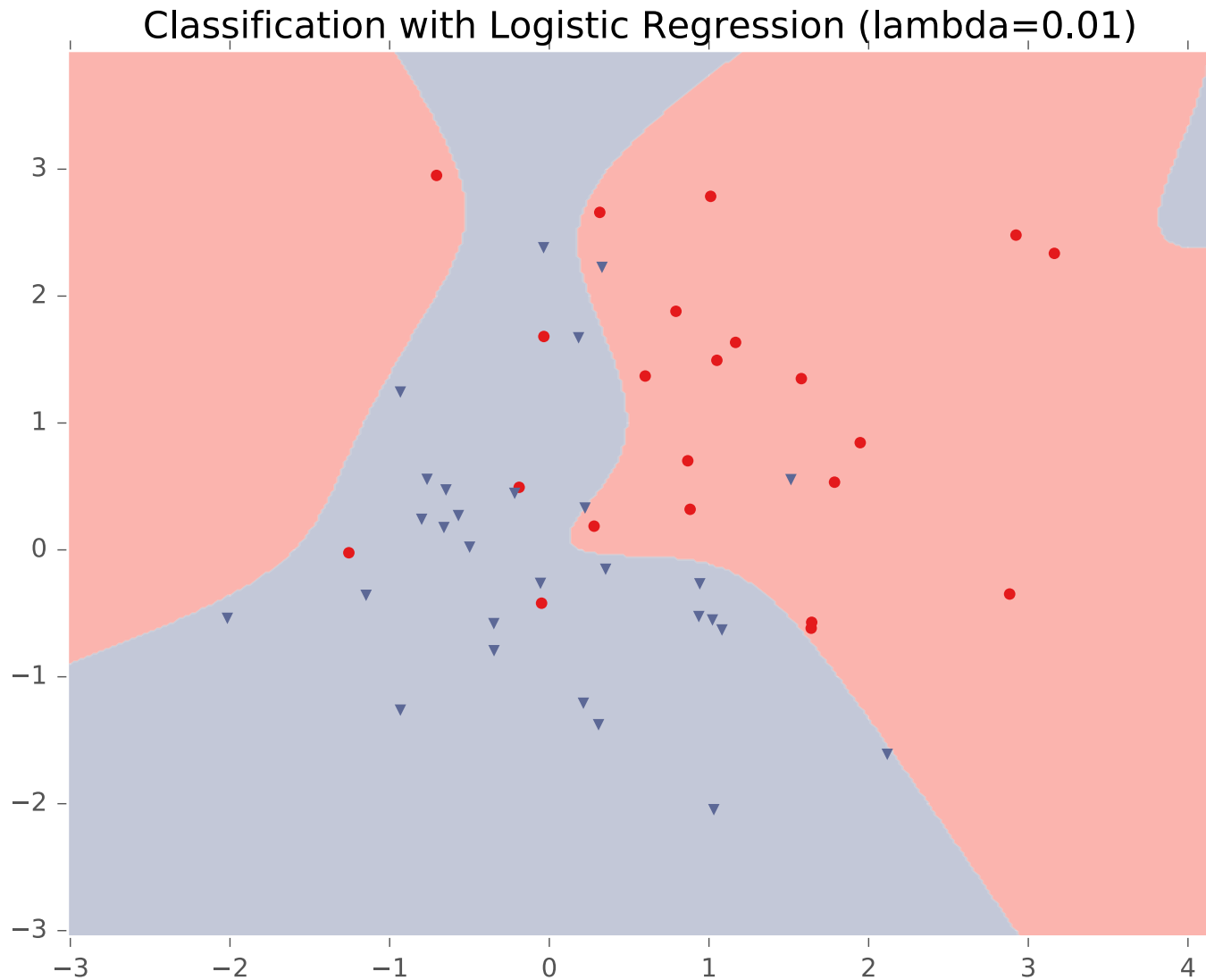
Example: Logistic Regression



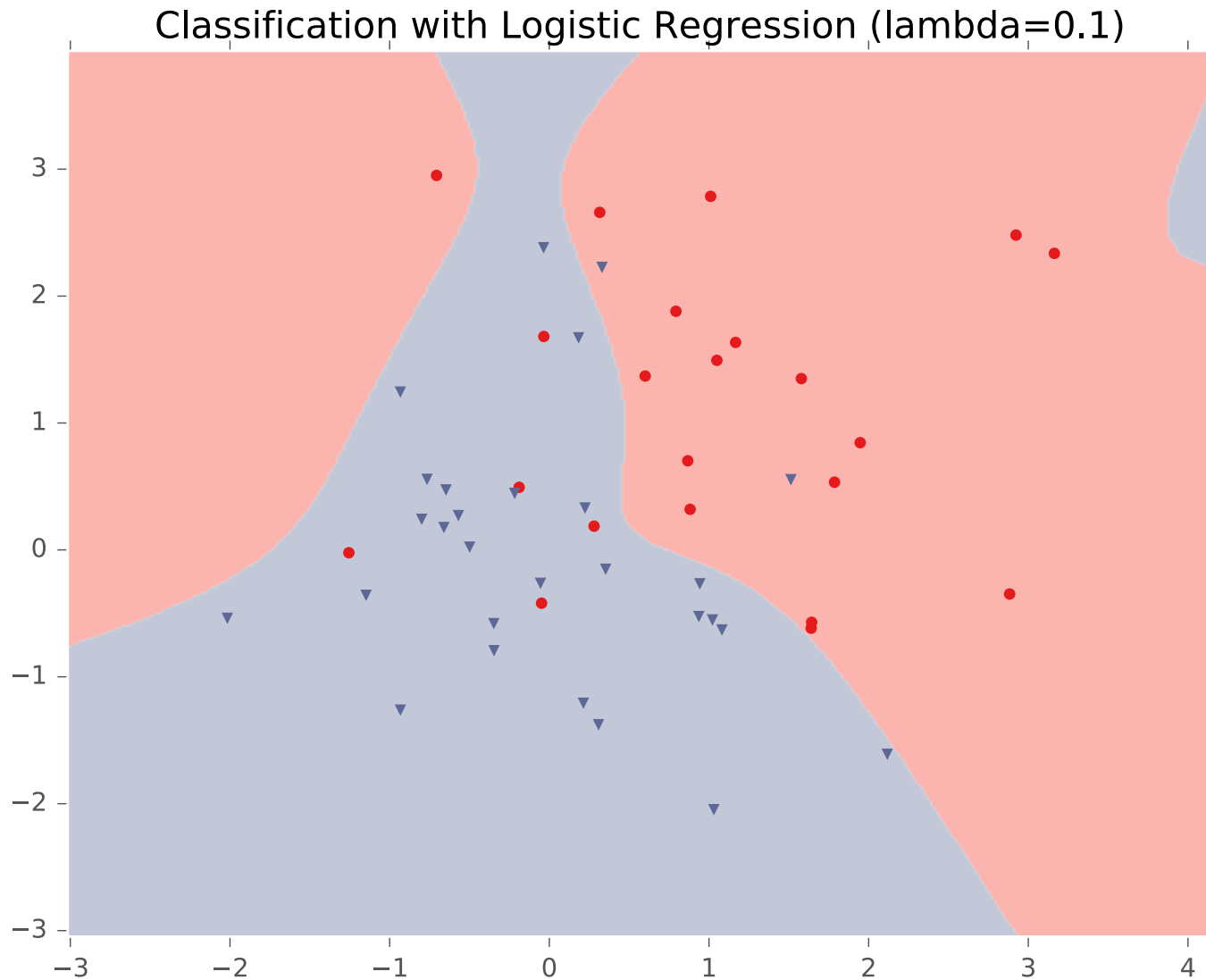
Example: Logistic Regression



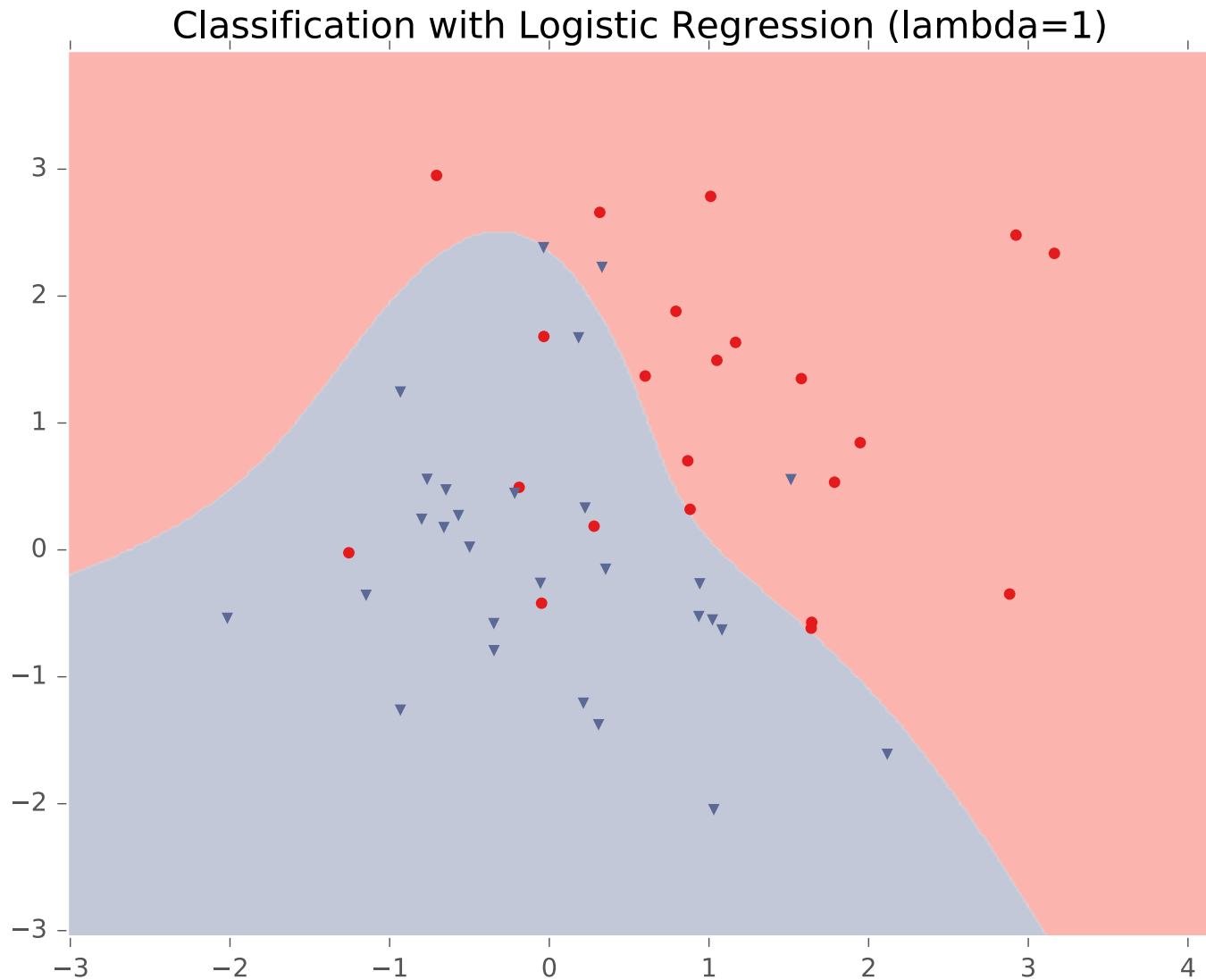
Example: Logistic Regression



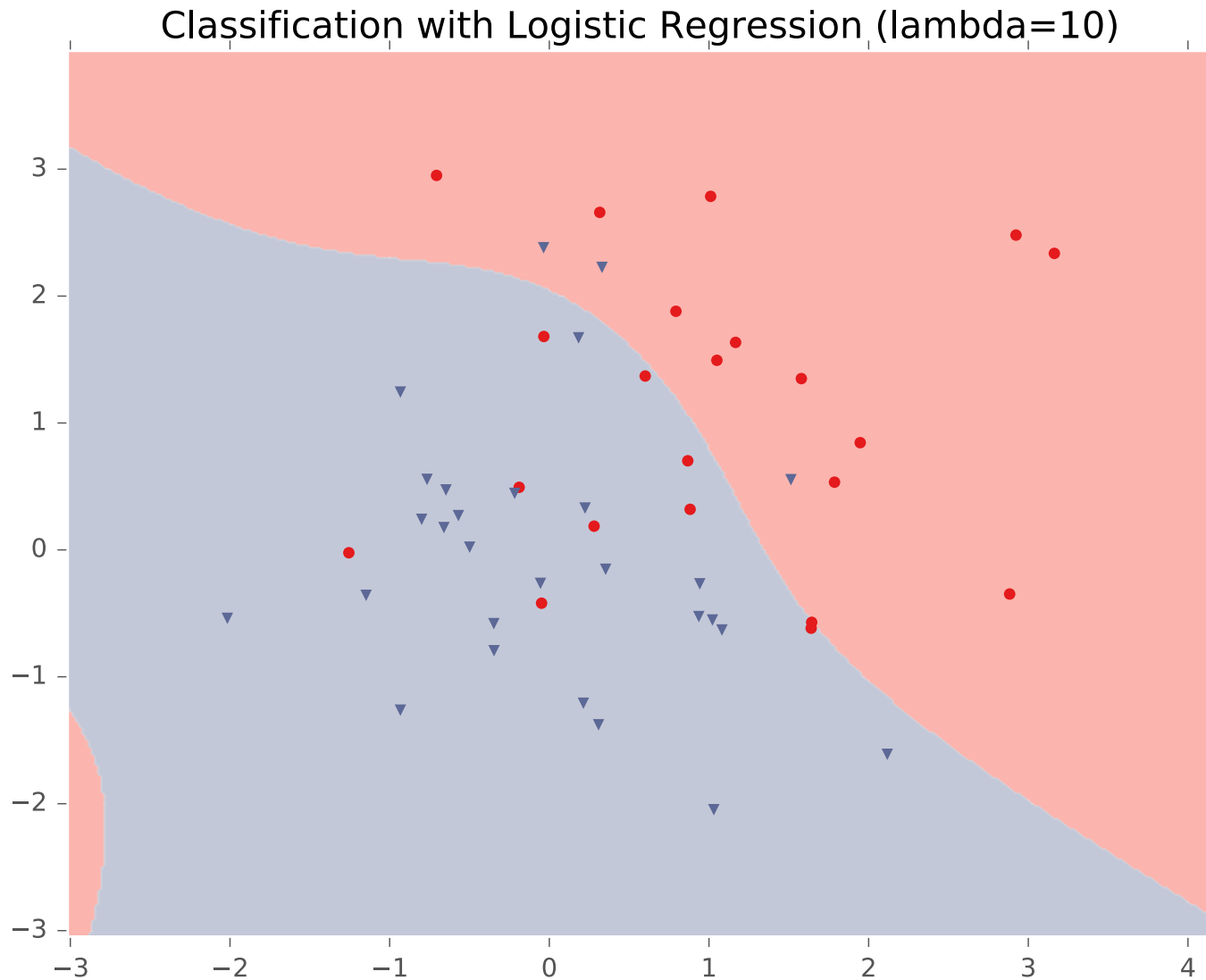
Example: Logistic Regression



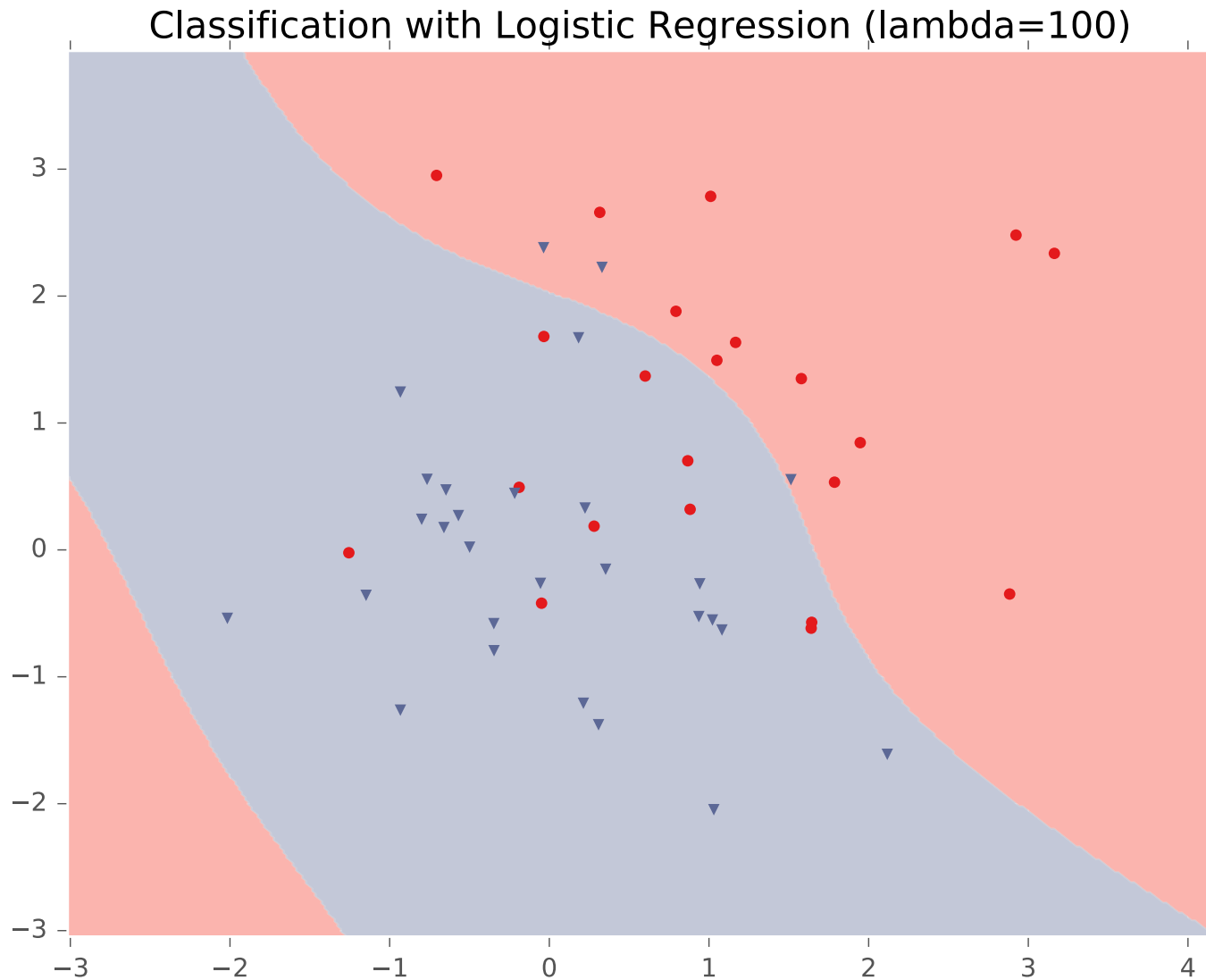
Example: Logistic Regression



