



# Convex Functions (cont. 2)

Optimization - 10725

Carlos Guestrin

Carnegie Mellon University

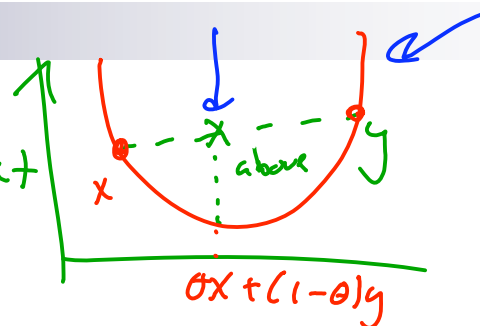
March 5<sup>th</sup>, 2008

# Convex Functions

- Function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$  is convex if

- Domain is convex

- $\forall x, y \in \text{dom } f, \theta \in [0, 1]$



$$f(\theta x + (1-\theta)y) \leq \theta f(x) + (1-\theta)f(y)$$

- Generalization: Jensen's inequality:

prob dist  $x \in \text{convex domain of } f$

$$\underline{f[E(x)]} \leq E_x[f(x)]$$

useful in ML

e.g., EM

- Strictly convex function:

$\forall x, y \in \text{dom } f, \theta \in (0, 1)$   
 $x \neq y$

e.g.,  $\cup$

convex  
non-strict

$$f(\theta x + (1-\theta)y) < \theta f(x) + (1-\theta)f(y)$$

# Operations that preserve convexity

- Many operations preserve convexity

- Knowing them will make your life much easier when you want to show that something is convex
- Examples in next few slides

- Simplest: Non-negative weighted sum:

- $f = \sum_i w_i f_i \quad w_i \geq 0$
- If all  $f_i$ 's are convex, then  $f$  is convex
- If all  $f_i$ 's are concave, then  $f$  is concave

- Example: integral of  $f(x,y)$  convex in  $x$

$$g(x) = \int_{y \in C} f(x,y) dy \quad \rightarrow \text{convex}$$

- Affine mapping:  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $A \in \mathbb{R}^{n \times m}$ ,  $b \in \mathbb{R}^m$

- $g(x) = f(Ax+b)$

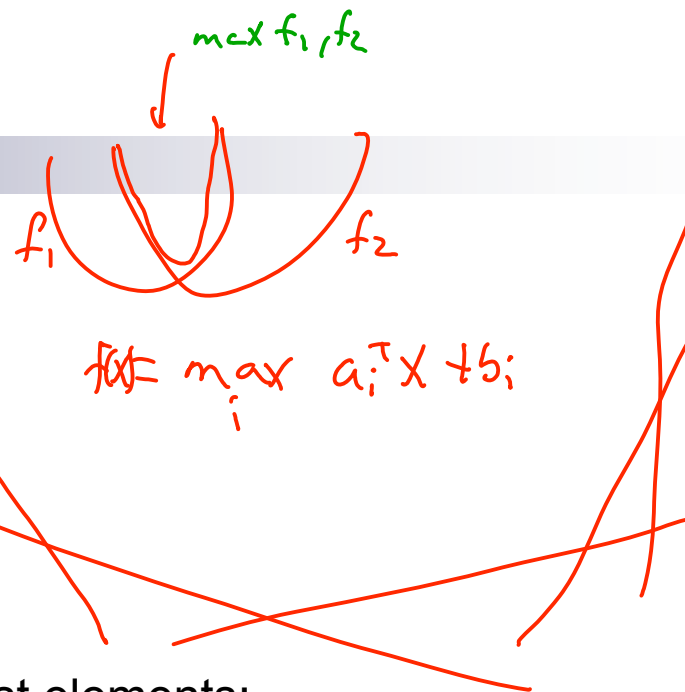
e.g.,  $A, b$  come from PCA

- $\text{dom } g = \{x \mid Ax+b \in \text{dom } f\} \leftarrow \text{always convex if } \text{dom } f \text{ convex}$
- If  $f$  is convex, then  $g$  is convex
- If  $f$  is concave, then  $g$  is concave

# Pointwise maximum and supremum

- If  $f_i$ 's are convex, then  

$$f(x) = \max_i f_i(x)$$
- Piecewise linear convex functions:
  - Fundamental for POMDPs



- For  $x$  in a convex set  $C$ , sum of the  $r$  largest elements:

- Sort  $x$ , pick  $r$  largest components, sum them: 
$$f(x) = \left\{ \sum_{i=1}^r x_{\ell_i} \mid x_{\ell_1} \geq x_{\ell_2} \geq \dots \geq x_{\ell_n} \right\}$$

$\max_{\text{of}} \binom{n}{r}$  different functions 
$$f(x) = \max_{A \subseteq \{1, \dots, n\} \mid |A|=r} x_{A_1} + x_{A_2} + \dots + x_{A_r}$$

- Maximum eigenvalue of symmetric matrix  $X \in \mathbb{R}^{n \times n}$ ,  $f: \mathbb{R}^{n \times n} \rightarrow \mathbb{R}$

- $f(X) = \max_{V, \|V\|_2=1} V^T X V$   
 $\nwarrow$  max of linear functions of  $X$

# Pointwise maximum of affine functions: general representation

- We saw: convex set can be written as intersection of (infinitely many) hyperplanes:
  - $C$  convex, then
  
- Convex functions can be written as supremum of (infinitely many) lower bounding hyperplanes:
  - $f$  convex function, then

