## Parameter and Structure Learning

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## Overview

- Parameter Learning
  - Classical view, estimation task
  - Estimators, properties of estimators
  - MLE, why MLE?
  - MLE in BNs, decomposability

- Structure Learning
  - Structure score, decomposable scores
  - TAN, Chow-Liu
  - HW2 implementation steps

## Note

- Plagiarism alert
  - Some slides taken from others
  - Credits/references at the end

#### Coin Toss

**Data:**  $\mathcal{D} = (HTHHHTT...)$ 

Parameters:  $\theta \stackrel{\text{def}}{=}$  Probability of heads

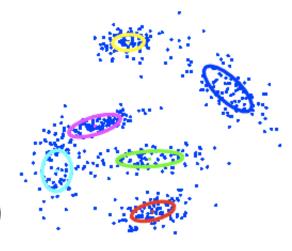
$$P(H|\theta) = \theta$$
$$P(T|\theta) = 1 - \theta$$

**Goal:** To infer  $\theta$  from the data and predict future outcomes  $P(H|\mathcal{D})$ .

# Clustering with Gaussian Mixtures (Density Estimation)

Data: 
$$\mathcal{D} = \{\mathbf{x}^{(n)}\}$$
 for  $n=1,\ldots,N$  
$$\mathbf{x}^{(n)} \in \mathbb{R}^D$$

Parameters:  $\boldsymbol{\theta} = \left( (\mu^{(1)}, \Sigma^{(1)}) \dots, (\mu^{(m)}, \Sigma^{(m)}), \boldsymbol{\pi} \right)$ 



Model:

$$\mathbf{x}^{(n)} \sim \sum_{i=1}^{m} \pi_i \, p_i(\mathbf{x}^{(n)})$$

where

$$p_i(\mathbf{x}^{(n)}) = \mathcal{N}(\boldsymbol{\mu}^{(i)}, \boldsymbol{\Sigma}^{(i)})$$

**Goal:** To infer  $\theta$  from the data and predict the density  $p(\mathbf{x}|\mathcal{D}, m)$ 

## Parameter Learning

- Classical statistics view / Point Estimation
  - Parameters unknown but not random
  - Point estimation = "find the right parameter"
  - Estimate parameters (or functions of parameters) of the model from data
- Estimators
  - Any statistic
  - Function of data alone
- Say you have a dataset  $\mathcal{D} = \{\mathbf{x}^{(n)}\}$ 
  - Need to estimate mean
  - Is  $\hat{\mu} = 5$ , an estimator?
  - What would you do?

#### Properties of estimator

- Since estimator gives rise an estimate that depends on sample points (x1,x2,,,xn) estimate is a function of sample points.
- Sample points are random variable therefore estimate is random variable and has probability distribution.
- We want that estimator to have several desirable properties like
  - Consistency
  - Unbiasedness
  - Minimum variance
- In general it is not possible for an estimator to have all these properties.

# A General MLE strategy

Suppose  $\theta = (\theta_1, \theta_2, ..., \theta_n)^T$  is a vector of parameters.

Task: Find MLE  $\theta$  assuming known form for p(Data|  $\theta$ ,stuff)

- Write LL = log P(Data | θ,stuff)
- Work out ∂LL/∂θ using high-school calculus
- 3. Solve the set of simultaneous equations

$$\frac{\partial LL}{\partial \theta_1} = 0$$

$$\frac{\partial LL}{\partial \theta_2} = 0$$
4. Check that you're at a maximum
$$\frac{\partial LL}{\partial \Omega} = 0$$

# The MLE μ

$$\mu^{mle} = \arg\max_{\mu} p(x_1, x_2, ... x_R \mid \mu, \sigma^2)$$

$$= \arg\min_{\mu} \sum_{i=1}^R (x_i - \mu)^2$$

$$= \mu \text{ s.t. } 0 = \frac{\partial LL}{\partial \mu} = \frac{\partial}{\partial \mu} \sum_{i=1}^R (x_i - \mu)^2$$

$$- \sum_{i=1}^R 2(x_i - \mu)$$
Thus  $\mu = \frac{1}{R} \sum_{i=1}^R x_i$ 

## **Unbiased Estimators**

- An estimator of a parameter is unbiased if the expected value of the estimate is the same as the true value of the parameters.
- If  $X_1, X_2, ... X_R \sim (i.i.d) N(\mu, \sigma^2)$  then

$$E[\mu^{mle}] = E\left[\frac{1}{R}\sum_{i=1}^{R}x_i\right] = \mu$$

 $\mu^{m/e}$  is unbiased

## Biased Estimators

- An estimator of a parameter is biased if the expected value of the estimate is different from the true value of the parameters.
- If  $X_1, X_2, ... X_R \sim (i.i.d) N(\mu, \sigma^2)$  then

$$E\left[\sigma_{mle}^{2}\right] = E\left[\frac{1}{R}\sum_{i=1}^{R}(x_{i} - \mu^{mle})^{2}\right] = E\left|\frac{1}{R}\left(\sum_{i=1}^{R}x_{i} - \frac{1}{R}\sum_{j=1}^{R}x_{j}\right)^{2}\right| \neq \sigma^{2}$$

 $\sigma^2_{mle}$  is biased

## So why MLE?

- MLE has some nice properties
  - MLEs are often simple and easy to compute.
  - MLEs have asymptotic optimality properties (consistency and efficiency).
  - MLEs are invariant under reparameterization.
  - and more...