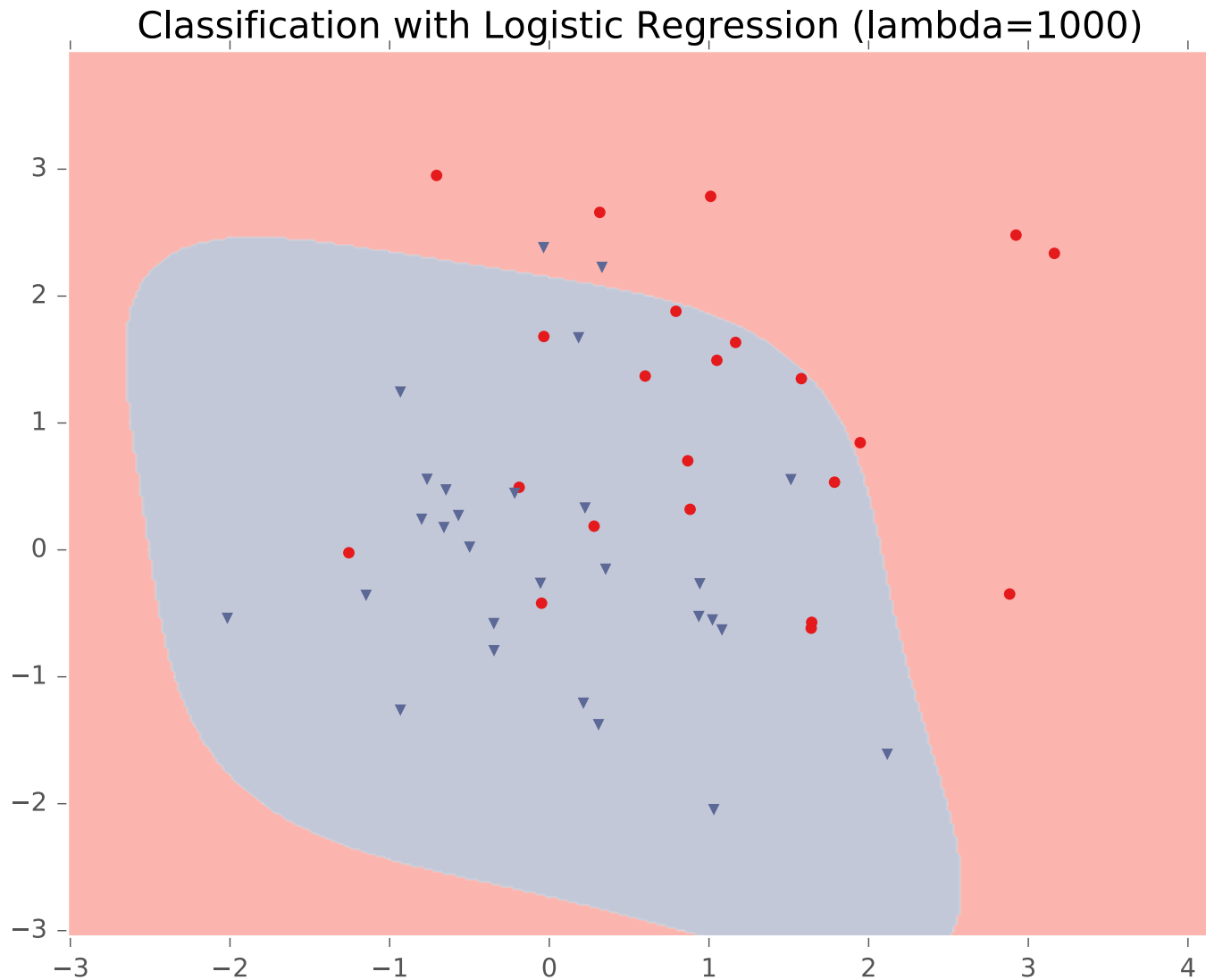
Example: Logistic Regression



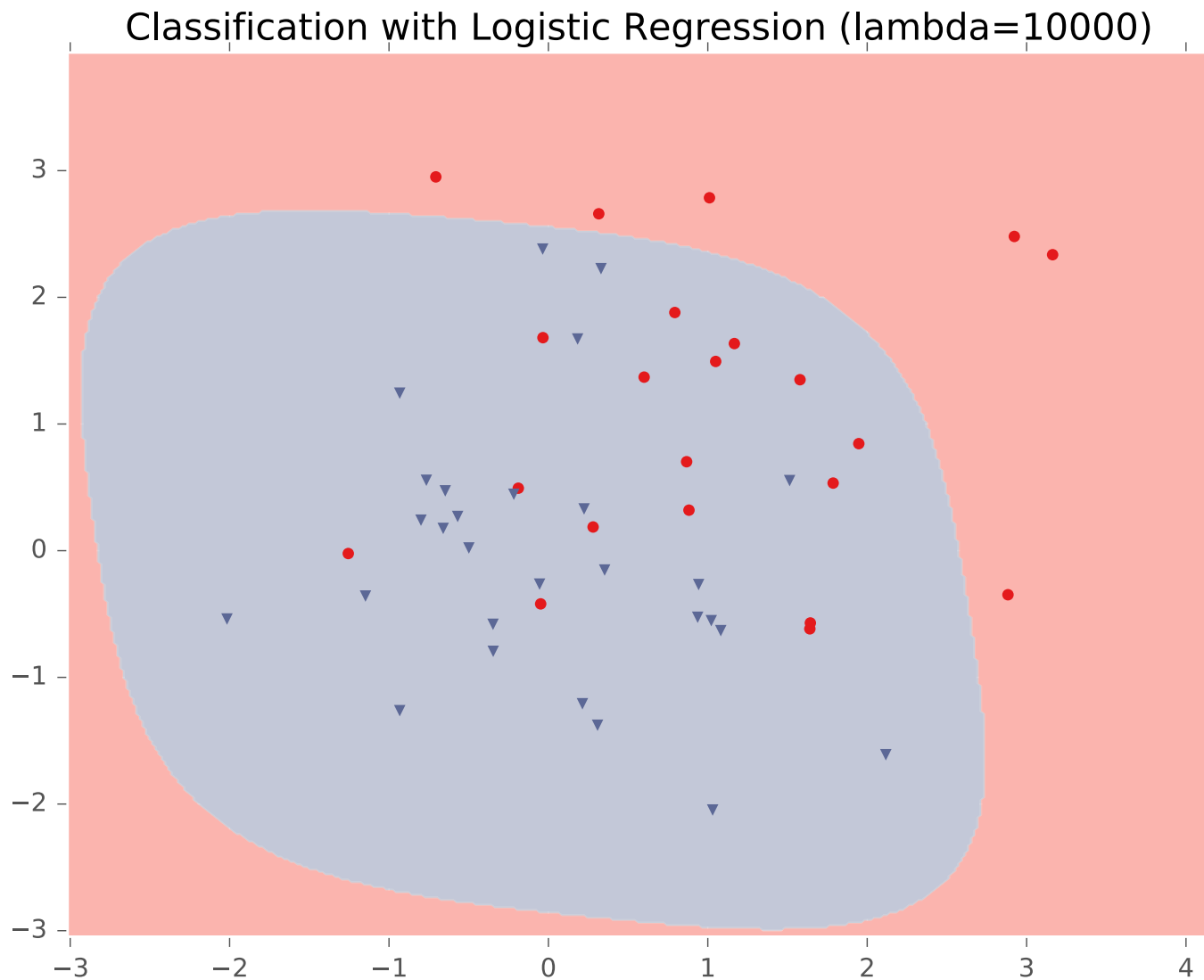
Example: Logistic Regression



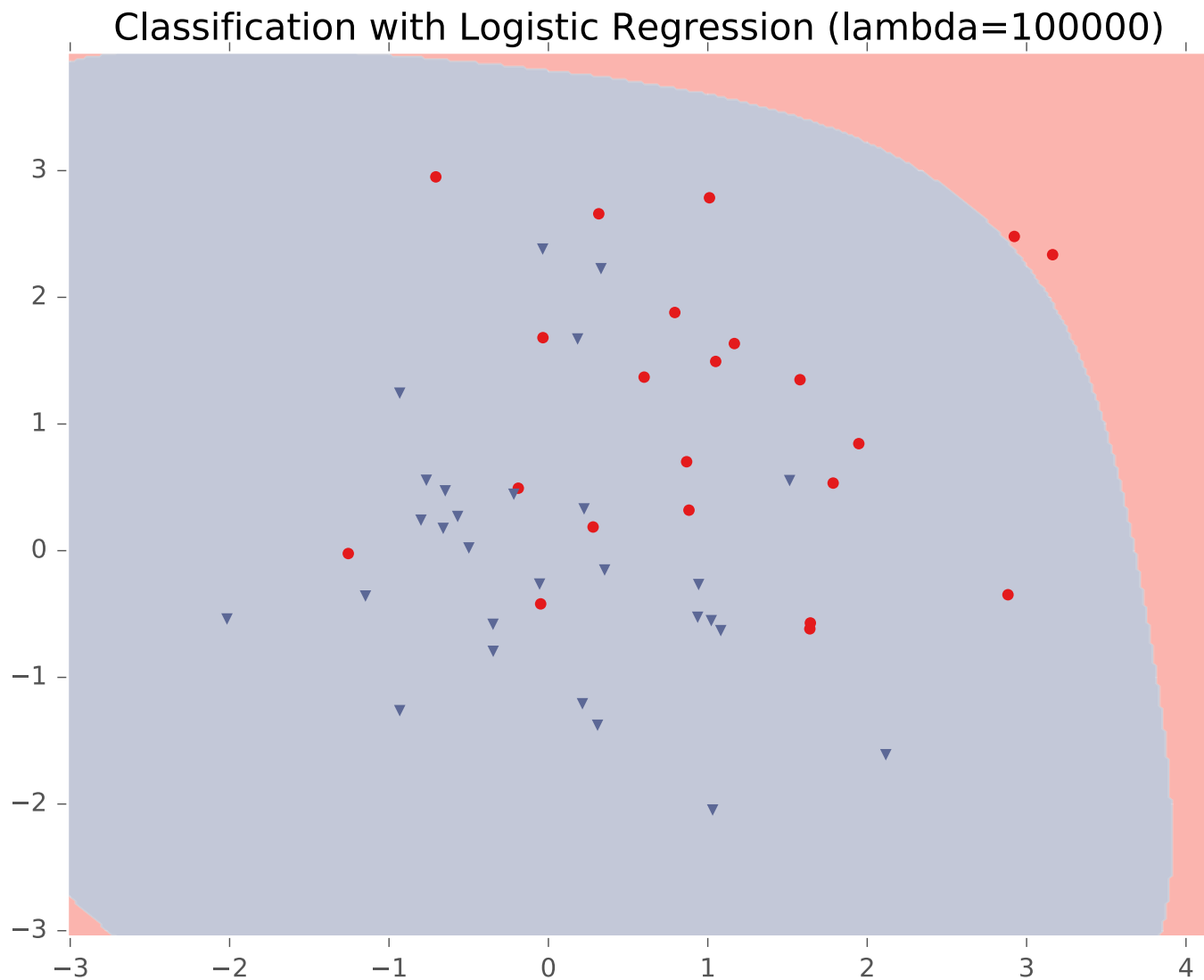
Example: Logistic Regression



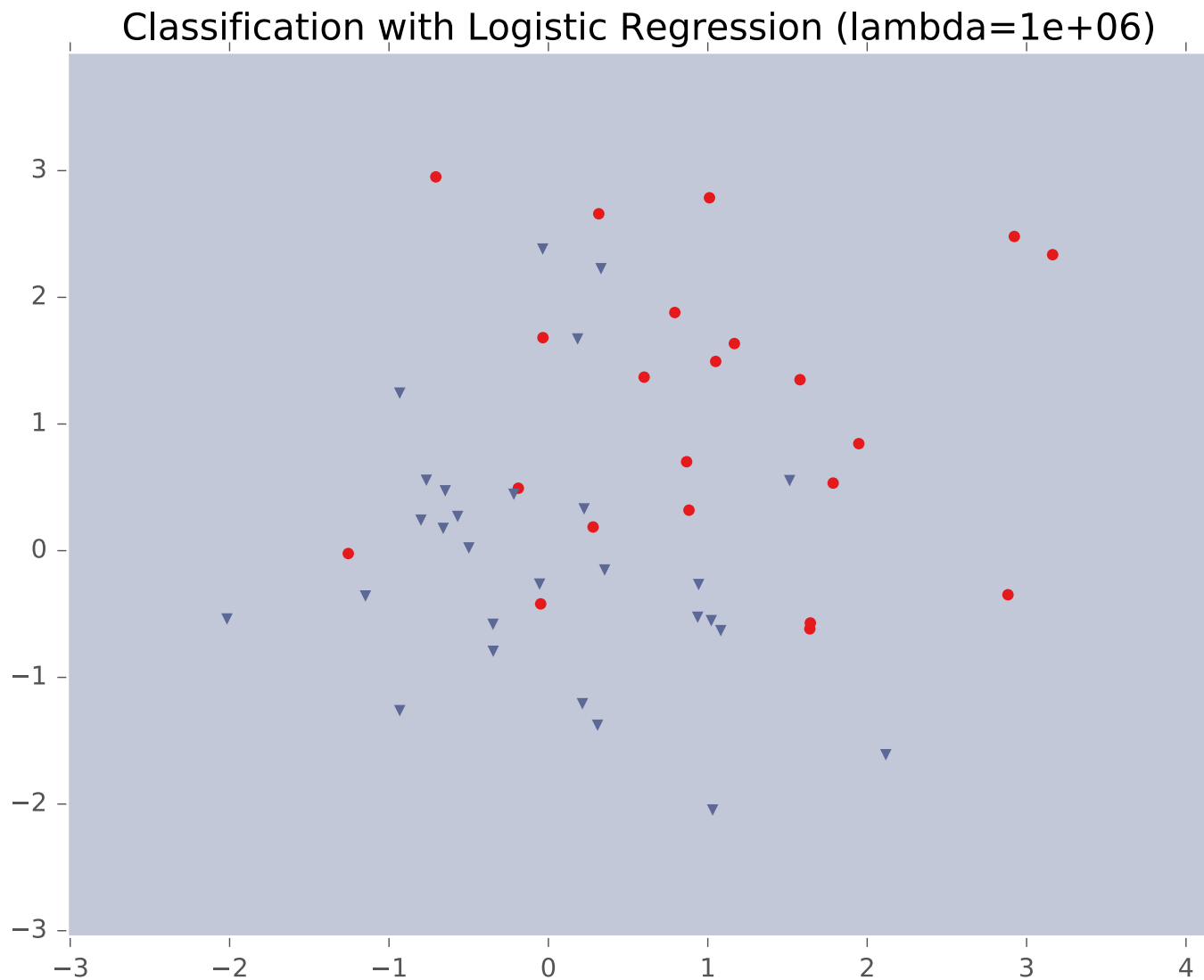
Example: Logistic Regression



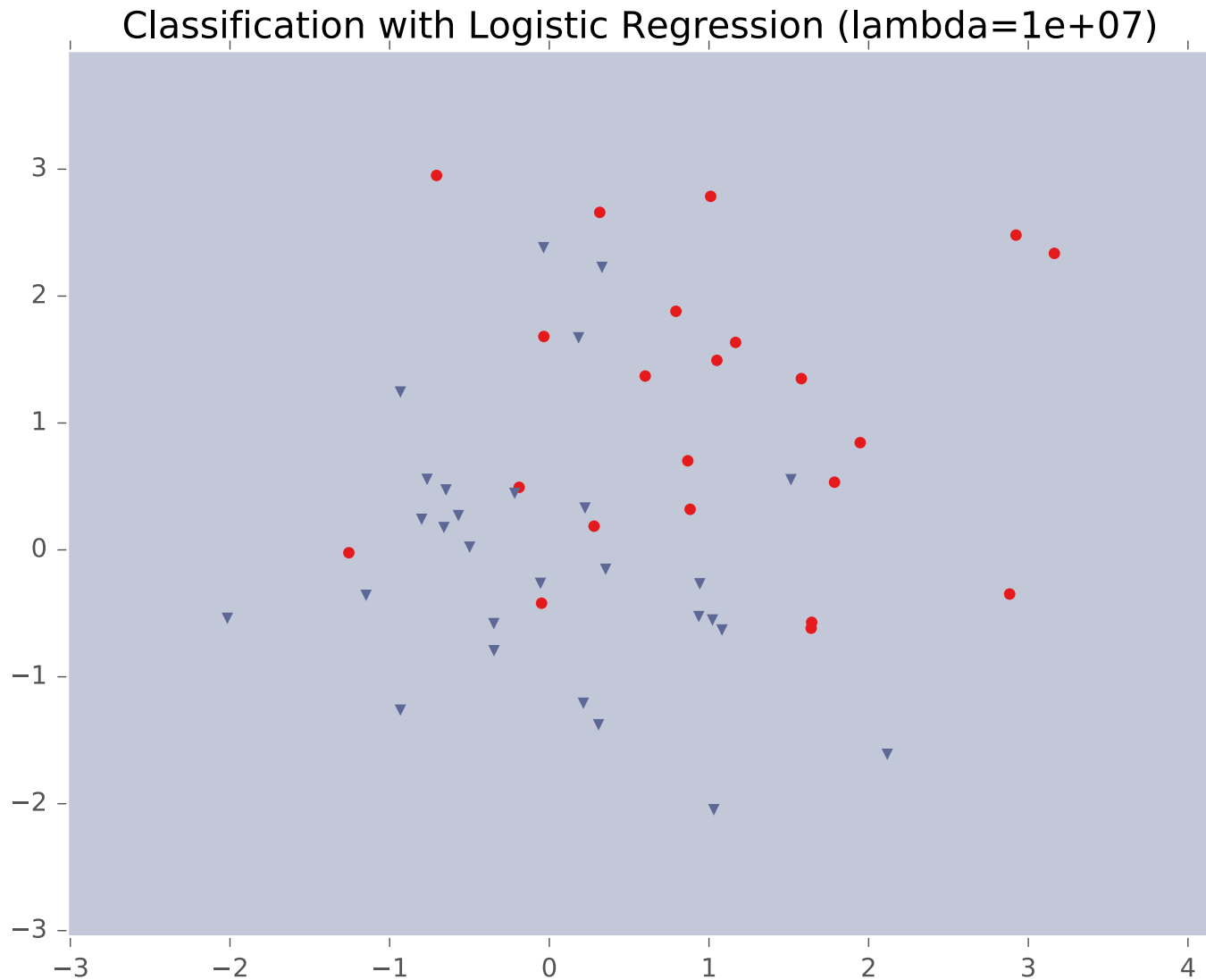
Example: Logistic Regression



