

10-418/10-618 Machine Learning for Structured Data



Machine Learning Department School of Computer Science Carnegie Mellon University

Coordinate Ascent Variational Inference

Matt Gormley Lecture 17 Nov. 2, 2022

Reminders

- Lecture on Friday, Recitation on Monday
- Exam Rubrics and Exam Viewings
- Homework 4: MCMC
 - Out: Mon, Oct 24
- Homework 5: Variational Inference
 - Out: Fri, Nov §
 - Due: Wed, Nov 16 at 11:59pm

MEAN FIELD WITH GRADIENT ASCENT

- 1. Goal: estimate $p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ we assume this is intractable to compute exactly
- 2. <u>Idea</u>: approximate with another distribution $q_{\theta}(\mathbf{z}) \approx p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ for each \mathbf{x}
- 3. <u>Mean Field</u>: assume $q_{\theta}(\mathbf{z}) = \prod_{t} q_{t}(z_{t}; \theta)$ i.e., we decompose over variables other choices for the decomposition of $q_{\theta}(\mathbf{z})$ give rise to "structured mean field"
- 4. Optimization Problem: pick the q that minimizes KL(q || p)

$$\begin{split} \hat{q}(\mathbf{z}) &= \operatorname*{argmin}_{q(\mathbf{z}) \in \mathcal{Q}} \mathsf{KL}(q(\mathbf{z}) || p(\mathbf{z} \mid \mathbf{x})) \\ \hat{\theta} &= \operatorname*{argmin}_{\theta \in \Theta} \mathsf{KL}(q_{\theta}(\mathbf{z}) || p_{\alpha}(\mathbf{z} \mid \mathbf{x})) \end{split} \quad \text{equivalent}$$

5. Optimization Algorithm: pick your favorite {coordinate descent, gradient descent, etc.}

- 1. Goal: estimate $p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ we assume this is intractable to compute exactly
- 2. <u>Idea</u>: approximate with another distribution $q_{\theta}(\mathbf{z}) \approx p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ for each \mathbf{x}
- 3. <u>Mean Field</u>: assume $q_{\theta}(\mathbf{z}) = \prod_{t} q_{t}(z_{t}; \theta)$ i.e., we decompose over variables other choices for the decomposition of $q_{\theta}(\mathbf{z})$ give rise to "structured mean field"
- 4. Optimization Problem: pick the q that minimizes KL(q || p)

$$\begin{split} \hat{\theta} &= \operatorname*{argmin}_{\theta} \mathsf{KL}(q_{\theta}(\mathbf{z}) \parallel p_{\alpha}(\mathbf{z} \mid \mathbf{x})) = \operatorname*{argmax}_{\theta} \mathsf{ELBO}(q_{\theta}) \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log p_{\alpha}(\mathbf{x}, \mathbf{z}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log \tilde{p}_{\alpha}(\mathbf{z} \mid \mathbf{x}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \end{split}$$

5. Optimization Algorithm: pick your favorite {coordinate ascent, gradient ascent, etc.}

- 1. Goal: estimate $p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ we assume this is intractable to compute exactly
- 2. <u>Idea</u>: approximate with another distribution $q_{\theta}(\mathbf{z}) \approx p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ for each \mathbf{x}
- 3. <u>Mean Field</u>: assume $q_{\theta}(\mathbf{z}) = \prod_{t} q_{t}(z_{t}; \theta)$ i.e., we decompose over variables other choices for the decomposition of $q_{\theta}(\mathbf{z})$ give rise to "structured mean field"
- 4. Optimization Problem: pick the q that minimizes KL(q || p)

$$\begin{split} \hat{\theta} &= \operatorname*{argmin}_{\theta} \mathsf{KL}(q_{\theta}(\mathbf{z}) \parallel p_{\alpha}(\mathbf{z} \mid \mathbf{x})) = \operatorname*{argmax}_{\theta} \mathsf{ELBO}(q_{\theta}) \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log p_{\alpha}(\mathbf{x}, \mathbf{z}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log \tilde{p}_{\alpha}(\mathbf{z} \mid \mathbf{x}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \end{split}$$

