

Variable Elimination

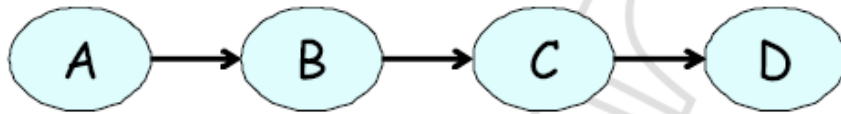
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10-708 Recitation
10/16/2008

Overview

- Variable Elimination
 - Example on chain networks
 - Intuition
 - Tools for VE, factor product, marginalization
 - Implementation hints

Chain Networks

- BN:



- Goal: Need all marginals $P(X)$

Chain Networks

- Naïve solution

$$\begin{array}{l}
 P(a^1) \quad P(b^1 | a^1) \quad P(c^1 | b^1) \quad P(d^1 | c^1) \\
 + P(a^2) \quad P(b^1 | a^2) \quad P(c^1 | b^1) \quad P(d^1 | c^1) \\
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 \end{array}$$

Chain Networks

- A little smarter solution: Phased Computation

$$P(B) = \sum_a P(a)P(B | a).$$
$$P(C) = \sum_b P(b)P(C | b).$$

- General Chains:

$$P(X_{i+1}) = \sum_{x_i} P(X_{i+1} | x_i)P(x_i)$$

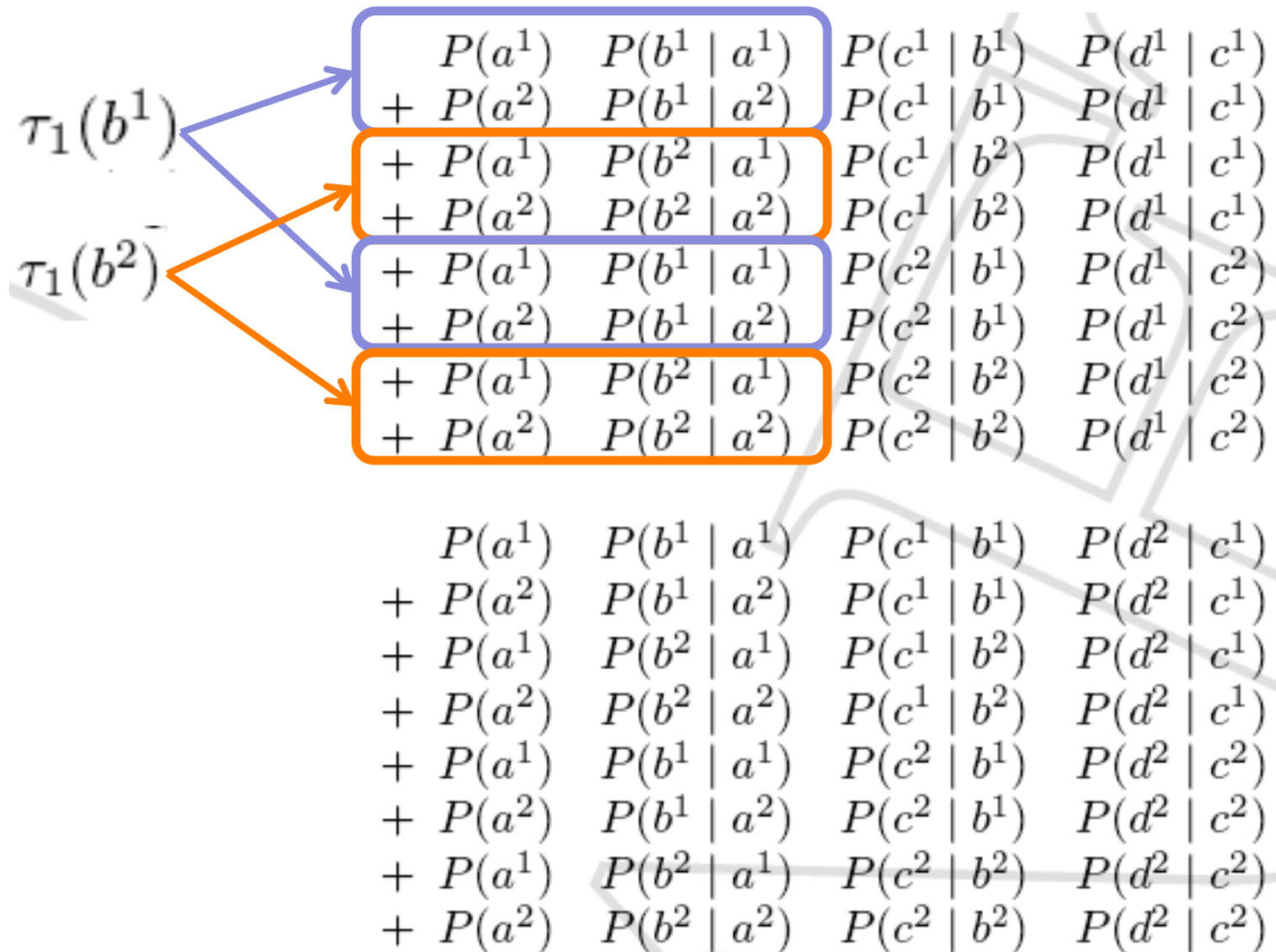
- Why is this better?

