

Supporting hyperplane

$$\min 3x + y \text{ s.t.}$$

$$x + y \geq 2$$

$$x \geq 0$$

$$y \geq 0$$

$$\max 2a \text{ s.t.}$$

$$a + b = 3$$

$$a + c = 1$$

$$a, b, c \geq 0$$

The graduate student nutrition problem

$$\min 3x + y \text{ s.t.}$$

$$x + y \geq 2$$

$$x \geq 0$$

$$y \geq 0$$

$$\max 2a \text{ s.t.}$$

$$a + b = 3$$

$$a + c = 1$$

$$a, b, c \geq 0$$

The Lagrangian

Primal

$$\begin{aligned} & \min 3x + y \text{ s.t.} \\ & x + y \geq 2 \\ & x, y \geq 0 \end{aligned}$$

- $L(a, b, c, x, y) = [3x + y] - [a(x + y - 2) + bx + cy]$

dual

- $\min_{x,y} \max_{a,b,c \geq 0} L(a,b,c,x,y)$

$$\begin{aligned} & \max 2a \text{ st} \\ & a + b = 3 \\ & a + c = 1 \\ & a, b, c \geq 0 \end{aligned}$$

Lagrangian cont'd

$$\min 3x + y \text{ s.t.}$$

$$x + y \geq 2$$

$$x, y \geq 0$$

- $L(a,b,c,x,y) =$

$$[3x + y] - [a(x + y - 2) + bx + cy]$$

