

Branch & bound

$[\text{schema}, \text{value}] = \text{bb}(\text{F}, \text{sch}, \text{bnd})$

- $[\text{v}_{\text{rx}}, \text{rsch}] = \text{relax}(\text{F}, \text{sch})$
- if $\text{integer}(\text{rsch})$: return $[\text{rsch}, \text{v}_{\text{rx}}]$
- if $\text{v}_{\text{rx}} \geq \text{bnd}$: return $[\text{sch}, \text{v}_{\text{rx}}]$
- Pick variable x_i
- $[\text{sch}^{(0)}, \text{v}^{(0)}] = \text{bb}(\text{F}, \text{sch}/(x_i \rightarrow 0), \text{bnd})$
- $[\text{sch}^{(1)}, \text{v}^{(1)}] = \text{bb}(\text{F}, \text{sch}/(x_i \rightarrow 1), \min(\text{bnd}, \text{v}^{(0)}))$
- if $(\text{v}^{(0)} \leq \text{v}^{(1)})$: return $[\text{sch}^{(0)}, \text{v}^{(0)}]$
- else: return $[\text{sch}^{(1)}, \text{v}^{(1)}]$

A random 3-CNF formula

$$\begin{aligned} & (x_5 \vee x_1 \vee x_2) \wedge (x_7 \vee x_2 \vee \bar{x}_4) \wedge (x_5 \vee x_2 \vee \bar{x}_8) \wedge (\bar{x}_6 \vee \bar{x}_1 \vee \bar{x}_7) \\ & \wedge (x_1 \vee x_3 \vee x_5) \wedge (\bar{x}_7 \vee x_1 \vee \bar{x}_6) \wedge (x_8 \vee x_5 \vee x_7) \wedge (\bar{x}_4 \vee \bar{x}_6 \vee \bar{x}_7) \\ & \wedge (\bar{x}_7 \vee x_2 \vee x_1) \wedge (\bar{x}_6 \vee x_4 \vee \bar{x}_4) \wedge (\bar{x}_2 \vee x_3 \vee \bar{x}_2) \wedge (x_4 \vee x_2 \vee \bar{x}_1) \\ & \wedge (x_1 \vee \bar{x}_6 \vee x_6) \wedge (x_7 \vee \bar{x}_8 \vee \bar{x}_3) \wedge (x_3 \vee \bar{x}_4 \vee x_4) \wedge (\bar{x}_4 \vee x_7 \vee \bar{x}_3) \\ & \wedge (x_2 \vee x_4 \vee x_1) \wedge (\bar{x}_6 \vee \bar{x}_7 \vee x_5) \wedge (\bar{x}_2 \vee x_7 \vee \bar{x}_4) \wedge (\bar{x}_5 \vee x_6 \vee x_3) \\ & \wedge (x_7 \vee \bar{x}_1 \vee x_6) \wedge (x_7 \vee x_4 \vee x_7) \wedge (\bar{x}_5 \vee \bar{x}_6 \vee x_5) \wedge (x_7 \vee x_8 \vee \bar{x}_1) \\ & \wedge (\bar{x}_1 \vee \bar{x}_1 \vee x_3) \wedge (\bar{x}_8 \vee x_3 \vee \bar{x}_3) \wedge (x_5 \vee x_4 \vee \bar{x}_6) \wedge (x_4 \vee \bar{x}_1 \vee x_4) \\ & \wedge (\bar{x}_8 \vee x_4 \vee x_4) \wedge (\bar{x}_4 \vee \bar{x}_4 \vee \bar{x}_1) \wedge (\bar{x}_8 \vee x_7 \vee x_7) \wedge (\bar{x}_2 \vee x_8 \vee \bar{x}_8) \\ & \wedge (x_1 \vee x_2 \vee x_6) \wedge (\bar{x}_5 \vee \bar{x}_2 \vee x_1) \end{aligned}$$

