

$$v^* = \text{opt}$$

Convex program duality

f, g_i convex

- $\min \underline{\underline{f(x)}}$ s.t.

$$\underline{\underline{Ax = b}}$$

$$\underline{\underline{g_i(x) \leq 0}} \quad i \in I$$

$$g(x) = \begin{pmatrix} g_1(x) \\ g_2(x) \\ \vdots \end{pmatrix}$$

for feasible x

$$\underline{\underline{y^\top (Ax - b) = 0}}$$

$$\underline{\underline{z^\top g(x) \leq 0}} \quad \text{if } z \geq 0$$

$$\underline{\underline{f(x) \geq f(x) + y^\top (Ax - b) + z^\top g(x)}}$$

$$\underline{\underline{= L(x, y, z)}}$$

$$\rightarrow \underline{\underline{v^* = \inf_{\text{feasible } x} f(x) \geq \inf_{\text{feasible } x} L(x, y, z) \geq \inf_x L(x, y, z) \equiv L(y, z)}}$$

$$v^* \geq d^*$$

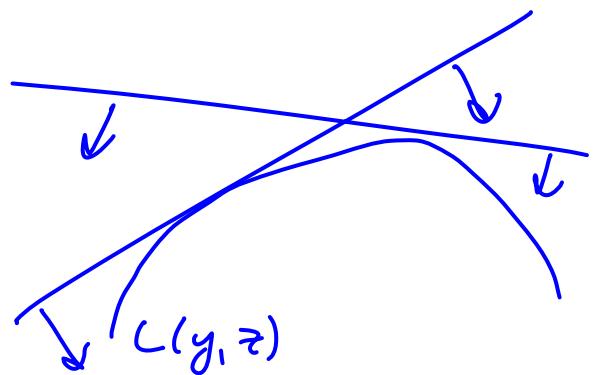
$$\text{Dual prob: } \max \underline{\underline{L(y, z)}} \quad \text{s.t. } \underline{\underline{z \geq 0}}$$

d^* = dual optimal value

$f(x) = \infty$ for $x \notin \text{dom } f$

Properties

- Weak duality $v^* \geq d^*$



- $L(y, z)$ is closed, concave

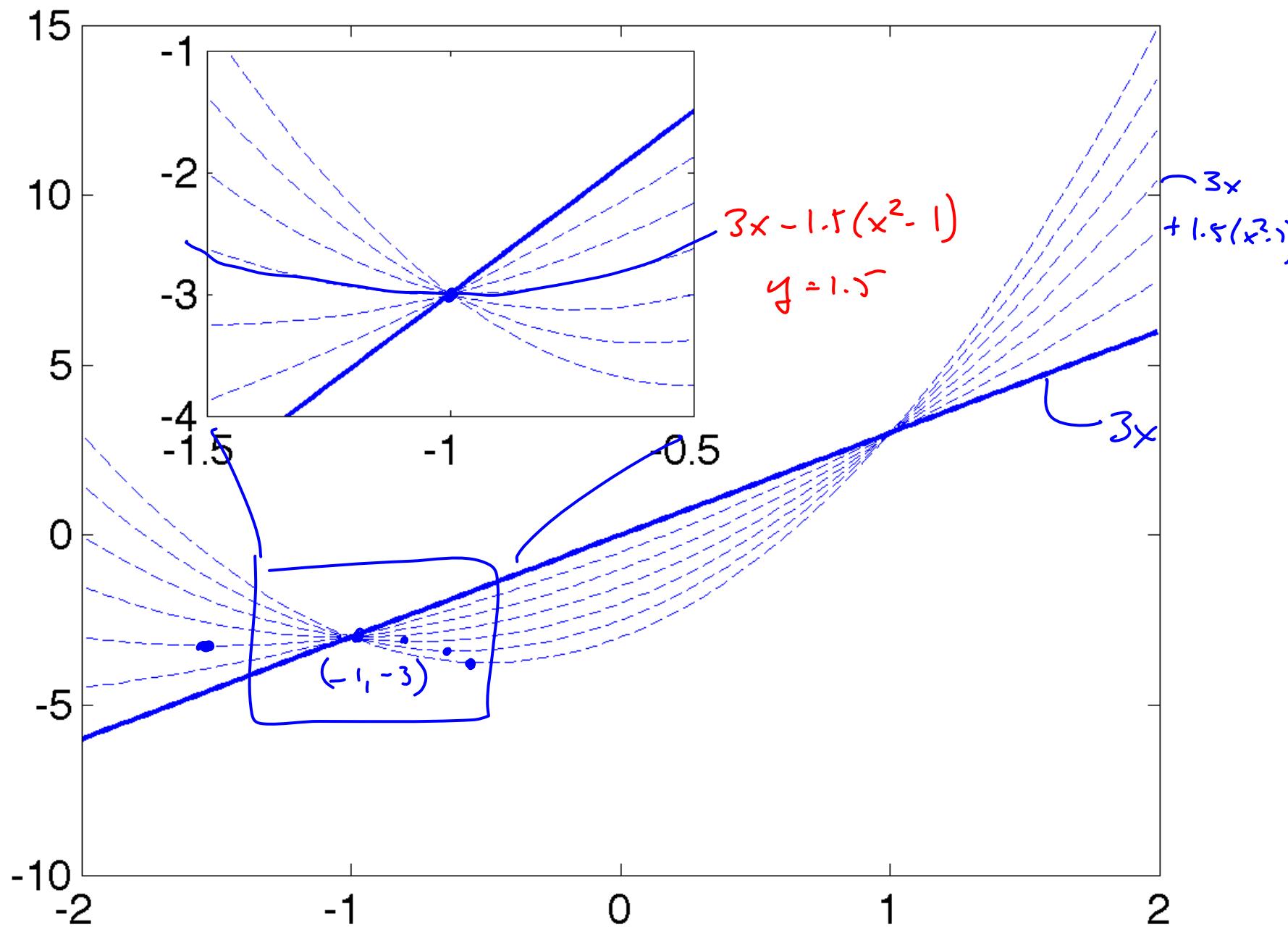
$$L(y, z) = \inf_x (f(x) + y^\top (Ax - b) + z^\top g(x))$$