- $\min_{x,y} \max_{a,b,c \geq 0} L(a,b,c,x,y)$

$$\max 2a \text{ st}$$

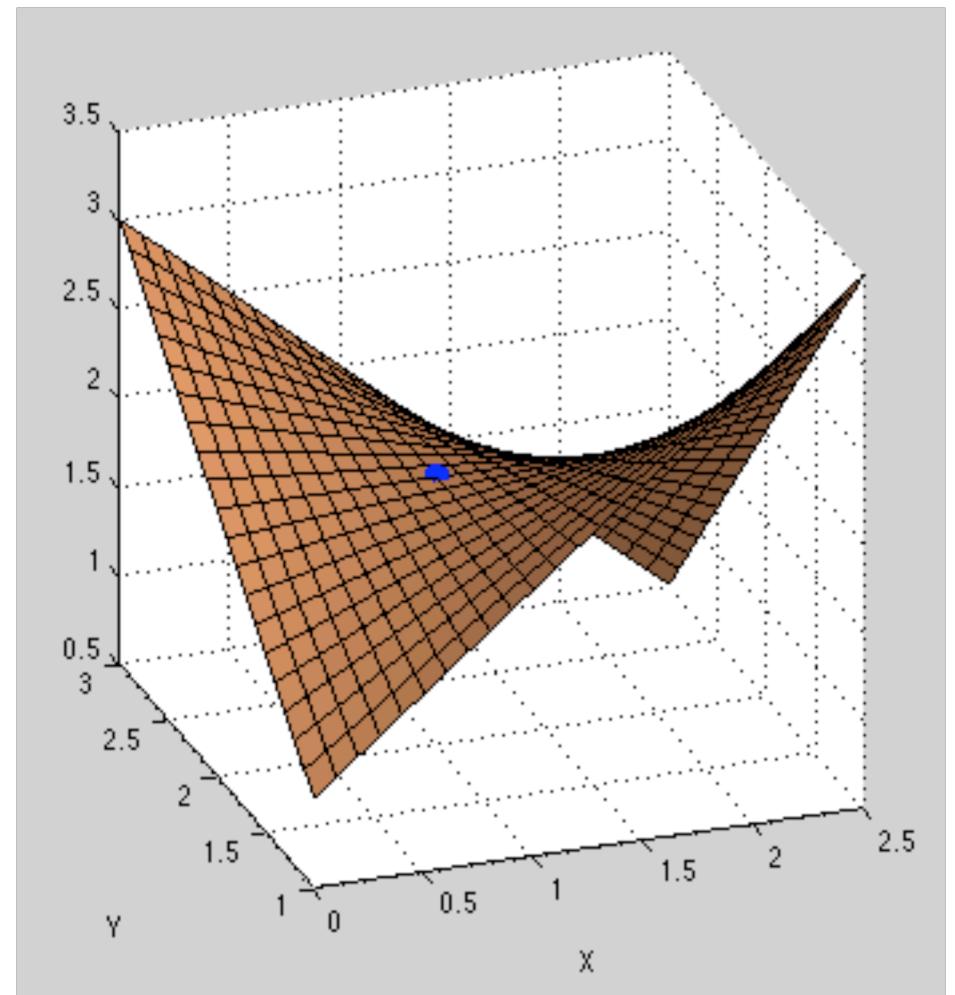
$$a + b = 3$$

$$a + c = 1$$

$$a, b, c \geq 0$$

Saddle-point picture

- $\min y$ s.t. $y \geq 2$



+ vs – in Lagrangian

$\min y$ s.t. $2 \leq y \leq 4$

$\max y$ s.t. $2 \leq y \leq 4$

Duality summary

Primal

min problem

max problem

constraint

\leq constraint

\geq constraint

$=$ constraint

variable

Dual

Duality summary

Primal

tight constraint

slack constraint

zero/nonzero variable

infeasible problem

unbounded problem

finite optimal value

Dual

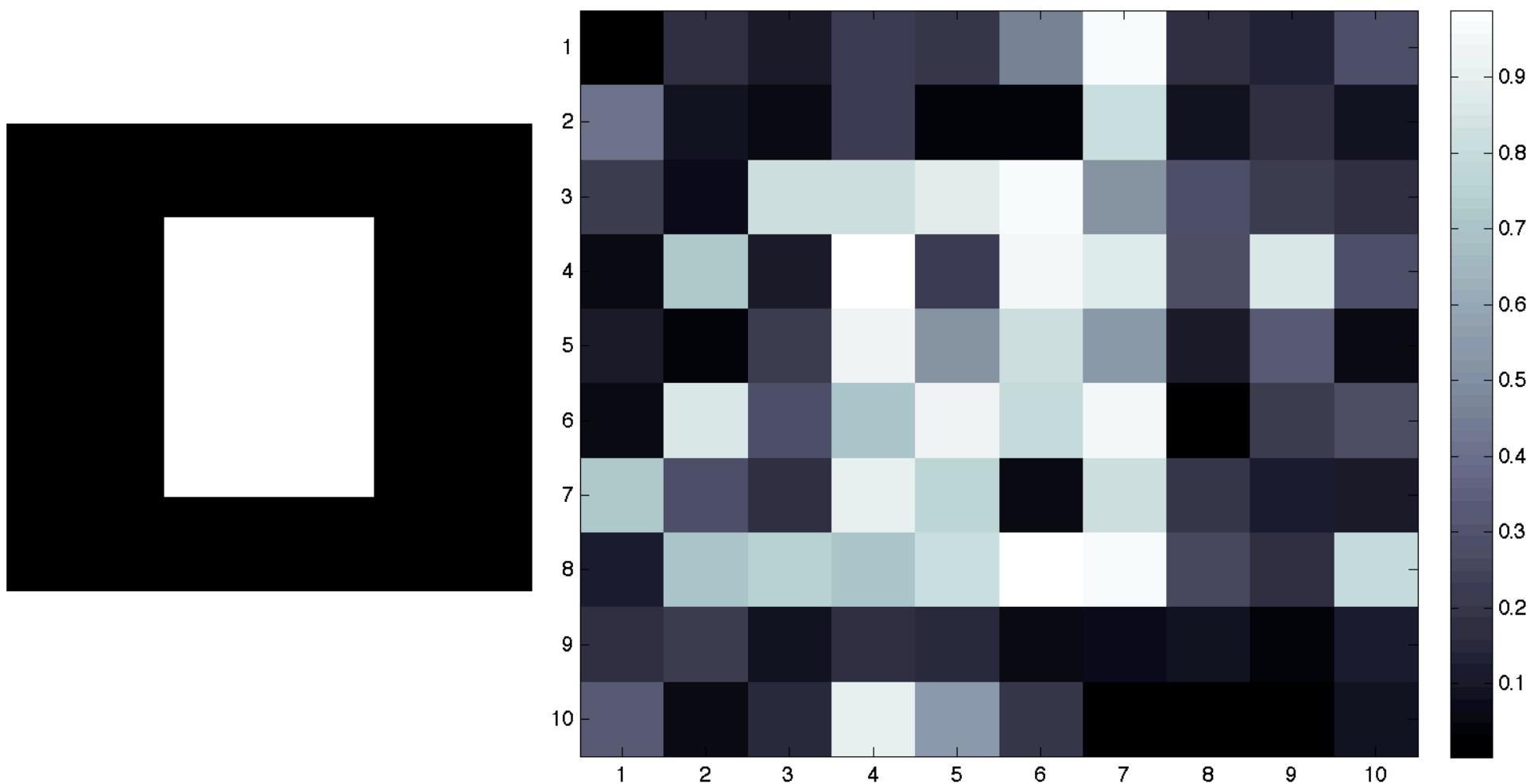
Example: max flow

- Given a directed graph
 - edges $(i,j) \in E$
 - flows f_{ij} , capacities c_{ij}
 - source s , terminal t ($c_{ts} = \infty$)
- $\max f_{ts}$ s.t.
 - positive flow
 - capacity
 - flow conservation