Example search tree

Ordering rules

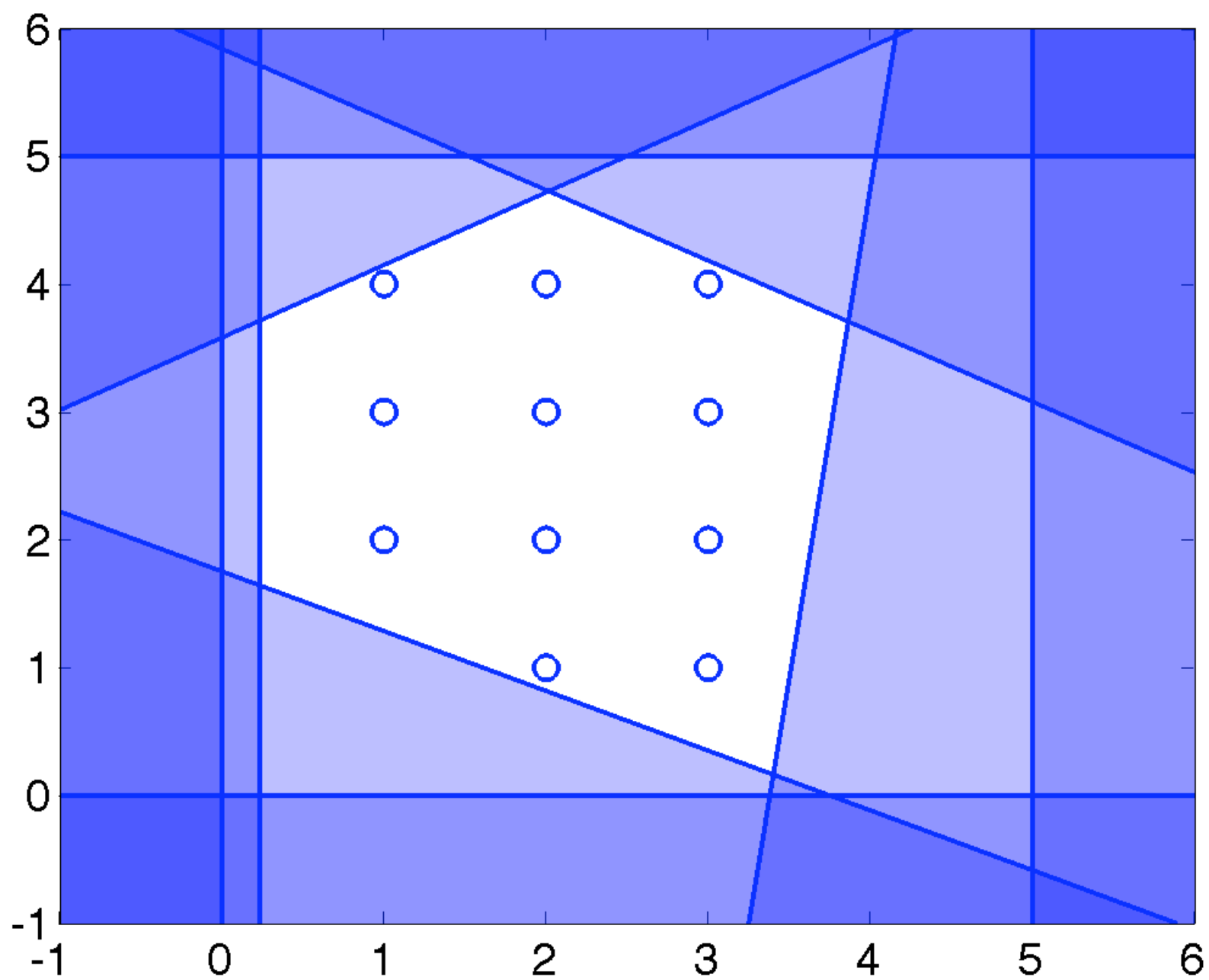
- If relaxation is available:
 - most certain variable first
 - most uncertain variable first
- If no relaxation:
 - most constrained variable first (fewest remaining values in domain)
 - activity rules (branch on variables that are “near” recent vars)