5. Optimization Algorithm: gradient ascent

Mean Field w/Gradient Ascent

- Note: GA does local maximization, but ELBO is generally non-convex
- Algorithm:
 - Initialize θ
 - while not converged:

$$\theta \leftarrow \theta + \gamma \nabla_{\theta} \mathsf{ELBO}(q_{\theta})$$

Gradient of ELBO:

$$\begin{split} \nabla_{\theta} \mathsf{ELBO}(q_{\theta}) &= \nabla_{\theta} \mathbb{E}_{q_{\theta}} [\log p_{\alpha}(x,z)] - \nabla_{\theta} \mathbb{E}_{q_{\theta}} [\log q_{\theta}(z)] \\ &= \cdots \\ &= \cdots \\ &= \mathsf{easy} \; \mathsf{b/c} \; \mathsf{of} \; \mathsf{a} \; \mathsf{simple} \; q_{\theta} \end{split}$$

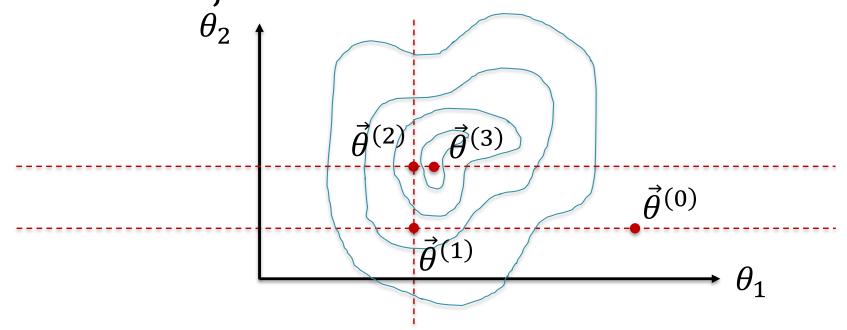
BACKGROUND: BLOCK COORDINATE DESCENT

Coordinate Descent

Goal: minimize some objective

$$\vec{\theta}^* = \underset{\vec{\theta}}{\operatorname{argmin}} J(\vec{\theta})$$

• Idea: iteratively pick one variable and minimize the objective w.r.t. just that one variable, keeping all the others fixed.



Block Coordinate Descent

Goal: minimize some objective (with 2 blocks)

$$\vec{\alpha}^*, \vec{\beta}^* = \underset{\vec{\alpha}, \vec{\beta}}{\operatorname{argmin}} J(\vec{\alpha}, \vec{\beta})$$

• Idea: iteratively pick one *block* of variables ($\vec{\alpha}$ or $\vec{\beta}$) and minimize the objective w.r.t. that block, keeping the other(s) fixed.

while not converged:

$$\vec{\alpha} = \underset{\vec{\alpha}}{\operatorname{argmin}} J(\vec{\alpha}, \vec{\beta})$$

$$\vec{\beta} = \underset{\vec{\beta}}{\operatorname{argmin}} J(\vec{\alpha}, \vec{\beta})$$

Block Coordinate Descent

Goal: minimize some objective (with T blocks)

$$\boldsymbol{\alpha}_1, \dots, \boldsymbol{\alpha}_T = \operatorname*{argmin} \cdots \operatorname*{argmin} J(\boldsymbol{\alpha}_1, \dots, \boldsymbol{\alpha}_T)$$

• Idea: iteratively pick one *block* of variables (e.g. the vector α_t) and minimize the objective w.r.t. that block, keeping the other(s) fixed.

while not converged:

for
$$t = 1, ..., T$$
:
$$\boldsymbol{\alpha}_t = \operatorname*{argmin}_{\boldsymbol{\alpha}_t} J(\boldsymbol{\alpha}_1, ..., \boldsymbol{\alpha}_T)$$

COORDINATE ASCENT VARIATIONAL INFERENCE (CAVI)

