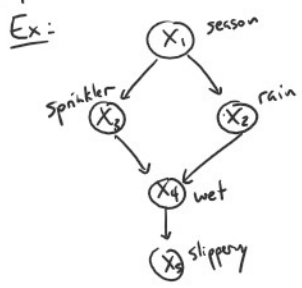


Causal Bayesian Networks

Bayes Net

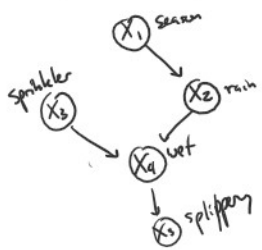


$$\begin{aligned}
 p(x_4 | x_3 = 0N) &\propto \sum_{x_1} \sum_{x_2} \sum_{x_5} p(x_1, \dots, x_5) \\
 &= \sum_{x_1} \sum_{x_2} p(x_4 | x_3 = 0N, x_2) \\
 &\quad p(x_3 = 0N | x_1) \\
 &\quad p(x_2 | x_1) \\
 &\quad p(x_1)
 \end{aligned}$$

depend on the season

Causal Bayes Net

- Ex: • Suppose we intervene by turning on the sprinkler denoted by, $do(x_2 = 0N)$
 • Remove dependence of x_3 on x_1



$$\begin{aligned}
 p(x_4 | do(x_2 = 0N)) &\propto \sum_{x_1} \sum_{x_2} \sum_{x_5} p(x_1) p(x_2 | x_1) p(x_4 | x_2, x_3 = 0N) p(x_5 | x_4) \\
 &= \sum_{x_1} \sum_{x_2} p(x_3 | x_2, do(x_3 = 0N)) \\
 &\quad p(x_2 | x_1) \\
 &\quad p(x_1)
 \end{aligned}$$

notably absent $p(x_3)$ or $p(x_3 | x_1)$

Structural Causal Model

Ex#1: Linear SCM (structural equations model)

path diagram	equations	unobserved vars.
	$X = U_x$	
	$Y = \beta X + U_y$	observed vars

Legend: X = severity of disease (smartphone use)
 Y = severity of symptom (depression)
 U_x, U_y = all other factors (noise/error)
 $\beta \in \mathbb{R}$ = quantifies causal effect of X on Y

Model: • Nature examines values of X and U_y and assigns var Y the value $Y = \beta X + U_y$
 • Process is not invertible (not true that $X = (Y - U_y) / \beta$)
 • Causal assumptions:
 ↳ not encoded in links in path diagram

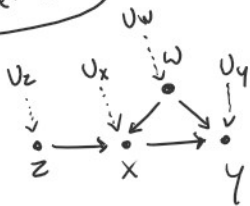
- Causal assumptions:
 - ↳ not encoded in links in path diagram
 - ↳ encoded in the absence of a link
 - no direct arrow \Rightarrow claim zero influence
 - direct arrow \Rightarrow could be a causal effect

Inference: Given (a) certain conditions (e.g. $\text{cov}(U_x, U_y) = 0$)
 (b) trust in causal assumptions of model

one can infer magnitude β of causal effects from observed non-experimental data

Ex#2: Nonlinear SCM

Model M

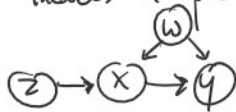


$$\begin{aligned} w &= f_w(U_w) \\ z &= f_z(U_z) \\ x &= f_x(z, w, U_x) \\ y &= f_y(x, w, U_y) \end{aligned}$$

claim of model: changes in z will leave y unchanged given x, w, U_y

PGM

• Model M induces a pre-intervention distribution $p_M(w, x, y, z) = p(z)p(w)p(x|z, w)p(y|x, w)$



• We learn $p(v|\text{parents}(v)) \forall v \in \{w, x, y, z\}$ from observational data alone

Model M_x

Intervention: