

09/18/08

DHRUV BATRA

→ BN Semantics / Representation

→ Defn. of BN (general BN)

structure { → set of random variables $\{x_1, \dots, x_n\} \triangleq X$
 → DAG over X

parameters { → CPTs $P(x_i | Pa(x_i))$

→ Joint factorizes $P(X) = \prod_{i=1}^n P(x_i | Pa(x_i))$

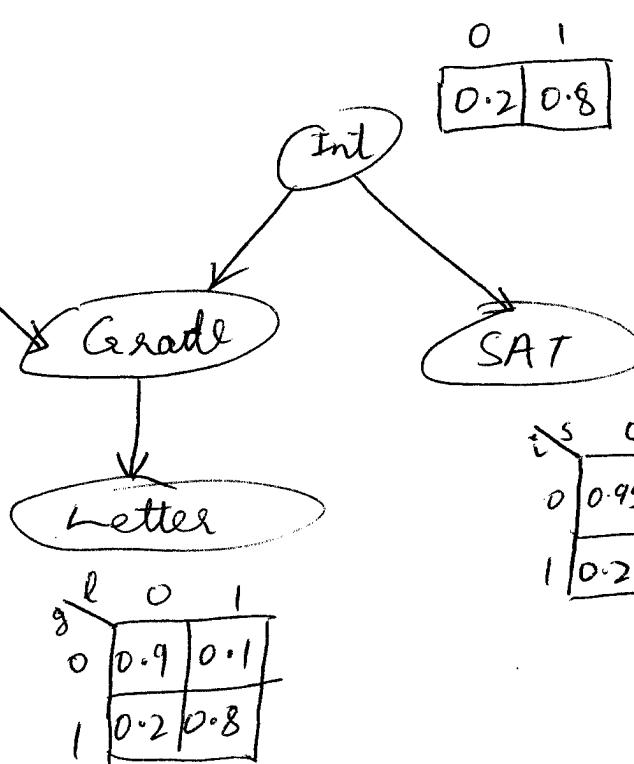
→ why?
 → Local Markov Assumption
 $(x_i \perp \text{NonDesc} | Pa(x_i))$

→ Example

0	1
0.1	0.9

(Diff)

di	g	0	1
00	0.5	0.5	
01	0.01	0.99	
10	0.49	0.01	
11	0.3	0.7	



→ ~~Answers~~ Queries

→ Inference / MAP

→ MPE (Most probable explanation)

Inference!

Ask for prob. of subset given observations

① $P(L|G)$ (simplest query) Why?

Lookup in CPT

Ask for prob of a complete assignment

② $P(d=1, i=1, s=0, g=1, l=1)$

$$= P(D=1) P(I=1) P(G=1 | D=1, I=1) \cdot P(S=0 | I=1)$$
$$P(L=1 | G=1)$$

$$= 0.9 \times 0.8 \times 0.7 \times 0.2 \times 0.8$$

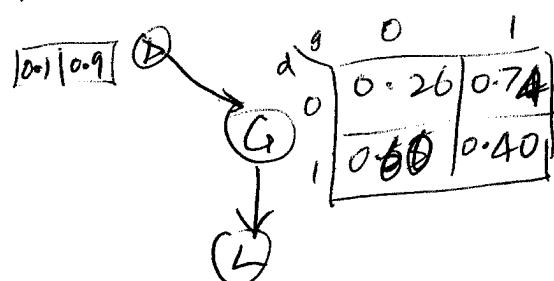
$$= 63 \times 64 \times 2 \times 10^{-5} = (4096 - 64) \cdot 2 \times 10^{-5}$$

$$= 4032 \cdot 2 \times 10^{-5}$$

$$= 8064 \times 10^{-5} \approx 0.081$$

③ $P(D|G=1)$

[Assume partial graph]



$$P(D=1 | G=1) = \frac{P(G=1 | D=1) P(D=1)}{P(G=1)}$$

$$= \frac{P(G=1 | D=1) P(D=1)}{\sum_{d=0} P(G=1 | D=d) P(D=d)}$$

$$= \frac{0.9 \times 0.4}{(0.1 \times 0.74) + (0.9 \times 0.4)} \rightarrow 0.83$$

Do you expect this to change when rest of variables are added in?

why? (hint: v-structure)



MAP

$$\textcircled{1} \quad \underset{\text{MAP}}{\cancel{\text{what is}}} \underset{\text{arg}}{\cancel{\text{max}}} \underset{\text{of}}{\cancel{\text{arg}}} \underset{\text{P}(Q|E)}{\cancel{}}$$

e.g. what is MAP value of $D | G=1$
 [ans 1]

Discussion: Sometimes we're more interested in MAP than prob.

MPE

Most probable explanation of all variables other than observation

①. No observation

"Most likely student"

$\arg\max P(D, I, A, L, S)$

Naively 2^5



(*)

Discussion MPE vs MAP explanations
might be different!

→ Graphs & Distributions ③

→ Defns: $I_e(G)$ Local Markov Assumptions

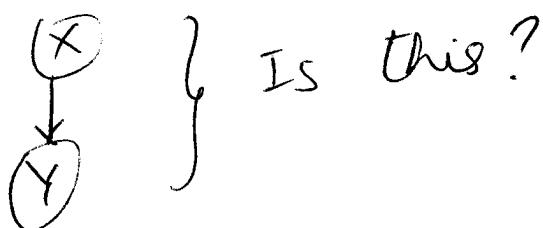
→ $I(P)$,^(true) independence assertions from data/madd world

→ [Defn]: I-map

G is I-map if $I_e(G) \subseteq I(P)$

Example

$\begin{array}{c} (X) \\ (Y) \end{array} \quad \left. \begin{array}{l} \text{Is this an I-map for any/all} \\ P(x, y)? \end{array} \right\}$



→ ~~Defn~~ what does it mean for a distribution P to "factorize" over BN G

[Defn]: P factorizes over G if

$$P(X) = \prod_{i=1}^n P(X_i | Pa(X_i))$$

Refined Defn of BN as (G, P) where P factorizes over G



~~2nd~~ Equivalence of I-maps to P 's (that factorize)

Given: G over $X = \{x_1, \dots, x_n\}$, P distribution over X

→ ~~Def~~ Claim 1:

G is an I-map \Rightarrow
for P

P factorizes
according to G

$$\text{i.e. } I_e(G) \subseteq I(P)$$

→ Proof: Topological ordering + Chain Rule

Th 3.2.6 KF

Implication: If we find an I-map, we can (potentially) save some parameters

→ A trivial I-map always exists, but that doesn't help

(4)

→ Claim 2:

P factorizes according to $G \Rightarrow G$ is an I-map of P

Proof: HW1

Implication: G can help us read-off
independence / dependence relations
beyond $I_e(G)$