$$O(nk^2) \quad \text{vs} \quad O(k^n)$$

- What's the intuition?

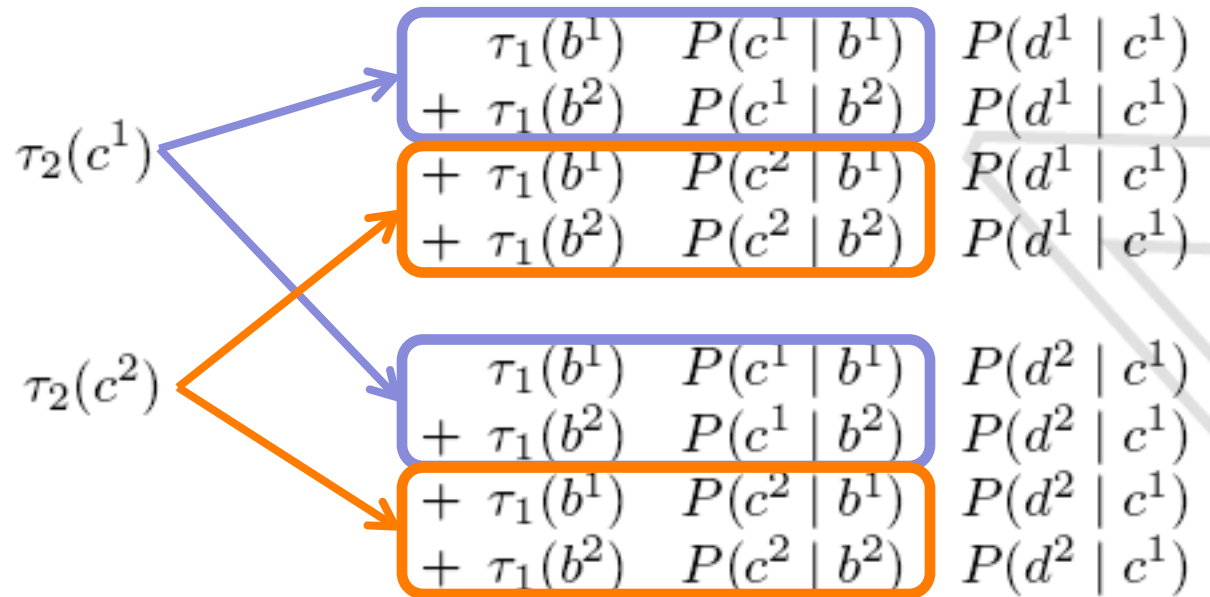
Chain Networks

- A lot of structure



Chain Networks

- Let's cache



Chain Networks

- Let's cache again

$$\begin{aligned} & \tau_2(c^1) P(d^1 | c^1) \\ + & \tau_2(c^2) P(d^1 | c^2) \end{aligned}$$

