

A 3-Valued Logic for the Specification and the Verification of Security Properties

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Outline

- Motivation
- Standard semantics
- 3-Valued semantics
- Extensions
- Future Work

μ -calculus

- Syntax

$$\psi ::= \text{tt} \mid \text{ff} \mid \neg\psi \mid \psi \vee \psi' \mid \psi \wedge \psi' \mid \langle K \rangle \psi \mid [K] \psi \mid X \mid \mu X.\psi \mid \nu X.\psi$$
$$K ::= \{a_i \mid i = 1..n\} \mid K - K'$$
$$a_i ::= \textit{Critical Functions}$$

- A state satisfies the formula $\langle K \rangle \psi$ if it can evolve to some state obeying ψ by performing an action from K .
- A state satisfies the formula $[K] \psi$ if, after the performance of any action in K , the result state satisfies ψ .
- Fixpoint operators allow the specification of recursive behaviors and to reason about all the states of the model.

μ -calculus

- Abbreviations:

- $\text{always}(\psi) = \nu X.\psi \wedge [\text{all}] X$
- $\text{eventually}(\psi) = \mu X.\psi \vee \langle \text{all} \rangle X$
- $\text{never}(\psi) = \neg \text{eventually}(\psi)$
- $\text{loop}(a) = \nu X.\langle a \rangle X$

- Examples of properties:

- $[\text{readPassword}] \langle \text{checkPassword} \rangle \text{true}$
- $\text{never}(\langle \text{formatDisk}, \text{send} \rangle \text{tt})$
- $\text{always}([\text{readFile}] \text{never}(\text{do}(\text{send})))$
- $\text{always}([\text{openSocket}] \text{eventually}(\langle \text{closeSocket} \rangle \text{true}))$
- $\text{never}(\text{loop}(\text{createProcess}))$

μ -calculus

- Model: Labelled Transition System.

- Semantics: $\llbracket \cdot \rrbracket_e^M : \mathcal{F} \rightarrow 2^{\mathcal{S}}$

$$\llbracket \text{tt} \rrbracket_e^M = \mathcal{S}$$

$$\llbracket \text{ff} \rrbracket_e^M = \emptyset$$

$$\llbracket X \rrbracket_e^M = e(X)$$

$$\llbracket \neg\psi \rrbracket_e^M = \overline{\llbracket \psi \rrbracket_e^M}$$

$$\llbracket \psi_1 \vee \psi_2 \rrbracket_e^M = \llbracket \psi_1 \rrbracket_e^M \cup \llbracket \psi_2 \rrbracket_e^M$$

$$\llbracket \psi_1 \wedge \psi_2 \rrbracket_e^M = \llbracket \psi_1 \rrbracket_e^M \cap \llbracket \psi_2 \rrbracket_e^M$$

$$\llbracket \langle K \rangle \psi \rrbracket_e^M = \{s \mid (\exists s' \mid s' \in \llbracket \psi \rrbracket_e^M : (\exists a \mid a \in K : s \xrightarrow{a} s'))\}$$

$$\llbracket [K] \psi \rrbracket_e^M = \{s \mid (\forall s' \mid : (\forall a \mid a \in K : s \xrightarrow{a} s' \Rightarrow s' \in \llbracket \psi \rrbracket_e^M))\}$$

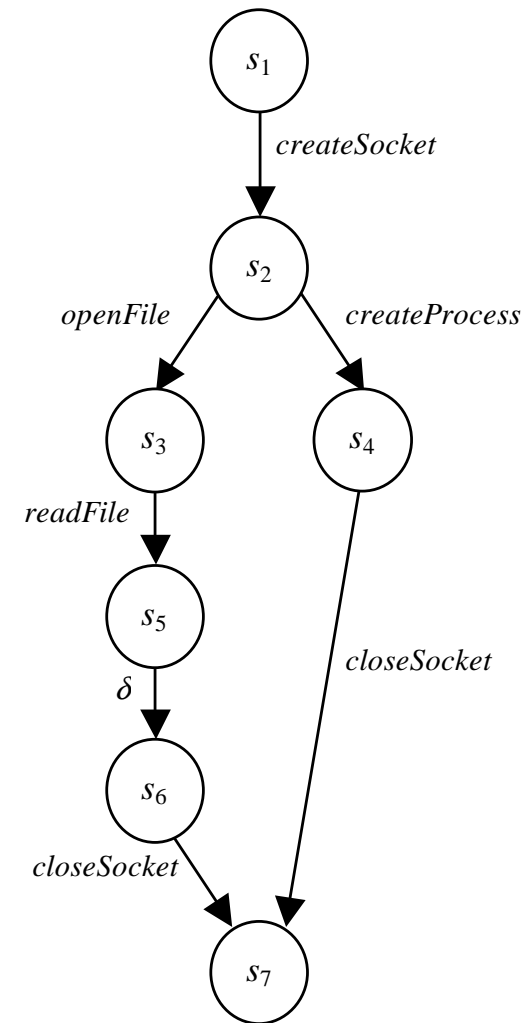
$$\llbracket \mu X. \psi \rrbracket_e^M = \bigcap \{Q \subseteq \mathcal{S} \mid \llbracket \psi \rrbracket_{e[X \mapsto Q]}^M \subseteq Q\}$$