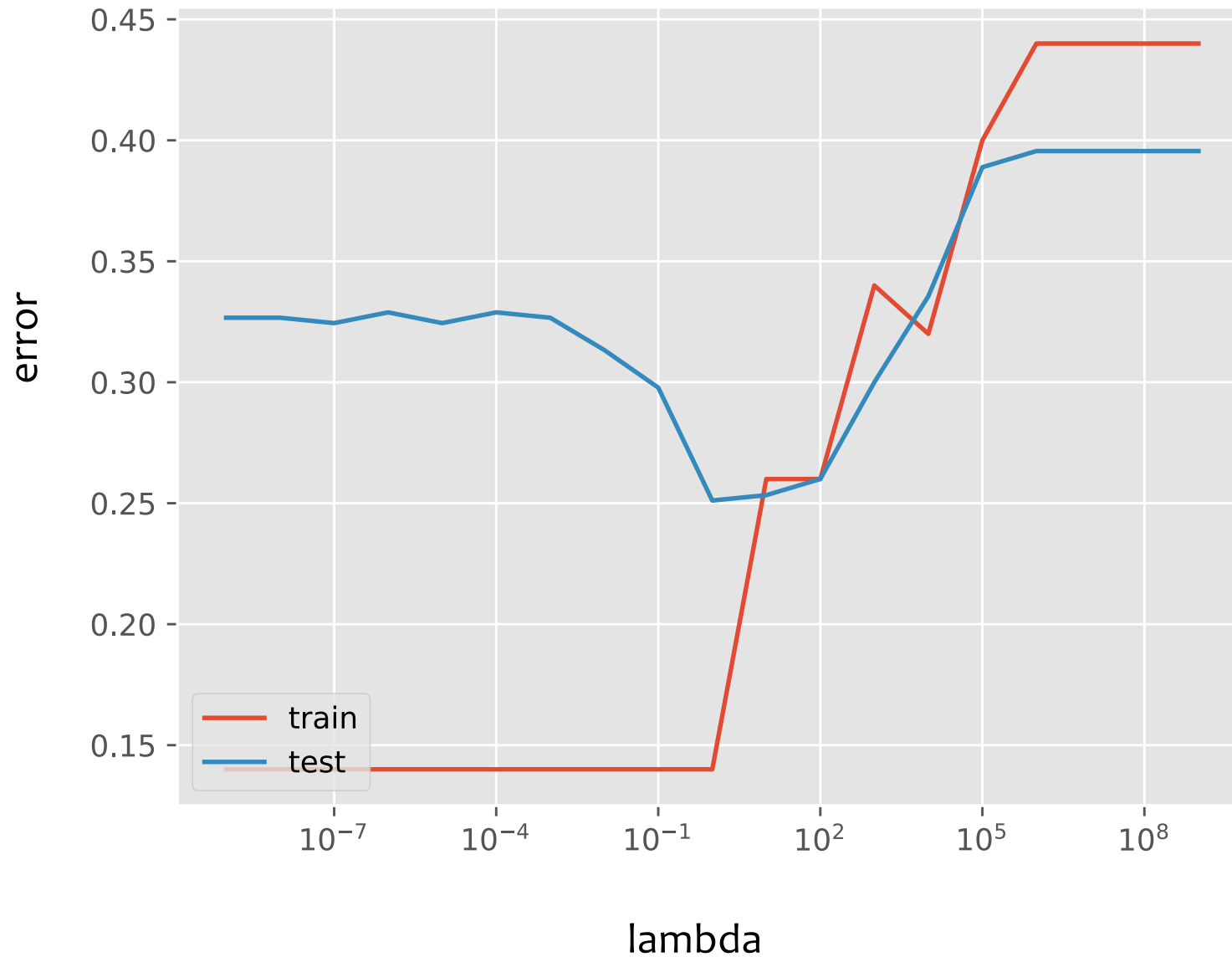
Example: Logistic Regression



Example: Logistic Regression



Example: Logistic Regression



OPTIMIZATION FOR L1 REGULARIZATION

Optimization for L1 Regularization

Can we apply SGD to the LASSO learning problem?

$$\operatorname{argmin}_{\boldsymbol{\theta}} J_{\text{LASSO}}(\boldsymbol{\theta})$$