fixed x : linear fn of y, z

inf of linear fns: $L(y, z)$ concave closed

Duality example

- $\min \underline{3x} \text{ s.t. } \underline{x^2 \leq 1}$
- $L(x, y) = 3x + y(x^2 - 1) \quad y \geq 0$
 \nearrow primal \searrow dual



Dual function

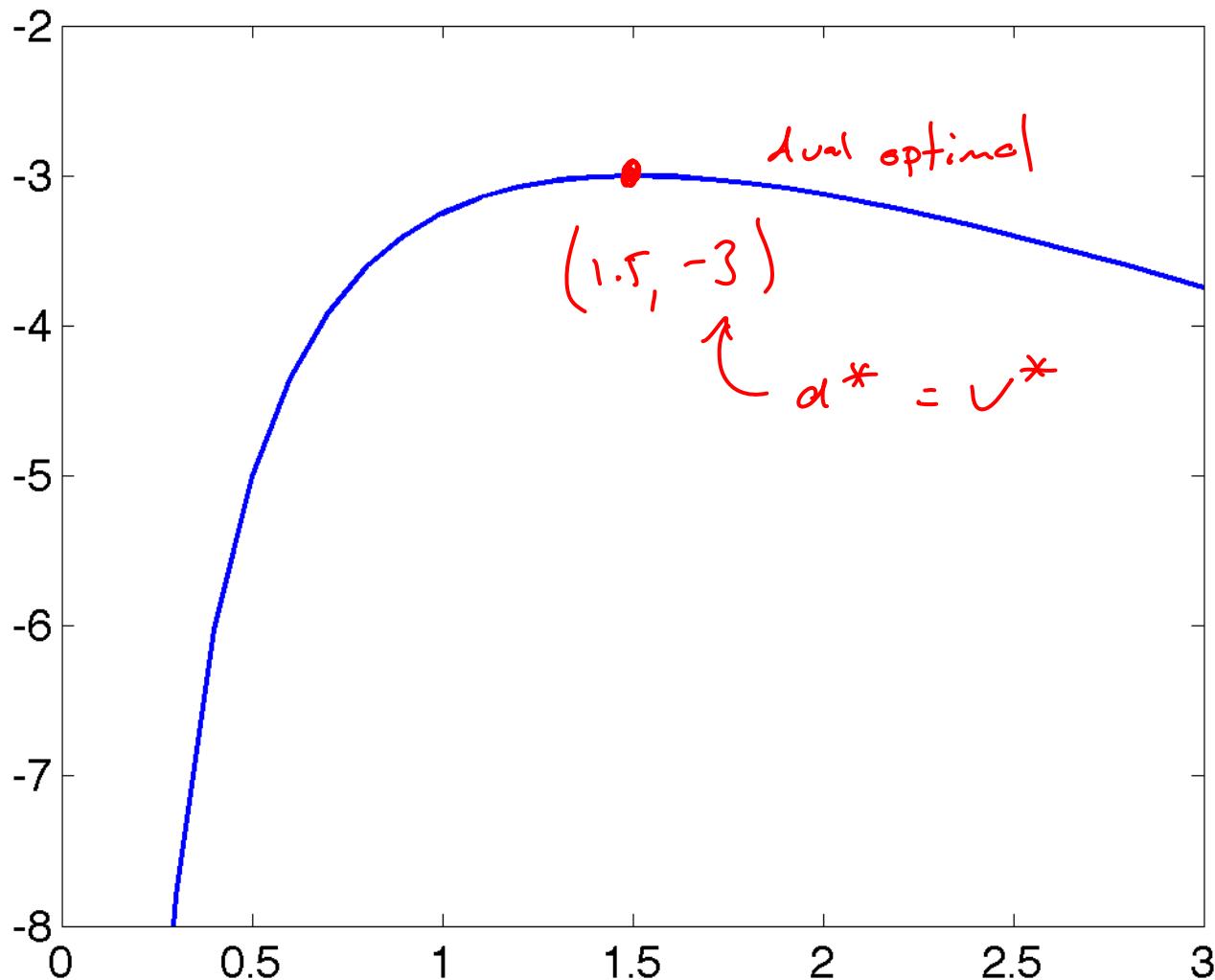
- $L(y) = \inf_x L(x,y) = \inf_x 3x + y(x^2 - 1)$