$$\llbracket \nu X. \psi \rrbracket_e^M = \bigcup \{Q \subseteq \mathcal{S} \mid Q \subseteq \llbracket \psi \rrbracket_{e[X \mapsto Q]}^M\}$$

- Model-Checker: True/False

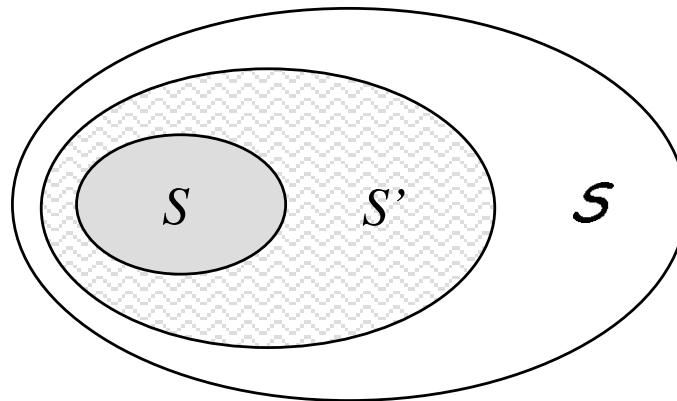
Model with δ -transitions

- Name of some function calls unavailable statically.
- Pointers, functions pointers, etc.
- 3-valued semantics: allows to reason under uncertainty (lack of information).



Toward a 3-Valued Semantics

- New meaning function: $\llbracket \cdot \rrbracket_e^M : \mathcal{F} \rightarrow 2^{\mathcal{S}} \times 2^{\mathcal{S}}$
- Semantically, formulae of the logic correspond to sets of states for which they are true (\mathcal{S}) and to sets of states for which they may be true (\mathcal{S}'), including those that are true.



The remaining states in \mathcal{S} do not satisfy the formulae.