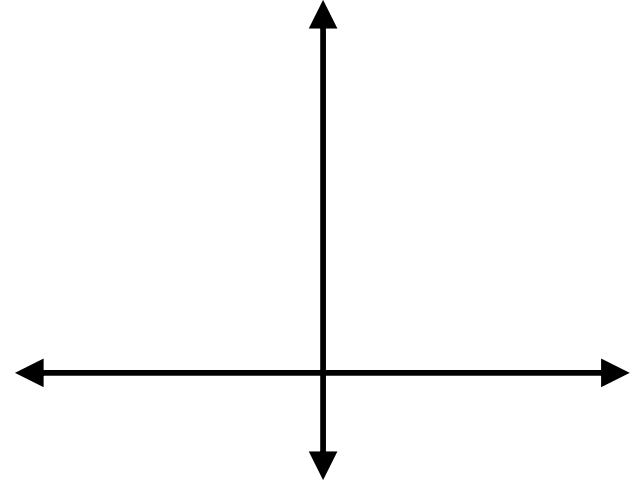
$$J_{\text{LASSO}}(\boldsymbol{\theta}) = J(\boldsymbol{\theta}) + \lambda \|\boldsymbol{\theta}\|_1$$

$$= \frac{1}{2} \sum_{i=1}^N (\boldsymbol{\theta}^T \mathbf{x}^{(i)} - y^{(i)})^2 + \lambda \sum_{k=1}^K |\theta_k|$$

Optimization for L1 Regularization

- Consider the absolute value function:

$$r(\boldsymbol{\theta}) = \lambda \sum_{k=1}^K |\theta_k|$$



- The L1 penalty is subdifferentiable (i.e. not differentiable at 0)

Def: A vector $\mathbf{g} \in \mathbb{R}^M$ is called a **subgradient** of a function $f(\mathbf{x}) : \mathbb{R}^M \rightarrow \mathbb{R}$ at the point $\mathbf{x}$ if, for all $\mathbf{x}' \in \mathbb{R}^M$, we have:

$$f(\mathbf{x}') \geq f(\mathbf{x}) + \mathbf{g}^T (\mathbf{x}' - \mathbf{x})$$

Optimization for L1 Regularization

- The L1 penalty is subdifferentiable (i.e. not differentiable at 0)
- An array of optimization algorithms exist to handle this issue:
 - Subgradient descent
 - Stochastic subgradient descent
 - Coordinate Descent
 - Othant-Wise Limited memory Quasi-Newton (OWL-QN) (Andrew & Gao, 2007) and provably convergent variants
 - Block coordinate Descent (Tseng & Yun, 2009)
 - Sparse Reconstruction by Separable Approximation (SpaRSA) (Wright et al., 2009)
 - Fast Iterative Shrinkage Thresholding Algorithm (FISTA) (Beck & Teboulle, 2009)



Basically the same as GD and SGD, but you use one of the subgradients when necessary

Regularization as MAP

- L1 and L2 regularization can be interpreted as **maximum a-posteriori (MAP) estimation** of the parameters
- To be discussed later in the course...

Takeaways

1. **Nonlinear basis functions** allow **linear models** (e.g. Linear Regression, Logistic Regression) to capture **nonlinear** aspects of the original input
2. Nonlinear features **require no changes to the model** (i.e. just preprocessing)
3. **Regularization** helps to avoid **overfitting**
4. **Regularization** and **MAP estimation** are equivalent for appropriately chosen priors

Feature Engineering / Regularization Objectives

You should be able to...

- Engineer appropriate features for a new task
- Use feature selection techniques to identify and remove irrelevant features
- Identify when a model is overfitting
- Add a regularizer to an existing objective in order to combat overfitting
- Explain why we should **not** regularize the bias term
- Convert linearly inseparable dataset to a linearly separable dataset in higher dimensions
- Describe feature engineering in common application areas

NEURAL NETWORKS

Background

A Recipe for Machine Learning

1. Given training data:

$$\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^N$$

2. Choose each of these:

– Decision function

$$\hat{\mathbf{y}} = f_{\theta}(\mathbf{x}_i)$$

– Loss function

$$\ell(\hat{\mathbf{y}}, \mathbf{y}_i) \in \mathbb{R}$$

Face



Face



Not a face



Examples: Linear regression,
Logistic regression, Neural Network

Examples: Mean-squared error,
Cross Entropy

Background

A Recipe for Machine Learning

1. Given training data:

$$\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^N$$

2. Choose each of these:

– Decision function

$$\hat{\mathbf{y}} = f_{\boldsymbol{\theta}}(\mathbf{x}_i)$$

– Loss function

$$\ell(\hat{\mathbf{y}}, \mathbf{y}_i) \in \mathbb{R}$$

3. Define goal:

$$\boldsymbol{\theta}^* = \arg \min_{\boldsymbol{\theta}} \sum_{i=1}^N \ell(f_{\boldsymbol{\theta}}(\mathbf{x}_i), \mathbf{y}_i)$$

4. Train with SGD:

(take small steps
opposite the gradient)

$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} - \eta_t \nabla \ell(f_{\boldsymbol{\theta}}(\mathbf{x}_i), \mathbf{y}_i)$$

Background

1. Given training data

$$\{\mathbf{x}_i, \mathbf{y}_i\}_{i=1}^N$$

2. Choose each of the

– Decision function

$$\hat{\mathbf{y}} = f_{\boldsymbol{\theta}}(\mathbf{x}_i)$$

– Loss function

$$\ell(\hat{\mathbf{y}}, \mathbf{y}_i) \in \mathbb{R}$$

Gradients

Backpropagation can compute this gradient!

And it's a **special case of a more general algorithm** called reverse-mode automatic differentiation that can compute the gradient of any differentiable function efficiently!

opposite the gradient)


$$\boldsymbol{\theta}^{(t+1)} = \boldsymbol{\theta}^{(t)} - \eta_t \nabla \ell(f_{\boldsymbol{\theta}}(\mathbf{x}_i), \mathbf{y}_i)$$

Goals for Today's Lecture

1. Explore a **new class of decision functions** (Neural Networks)
2. Consider **variants of this recipe** for training

2. CHOOSE each of these:

– Decision function

$$\hat{y} = f_{\theta}(x_i)$$

– Loss function

$$\ell(\hat{y}, y_i) \in \mathbb{R}$$

4. Train with SGD:

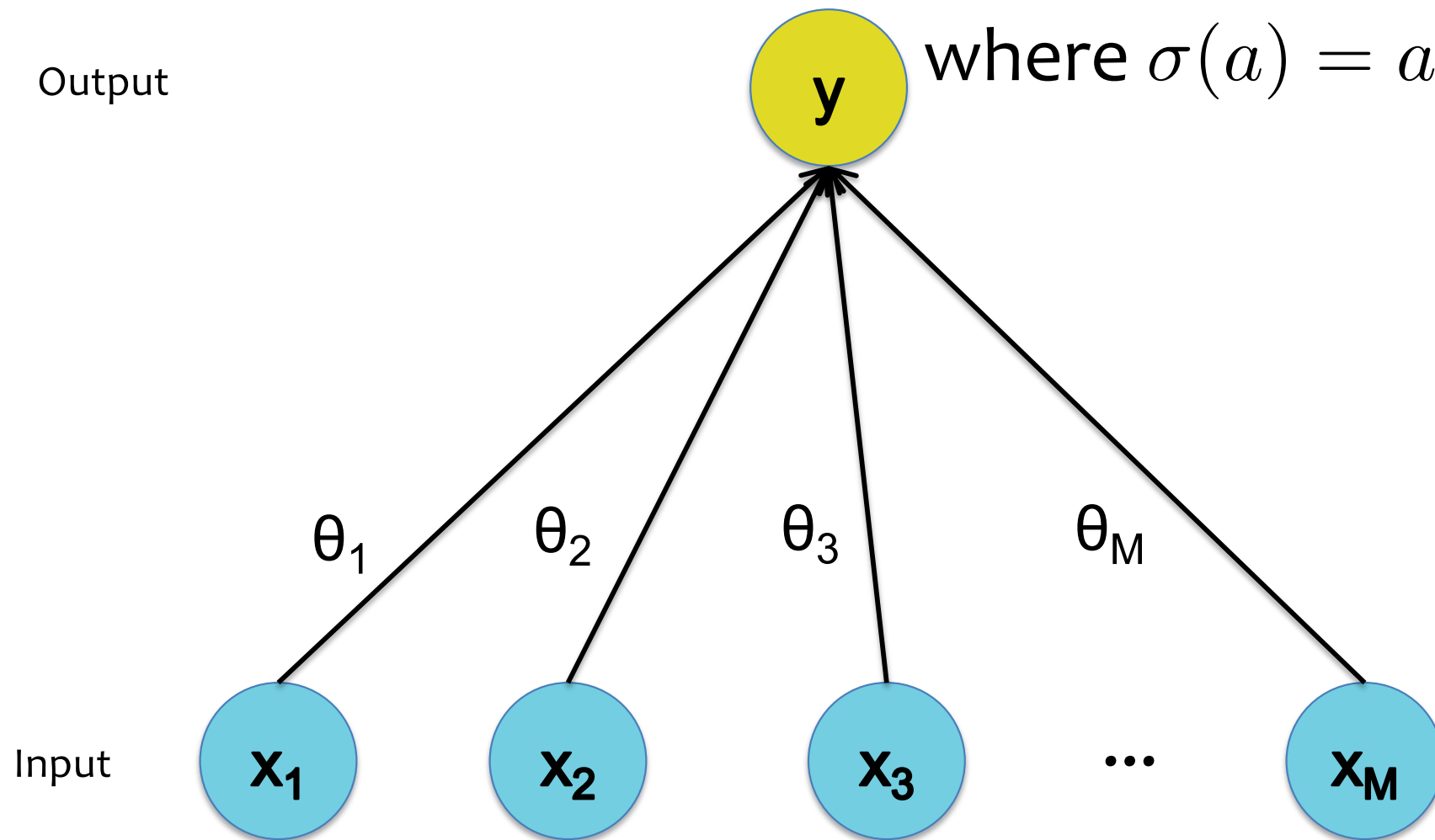
– Take small steps opposite the gradient)

$$\theta^{(t+1)} = \theta^{(t)} - \eta_t \nabla \ell(f_{\theta}(x_i), y_i)$$

$$y = h_{\theta}(\mathbf{x}) = \sigma(\boldsymbol{\theta}^T \mathbf{x})$$

where $\sigma(a) = a$

Output



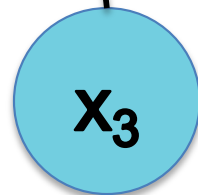
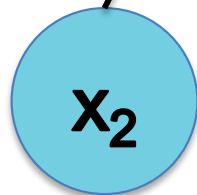
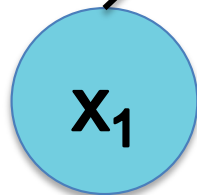
$$y = h_{\theta}(x) = \sigma(\theta^T x)$$

$$\text{where } \sigma(a) = \frac{1}{1 + \exp(-a)}$$

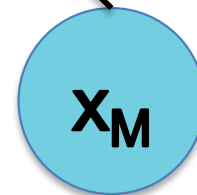
Output



Input



...

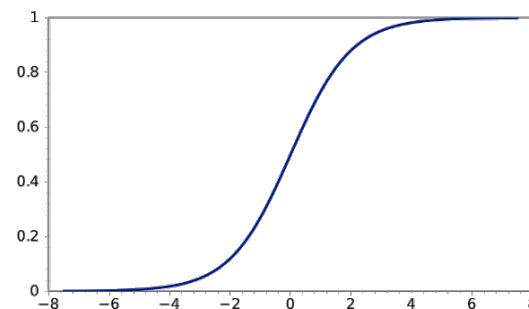


θ_1

θ_2

θ_3

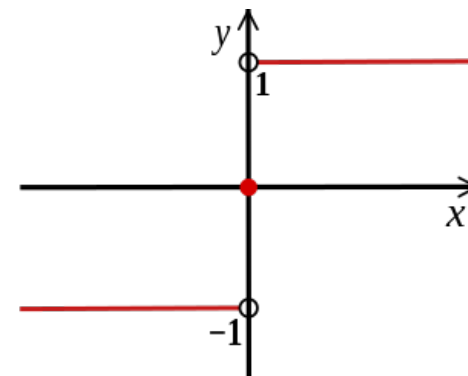
θ_M



$$y = h_{\theta}(\mathbf{x}) = \sigma(\theta^T \mathbf{x})$$

$$\text{where } \sigma(a) = \text{sign}(a)$$

Output



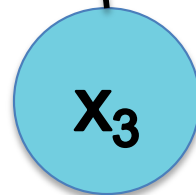
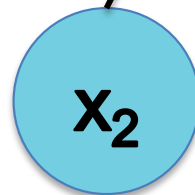
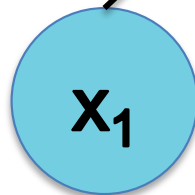
θ_1