$$0 = \frac{\partial}{\partial x} = 3 + 2xy$$

$$x = \frac{-3}{2y}$$

$$L(y) = \underbrace{3 \cdot \left(\frac{-3}{2y}\right)}_{-\frac{9}{2y}} + y \left(\frac{9}{4y^2} - 1 \right) = -\frac{9}{4y} - y$$

Dual function



Duality w/ linear constraints

convex f

- $\min \underline{f(x)} \text{ s.t. } \underline{Ax = b}, \underline{Cx \leq d}$
- $L(x, y, z) = f(x) + y^T(Ax - b) + z^T(Cx - d) \quad z \geq 0$
- $L(y, z) = \inf_x [f(x) + x^T(A^T y + C^T z) - b^T y - d^T z]$
~~OPT~~ $\sup_x [-f(x) + \underline{x^T(-A^T y - C^T z)}] = -b^T y - d^T z$
 $f^*(-A^T y - C^T z)$
- Dual problem
 $\max -f^*(-A^T y - C^T z) - b^T y - d^T z \quad \text{s.t. } z \geq 0$

CP duality w/ cone constraints

- $\min \underline{f(x)}$ s.t.

$$g_i(x) = I_K^-(A_i x + b_i) \leq 0$$

$$\rightarrow A_0 x + b_0 = 0$$

$$A_i x + b_i \in K^- \quad i \in I$$

$\forall x \in X$

$$y^\top (A_0 x + b_0) + \sum_i z_i^\top (A_i x + b_i) \geq 0 \quad z_i \in K^{*-}$$

$$x^\top (A_0^\top y + \sum_i A_i^\top z_i) \geq -b_0^\top y - \sum_i b_i^\top z_i$$

$$f(x) \geq \omega^\top x - f^*(\omega)$$

$$f(x) \geq -b_0^\top y - \sum_i b_i^\top z_i - f^*(\omega)$$
- Dual: $\max_y -b_0^\top y - \sum_i b_i^\top z_i - \underline{f^*(A_0^\top y + \sum_i A_i^\top z_i)}$