- 1. Goal: estimate $p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ we assume this is intractable to compute exactly
- 2. <u>Idea</u>: approximate with another distribution $q_{\theta}(\mathbf{z}) \approx p_{\alpha}(\mathbf{z} \mid \mathbf{x})$ for each \mathbf{x}
- 3. <u>Mean Field</u>: assume $q_{\theta}(\mathbf{z}) = \prod_{t} q_{t}(z_{t}; \theta)$ i.e., we decompose over variables other choices for the decomposition of $q_{\theta}(\mathbf{z})$ give rise to "structured mean field"
- 4. Optimization Problem: pick the q that minimizes KL(q || p)

$$\begin{split} \hat{\theta} &= \operatorname*{argmin}_{\theta} \mathsf{KL}(q_{\theta}(\mathbf{z}) \parallel p_{\alpha}(\mathbf{z} \mid \mathbf{x})) = \operatorname*{argmax}_{\theta} \mathsf{ELBO}(q_{\theta}) \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log p_{\alpha}(\mathbf{x}, \mathbf{z}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \\ &= \mathsf{ELBO}(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[\log \tilde{p}_{\alpha}(\mathbf{z} \mid \mathbf{x}) \right] - E_{q_{\theta}(\mathbf{z})} \left[\log q_{\theta}(\mathbf{z}) \right] \end{split}$$

5. Optimization Algorithm: coordinate ascent i.e. pick the best $q_t(z_t)$ based on the other $\{q_s(z_s)\}_{s\neq t}$ being fixed



Choosing coordinate descent here yields the Coordinate Ascent Variational Inference (CAVI) algorithm

CAVI Algorithm

Coordinate Ascent Variational Inference (CAVI)

- here we assume a mean field approximation
- application of coordinate ascent to maximization of ELBO
- converges to a local optimum of the nonconvex ELBO objective

```
1: procedure CAVI(p_{\alpha})
           Let q_{\theta}(\mathbf{z}) = \prod_{t=1}^{T} q_{t}(z_{t})
                                                                                              ▶ Mean field approx.
2:
           while ELBO(q_{\theta}) has not converged do
3:
                 for t \in \{1, \ldots, T\} do
                                                                                                 ⊳ For each variable
4:
                        Set q_t(z_t) \propto \exp(E_{q_{\neg t}}[\log p_{\alpha}(z_t \mid z_{\neg t}, x)])
5:
                        while keeping all \{q_s(\cdot)\}_{s\neq t} fixed
6:
                 Compute ELBO(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[ \log p_{\alpha}(\mathbf{x}, \mathbf{z}) \right] - E_{q_{\theta}(\mathbf{z})} \left[ \log q_{\theta}(\mathbf{z}) \right]
7:
           return q_{\theta}
8:
```

CAVI Algorit

Coordinate

- here
- appl
- conv

Similar to Belief Propagation: can be viewed as message passing where we update our variable beliefs based on what neighbors think it should be

e (CAVI) Ition imization

nconvex

Like Gibbs Sampling, we compute a variable specific quantity at each step conditioned on the **Markov boundary**

```
1: procedure CAVI(p_{\alpha})
           Let q_{\theta}(\mathbf{z}) = \prod_{t=1}^{T} q_{t}(z_{t})
                                                                                              ▶ Mean field approx.
2:
           while ELBO(q_{\theta}) has not converged do
3:
                 for t \in \{1, \ldots, T\} do
                                                                                                  ⊳ For each variable
4:
                        Set q_t(z_t) \propto \exp(E_{q_{\neg t}}[\log p_{\alpha}(z_t \mid z_{\neg t}, x)])
5:
                        while keeping all \{q_s(\cdot)\}_{s\neq t} fixed
6:
                 Compute ELBO(q_{\theta}) = E_{q_{\theta}(\mathbf{z})} \left[ \log p_{\alpha}(\mathbf{x}, \mathbf{z}) \right] - E_{q_{\theta}(\mathbf{z})} \left[ \log q_{\theta}(\mathbf{z}) \right]
7:
           return q_{\theta}
8:
```

Unlike Gibbs Sampling:

- we compute an entire distribution (instead of sampling a value)
- we condition on variable marginals (instead of on variable assignment)