θ_2

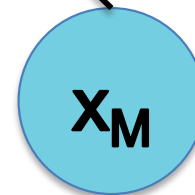
θ_3

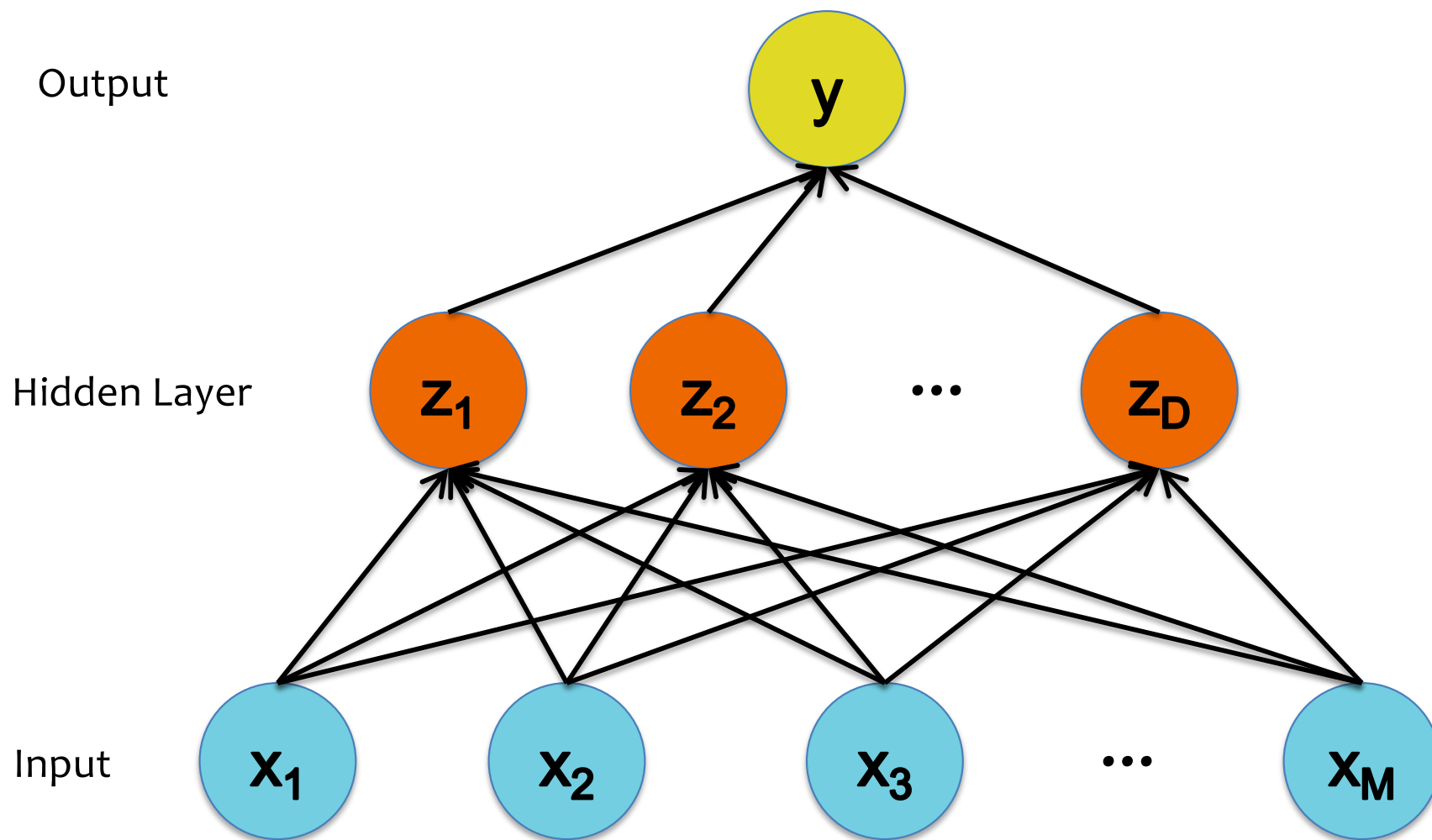
θ_M

Input



...

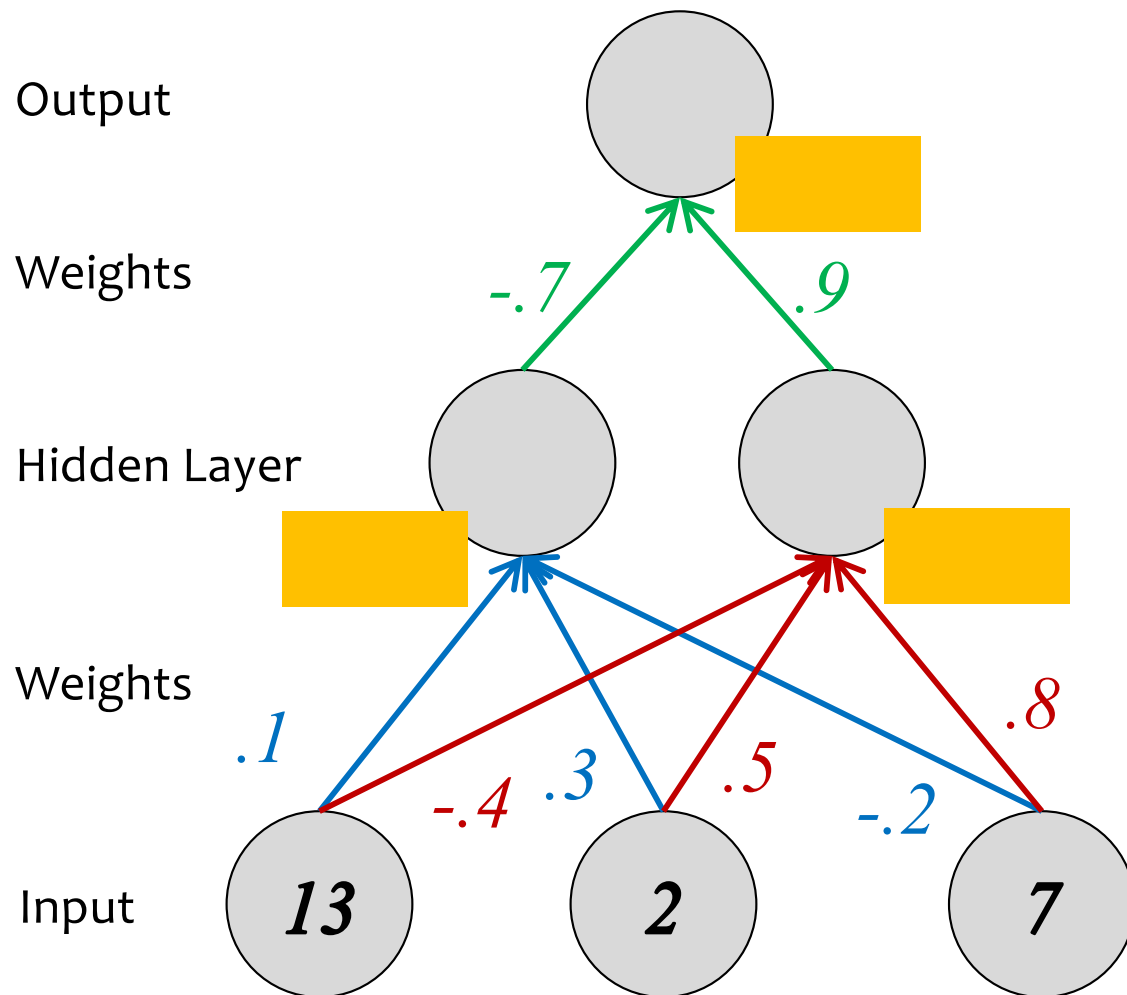




COMPONENTS OF A NEURAL NETWORK

Decision Functions

Neural Network

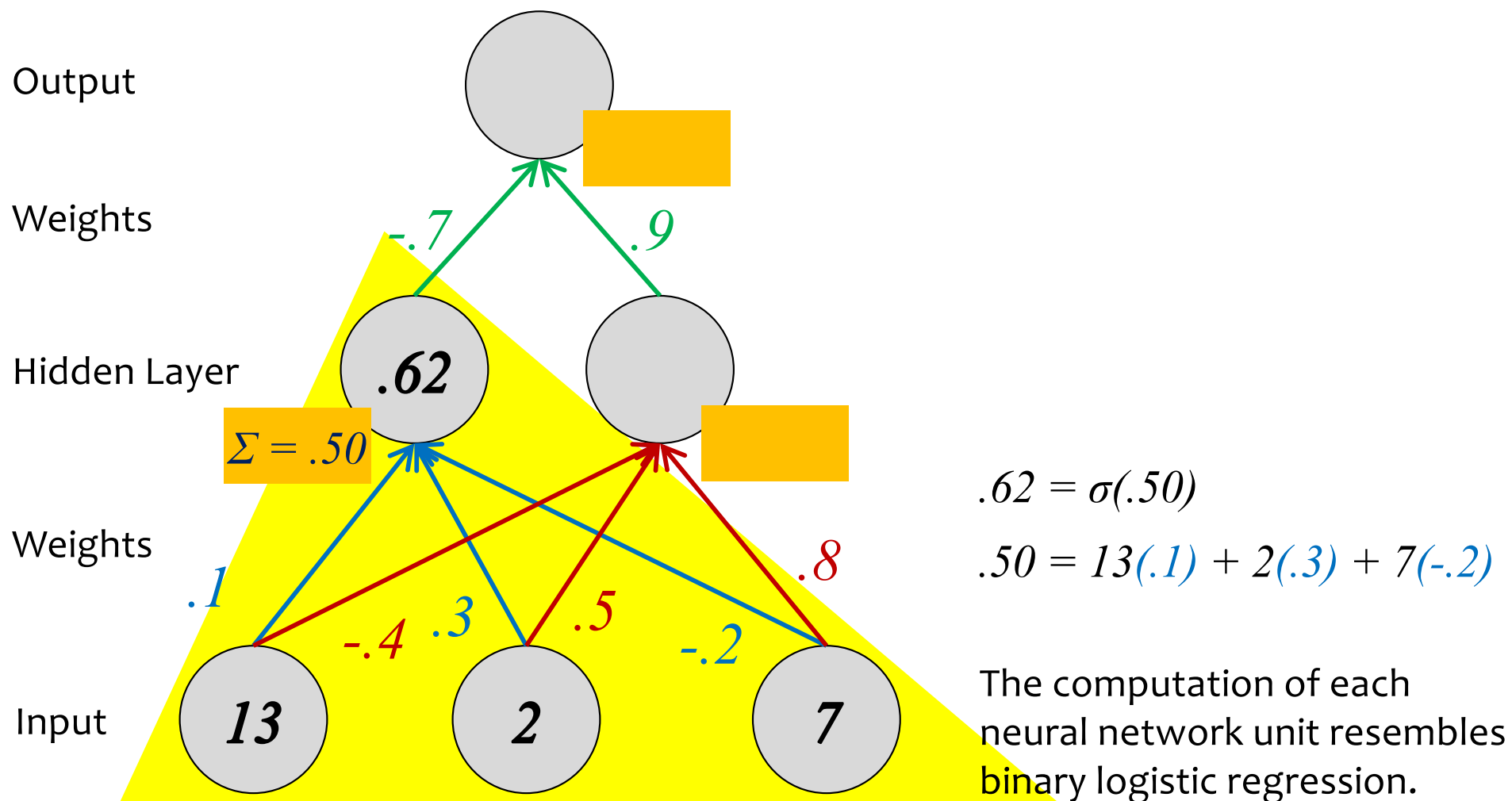


Suppose we already learned the weights of the neural network.

To make a new prediction, we take in some new features (aka. the input layer) and perform the feed-forward computation.