$$\text{s.t. } z_i \in \underline{K^{*-}}$$

Ex: 2nd order cone program

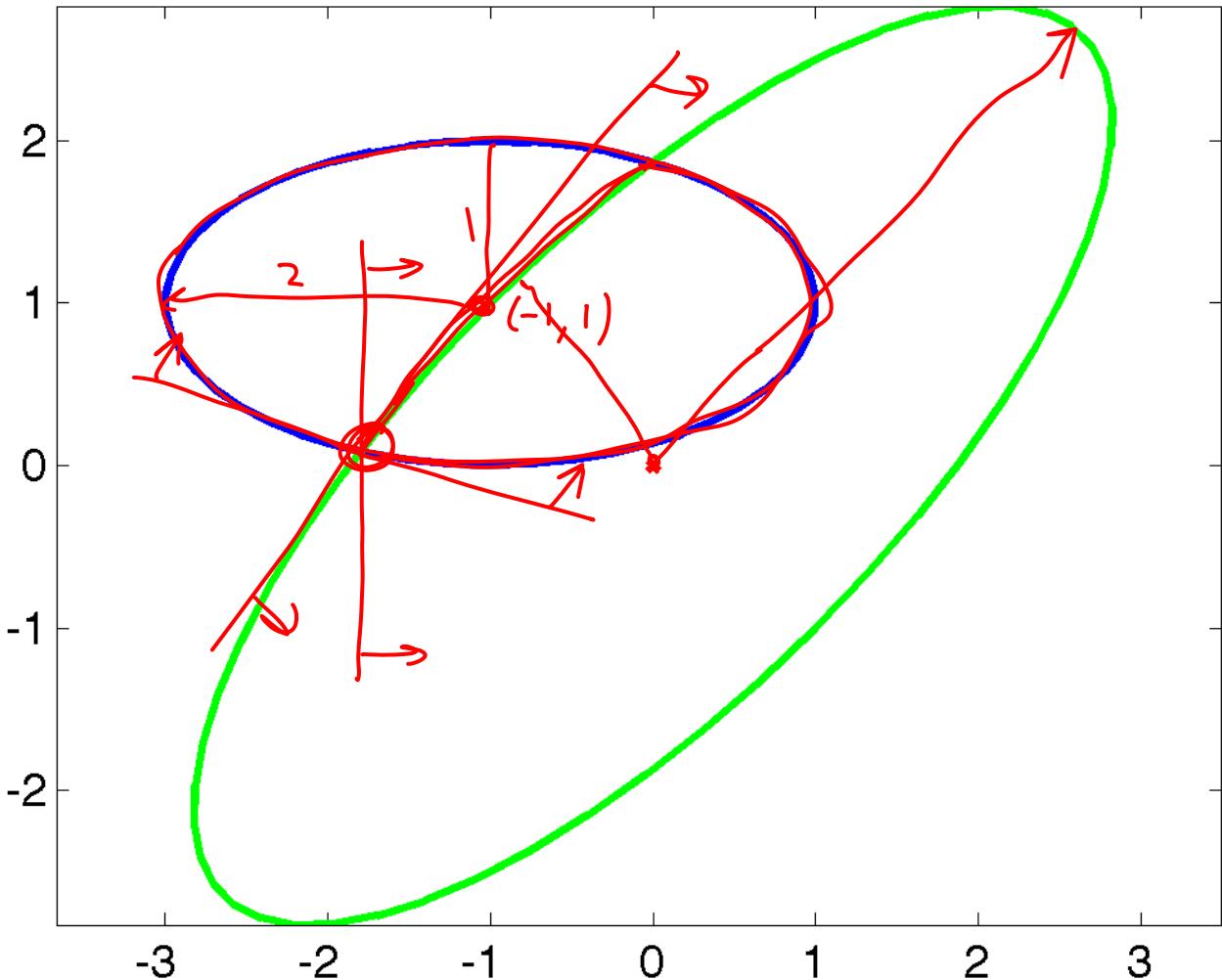
$$A_1 = \begin{pmatrix} \frac{1}{2} & 0 \\ -\frac{1}{2} & 0 \\ 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$K = SOC$ $\min x$

$$b_1 = \begin{pmatrix} +\sqrt{2} \\ -1 \\ 1 \end{pmatrix} \leftarrow \begin{array}{l} x_c = 1 \\ y_c = 1 \end{array}$$

$$A_2 = \begin{pmatrix} \frac{1}{2} & \frac{1}{2} \\ 1 & -1 \\ 0 & 0 \end{pmatrix}$$

$$b_2 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$



Strong duality

- $v^* = \inf_x f(x)$ s.t. $\underline{Ax=b}$, $\underline{g(x) \leq 0}$

$$L(x, y, z) = f(x) + y^\top (Ax - b) + z^\top g(x) \quad \begin{matrix} y \geq 0 \\ z \geq 0 \end{matrix}$$

$$L(y, z) = \inf_x L(x, y, z)$$

- $d^* = \sup_{yz} L(y, z)$ s.t. $\underline{z \geq 0}$

- Strong duality: $v^* = d^*$ (weak duality $v^* \leq d^*$)