## Let's try

#### 5 [10 pts] ML and MAP Estimation

Recall the probability mass function for a Poisson distribution:

$$p(x|\theta) = \frac{\theta^x e^{\theta}}{x!}$$

#### $5.1 \quad [2 \text{ pts}]$

Derive the maximum likelihood estimate of  $\theta$ .

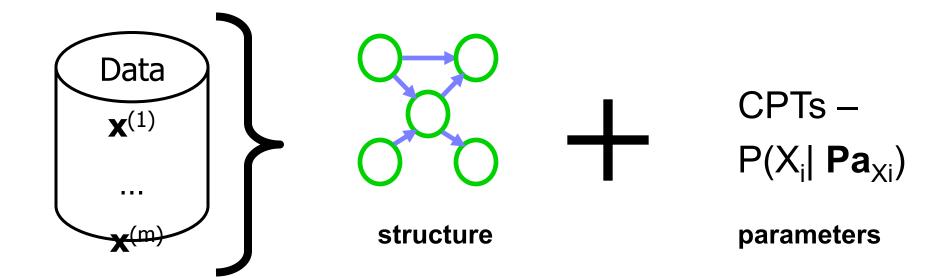
#### 5.2 [4 pts]

Prove that the maximum likelihood estimate is invariant to any 1-1 reparameterization of  $\theta$ . That is, given an invertible function  $f(\mu) = \theta$  which yields the reparametrized distribution  $p(x|f(\mu)) = p(x|\theta)$ , prove that the maximum likelihood estimates of  $\mu$  and  $\theta$  satisfy,

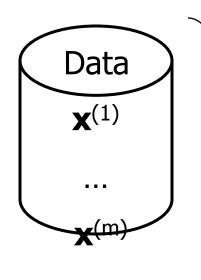
$$f(\hat{\mu}) = \hat{\theta}$$

#### Back to BNs

- MLE in BN
  - Data
  - Model DAG G
  - Parameters CPTs
  - Learn parameters from data



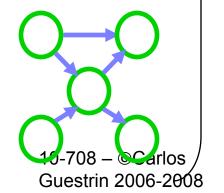
## Learning the CPTs



For each discrete variable  $X_i$   $Pax_i = 0$ 

$$\widehat{P}_{nlf}(x_{i}|U) = Count(X_{i}=x_{i}, U=u)$$

$$Count(U=u)$$

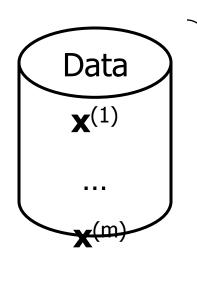


MLE:  $P(X_i = x_i \mid X_j = x_j) = \frac{\text{Count}(X_i = x_i, X_j = x_j)}{\text{Count}(X_i = x_j)}$ 

# Example

Learning MLE parameters

## Learning the CPTs



For each discrete variable  $X_i$   $P_{ax} := 0$ 

$$\hat{P}_{nlf}(x_i|U) = Count(X_i = x_i, U = u)$$
(ount(U = u)

Why??

MLE:  $P(X_i = x_i \mid X_j = x_j) = \frac{\text{Count}(X_i = x_i, X_j = x_j)}{\text{Count}(X_j = x_j)}$ 

# Maximum likelihood estimation (MLE) of BN parameters – example

Given structure, log likelihood of data:

• Given structure, log likelihood of data:

$$\log P(\mathcal{D} \mid \theta_{G}, \mathcal{G}) = \log \prod_{j=1}^{\infty} \frac{P(x^{(j)} \mid \theta_{G}, G)}{P(x^{(j)} \mid \theta_{G}, G)} = \sum_{j=1}^{\infty} \log P(x^{(j)} \mid \theta_{G}, G) P(x^{(j)} \mid \theta_{G}, G) P(x^{(j)} \mid \theta_{G}, G) P(x^{(j)} \mid x^{(j)} \mid x^{(j)}$$

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## Decomposability

Likelihood Decomposition

$$L(\theta : \mathcal{D}) = \prod_{m} P_{\mathcal{G}}(\xi[m] : \theta)$$

$$= \prod_{m} \prod_{i} P(x_{i}[m] \mid \mathbf{pa}_{i}[m] : \theta)$$

$$= \prod_{i} \left[ \prod_{m} P(x_{i}[m] \mid \mathbf{pa}_{i}[m] : \theta) \right]$$

$$L(\theta : \mathcal{D}) = \prod_{i} L_i(\theta_{X_t | \mathbf{Pa}_t} : \mathcal{D}),$$

Local likelihood function

$$L_i(\theta_{X_i|\mathbf{Pa}_i}:\mathcal{D}) = \prod P(x_i[m] \mid \mathbf{pa}_i[m]:\theta_{X_i|\mathbf{Pa}_i}).$$

What's the difference?