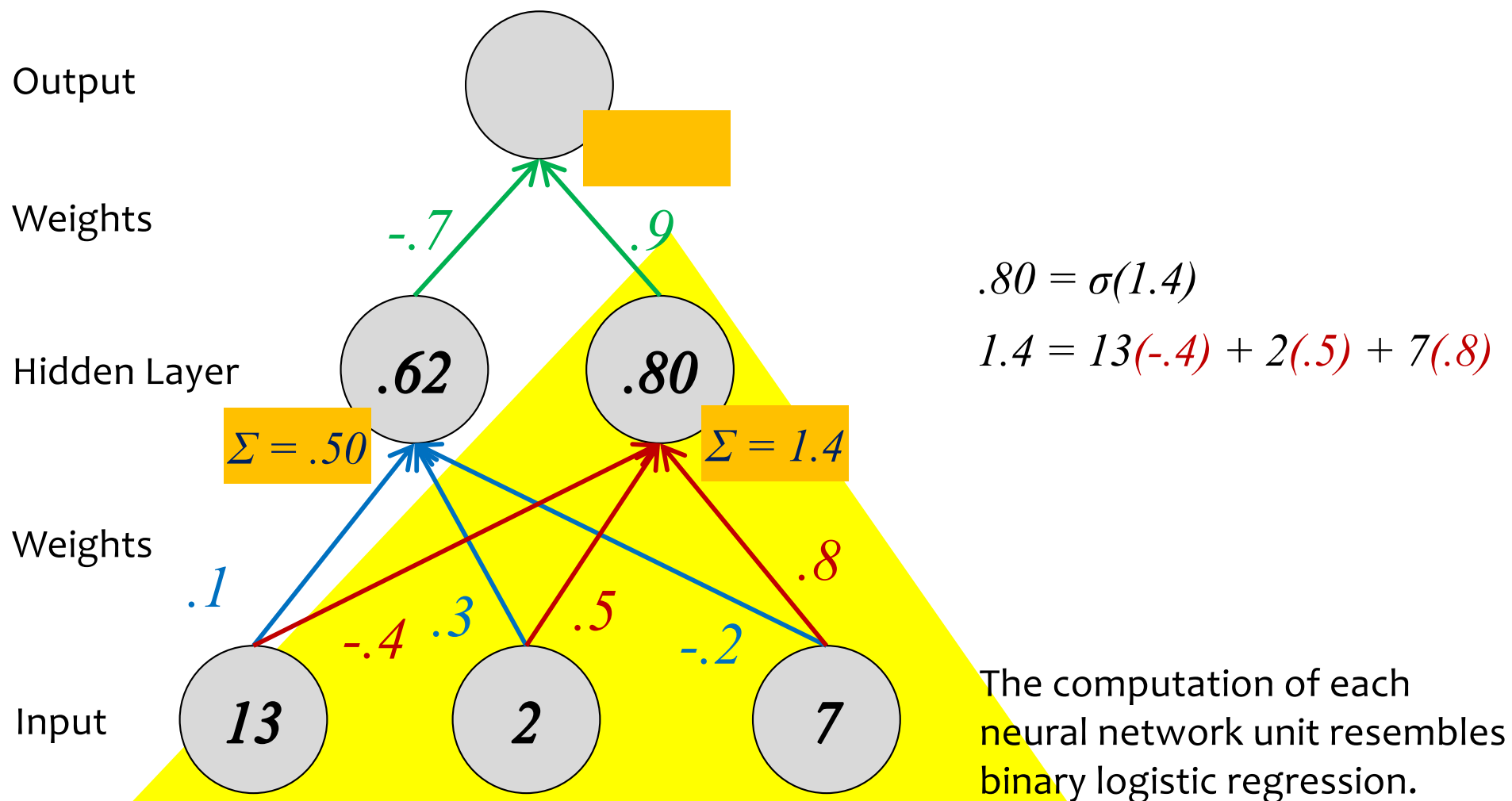
Decision Functions

Neural Network



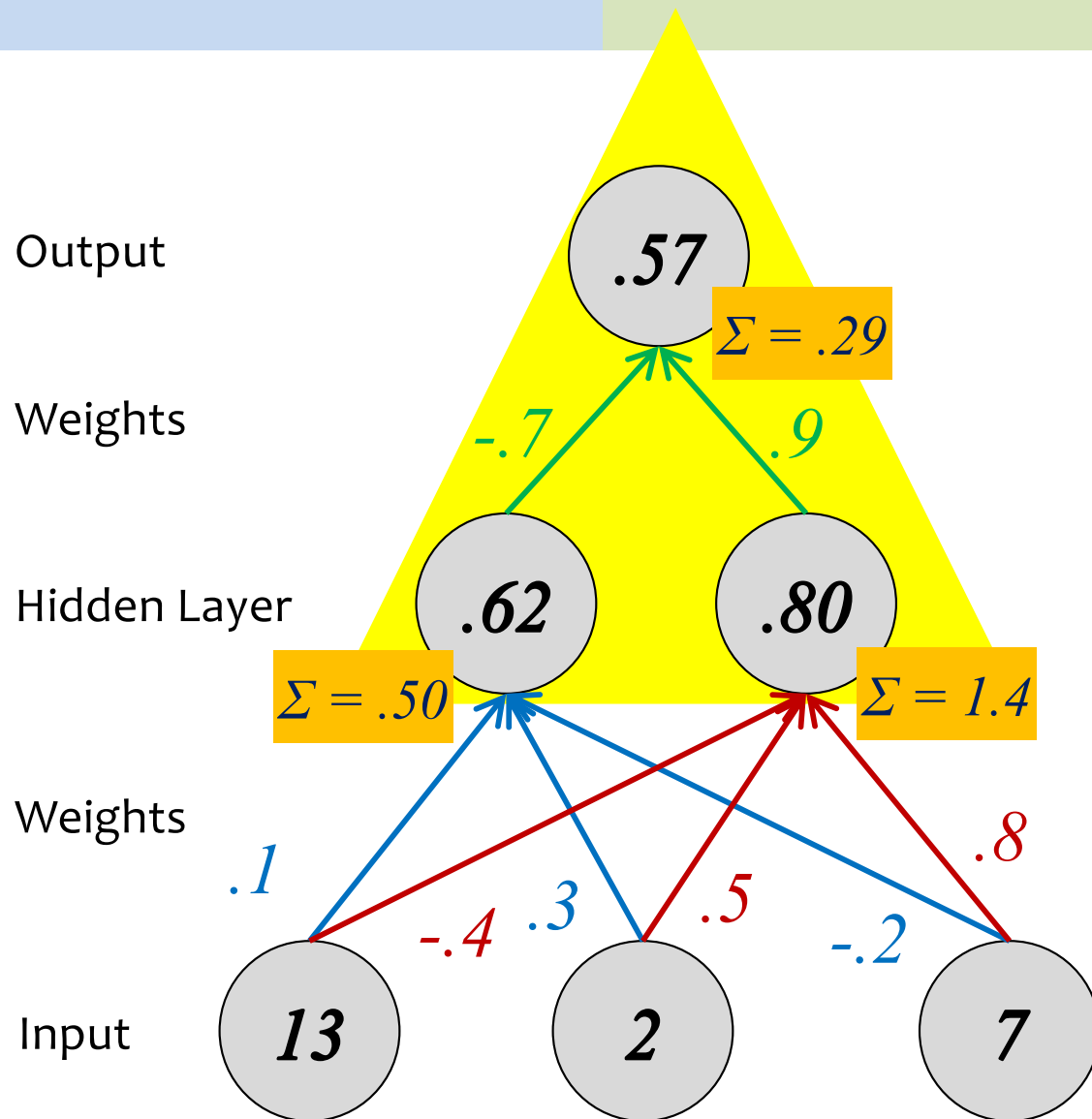
Decision Functions

Neural Network



Decision Functions

Neural Network



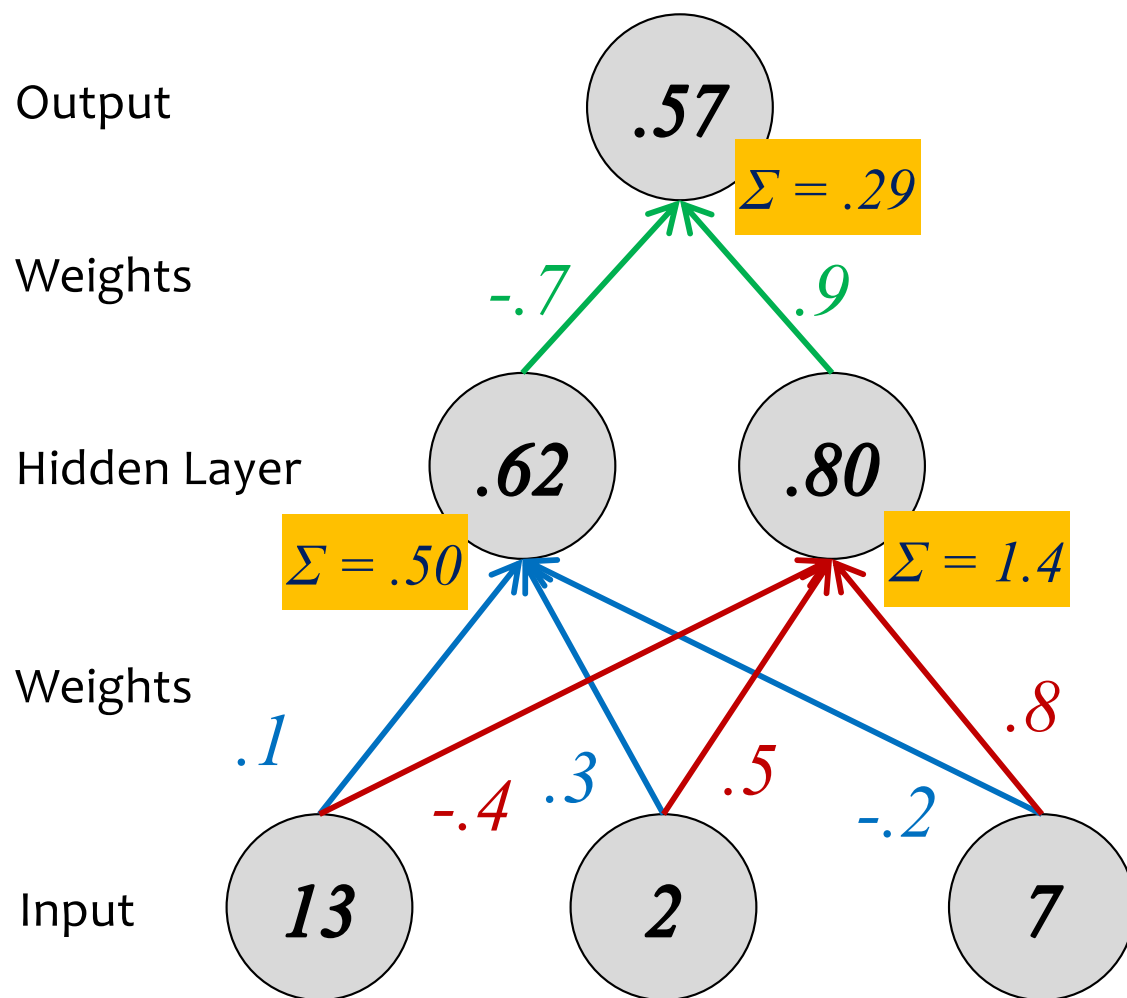
$$.57 = \sigma(.29)$$

$$.29 = .62(-.7) + .80(.9)$$

The computation of each neural network unit resembles binary logistic regression.

Decision Functions

Neural Network



$$.57 = \sigma(.29)$$

$$.29 = .62(-.7) + .80(.9)$$

$$.80 = \sigma(1.4)$$

$$1.4 = 13(-.4) + 2(.5) + 7(.8)$$

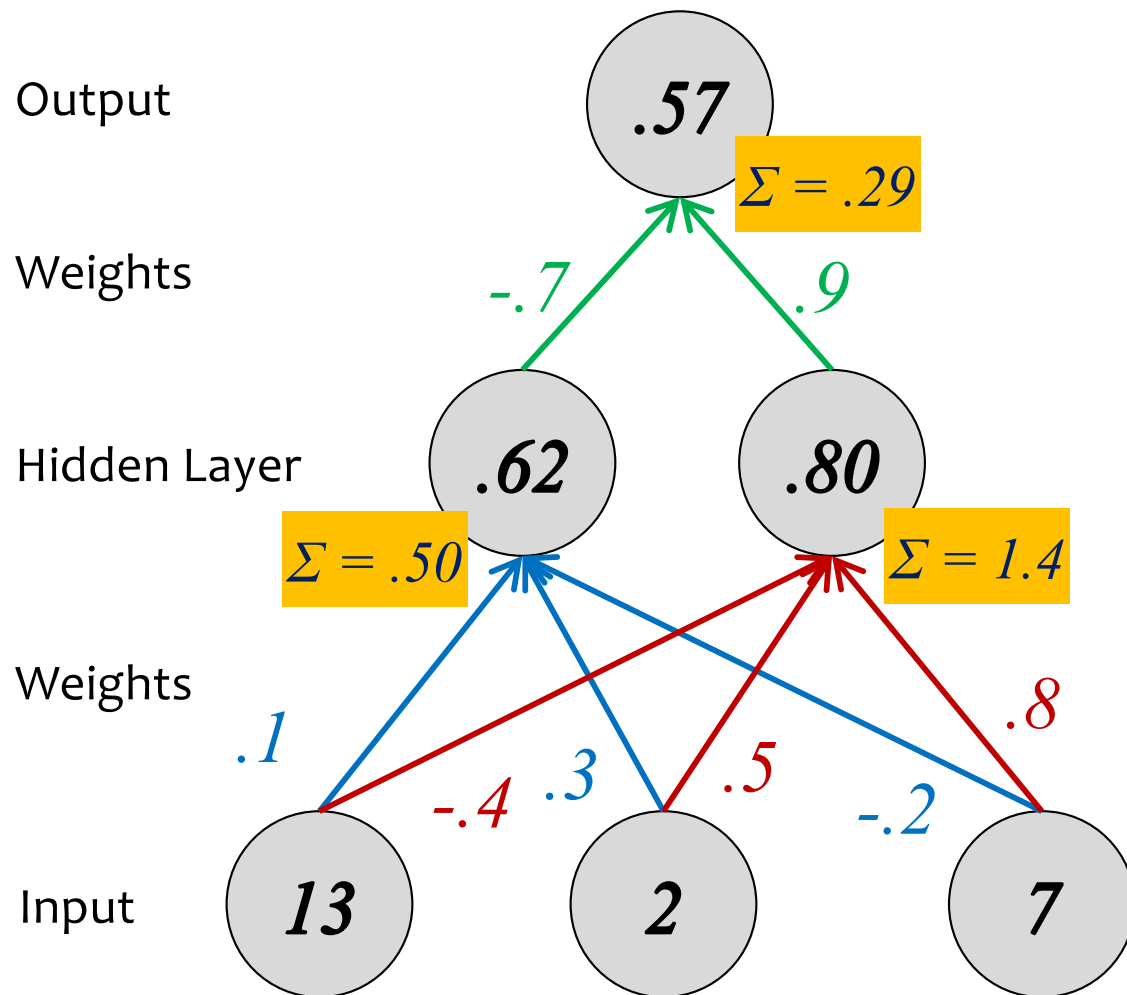
$$.62 = \sigma(.50)$$

$$.50 = 13(.1) + 2(.3) + 7(-.2)$$

The computation of each neural network unit resembles binary logistic regression.

Decision Functions

Neural Network



Except we only have the target value for y at training time!

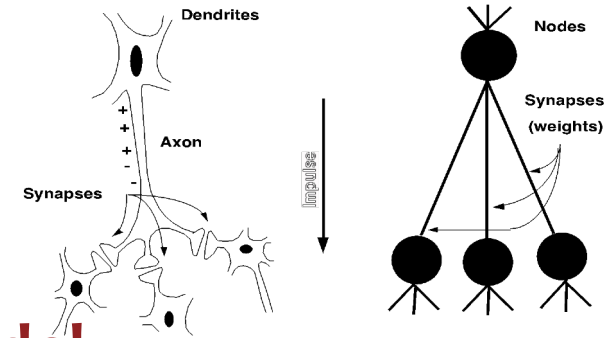
We have to learn to create “useful” values of z_1 and z_2 in the hidden layer.



The computation of each neural network unit resembles binary logistic regression.

From Biological to Artificial

The motivation for Artificial Neural Networks comes from biology...