- Slater's condition: \Rightarrow strong duality

— f, g_i : convex

— strictly feasible point $\exists x \in \text{rel int dom } f, \quad g(x) < 0$

Slater's condition, part II

- If $g_i(x)$ affine, only need $g_i(x) \leq 0$

Can mix & match:
| \leq for all affine g_i ←
| $<$ for all other g_i ←

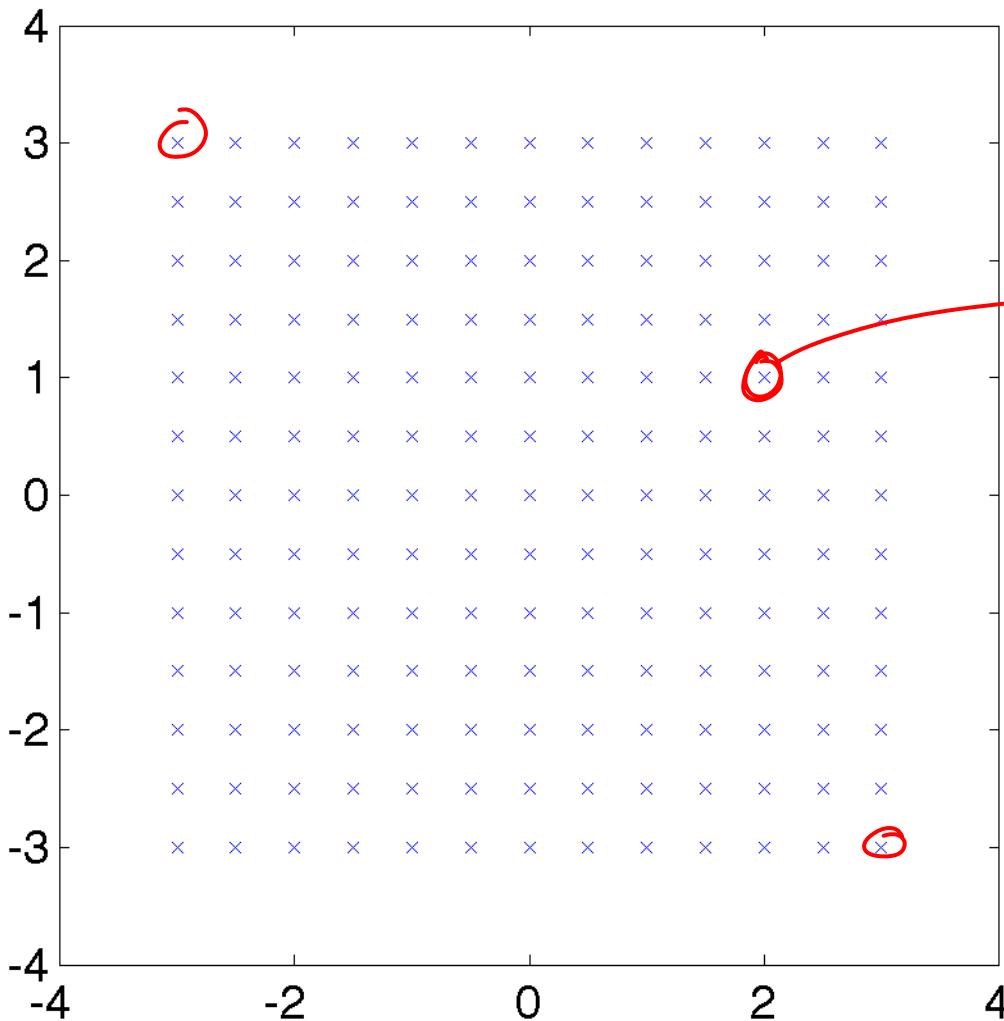
- E.g., for $\inf_x f(x)$ s.t. $Ax = b$, $Cx \leq d$

convex ~~non-empt~~
non-empty domain \Rightarrow strong duality
 $\exists x. \underline{Cx \leq d} \wedge f(x) < \infty \wedge Ax = b$