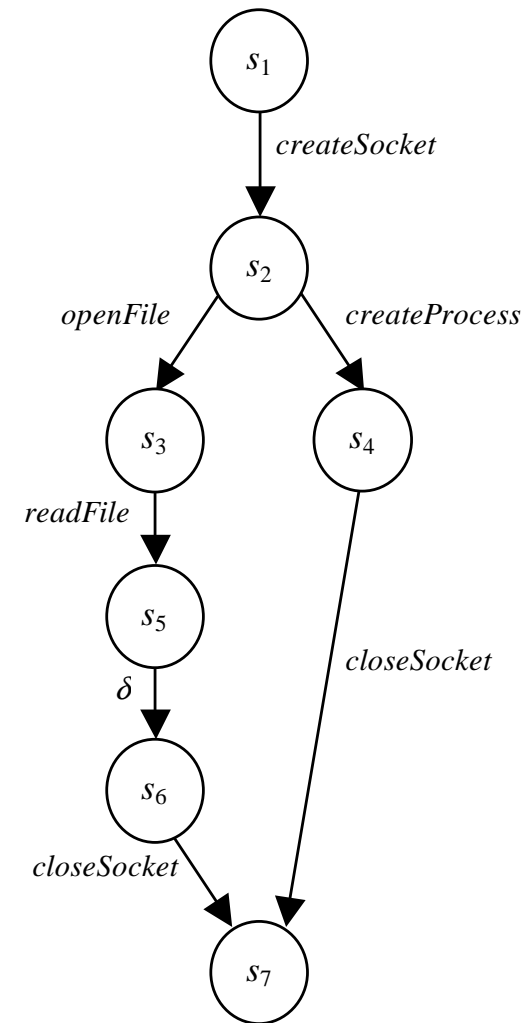
- Model-Checker: True/False/May be

3-Valued Semantics - First Version

- $$\begin{aligned} \llbracket \text{tt} \rrbracket_e^M &= (\mathcal{S}, \mathcal{S}) \\ \llbracket \text{ff} \rrbracket_e^M &= (\emptyset, \emptyset) \\ \llbracket X \rrbracket_e^M &= e(X) \\ \llbracket \neg\psi \rrbracket_e^M &= (\overline{\pi_2(\llbracket \psi \rrbracket_e^M)}, \overline{\pi_1(\llbracket \psi \rrbracket_e^M)}) \\ \llbracket \psi_1 \vee \psi_2 \rrbracket_e^M &= (\pi_1(\llbracket \psi_1 \rrbracket_e^M) \cup \pi_1(\llbracket \psi_2 \rrbracket_e^M), \pi_2(\llbracket \psi_1 \rrbracket_e^M) \cup \pi_2(\llbracket \psi_2 \rrbracket_e^M)) \\ \llbracket \psi_1 \wedge \psi_2 \rrbracket_e^M &= (\pi_1(\llbracket \psi_1 \rrbracket_e^M) \cap \pi_1(\llbracket \psi_2 \rrbracket_e^M), \pi_2(\llbracket \psi_1 \rrbracket_e^M) \cap \pi_2(\llbracket \psi_2 \rrbracket_e^M)) \\ \llbracket \langle K \rangle \psi \rrbracket_e^M &= (\{s \mid (\exists s' \mid s' \in \pi_1(\llbracket \psi \rrbracket_e^M) : (\exists a \mid a \in K : s \xrightarrow{a} s'))\}, \\ &\quad \{s \mid (\exists s' \mid s' \in \pi_2(\llbracket \psi \rrbracket_e^M) : (\exists a \mid a \in K_\delta : s \xrightarrow{a} s'))\} \\ &) \\ \llbracket [K] \psi \rrbracket_e^M &= (\{s \mid (\forall s' \mid : (\forall a \mid a \in K_\delta : s \xrightarrow{a} s' \Rightarrow s' \in \pi_1(\llbracket \psi \rrbracket_e^M)))\}, \\ &\quad \{s \mid (\forall s' \mid : (\forall a \mid a \in K : s \xrightarrow{a} s' \Rightarrow s' \in \pi_2(\llbracket \psi \rrbracket_e^M)))\} \\ &) \\ \llbracket \mu X. \psi \rrbracket_e^M &= \bigcap \{ (Q, Q') \subseteq (\mathcal{S} \times \mathcal{S}) \mid \llbracket \psi \rrbracket_{e[X \mapsto (Q, Q')]}^M \subseteq (Q, Q') \} \\ \llbracket \nu X. \psi \rrbracket_e^M &= \bigcup \{ (Q, Q') \subseteq (\mathcal{S} \times \mathcal{S}) \mid (Q, Q') \subseteq \llbracket \psi \rrbracket_{e[X \mapsto (Q, Q')]}^M \} \end{aligned}$$

Examples

- Ex1: $[createProcess] \langle closeSocket \rangle tt$
- Ex2: $\langle all \rangle \langle closeSocket \rangle tt$



3-Valued Semantics - Final Version

•

⋮

$$\begin{aligned} \llbracket \langle K \rangle \psi \rrbracket_e^M = & (\{s \mid (\exists s' \mid s' \in \pi_1(\llbracket \psi \rrbracket_e^M) : (\exists a \mid a \in K : s \xrightarrow{a} s'))\} \cup \\ & \{s \mid (K = \mathbf{all}) \wedge (\exists s' \mid s' \in \pi_1(\llbracket \psi \rrbracket_e^M) : s \xrightarrow{\delta} s')\}, \\ & \{s \mid (\exists s' \mid s' \in \pi_2(\llbracket \psi \rrbracket_e^M) : (\exists a \mid a \in K_\delta : s \xrightarrow{a} s'))\} \\ &) \end{aligned}$$

$$\begin{aligned} \llbracket [K] \psi \rrbracket_e^M = & (\{s \mid (\forall s' \mid : (\forall a \mid a \in K_\delta : s \xrightarrow{a} s' \Rightarrow s' \in \pi_1(\llbracket \psi \rrbracket_e^M)))\}, \\ & \{s \mid (\forall s' \mid : (\forall a \mid a \in K : s \xrightarrow{a} s' \Rightarrow s' \in \pi_2(\llbracket \psi \rrbracket_e^M)))\} \cap \\ & \{s \mid (K = \mathbf{all}) \Rightarrow (\forall s' \mid : s \xrightarrow{\delta} s' \Rightarrow s' \in \pi_2(\llbracket \psi \rrbracket_e^M))\} \\ &) \end{aligned}$$