# Composition: scalar differentiable, real domain case

- How do I prove convexity of log-sum-exp-positive-weighted-sum-monomials? :)
  -
- If  $h: \mathbb{R}^k \rightarrow \mathbb{R}$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ , when is  $f(x) = h(g(x))$  convex (concave)?
  - $\text{dom } f = \{x \in \text{dom } g \mid g(x) \in \text{dom } h\}$
- Simple case:  $h: \mathbb{R} \rightarrow \mathbb{R}$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $\text{dom } g = \text{dom } h = \mathbb{R}$ ,  $g$  and  $h$  differentiable
  - E.g.,  $g(x) = x^T \Sigma x$ ,  $\Sigma$  psd,  $h(y) = e^y$
- Second derivative:
  - $f''(x) = h''(g(x))g'(x)^2 + h'(g(x))g''(x)$ 
    - When is  $f''(x) \geq 0$  (or  $f''(x) \leq 0$ ) for all  $x$ ?
- Example of sufficient (but not necessary) conditions:
  - $f$  convex if  $h$  is convex and nondecreasing and  $g$  is convex
  - $f$  convex if  $h$  is convex and nonincreasing and  $g$  is concave
  - $f$  concave if  $h$  is concave and nondecreasing and  $g$  is concave
  - $f$  concave if  $h$  is concave and nonincreasing and  $g$  is convex

# Composition: scalar, general case

- If  $h: \mathbb{R}^k \rightarrow \mathbb{R}$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ , when is  $f(x) = h(g(x))$  convex (concave)?
  - $\text{dom } f = \{x \in \text{dom } g \mid g(x) \in \text{dom } h\}$
- Simple case:  $h: \mathbb{R} \rightarrow \mathbb{R}$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}$ , general domain and non-differentiable
  - Example of sufficient (but not necessary) conditions:
    - $f$  convex if  $h$  is convex and  $\tilde{h}$  nondecreasing and  $g$  is convex
    - $f$  convex if  $h$  is convex and  $\tilde{h}$  nonincreasing and  $g$  is concave
    - $f$  concave if  $h$  is concave and  $\tilde{h}$  nondecreasing and  $g$  is concave
    - $f$  concave if  $h$  is concave and  $\tilde{h}$  nonincreasing and  $g$  is convex
- nondecreasing or nonincreasing condition on extend value extension of  $h$  is fundamental
  - counter example in the book if nondecreasing property holds for  $h$  but not for  $\tilde{h}$ , the composition no longer convex
  - If  $h(x) = x^{3/2}$  with  $\text{dom } h = \mathbb{R}_+$ , convex but extension is not nondecreasing
  - If  $h(x) = x^{3/2}$  for  $x \geq 0$ , and  $h(x) = 0$  for  $x < 0$ ,  $\text{dom } h = \mathbb{R}$ , convex and extension is nondecreasing

# Vector composition: differentiable

- If  $h: \mathbb{R}^k \rightarrow \mathbb{R}$  and  $g: \mathbb{R}^n \rightarrow \mathbb{R}^k$ , when is  $f(x) = h(g(x))$  convex (concave)?
  - $\text{dom } f = \{x \in \text{dom } g \mid g(x) \in \text{dom } h\}$
- Focus on  $f(x) = h(g(x)) = h(g_1(x), g_2(x), \dots, g_k(x))$
- Second derivative:
  - $f''(x) = g'(x)^T \nabla^2 h(g(x)) g'(x) + \nabla h(g(x)) g''(x)$ 
    - When is  $f''(x) \geq 0$  (or  $f''(x) \leq 0$ ) for all  $x$ ?
- Example of sufficient (but not necessary) conditions:
  - $f$  convex if  $h$  is convex and nondecreasing in each argument, and  $g_i$  are convex
  - $f$  convex if  $h$  is convex and nonincreasing in each argument, and  $g_i$  are concave
  - $f$  concave if  $h$  is concave and nondecreasing in each argument, and  $g_i$  are concave
  - $f$  concave if  $h$  is concave and nonincreasing in each argument, and  $g_i$  are convex
- Back to log-sum-exp-positive-weighted-sum-monomials
  - 
  - $\text{dom } f = \mathbb{R}_{++}^n, c_i > 0, a_i \geq 1$
  - log sum exp convex



# Minimization

- If  $f(x,y)$  is convex in  $(x,y)$  and  $C$  is a convex set, then:
- Norm is convex:  $\|x-y\|$ 
  - minimum distance to a set  $C$  is convex:

# Perspective function

- If  $f$  is convex (concave), then the perspective of  $f$  is convex (concave):
  - $t > 0, g(x, t) = t f(x/t)$
- KL divergence:
  - $f(x) = -\log x$  is convex
  - Take the perspective:
  - Sum over many pairs  $(x_i, t_i)$

# Quasiconvex functions

- Unimodal functions are not always convex
- But they are (usually) still easy to optimize: Quasiconvex function:
  - All sublevel sets are convex, for all  $\alpha \in \mathbb{R}$ :
- Equivalent definition: max of extremes is higher than function
- Applications include computer vision (geometric reconstruction) [Ke & Kanade '05]

# Log-convex functions

- Function  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ , with  $f(x) > 0$  in all (convex) **dom**  $f$ 
  - $f$  log-convex if and only if:
- Or equivalently:
- Examples
  - Gaussian  $f(x) = \frac{1}{\sqrt{(2\pi)^n \det \Sigma}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$

# What should you know: Convex fns

- definition
- showing that a function is convex/concave
  - first principle
  - first and second order condition
  - epigraph
  - operations that preserve convexity
- quasiconvexity
- log-convexity