Slater's condition: sufficient but not necessary for strong duality

$$P \in \mathbb{R}^{1 \times 5} \quad P \geq 0 \quad \sum_i P_i = 1$$

Example: maxent

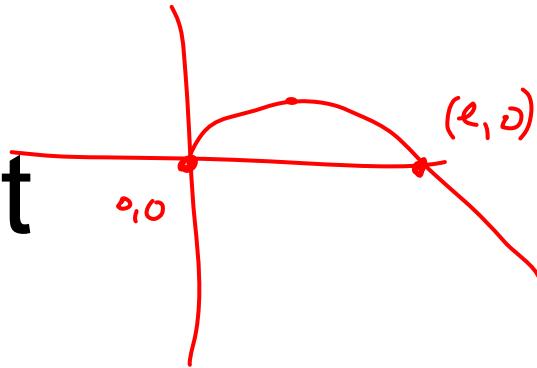


$$T^T P = E_P(t) \quad E_P(t_i) = 1$$

$$t_i = \begin{pmatrix} 1 \\ x \\ y \\ z \\ xy \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \\ 1 \\ 4 \\ -1 \end{pmatrix}$$

$$T = \begin{pmatrix} 1 & -3 & 3 & 9 & 9 & 9 \\ 1 & 2 & 1 & 4 & 1 & 2 \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ 1 & 3 & -3 & 9 & 9 & 9 \end{pmatrix}$$

Example: maxent



- Maxent problem:

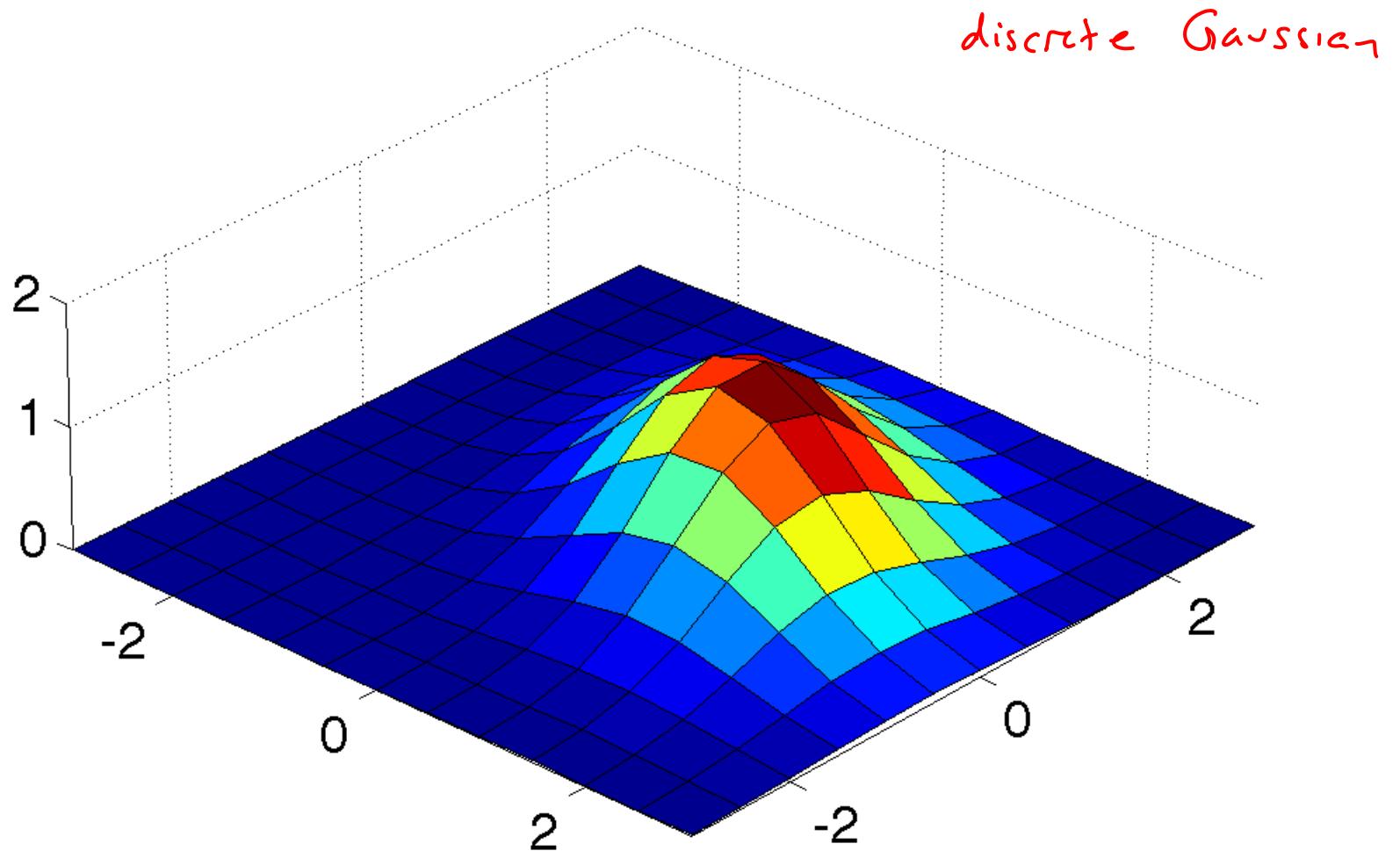
$$\max \underline{H(p)} \text{ s.t. } \underline{T'p = b} = \underline{T^T p_0}$$