$$\begin{aligned} & \tau_2(c^1) P(d^2 | c^1) \\ + & \tau_2(c^2) P(d^2 | c^2) \end{aligned}$$

$$\begin{aligned} \tau_2(c^1) &= \tau_1(b^1)P(c^1 | b^1) + \tau_1(b^2)P(c^1 | b^2) \\ \tau_2(c^2) &= \tau_1(b^1)P(c^2 | b^1) + \tau_1(b^2)P(c^2 | b^2) \end{aligned}$$

Chain Networks

- Intuitions from this process
 - Group common things/terms/factors based on scope
 - Dynamic programming ideas: cache computations
- VE extends/formalizes these intuitions to general graphs
 - but separates the elimination ordering from the process

Another Idea

- A commonly used idea

- Goal $P(Y | E = e) = \frac{P(Y, e)}{P(e)}$

$$P(y, e) = \sum_w P(y, e, w).$$

$$P(e) = \sum_y P(y, e)$$

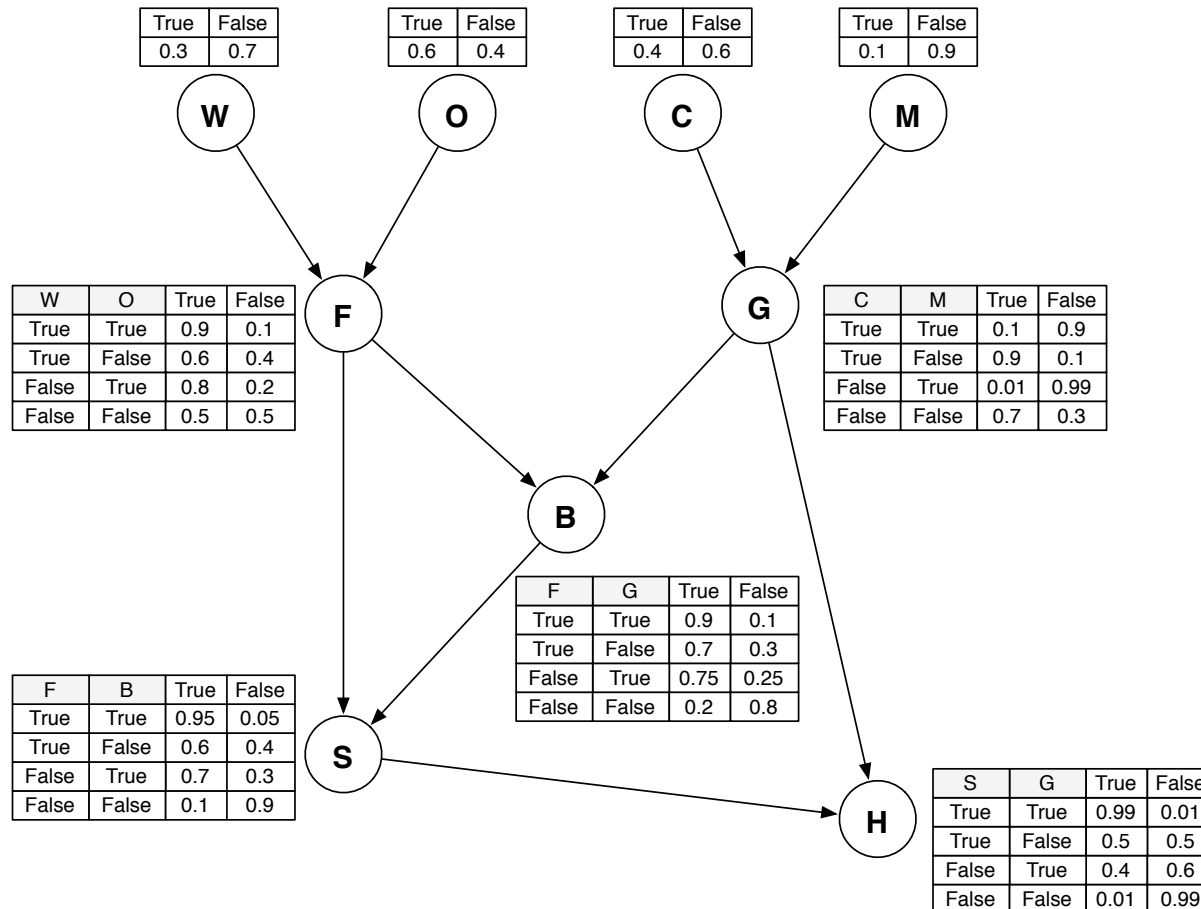
- Can forget about denominator; just renormalize when done