Biological “Model”

- **Neuron:** an excitable cell
- **Synapse:** connection between neurons
- A neuron sends an **electrochemical pulse** along its synapses when a sufficient voltage change occurs
- **Biological Neural Network:** collection of neurons along some pathway through the brain

Biological “Computation”

- Neuron switching time : ~ 0.001 sec
- Number of neurons: $\sim 10^{10}$
- Connections per neuron: $\sim 10^{4-5}$
- Scene recognition time: ~ 0.1 sec

Artificial Model

- **Neuron:** node in a directed acyclic graph (DAG)
- **Weight:** multiplier on each edge
- **Activation Function:** nonlinear thresholding function, which allows a neuron to “fire” when the input value is sufficiently high
- **Artificial Neural Network:** collection of neurons into a DAG, which define some differentiable function

Artificial Computation

- Many neuron-like threshold switching units
- Many weighted interconnections among units
- Highly parallel, distributed processes

DEFINING A 1-HIDDEN LAYER NEURAL NETWORK

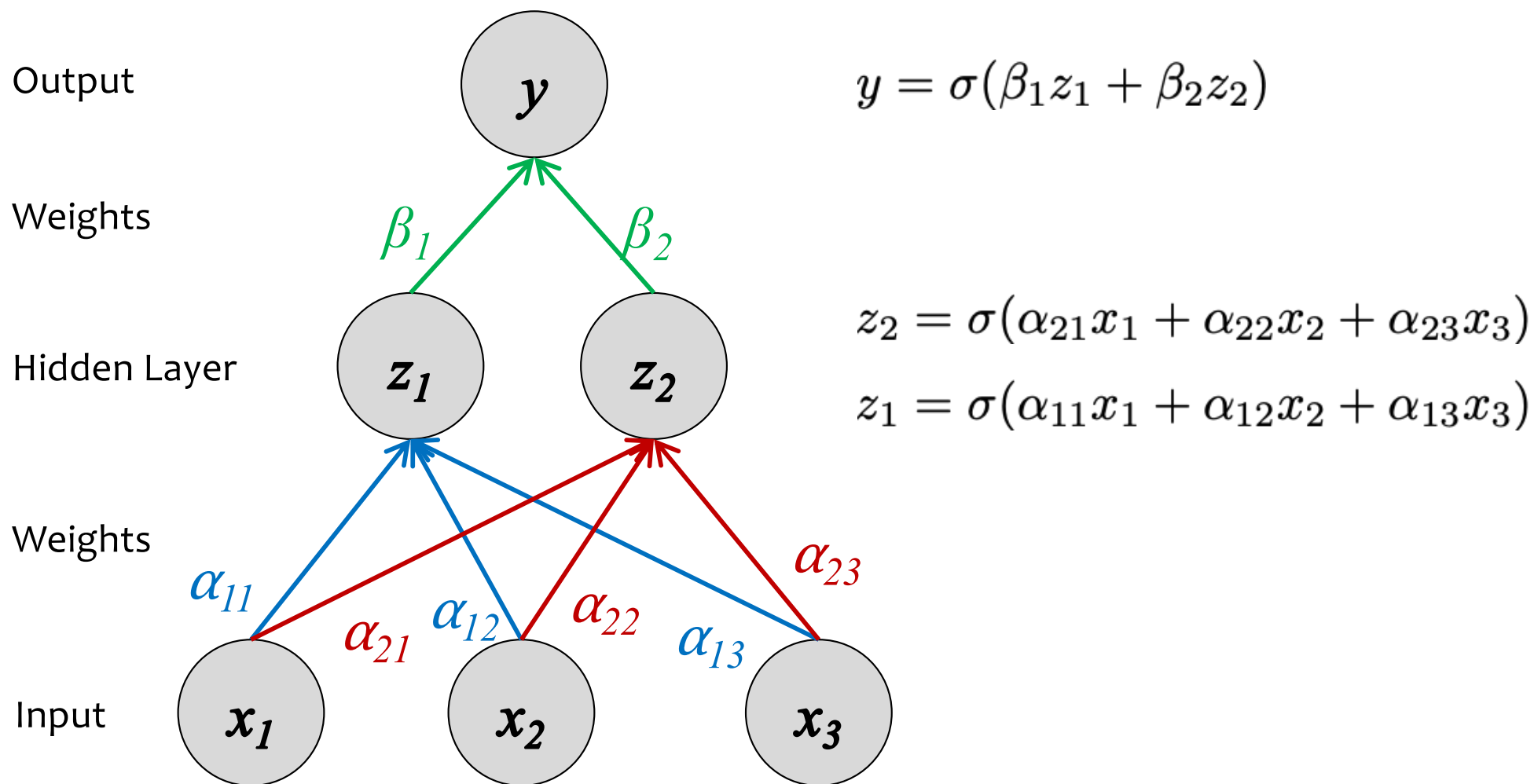
Neural Networks

Chalkboard

- Example: Neural Network w/1 Hidden Layer

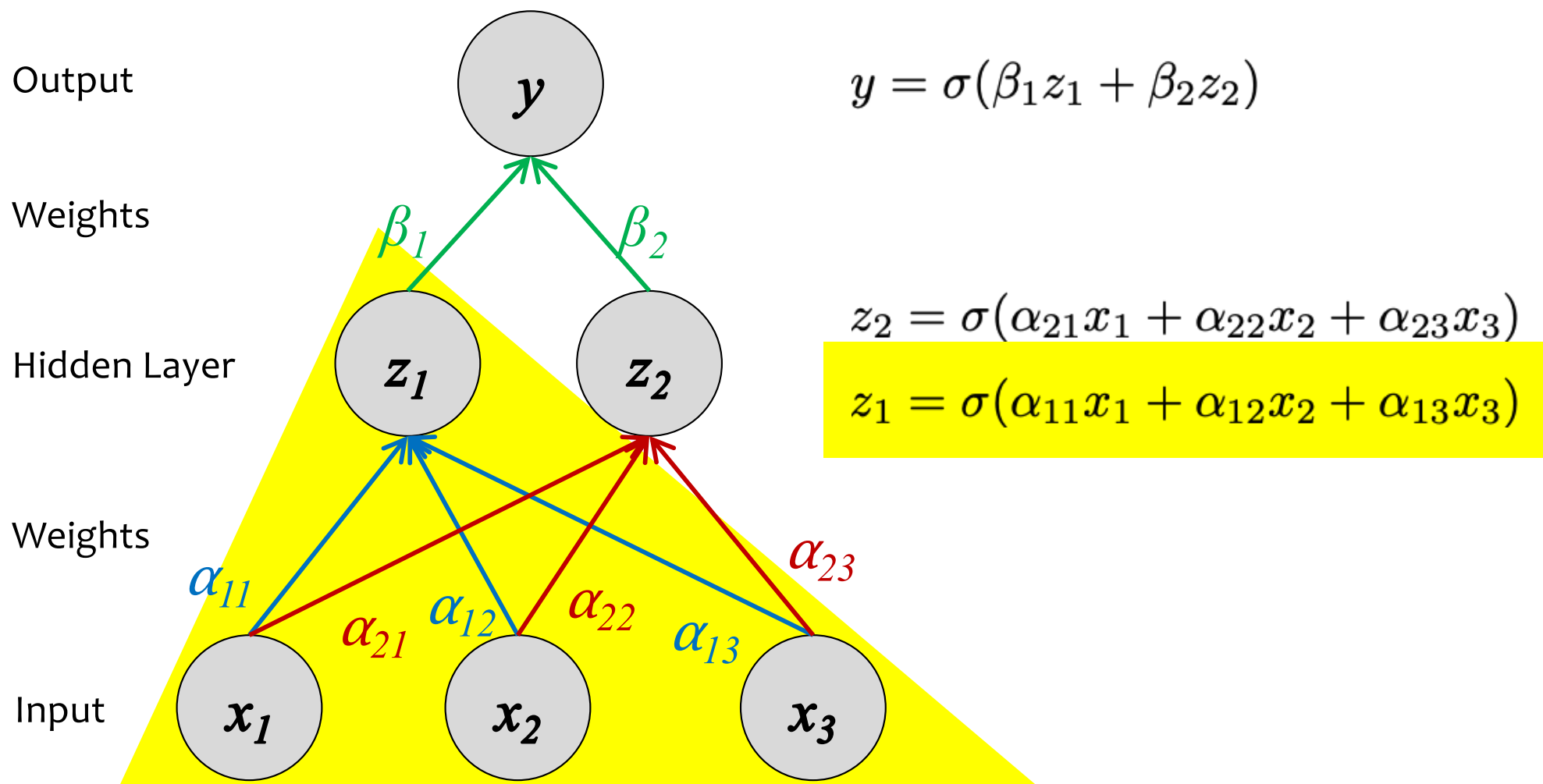
Decision Functions

Neural Network



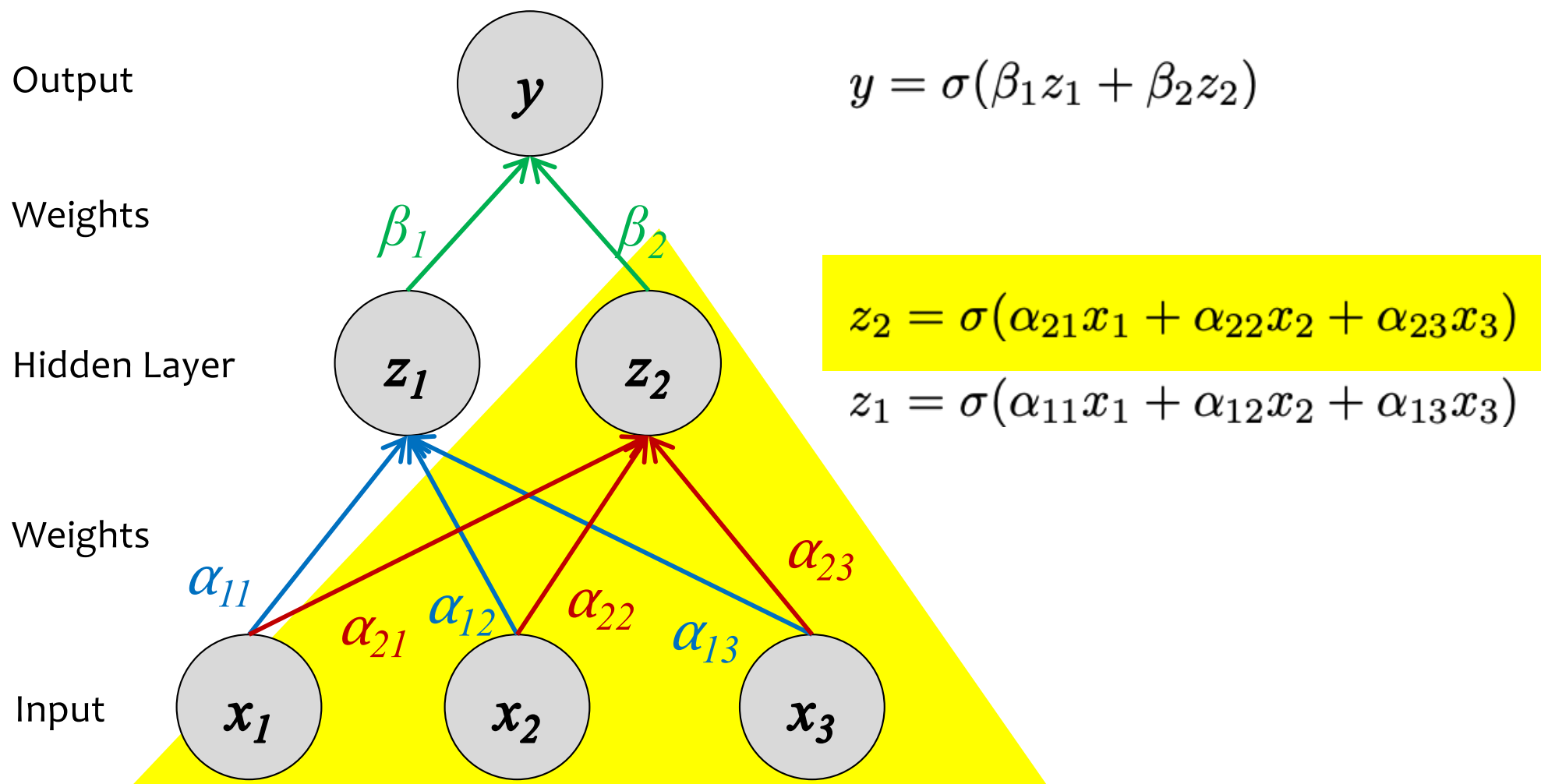
Decision Functions

Neural Network



Decision Functions

Neural Network



Decision Functions

Neural Network

Output

$$y = \sigma(\beta_1 z_1 + \beta_2 z_2)$$

Weights

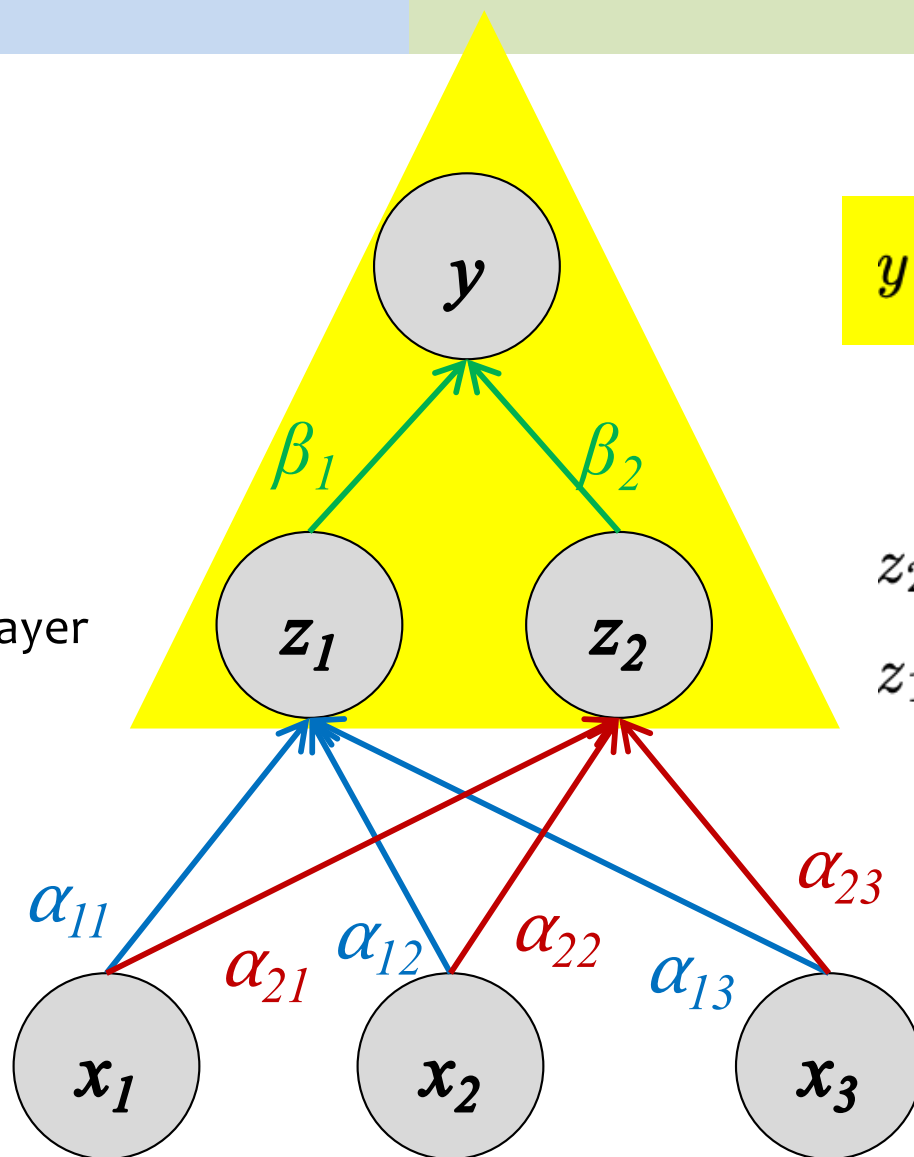
Hidden Layer

$$z_2 = \sigma(\alpha_{21}x_1 + \alpha_{22}x_2 + \alpha_{23}x_3)$$

$$z_1 = \sigma(\alpha_{11}x_1 + \alpha_{12}x_2 + \alpha_{13}x_3)$$

Weights

Input



Decision Functions

Neural Network

Output

$$y = \sigma(\beta_1 z_1 + \beta_2 z_2)$$

Weights

Hidden Layer

$$z_2 = \sigma(\alpha_{21}x_1 + \alpha_{22}x_2 + \alpha_{23}x_3)$$

$$z_1 = \sigma(\alpha_{11}x_1 + \alpha_{12}x_2 + \alpha_{13}x_3)$$

Weights

Input

The diagram illustrates a neural network structure with three layers: Input, Hidden Layer, and Output. The input layer consists of three nodes labeled x_1 , x_2 , and x_3 . The hidden layer consists of two nodes labeled z_1 and z_2 . The output layer consists of one node labeled y . Weights are labeled α for connections from input to hidden and β for connections from hidden to output. The connections are as follows: x_1 to z_1 (blue, α_{11}), x_1 to z_2 (red, α_{21}), x_2 to z_1 (blue, α_{12}), x_2 to z_2 (red, α_{22}), x_3 to z_1 (blue, α_{13}), and x_3 to z_2 (red, α_{23}). The hidden layer nodes z_1 and z_2 are connected to the output node y with weights β_1 and β_2 respectively. The entire hidden layer and output node are enclosed in a yellow triangle.

