

Consider $A = \begin{pmatrix} 0 & -1 \\ 2 & 0 \end{pmatrix}$.

We could perform an eigenvalue/eigenvector decomposition $A = S \lambda S^{-1}$, but it is complicated & produces complex values.

There is a simpler geometric interpretation.

Think of A as ${}^B[f]_B$ for basis B given by the vectors $\begin{pmatrix} 1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix}$.

Now let B' be $\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ -1 \end{pmatrix}$, i.e., $\begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ -1 \end{pmatrix}$.

Then ${}^{B'}[f]_{B'} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$.

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There is a simpler geometric interpretation.

Think of A as ${}^B[f]_B$ for basis B given by the vectors $\begin{pmatrix} \uparrow \\ \rightarrow \end{pmatrix}$ & $\begin{pmatrix} \uparrow \\ \downarrow \end{pmatrix}$.

Now let B' be $\begin{pmatrix} \uparrow \\ \leftrightarrow \end{pmatrix}$, i.e., $\begin{pmatrix} \uparrow \\ \downarrow \end{pmatrix} + \begin{pmatrix} \uparrow \\ \downarrow \end{pmatrix}$.

Then ${}^{B'}[f]_{B'} = \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$.

Why?

Because we see from A that

$$f(\rightarrow) = 2 \cdot \uparrow + 0 \cdot \leftarrow$$

$$\# f(\uparrow) = 0 \cdot \uparrow + 1 \cdot \leftarrow.$$

That tells us $A = \begin{pmatrix} \text{(coordinate change)} \\ \text{matrix} \\ \text{from } \mathbb{B}' \text{ to } \mathbb{B} \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}$:

$$\begin{pmatrix} 0 & -1 \\ 2 & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix}.$$

And that again means we can solve $Ax = b$ easily.

E.g.,

$$Ax = \begin{pmatrix} 7 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 7 \\ 2 \end{pmatrix}.$$

inverse is transpose
just as with
orthogonal eigenvectors

$$\text{so } \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 7 \\ 2 \end{pmatrix}.$$

$$\text{Then } \begin{pmatrix} 2 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 2 \\ -7 \end{pmatrix}.$$

$$\text{so } x_1 = \frac{2}{2} = 1$$

$$\text{& } x_2 = \frac{-7}{1} = -7.$$

That tells us $A = \begin{pmatrix} \text{(coordinate change)} \\ \text{matrix} \\ \text{from } \mathbb{B}' \text{ to } \mathbb{B} \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & 1 \end{pmatrix}$:

$$\begin{pmatrix} 0 & -1 \\ z & 0 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & 1 \end{pmatrix}.$$

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E.g.,

$$Ax = \begin{pmatrix} 7 \\ 2 \end{pmatrix}$$

$$\begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} z & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 7 \\ 2 \end{pmatrix}.$$

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$$\text{so } \begin{pmatrix} z & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} \begin{pmatrix} 7 \\ 2 \end{pmatrix}.$$

$$\text{Then } \begin{pmatrix} z & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} z \\ -7 \end{pmatrix}.$$

$$\text{so } x_1 = \frac{z}{z} = 1$$

$$\text{& } x_2 = \frac{-7}{1} = -7.$$

(A) is simple enough here that we could have read off this answer directly, but this process hints at the more general process we will see with SVD.

Fact:

Not all matrices have nice
eigenvector decompositions.

However, if we allow ourselves to choose nice bases for the domain & range of a linear function (possibly different bases even if domain & range are the same), then we can always represent the function using a diagonal matrix.

That's what SVD gives us, as we will see.