Global parameter independence!

# Taking derivatives of MLE of BN parameters – General case

$$\log P(\mathcal{D} \mid \theta_{\mathcal{G}}, \mathcal{G}) = \sum_{j=1}^{m} \sum_{i=1}^{n} \log P\left(X_{i} = x_{i}^{(j)} \mid \mathbf{Pa}_{X_{i}} = \mathbf{x}^{(j)} \left[\mathbf{Pa}_{X_{i}}\right]\right)$$

$$P(X_{i} = x_{i} \mid Pa_{X_{i}} = \mathbf{U}) = \Theta_{X_{i} = X_{i}} \mid Pa_{X_{i}} = \mathbf{U} = \Theta_{X_{i} \mid \mathbf{U}}$$

$$\frac{\partial}{\partial \Theta_{X_{i} \mid \mathbf{U}}} \log P(\mathbf{D} \mid \Theta_{G_{i}} G) = \sum_{k=1}^{n} \sum_{j=1}^{n} \frac{\partial}{\partial \Theta_{X_{i} \mid \mathbf{U}}} \log P(X_{k} = x_{k}^{(i)} \mid Pa_{X_{k}} = x_{k$$

## Structure Learning

- Constraint Based
  - Check independences, learn PDAG
  - HW1

- Score Based
  - Give a score for all possible structures
  - Maximize score

- What's a good score function?
- How about our old friend, log likelihood?

$$\begin{aligned} \max_{\mathcal{G},\pmb{\theta}_{\mathcal{G}}} L(\langle \mathcal{G},\pmb{\theta}_{\mathcal{G}} \rangle : \mathcal{D}) &= & \max_{\mathcal{G}} [\max_{\pmb{\theta}_{\mathcal{G}}} L(\langle \mathcal{G},\pmb{\theta}_{\mathcal{G}} \rangle : \mathcal{D})] \\ &= & \max_{\mathcal{G}} [L(\langle \mathcal{G},\hat{\pmb{\theta}}_{\mathcal{G}} \rangle : \mathcal{D})] \end{aligned}$$

So here's our score function:

$$\mathrm{score}_L(\mathcal{G}\ :\ \mathcal{D}) = \ell(\langle \mathcal{G}, \hat{\boldsymbol{\theta}}_{\mathcal{G}} \rangle : \mathcal{D})$$

- [Defn]: Decomposable scores
- Why do we care about decomposable scores?
- Log likelihood based score decomposes!

$$\operatorname{score}_{L}(\mathcal{G} : \mathcal{D}) = M \sum_{i=1}^{n} \mathbf{I}_{\hat{P}}(X_{i}; \operatorname{Pa}_{X_{i}}^{\mathcal{G}}) - M \sum_{i=1}^{n} \mathbf{H}_{\hat{P}}(X_{i})$$

Need regularization

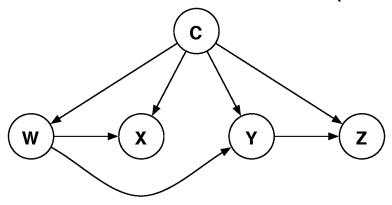
#### Chow-Liu

1. Compute  $I_{\hat{P}_D}(X_i; X_j)$  between each pair of variables,  $i \neq j$ , where

$$I_P(\mathbf{X}; \mathbf{Y}) = \sum_{\mathbf{x}, \mathbf{y}} P(\mathbf{x}, \mathbf{y}) \log \frac{P(\mathbf{x}, \mathbf{y})}{P(\mathbf{x})P(\mathbf{y})}$$

- 2. Build a complete undirected graph in which the vertices are the variables in  $\mathbf{X}$ . Annotate the weight of an edge connecting  $X_i$  to  $X_j$  by  $I_{\hat{P}_D}(X_i; X_j)$ .
- 3. Build a maximum weighted spanning tree.
- 4. Transform the resulting undirected tree to a directed one by choosing a root variable and setting the direction of all edges to be outward from it.

Chow-Liu modification for TAN (HW2)



- 1. Compute  $I_{\hat{P}_D}(A_i; A_j \mid C)$  between each pair of attributes,  $i \neq j$ .
- 2. Build a complete undirected graph in which the vertices are the attributes  $A_1, \ldots, A_n$ . Annotate the weight of an edge connecting  $A_i$  to  $A_j$  by  $I_{\hat{P}_D}(A_i; A_j \mid C)$ .
- 3. Build a maximum weighted spanning tree.
- 4. Transform the resulting undirected tree to a directed one by choosing a root variable and setting the direction of all edges to be outward from it.
- 5. Construct a TAN model by adding a vertex labeled by C and adding an arc from C to each  $A_i$ .

#### Slide and other credits

- Zoubin Ghahramani, guest lectures in 10-702
- Andrew Moore tutorial
  - http://www.autonlab.org/tutorials/mle.html
- http://cnx.org/content/m11446/latest/
- Lecture slides by Carlos Guestrin