$$H(p) = \sum_i (p_i - p_i \ln p_i)$$

$$H'(p) = \frac{dH}{dp_i} = \cancel{1 - p_i \frac{1}{p_i}} - \ln p_i = -\ln p_i \quad H'(p) = -\ln p$$

- Slater's condition: holds \rightarrow ~~assumption~~ p_0

Example of maxent solution



Dual of maxent

- max $H(p)$ s.t. $T^T p = b \Rightarrow T^T p_0$
- $L(\underline{p}, \underline{y}) = \underline{H(p)} + \underline{y^T (T^T p - b)}$ ~~Maximize~~
- $L(y) = \inf_p L(p, y) =$

$$0 = \frac{1}{\lambda p} L(p, y) = -\ln p + T y \Rightarrow p = e^{Ty} \quad \text{exponential family}$$

$$L(y) = 1^T e^{Ty} - (e^{Ty})^T T y + y^T (T^T e^{Ty} - b) = 1^T e^{Ty} - y^T b$$

Dual: $\min \left(1^T e^{Ty} - y^T b \right) = L(y)$

$$\frac{\partial}{\partial y_i} L(y) = 1^T e^{Ty} - b_i = 0 \quad 1^T e^{Ty} = 1$$

Rev. dual. $\min - \underbrace{y^T b}_{\text{const}}$ st. $\frac{1^T e^{Ty}}{1^T e^{Ty}} = 1$

$$p = \exp(Ty) \quad \max \underbrace{y^T T^T p_0}_{\text{const}} = \underbrace{p_0^T \ln p}$$

maximum likelihood
in exponential
family

Is Slater necessary? No

$$A = USU^T \quad A = A^T \quad A \succcurlyeq 0 \quad x \in \mathbb{R}^n$$

\mathbb{R}^{diag}

$$\rightarrow \min_x \underline{x^T A x} + \underline{2b^T x} \quad \text{s.t.} \quad \underline{\|x\|^2 \leq 1}$$

trust region
opt.

$$\text{relax} \quad \min_{X \in \mathbb{R}^{n \times n}} \underline{\text{tr}(X^T A)} - 2b^T x \quad \text{s.t.} \quad X = X^T \quad \text{tr}(X) \leq 1 \quad \begin{pmatrix} X & x \\ x^T & 1 \end{pmatrix} \geq 0$$

$X \geq 0$

$X - x x^T \geq 0$

$$\text{Slater: } X = I_n / 2, \quad x = 0 \quad x^T A x$$

$$\text{Suppose (at opt) } X = x x^T + P \quad \text{if } X = x x^T \quad \text{tr}(X^T A) = x^T A x$$

$$P \geq 0, \quad P \neq 0 \quad \text{tr}(P^T A) = \text{tr}(P^T U S U^T) = \text{tr}(U^T P^T U S) = \text{tr}(Q^T S)$$

$$Q = U P U^T$$

$$\text{hold } x \text{ fixed} \quad \min_Q \text{tr}(Q^T S) \text{ s.t. } \underline{\text{tr}(Q)} \leq 1 - x^T x \quad Q \geq 0$$

$$Q = \begin{pmatrix} Q & 0 \\ 0 & \lambda \end{pmatrix} \Rightarrow P = k u u^T \quad \text{assume wlog } u^T b \leq 0$$

$$x \rightarrow x + \sqrt{k} u; \quad \text{better} \rightarrow \text{contradiction}$$

~~$P \rightarrow 0$~~