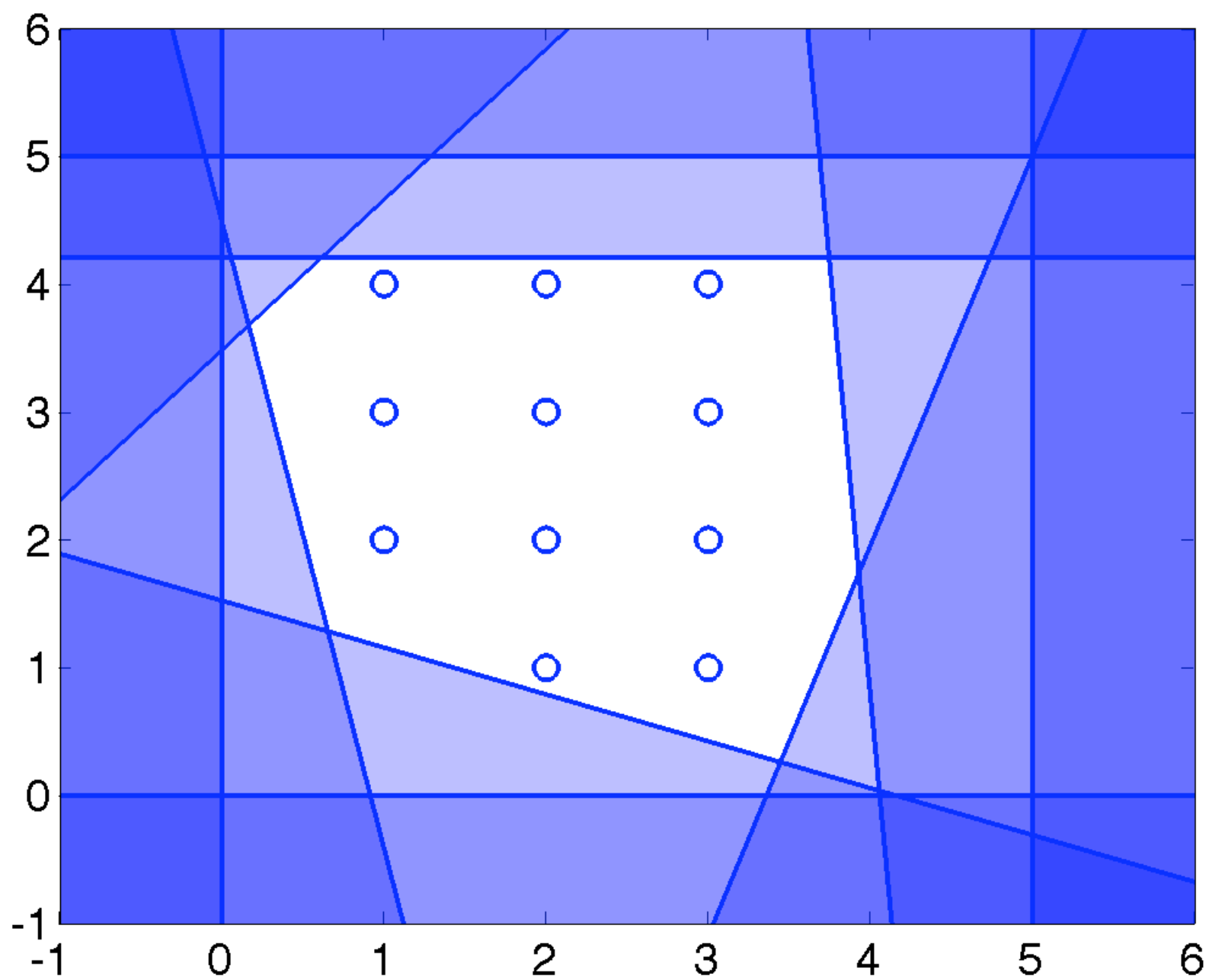
Summary so far

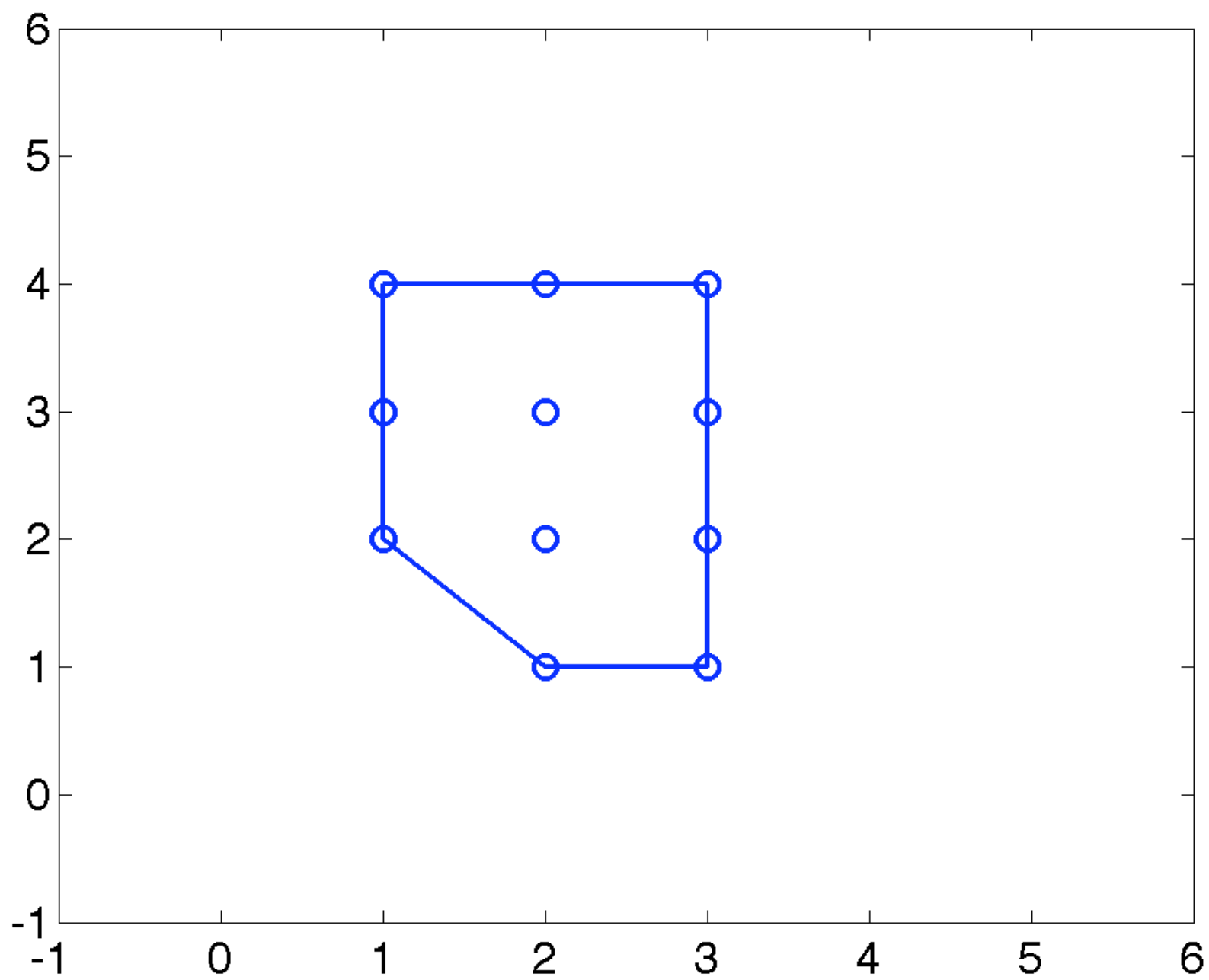
- Simple search
- Constraint propagation
- Branch & bound

Multiple representations

- Any given feasible region may have many different representations
- Can make problem much easier or harder to solve