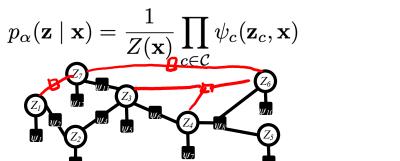
Variational Inference

Whiteboard

Computing marginals from a trained mean field approximation

EXAMPLE: CAVI FOR DISCRETE FACTOR GRAPH

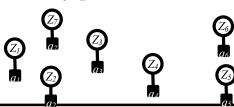
CAVI for a Discrete Factor Graph



return q_{θ}

8:

$$q_{\theta}(\mathbf{z}) = \prod_{t=1}^{I} q_{t}(z_{t})$$



```
1: procedure CAVI(p_{\alpha})

2: Let q_{\theta}(\mathbf{z}) = \prod_{t=1}^{T} q_{t}(z_{t}) \triangleright Mean field approx.

3: while ELBO(q_{\theta}) has not converged do

4: for t \in \{1, \dots, T\} do \triangleright For each variable

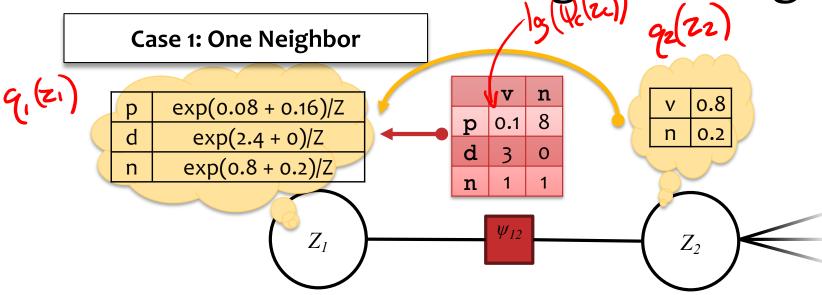
5: Set q_{t}(z_{t}) \propto \exp(E_{q_{\neg t}}[\log p_{\alpha}(z_{t} \mid z_{\neg t}, x)]) \triangleleft

6: while keeping all \{q_{s}(\cdot)\}_{s \neq t} fixed

7: Compute ELBO(q_{\theta}) = E_{q_{\theta}(\mathbf{z})}[\log p_{\alpha}(\mathbf{x}, \mathbf{z})] - E_{q_{\theta}(\mathbf{z})}[\log q_{\theta}(\mathbf{z})]
```

$$\Rightarrow q_t(z_t) \propto \exp\left(\sum_{\mathbf{z}_{\mathsf{MB}(z_t)}} \prod_{s \in \mathsf{MB}(z_t)} q_s(z_s) \lim_{c \in N(z_t)} \psi_c(\mathbf{z}_c)\right)$$

CAVI as Message Passing



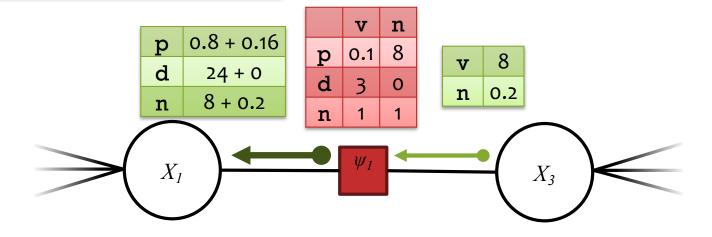
CAVI message passing differs from BP in several ways:

- the beliefs are normalized (i.e. beliefs = marginals)
- no messages **to** factors (i.e. all messages are directly to a variable)
- matrix-vector product is exponentiated and normalized