Example

- Let's do an example for general graphs

$$P(S = T | C = T) = ?$$

$$P(F = T | G = T)$$

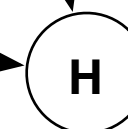
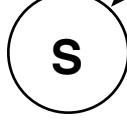
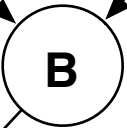
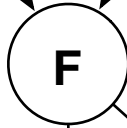
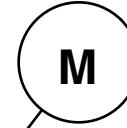
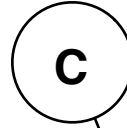
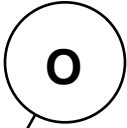


True	False
0.3	0.7

True	False
0.6	0.4

True	False
0.4	0.6

True	False
0.1	0.9



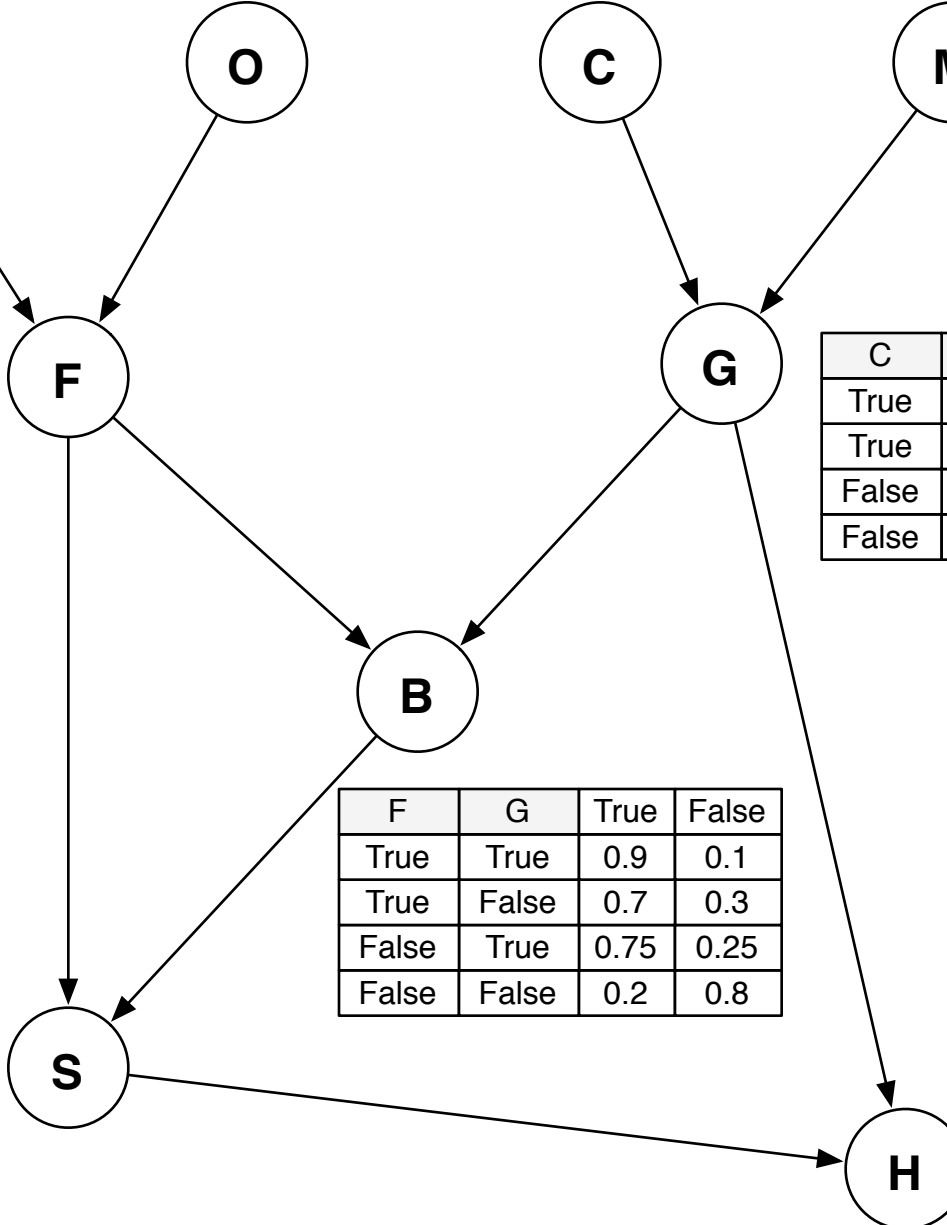
W	O	True	False
True	True	0.9	0.1
True	False	0.6	0.4
False	True	0.8	0.2
False	False	0.5	0.5

