

At the end of the Algorithm (CAVI):

Use $q_{\hat{\theta}}(\vec{z}) = \prod_{t=1}^T q_t(z_t; \hat{\theta})$ as approximation to $p_{\alpha}(\vec{z}|\vec{x})$

Three cases to consider:

① variable marginals: $q_t(z_t; \hat{\theta}) \approx p_{\alpha}(z_t|\vec{x}) = \sum_{\vec{z}_{-t}} p_{\alpha}(z_t, \vec{z}_{-t}|\vec{x})$

② two-variable marginal:

$$q(z_t, z_s; \hat{\theta}) = \underline{q(z_t; \hat{\theta}) q(z_s; \hat{\theta})} \approx p_{\alpha}(z_t, z_s|\vec{x})$$

Q1 in L17 poll

③ three-variable marginal:

$$q(z_t, z_s, z_r) = q(z_t) q(z_s) q(z_r)$$

Why? * thanks to our M.F. assumption

$$\begin{aligned} q(z_1, z_2) &= \sum_{z_3} \sum_{z_4} \dots \sum_{z_T} q(z_1, z_2, \dots, z_T) \\ &= \sum_{z_3} \dots \sum_{z_T} \prod_{t=1}^T q_t(z_t) \quad \xrightarrow{\text{red arrows}} \quad q_1(z_1) q_2(z_2) \dots q_T(z_T) \\ &= q_1(z_1) q_2(z_2) \underbrace{\sum_{z_3} q_3(z_3)}_1 \underbrace{\sum_{z_4} q_4(z_4)}_1 \dots \underbrace{\sum_{z_T} q_T(z_T)}_1 \\ &= q_1(z_1) q_2(z_2) \end{aligned}$$

CAVI Update Rule

Suppose we are given a factor graph over discrete random variables, $p_{\alpha}(z|\vec{x})$

$$\Rightarrow \text{full conditionals: } p_{\alpha}(z_t | \vec{z}_{-t}, \vec{x}) \propto \prod_{c \in N(z_t)} \psi_c(\vec{z}_c)$$

$\Rightarrow$ full conditionals are categorical distributions

Case #1: Exponential Family

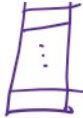
$\hookrightarrow$ not covered today...

Case #2: Multinomial

• z_t is discrete and finite valued

• suppose $p(z_t | \vec{z}_{-t}, \vec{x}) \triangleq \pi(z_t | \vec{z}_{-t}, \vec{x}) =$

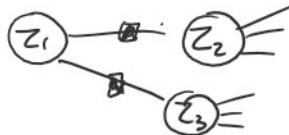
$$\pi(\cdot | \vec{z}_{-t}, \vec{x})$$


- z_t is discrete and finite valued
- suppose $p(z_t | \vec{z}_{-t}, \vec{x}) \triangleq \pi(z_t | \vec{z}_{-t}, \vec{x}) =$ 
- then the CAVI updates are

$$\begin{aligned}
 q_t(z_t) &= \frac{1}{Z} \exp\left(E_{q_{-t}}[\log p(z_t | \vec{z}_{-t}, \vec{x})]\right) \quad \text{normalizing constant for } q_t \\
 &= \frac{1}{Z} \exp\left(E_{q_{-t}}[\log \pi(z_t | \vec{z}_{-t}, \vec{x})]\right) \\
 &= \frac{1}{Z} \exp\left(\sum_{\vec{z}_{-t}} q(\vec{z}_{-t}) \log \pi(z_t | \vec{z}_{-t}, \vec{x})\right) \quad \prod_{s:t \neq s} q_s(z_s) \\
 \text{for a factor graph} \quad &= \frac{1}{Z} \exp\left(C + \sum_{\vec{z}_{MB(z_t)}} \prod_{s \in MB(z_t)} q_s(z_s) \log \left[\prod_{c \in N(z_t)} \psi_c(\vec{z}_c) \right]\right) \\
 &= \frac{1}{Z} \exp\left(\sum_{\vec{z}_{MB(z_t)}} \prod_{s \in MB(z_t)} q_s(z_s) \sum_{c \in N(z_t)} \log \psi_c(\vec{z}_c)\right) \\
 &\quad \text{easy to compute assuming \#neighbors is not too large} \\
 &\quad \text{where is } C? \\
 &\quad \frac{1}{Z} \exp(a+b) = \frac{\exp(a)\exp(b)}{Z} = \frac{\exp(b)}{Z'} \\
 &= \frac{1}{Z} \exp\left(\sum_{\vec{z}_{MB(z_t)}} \sum_{c \in N(z_t)} \log \psi_c(\vec{z}_c) \prod_{s \in MB(z_t)} q_s(z_s)\right)
 \end{aligned}$$

Pairwise MRF Update Rule

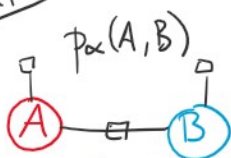
example from slide...



$$\begin{aligned}
 q_1(z_1) &\propto \exp\left(\sum_{z_2} \sum_{z_3} q_2(z_2) q_3(z_3) \log \psi_{12}(z_1, z_2) \log \psi_{13}(z_1, z_3)\right) \\
 &= \left(\sum_{z_2} q_2(z_2) \log \psi_{12}(z_1, z_2)\right) \left(\sum_{z_3} q_3(z_3) \log \psi_{13}(z_1, z_3)\right) \\
 &= \mu_{2 \rightarrow 1}(z_1) \mu_{3 \rightarrow 1}(z_1)
 \end{aligned}$$

Ex: Two Variable Factor Graph

Joint:

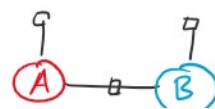


M.F. Approx

$$q_{\theta}(A, B) = q_{\theta_A}(A) q_{\theta_B}(B)$$



Gibbs Sampler



one-hot representation

