

## **Clark**

Add a new row to Table 1, labeled Robotic Telepresence – and explain what would be on that row (in the right column of course, under Constraints). By R.T. I mean two individuals interact, but one is present telepresently and embodied by a robot vessel.

Here is a vague question- but do your best. If Grounding and its associated needs & costs makes sense, then a natural question to ask is—consider a human and an autonomous robot interacting. In terms of grounding, what needs to be grounded in ways that are ‘extensions’ of what Clark is describing, peculiar to a robot-human interaction (free example: with human-to-human, we ‘get’ eye contact and awareness; with interaction toward a robot, we cannot necessarily make such assumptions, can we?) So, in essence if you want to extend Clark’s Grounding context beyond two-human interaction to one human and one robot interacting, where does grounding need to expand?