C	M	True	False
True	True	0.1	0.9
True	False	0.9	0.1
False	True	0.01	0.99
False	False	0.7	0.3

F	G	True	False
True	True	0.9	0.1
True	False	0.7	0.3
False	True	0.75	0.25
False	False	0.2	0.8

F	B	True	False
True	True	0.95	0.05
True	False	0.6	0.4
False	True	0.7	0.3
False	False	0.1	0.9

S	G	True	False
True	True	0.99	0.01
True	False	0.5	0.5
False	True	0.4	0.6
False	False	0.01	0.99



Implementing VE

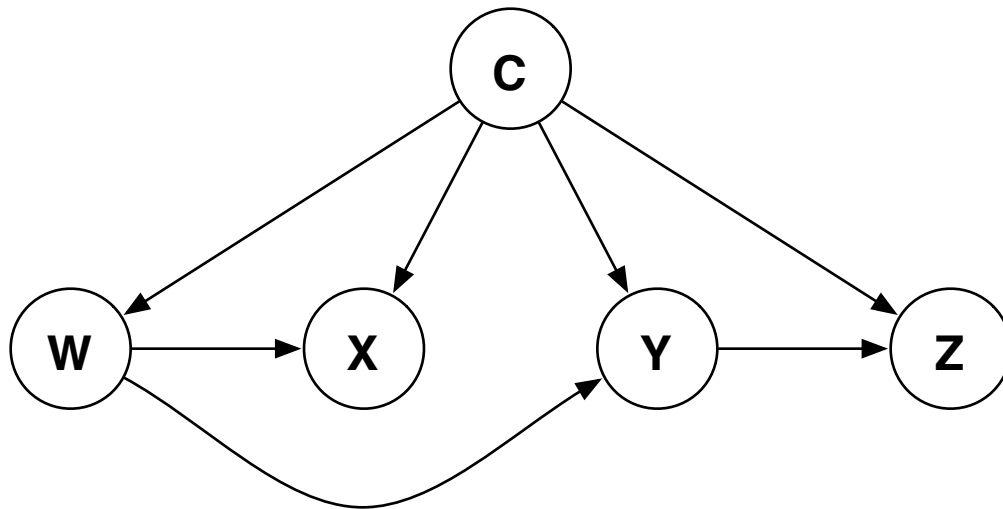
- What do you need to implement VE?
 - Reuse some code from HW2