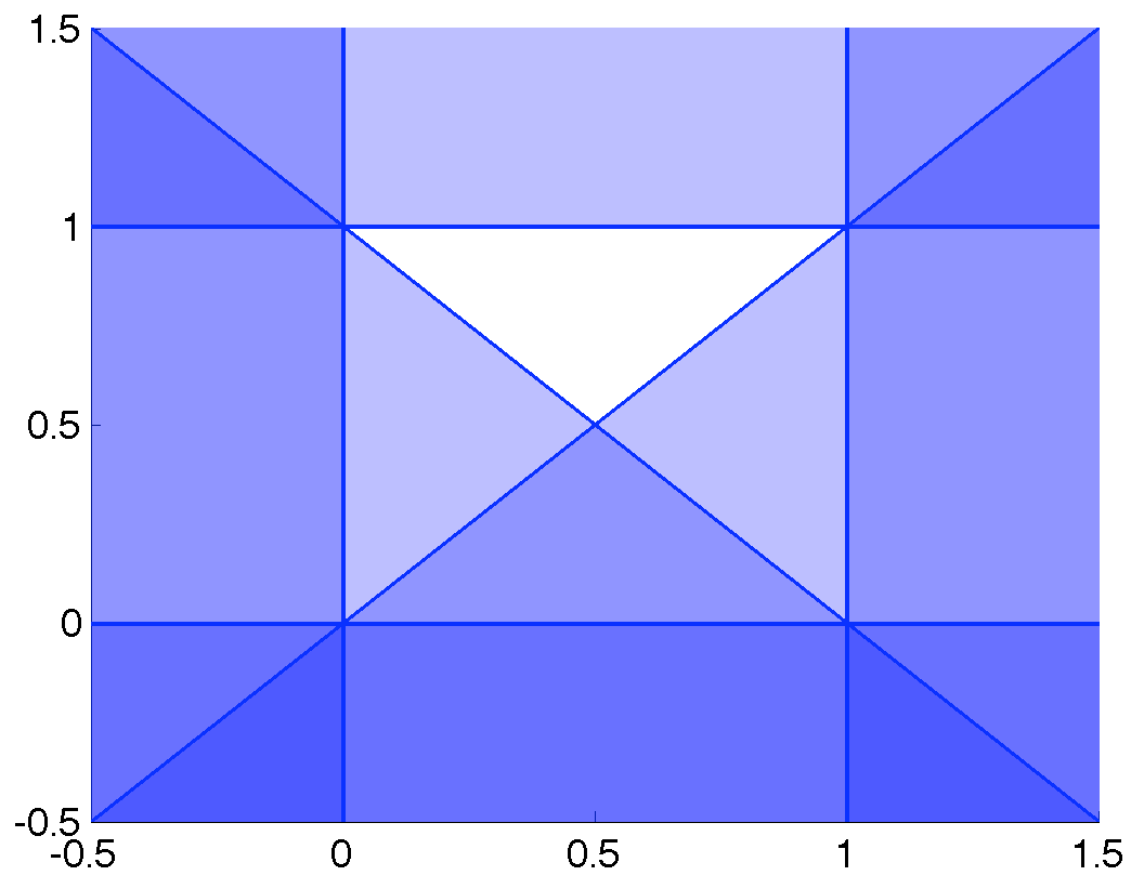


Multiple representations

- Typically, tension btwn tight & small
- Tightest: hull of integer feasible points
 - not small: can be exponentially many faces
- If we have the exact convex hull:
- So:
- Few variables, lots of constraints:

Cutting planes example

$$\min y \text{ st } (1-x) + y \geq 1, \quad x + y \geq 1, \quad x, y \in \{0,1\}$$



Resolution

$$(a \vee \neg b \vee c) \wedge (\neg a \vee c \vee d) \\ \Rightarrow (\neg b \vee c \vee d)$$

SAT and cutting planes

- These “resolution cuts” provide a partial description of the convex hull of integer feasible points for any SAT problem
- [Hooker 92]: can generalize to get a complete description
- Size:

Finding the convex hull

- If we have a non-integral optimal basic solution to current relaxation, we know that a cutting plane always exists
- But it might be difficult to find
- Interesting Q: is there a general way to find a cutting plane?

Summary so far

- Several improvements on simple search
 - constraint propagation
 - branch & bound
 - cutting planes
- B&B and cuts are very different
 - for a given problem, one can work much better than other
- Can we get best of both?

Branch & cut

$[\text{schema}, \text{value}] = \text{bc}(F, \text{sch}, \text{bnd})$

- repeat until (no cuts added)
 - $[v_{rx}, \text{rsch}] = \text{relax}(F, \text{sch})$
 - if integer(rsch): return $[\text{rsch}, v_{rx}]$
 - if $v_{rx} \geq \text{bnd}$: return $[\text{sch}, v_{rx}]$
 - If desired: $F := F \cup \{\text{new cuts based on rsch}\}$
- ... continue as for branch & bound (try both branches, return better one)

Branch & cut discussion

- Don't always need to solve relaxation to find cuts
 - e.g., on failure in a SAT problem, know a subset of our decisions led to contradiction
- If we find a good cut near leaves of search tree, can sometimes “lift” it to apply to ancestor nodes