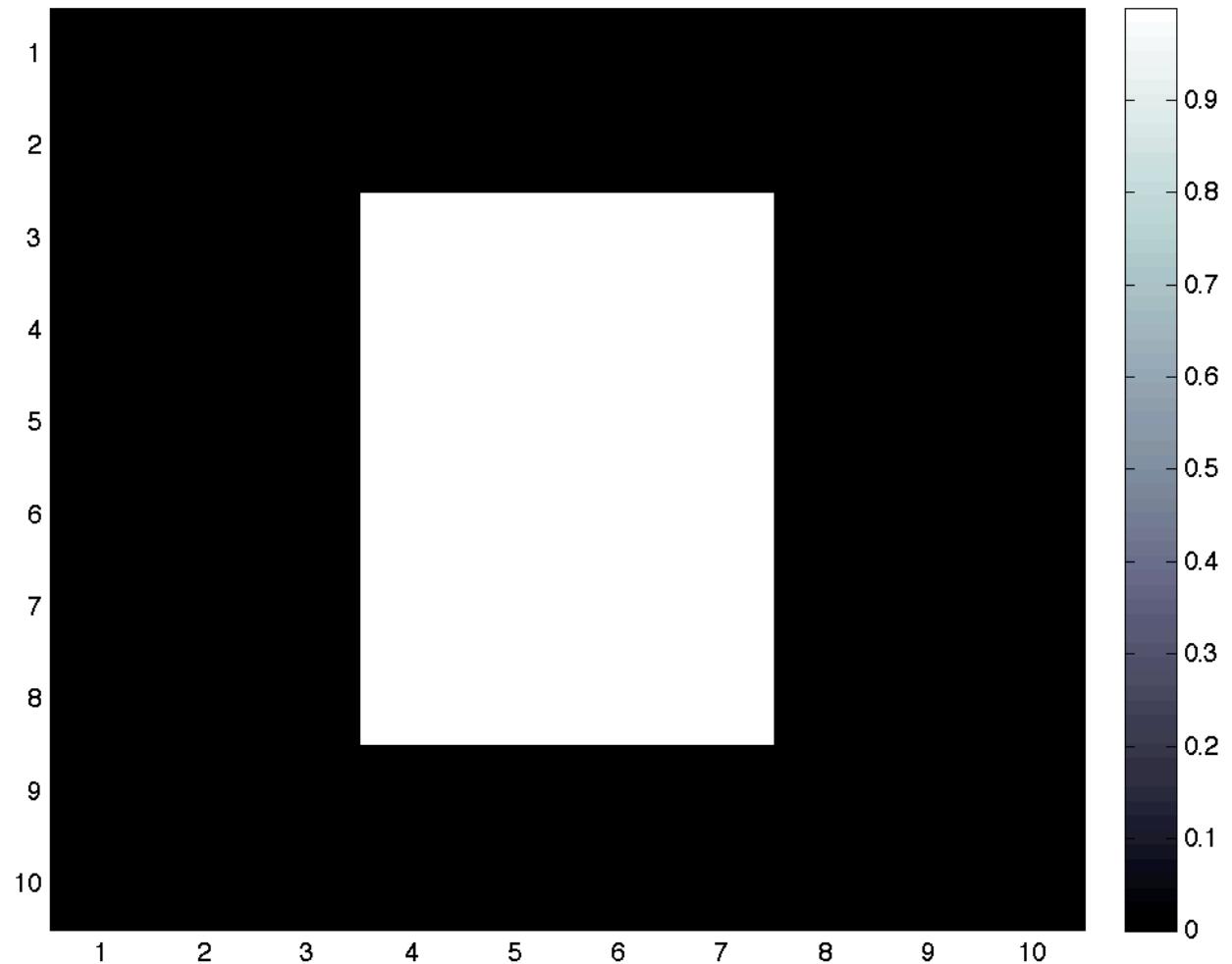
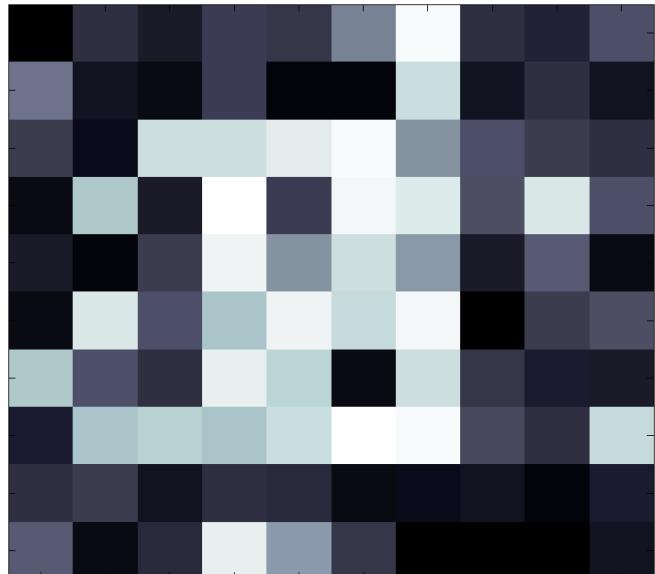
Dual of max flow

Interpreting dual

min cut: image segmentation



Solution



What about QP duality?

- $\min x^2 + y^2$ s.t.
 $x + 2y \geq 2$
 $x, y \geq 0$
- How can we lower-bound OPT?

Works at other points too

- $\min x^2 + y^2$ s.t.
 $x + 2y \geq 2$
 $x, y \geq 0$
- Try Taylor @ $(x, y) = (v, w)$

SVM duality

- Recall: $\min \quad \text{s.t.}$
- Taylor bound objective:
- Generic constraint:
- To get bound, need:

SVM dual

- $\max_{\alpha, v} \sum_i \alpha_i - \|v\|^2/2$ s.t.

$$\sum_i \alpha_i y_i = 0$$

$$\sum_i \alpha_i y_i x_{ij} = v_j \quad \forall j$$

$$\alpha_i \geq 0 \quad \forall i$$