Announcements

Assignment 1 is due Thursday at midnight
Turnin space:

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TA hours Tuesday 3-5 (Joel—cluster) and Thursday 3-5 (Michael—Wean 8121)
Or send any of us email

Questions on Assignment 1?
Written Assignment #1 out this afternoon
Wrap-up on Transformations

3D Viewing

Perspective projection
Viewing transformation

Shirley Chapter 7
Example: Modeling

Modeling with primitive shapes
Example: Animation

Setting up a scene and animating
Example: Modeling Deformations

Incorporating deformations into a modeling system

Influence lattice deforming sphere partially inside lattice.

Sphere no longer affected by influence lattice because it is now outside of the base lattice. (The base lattice is not displayed unless selected, but by default it is located inside the influence lattice, and has the influence lattice's original shape.)
Example: Viewing Transformation

WORLD

OBJECT

CAMERA
\begin{verbatim}
glTranslatef( 0.00, 0.00, 0.00 );

glRotatef( 0.0, 0.00, 1.00, 0.00 );

glScalef( 1.00, 1.00, 1.00 );

glBegin( . . . );

. . .
\end{verbatim}

Click on the arguments and move the mouse to modify values.
Question about rotating about an arbitrary axis
Implementing Transformation Sequences

• Calculate the matrices and cumulatively multiply them into a global *Current Transformation Matrix*

• Postmultiplication is more convenient in hierarchies -- multiplication is computed in the opposite order of function application

• The calculation of the transformation matrix, $M$,
  – initialize $M$ to the identity
  – in reverse order compute a basic transformation matrix, $T$
  – post-multiply $T$ into the global matrix $M$, $M \leftarrow MT$

• Example - to rotate by $\theta$ around [$x,y$]:

```c
glLoadIdentity()        /* initialize M to identity mat.*/
glTranslatef(x, y, 0)    /* LAST: undo translation */
glRotatef(theta,0,0,1)  /* rotate about z axis */
glTranslatef(-x, -y, 0)  /* FIRST: move [x,y] to origin. */
```

• Remember the last $T$ calculated is the first applied to the points
  – calculate the matrices in reverse order
Column Vector Convention

- The convention in the slides
  - transformation is by matrix times vector, $Mv$
  - textbook uses this convention, 90% of the world too

$$\begin{bmatrix}
  x' \\
  y' \\
  1
\end{bmatrix} = \begin{bmatrix}
  m_{11} & m_{12} & m_{13} \\
  m_{21} & m_{22} & m_{23} \\
  m_{31} & m_{32} & m_{33}
\end{bmatrix} \begin{bmatrix}
  x \\
  y \\
  1
\end{bmatrix}$$

- The composite function $A(B(C(D(x)))))$ is the matrix-vector product $ABCDx$
Beware: Row Vector Convention

• The transpose is also possible

\[
\begin{bmatrix}
  x' \\ y' \\ 1
\end{bmatrix} = \begin{bmatrix}
  x \\ y \\ 1
\end{bmatrix} \times \begin{bmatrix}
  m_{11} & m_{21} & m_{31} \\
  m_{12} & m_{22} & m_{32} \\
  m_{13} & m_{23} & m_{33}
\end{bmatrix}
\]

• How does this change things?
  – all transformation matrices must be transposed
  – ABCDx transposed is \( x'TDTCBTABA'T \)
  – pre- and post-multiply are reversed

• OpenGL uses transposed matrices!
  – You’ll only notice this if you DIRECTLY pass matrices as arguments to OpenGL subroutines, e.g. glLoadMatrix.
  – Most routines take only scalars or vectors as arguments.
3D Viewing

Canonical View Volume
Orthographic Projection
Perspective Projection

Shirley Chapter 7
Getting Geometry on the Screen

Given geometry positioned in the world coordinate system, how do we get it onto the display?

- Transform to camera coordinate system
- Transform (warp) into canonical view volume
- Clip
- Project to display coordinates
- Rasterize
Perspective and Orthographic Projection
Orthographic Projection

the focal point is at infinity, the rays are parallel, and orthogonal to the image plane.