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NONLINEAR DECISION BOUNDARIES AND NEURAL NETWORKS

Decision Functions

Logistic Regression

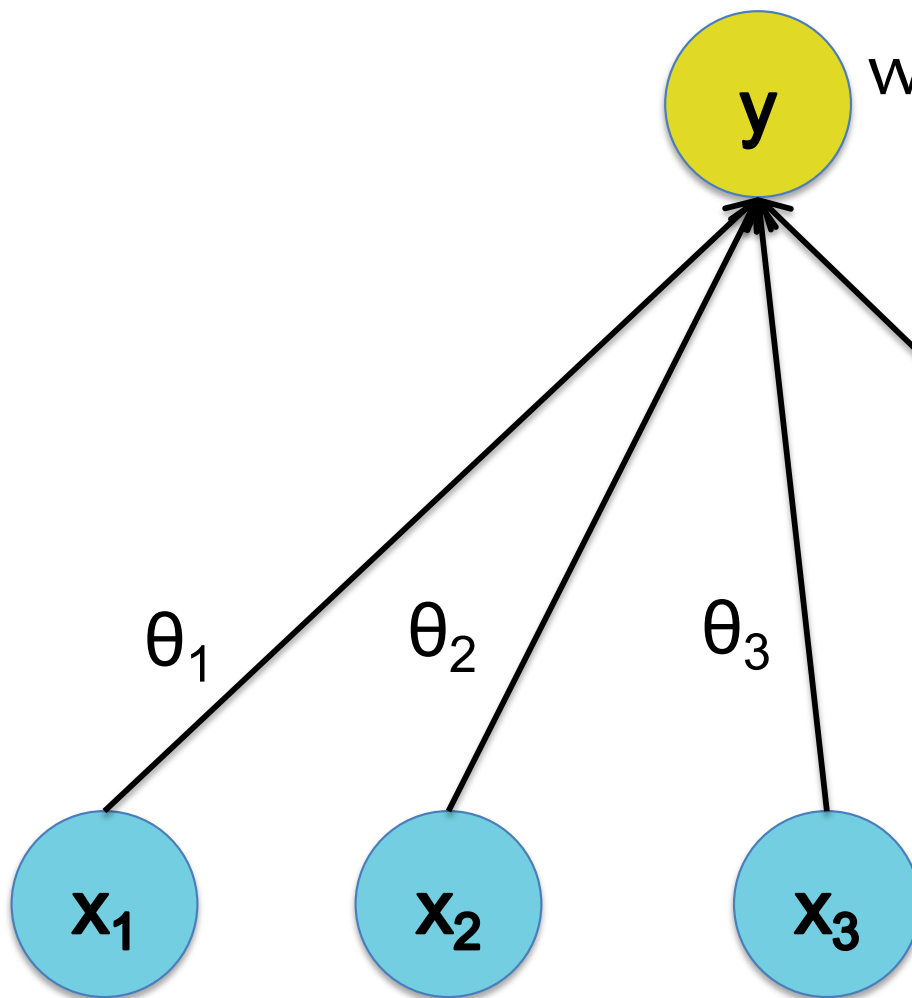
$$y = h_{\theta}(x) = \sigma(\theta^T x)$$

$$\text{where } \sigma(a) = \frac{1}{1 + \exp(-a)}$$

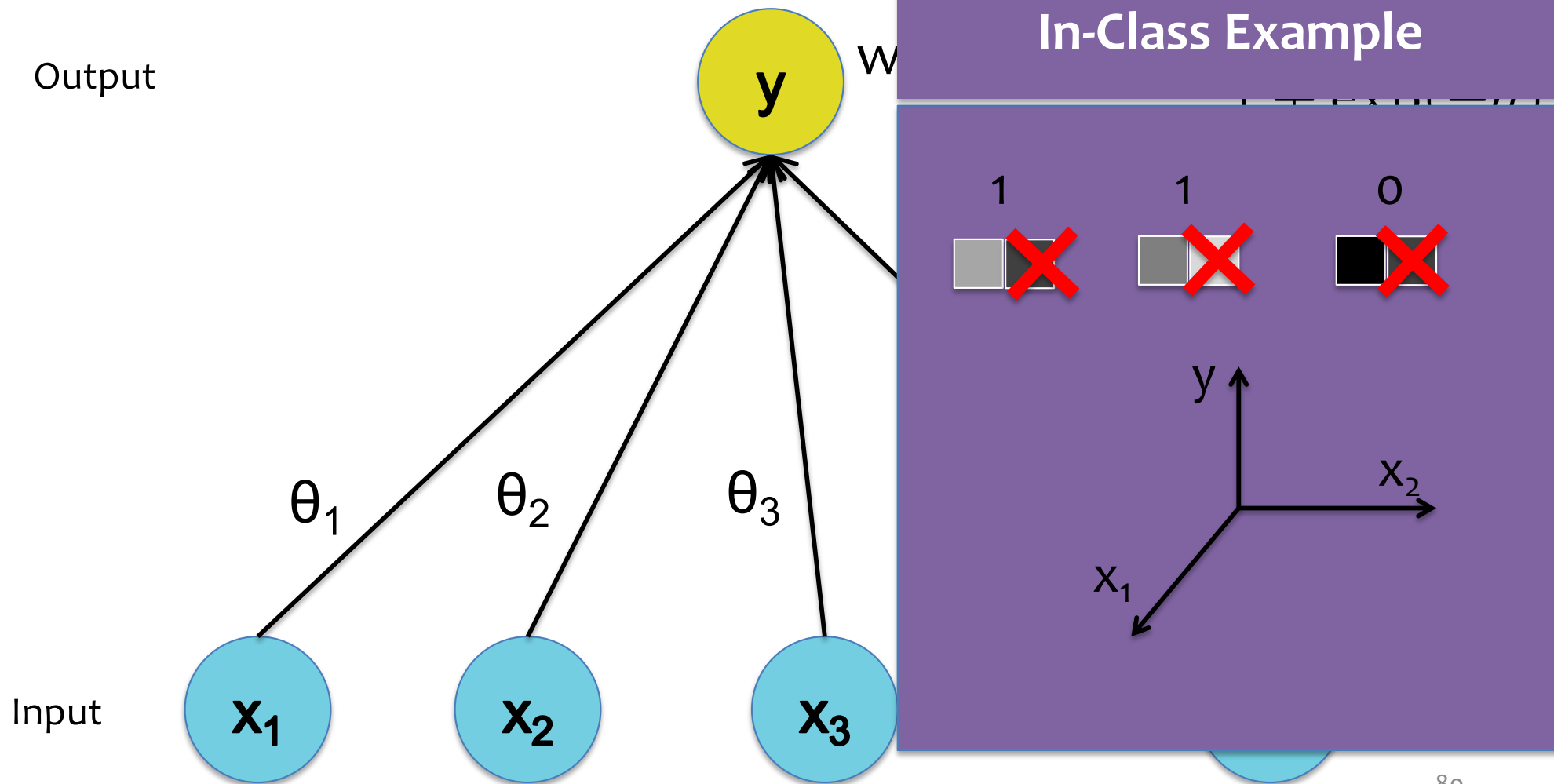
Output



Input



$$y = h_{\theta}(x) = \sigma(\theta^T x)$$



Neural Networks

Chalkboard

- 1D Example from linear regression to logistic regression
- 1D Example from logistic regression to a neural network

Decision Functions

Logistic Regression

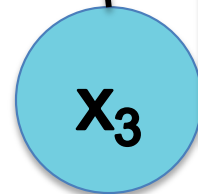
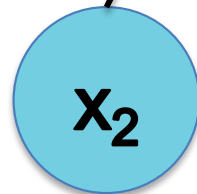
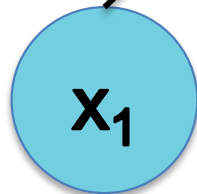
$$y = h_{\theta}(x) = \sigma(\theta^T x)$$

$$\text{where } \sigma(a) = \frac{1}{1 + \exp(-a)}$$

Output



Input



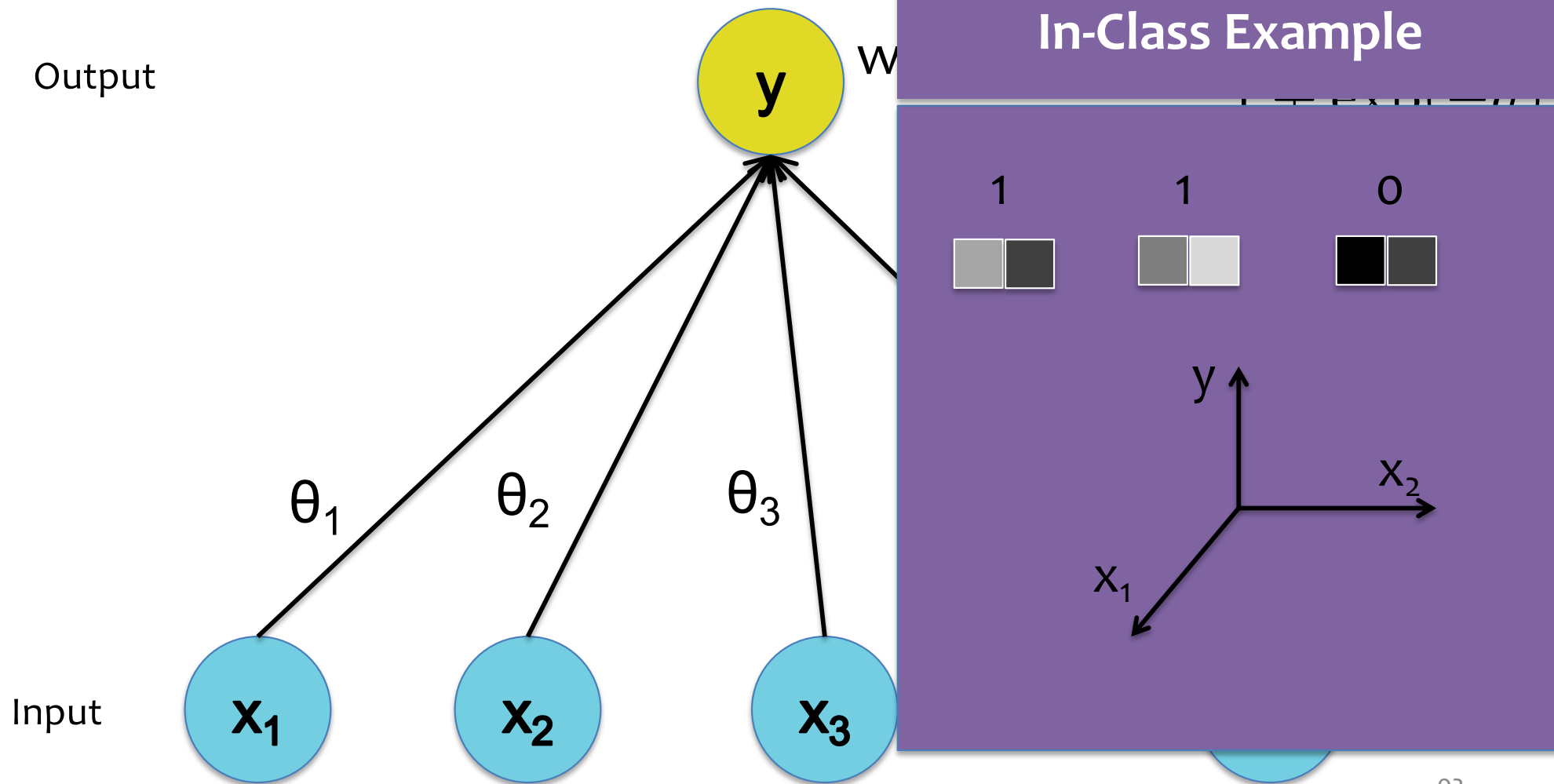
θ_1

θ_2

θ_3



$$y = h_{\theta}(x) = \sigma(\theta^T x)$$



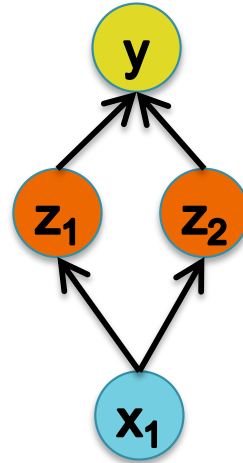
Neural Network Parameters

Question:

Suppose you are training a one-hidden layer neural network with sigmoid activations for binary classification.



True or False: There is a unique set of parameters that maximize the likelihood of the dataset above.



Answer: