

# 16x62: Course Outline

<b>Week</b>	<b>Date</b>	<b>New Stuff</b>	<b>Lab Stuff</b>	<b>Lab Due</b>
1 Tues	8/26	Intro	Lab tour, Team formation	
1 Thur	8/28		Team names, Assignment format	
2 Tues	9/2			<b>0.0, 0.1</b>
2 Thur	9/4	Feedback control;	Nomad robots: sensor delay	
3 Tues	9/9			<b>1.0, 1.1</b>
3 Thur	9/11	Reactivity, State	Diagnosis robot bugs	
4 Tues	9/16			<b>1.2, 1.3</b>
4 Thur	9/18	Mazeworld		
5 Tues	9/23			<b>2.0, 2.1</b>
5 Thur	9/25	GTNN		
6 Tues	9/30			<b>3.0</b>
6 Thur	10/2	State & Uncertainty		
7 Tues	10/7			<b>4.0, 4.1, 4.2</b>
7 Thur	10/9	Planning I	Assignment format: planning tasks	
8 Tues	10/14			<b>5.0, 5.1</b>
8 Thur	10/16	Planning II		
9 Tues	10/21			<b>5.2</b>
9 Thur	10/23	Interleaving Systems		
10 Tue	10/28		Illah @ IROS	<b>6.0, 6.1</b>
10 Thur	10/30	Vision, the Game+	Illah @ IROS	
11 Tue	11/4			<b>7.0</b>
11 Thur	11/6	Cooperation		
12 Tue	11/11	Simple cooperation tst		<b>8.0</b>
12 Thur	11/13	The Game: strategies	(T.A. lecture); Illah @ Toronto	
13 Tue	11/18	The Game: player 1		<b>8.1</b>
13 Thur	11/20	Robotics & Ethics		
14 Mo,Tu	11/24-25		<b>Practice Prelims</b>	
15 Tu,Wed	12/2-3		<b>6<sup>th</sup> Annual 16x62 Robot Contest</b>	<b>(9.0)</b>

## Lab Assignments Overview

I Introduction to the robot	0.0, 0.1
II Low-level Robot Control	
A PID/feedback Control	1.0, 1.1
B Reactive/functional Control	1.2, 1.3
C Mazeworld	2.0, 2.1, 3.0
III High-level Robot Control	
A Programmed Systems	4.0, 4.1, 4.2
B Deliberate Systems	5.0, 5.1, 5.2
C Interleaving Systems	6.0, 6.1
IV Strategic reasoning & control; vision: Game	7.0
V Cooperation & Communication	8.0