Good model for telephoto lens. No perspective effects.

When xy-plane is the image plane (x, y, z) -> (x, y, 0)
front orthographic view
Simple Perspective Camera

Canonical case:
- camera looks along the z-axis
- focal point is the origin
- image plane is parallel to the xy-plane at distance \( d \)
- (We call \( d \) the focal length, mainly for historical reasons)
Viewing and Projection

• Our eyes collapse 3-D world to 2-D retinal image (brain then has to reconstruct 3D)
• In CG, this process occurs by projection
• Projection has two parts:
  – Viewing transformations: camera position and direction
  – Perspective/orthographic transformation: reduces 3-D to 2-D
• Use homogeneous transformations (of course...)
Viewing and Projection

Build this up in stages

• Canonical view volume to screen
• Orthographic projection to canonical view volume
• Perspective projection to orthographic space
Canonical View Volume

Why this shape?
- Easy to clip to
- Trivial to project from 3D to 2D image plane
Orthographic Projection

X = l  left plane
X = r  right plane
Y = b  bottom plane
Y = t  top plane
Z = n  near plane
Z = f  far plane

Why near plane? Prevent points behind the camera being seen.
Why far plane? Allows z to be scaled to a limited fixed-point value (z-buffering).
Arbitrary View Positions

Eye position: e
Gaze direction: g
view-up vector: t
Perspective Projection
Perspective Projection of a Point

\[ y_s = \frac{d}{z} \]

\[ y \]
Perspective Projection

Warping a perspective projection into an orthographic one.
Lines for the two projections intersect at the view plane.
How can we put this in matrix form?
Need to divide by $z$—haven’t seen a divide in our matrices so far…
Requires our $w$ from last time (or $h$ in the book).
Clipping

Something is missing between projection and viewing...
Before projecting, we need to eliminate the portion of scene that is outside the viewing frustum

Need to clip objects to the frustum (truncated pyramid)
Now in a canonical position but it still seems kind of tricky...
Normalizing the Viewing Frustum

Solution: transform frustum to a cube before clipping

Converts perspective frustum to orthographic frustum
Yet another homogeneous transform!
World-space view  Screen-space view

Command manipulation window

fovy  aspect  zNear  zFar

```
 gluPerspective( 60.0 , 1.00 , 1.0 , 10.0 );
 gluLookAt( 0.00 , 0.00 , 2.00 ,  <- eye
         0.00 , 0.00 , 0.00 ,  <- center
         0.00 , 1.00 , 0.00 );  <- up
```

Click on the arguments and move the mouse to modify values.
Camera Control Values

• All we need is a single translation and angle-axis rotation (orientation), but...

• Good animation requires good camera control--we need better control knobs

• Translation knob - move to the lookfrom point

• Orientation can be specified in several ways:
  – specify camera rotations
  – specify a lookat point (solve for camera rotations)
A Popular View Specification Approach

• Focal length, image size/shape and clipping planes are in the perspective transformation

• In addition:
  – *lookfrom*: where the focal point (camera) is
  – *lookat*: the world point to be centered in the image

• Also specify camera orientation about the *lookat-lookfrom* axis
Implementation

Implementing the \textit{lookat/lookfrom/vup} viewing scheme

(1) Translate by \textit{-lookfrom}, bring focal point to origin

(2) Rotate \textit{lookat-lookfrom} to the $z$-axis with matrix $R$:
   - $v = (\text{lookat-lookfrom})$ (normalized) and $z = [0,0,1]$
   - rotation axis: $a = (v \times z)/|v \times z|$
   - rotation angle: $\cos \theta = v \cdot z$ and $\sin \theta = |v \times z|$.

\texttt{glRotate}(\theta, a_x, a_y, a_z)

(3) Rotate about $z$-axis to get $vup$ parallel to the $y$-axis
The Whole Picture

LOOKFROM: Where the camera is
LOOKAT: A point that should be centered in the image
VUP: A vector that will be pointing straight up in the image
FOV: Field-of-view angle.
d: focal length
WORLD COORDINATES
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