⋮

Properties

The semantics preserves the classical properties of μ -calculus:

$$\begin{aligned}\neg\neg\psi &\equiv \psi \\ \neg(\psi_1 \vee \psi_2) &\equiv \neg\psi_1 \wedge \neg\psi_2 \\ [K]\psi &\equiv \neg\langle K\rangle\neg\psi \\ \mu X.\psi &\equiv \neg\nu X.\neg\psi[\neg X/X]\end{aligned}$$

Tableau-based Proof System

- Local Model Checking: Does not require that every state in the model be examined.
- Two sequents:
 1. $H \vdash s \in \psi$
 2. $H \vdash s \approx \psi$where H is a mapping in $[\mathcal{V} \mapsto 2^{\mathcal{S}}]$, s is a state and ψ is a formula.
- Three results: **Finiteness**, **Soundness** and **Completeness**.

Toward a more Efficient Semantics

- Let's

- $M = \langle \{s_0, s_1\}, \{a, b, c\}, s_0 \xrightarrow{\delta} s_1, s_0 \rangle$ be a model, and
- $\psi = \langle a \rangle \text{tt} \vee \langle -a \rangle \text{tt}$ be a formula.

- By definition, we have the following:

$$\llbracket \langle a \rangle \text{tt} \vee \langle -a \rangle \text{tt} \rrbracket_e^M = (\pi_1(\llbracket \langle a \rangle \text{tt} \rrbracket_e^M) \cup \pi_1(\llbracket \langle -a \rangle \text{tt} \rrbracket_e^M), \\ \pi_2(\llbracket \langle a \rangle \text{tt} \rrbracket_e^M) \cup \pi_2(\llbracket \langle -a \rangle \text{tt} \rrbracket_e^M))$$

It is easy to see that: $\llbracket \langle a \rangle \text{tt} \rrbracket_e^M = \llbracket \langle -a \rangle \text{tt} \rrbracket_e^M = (\emptyset, \{s_0\})$

It follows that: $\llbracket \langle a \rangle \text{tt} \vee \langle -a \rangle \text{tt} \rrbracket_e^M = (\emptyset, \{s_0\})$

- However, the formula ψ expresses the two following facts:

1. A state has an a -transition;
2. A state has an " $-a$ "-transition, i.e., an $\{b, c\}$ -transition.

meaning that the state s_0 should satisfy the formula.

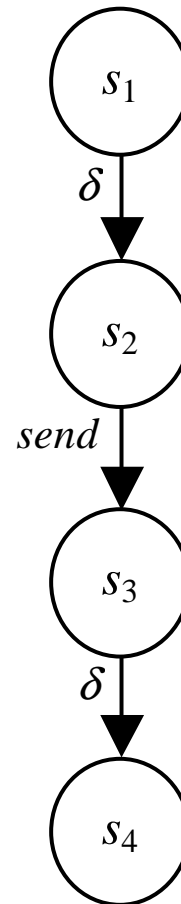
Outline

- Motivation
- Standard semantics
- 3-Valued semantics
- Extensions
 1. Naming δ -transition.
 2. Typing δ -transition.
- Future Work

Extension 1

```
extern int openFile(char*);  
extern void closeFile(int);  
extern int send(int, char*);
```