Tools for VE

- Factors

$$\pi_1[A, B] : Val(A, B) \mapsto \mathbb{R}^+$$

- Special kind of factors: CPTs



Operations on Factors

- Factor Product

- Consider two factors

$$\phi_1(\mathbf{X}, \mathbf{Y}) \text{ and } \phi_2(\mathbf{Y}, \mathbf{Z})$$

- Define factor product

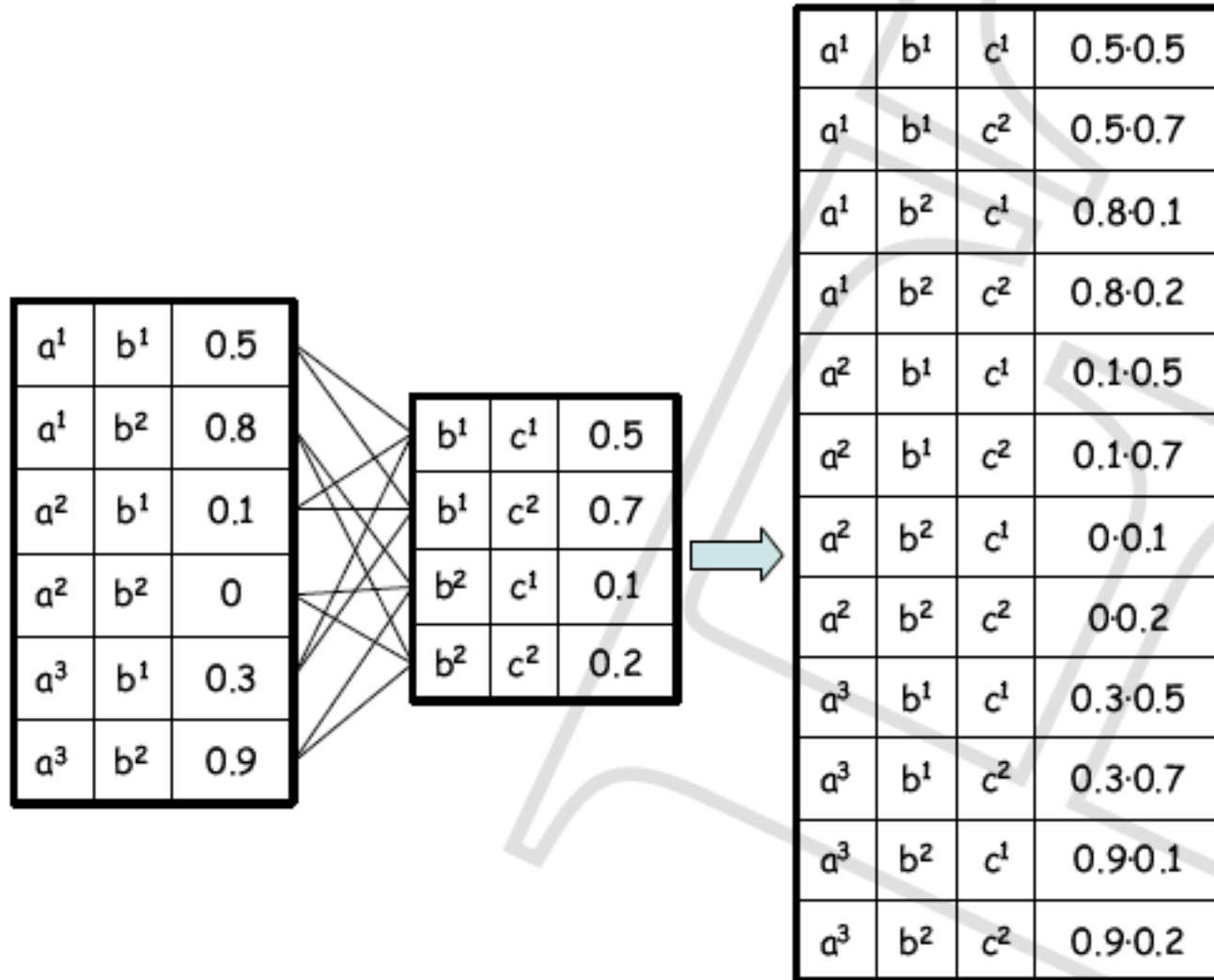
$$\psi : \text{Val}(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) \mapsto \mathbb{R}$$