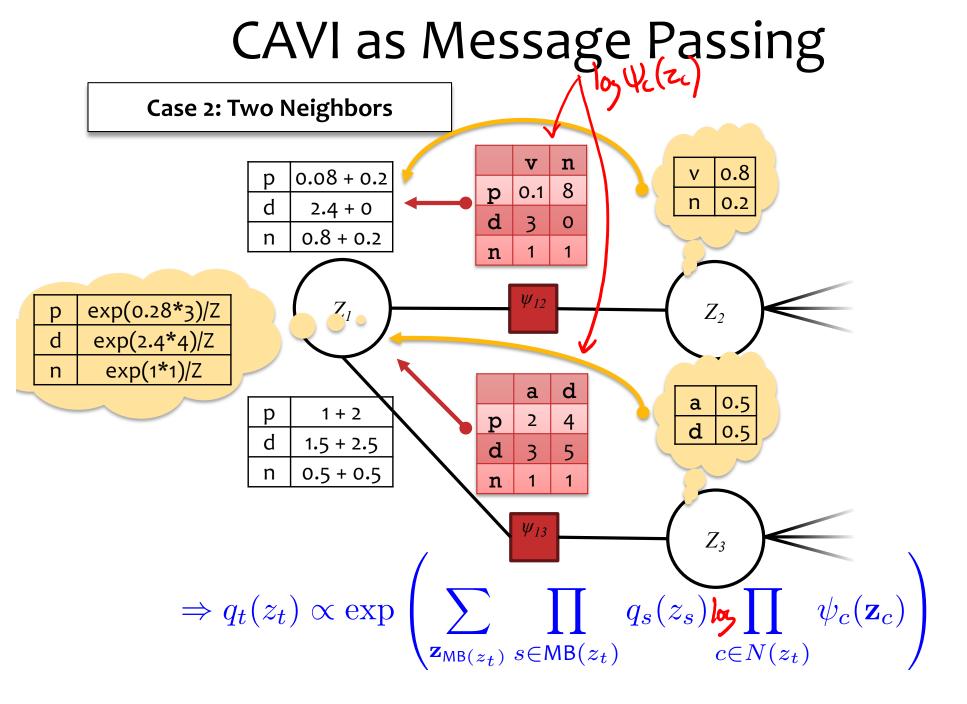
$$\Rightarrow q_t(z_t) \propto \exp\left(\sum_{\mathbf{z}_{\mathsf{MB}(z_t)}} \prod_{s \in \mathsf{MB}(z_t)} q_s(z_s) \prod_{c \in N(z_t)} \psi_c(\mathbf{z}_c)\right)$$

Sum-Product Belief Propagation Recall...

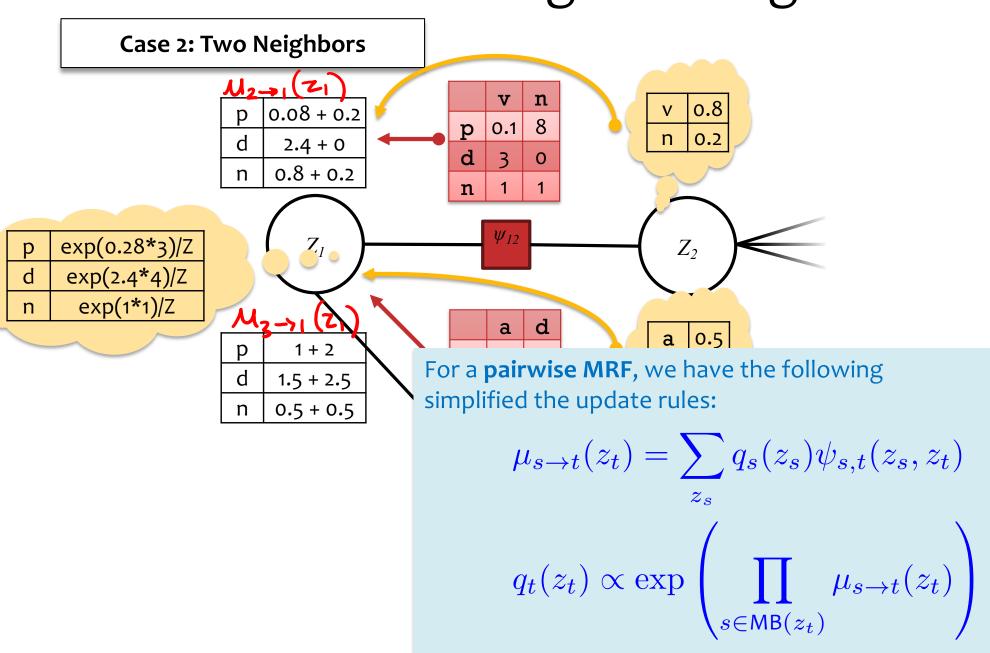
Factor Message



$$\mu_{\alpha \to i}(x_i) = \sum_{\boldsymbol{x_{\alpha}}: \boldsymbol{x_{\alpha}}[i] = x_i} \psi_{\alpha}(\boldsymbol{x_{\alpha}}) \prod_{j \in \mathcal{N}(\alpha) \setminus i} \mu_{j \to \alpha}(\boldsymbol{x_{\alpha}}[i])$$



CAVI as Message Passing



Variational Inference

Whiteboard

- Computing the CAVI update
 - Multinomial full conditionals
- Example: two variable factor graph
 - Joint distribution
 - Mean Field Variational Inference
 - Gibbs Sampling

Q2: What geresties de you have?

Q&A