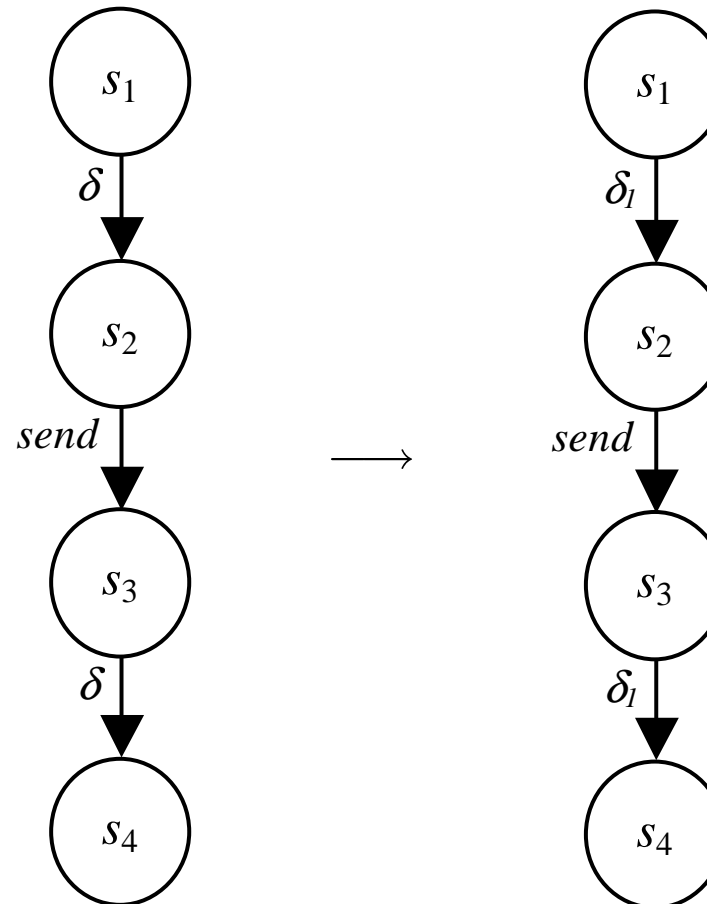
```
int main()  
{  
    int socket;  
    int file;  
    char fileName[1000];  
    int (*f)(char *);  
    ...  
    f("f1.ex");  
    send( socket, "done" );  
    f("f2.ex");  
    return 0;  
}
```



Extension 1

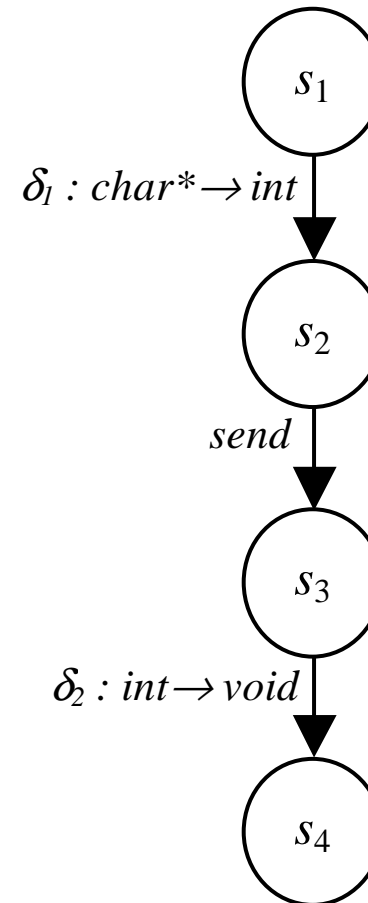
```
extern int openFile(char*);
extern void closeFile(int);
extern int send(int, char*);

int main()
{
    int socket;
    int file;
    char fileName[1000];
    int (*f)(char *);
    ...
    f("f1.ex");
    send( socket, "done" );
    f("f2.ex");
    return 0;
}
```



Extension 2

```
...
int main()
{
    int socket;
    int file;
    char fileName[1000];
    int (*f)(char*);
    void (*g)(int);
    ...
    file = f("f1.ex");
    send( socket, "done" );
    g(file);
    return 0;
}
```



Future Work

- More expressivity: Logic to specify properties involving data.
 - Examples:
 - * $\text{never}(\langle \text{read}(x, \rho_1^s) \rangle \text{eventually}(\langle \text{write}(x, \rho_2^p) \rangle \text{tt}))$
 - * $\text{always}([\text{write}(f, \text{dir}^\alpha(\text{tempdir}))] \text{eventually}(\langle \text{delete}(-, \text{file}^\alpha(f)) \rangle \text{tt}))$
 - 3-Valued semantics should help.
 - *Modal transition systems: A foundation for three-valued program analysis*, [Jagadeesan and Schmidt, 2001].
- Model?

Use of the certifying-compilation technology in order to generate a model suitable for security analysis.

 - Model-Carrying Code.
 - Effects Type Systems.
 - *Models for Security Policies in Proof-Carrying Code*, [Appel and Felten, 2001].