- such that

$$\psi(\mathbf{X}, \mathbf{Y}, \mathbf{Z}) = \phi_1(\mathbf{X}, \mathbf{Y}) \cdot \phi_2(\mathbf{Y}, \mathbf{Z}).$$

Operations on Factors

- Factor Product



Operations on Factors

- Factor Marginalization

- Consider a factor

$$\phi(\mathbf{X}, Y)$$

- Define factor marginal

$$\psi(\mathbf{X}) : Val(\mathbf{X}) \mapsto \mathbb{R}.$$

- such that

$$\psi(\mathbf{X}) = \sum_Y \phi(\mathbf{X}, Y).$$

Operations on Factors

- Factor Marginalization

The diagram illustrates the process of factor marginalization. It shows a large table on the left representing a joint distribution over factors a , b , and c . The rows are grouped by the value of a (a^1 , a^2 , a^3). The columns are a , b , c , and a numerical value. Lines connect the rows of the large table to the rows of a smaller table on the right, which represents the marginal distribution over a and c . The numerical values in the smaller table are the sum of the values in the large table for each combination of a and c .

a^1	b^1	c^1	0.25
a^1	b^1	c^2	0.35
a^1	b^2	c^1	0.08
a^1	b^2	c^2	0.16
a^2	b^1	c^1	0.05
a^2	b^1	c^2	0.07
a^2	b^2	c^1	0
a^2	b^2	c^2	0
a^3	b^1	c^1	0.15
a^3	b^1	c^2	0.21
a^3	b^2	c^1	0.09
a^3	b^2	c^2	0.18

a^1	c^1	0.33
a^1	c^2	0.51
a^2	c^1	0.05
a^2	c^2	0.07
a^3	c^1	0.24
a^3	c^2	0.39

Factors

- Are factors always distributions?
 - Obviously not
- Are factors produced in VE always distributions?
 - Yes, always conditional distributions
 - In SOME graph, not necessarily the original graph
 - HW3, prob 2. Hint: read 8.3.1.3

Implementing VE

- What do you need to implement VE?
 - Reuse some code from HW2
- Representation
 - BN as an array of factors
 - table_factor.m
 - assignment.m
- VE
 - multiply_factors.m
 - marginalize_factor.m
 - min_fill.m

Variable elimination algorithm

- Given a BN and a query $P(X|e) / P(X,e)$
- Instantiate evidence e
- Prune non-active vars for $\{X, e\}$ ← optional
- Choose an ordering on variables, e.g., X_1, \dots, X_n
- Initial *factors* $\{f_1, \dots, f_n\}$: $f_i = P(X_i | \mathbf{Pa}_{X_i})$ (CPT for X_i)
- For $i = 1$ to n , If $X_i \notin \{X, \mathbf{E}\}$
 - Collect factors f_1, \dots, f_k that include X_i
 - Generate a new factor by eliminating X_i from these factors

$$g = \sum_{X_i} \prod_{j=1}^k f_j$$

- Variable X_i has been eliminated!
- Normalize $P(X, e)$ to obtain $P(X|e)$

Questions?