

TENTATIVE SCHEDULE FOR Planning and Decision-making in Robotics CLASS
Fall 2019

Date	Day	Topic	HW out	HW due
26-Aug	Mon	Introduction; What is Planning?		
28-Aug	Wed	planning representations: explicit vs. implicit graphs, skeletonization, cell decomposition & lattice-based graphs		
2-Sep	Mon	LABOR DAY - NO CLASS		
4-Sep	Wed	search algorithms: A*, Weighted A*, Backward A*		
9-Sep	Mon	search algorithms: Heuristic functions, Multi-Heuristic A*	HW1	
11-Sep	Wed	interleaving planning and execution: Anytime heuristic search, Incremental heuristic search		
16-Sep	Mon	interleaving planning and execution: Real-time heuristic Search		
18-Sep	Wed	case study: planning for autonomous driving		
23-Sep	Mon	planning representations: PRM for continuous spaces		HW1
25-Sep	Wed	planning representations/search algorithms: RRT, RRT-Connect	HW2	
30-Sep	Mon	planning representations/search algorithms: RRT*		
2-Oct	Wed	case study: planning for mobile manipulators and legged robots		
7-Oct	Mon	search algorithms: Multi-goal A*, Markov Property, dependent vs. independent variables, Dominance		
9-Oct	Wed	case study: planning for coverage, mapping and surveillance tasks		HW2
14-Oct	Mon	planning representations: state-space vs. symbolic representation for task planning	HW3	
16-Oct	Wed	search algorithms: planning on symbolic representations		
21-Oct	Mon	planning under uncertainty: Minimax formulation, Minimax Backward A*		
23-Oct	Wed	planning under uncertainty: Markov Decision Processes, Value Iteration, RTDP		
28-Oct	Mon	planning under uncertainty: Partially-Observable Markov Decision Processes		HW3
30-Oct	Wed	planning under uncertainty: Partially-Observable Markov Decision Processes (cont'd)		
4-Nov	Mon	final project proposal presentations		
6-Nov	Wed	learning in planning		
11-Nov	Mon	learning in planning (cont'd)		
13-Nov	Wed	multi-robot planning		
18-Nov	Mon	multi-robot planning (cont'd)		
20-Nov	Wed	exam review		
25-Nov	Mon	exam		
27-Nov	Wed	THANKSGIVING - NO CLASS		
2-Dec	Mon	TBD		
4-Dec	Wed	final project presentations		